# Tehnici de Optimizare

Facultatea de Matematica si Informatica
Universitatea Bucuresti

Department Informatica-2021

#### Proiect

- Alegere 1-2 lucrari; maxim 2 alegeri per lucrare
- Documentatie (rezultate ale lucrarii); limita pagini: 5-20
- Simulari (algoritmi din lucrare); grafice de analiza
- Echipa: maxim 2 3 studenti
- Pondere nota: 60%
- Termen: in sesiune
- Evaluare: online fata-in-fata

#### Cursul de azi

Problema de fezabilitate convexa

- Probleme de optimizare cu constrangeri de egalitate
  - Functia Lagrange
  - Multiplicatori Lagrange
  - Conditii de optimalitate

#### Problema de fezabilitate convexa

Fie 
$$C_1$$
 si  $C_2$  multimi simple convexe, calculati  $x \in Q = C_1 \cap C_2$ 

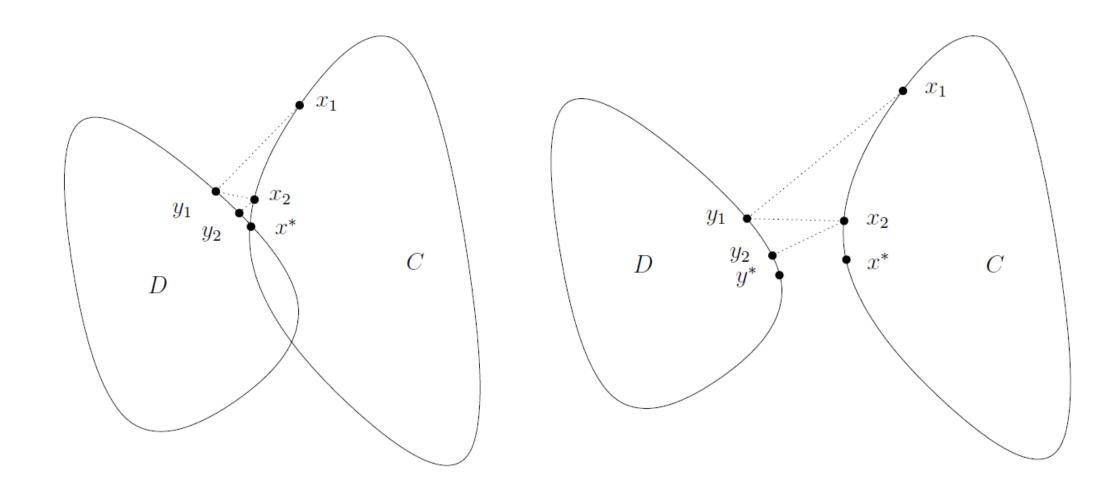
#### Algoritmul proiectiilor alternative:

1. 
$$x^k = \pi_{C_1}(y^k)$$

2. 
$$y^{k+1} = \pi_{C_2}(x^k)$$

Daca  $Q \neq \emptyset$ , se arata ca  $x^k \rightarrow x^* \in Q$ 

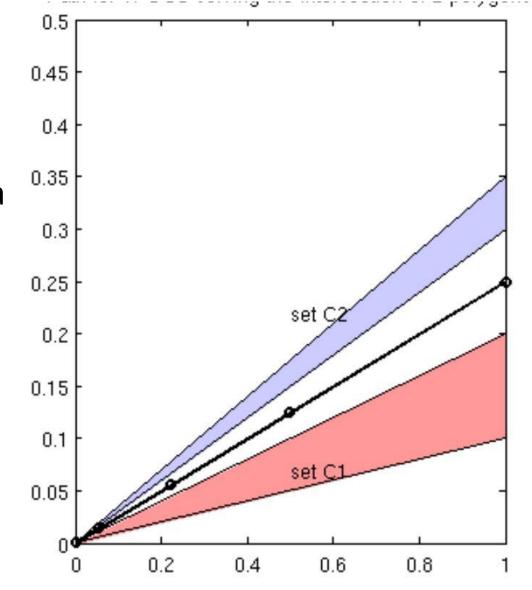
### Problema de fezabilitate convexa



#### Problema de fezabilitate convexa

• Daca  $C_1$  si  $C_2$  sunt subspatii/poligoane liniare, atunci APA are convergenta liniara

• Convergenta este strict legata de unghiul de la intersectia celor doua:  $\theta \approx 0$  implica un nr. mare de iteratii.



#### Cursul de azi

$$\min f(x)$$
 s.l.  $x \in Q$ 

• Problema de fezabilitate convexa

- Probleme de optimizare cu constrangeri de egalitate
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## Optimizare cu constrangeri de egalitate

$$\min_{\mathbf{x}} f(\mathbf{x}) \quad s. l. \ g_i(\mathbf{x}) = 0, \qquad i = 1, \dots, m$$

- f,  $g_i$  functii diferentiabile, notam  $g(x) = \begin{bmatrix} g_1(x) \\ \dots \\ g_m(x) \end{bmatrix}$
- Pentru g(x) = Ax b avem  $Q = \{x : g(x) = 0\}$  convexa (altfel neconvexa!)
- Exemplu:  $Q = \{x \in R^2: x_1^2 + x_2^2 = 1\}$

### Optimizare cu constrangeri de egalitate

$$\min_{\mathbf{x}} f(\mathbf{x})$$
 s.l.  $g_i(\mathbf{x}) = 0$ ,  $i = 1, \dots, m$ 

• In forma de mai sus, nu se intrevad conditii de optimalitate

Functia Lagrangian: L: 
$$\mathbb{R}^n \times \mathbb{R}^m \to R$$
,  $L(x, \lambda) = f(x) + \sum_i \lambda_i g_i(x)$ 

• Vom folosi functia Lagrange pentru a exprima conditii de optimalitate!

## Optimizare cu constrangeri de egalitate

$$\min_{\mathbf{x}} f(\mathbf{x}) \quad s. l. \quad g_i(\mathbf{x}) = 0, \qquad i = 1, \dots, m$$

Vecinatate 
$$V(x) = \{s: ||x - s|| \le r\}$$

Pct. de minim: 
$$x^* \in Q$$
,  $a.i.$   $f(x^*) \le f(x)$   $\forall x \in Q \cap V(x^*)$ 

Pct. de minim regulat : 
$$x^* \in Q$$
,  $a.i.$   $f(x^*) \le f(x)$   $\forall x \in Q \cap V(x^*)$ 

 $\nabla g_i(x^*)$  liniar independenti

+

$$v_1, \cdots, v_m \ l. \ d. \ daca \ exista \ \alpha \neq 0 \ a. \ i. \sum \alpha_i v_i = 0$$

$$\begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \end{bmatrix}$$
  $l.i., \begin{bmatrix} 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 2 \\ 0 \end{bmatrix}$   $l.d.$ 

### Exemplu minim regulat

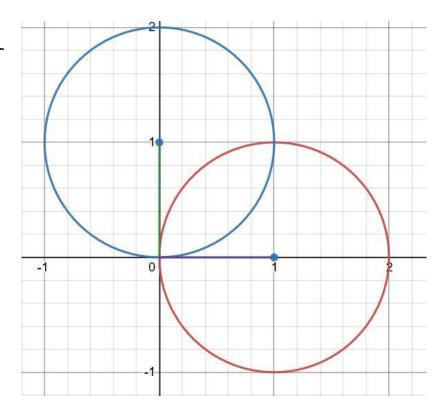
$$\min x_2$$
s.l. $(x_1 - 1)^2 + x_2^2 = 1$ 

$$x_1^2 + (x_2 - 1)^2 = 1$$

$$\nabla \mathbf{g_1}(\mathbf{0},\mathbf{0}) = \begin{bmatrix} -2\\ \mathbf{0} \end{bmatrix}$$

$$\nabla \mathbf{g}_2(\mathbf{0},\mathbf{0}) = \begin{bmatrix} \mathbf{0} \\ -2 \end{bmatrix}$$

Concluzie: minim regulat  $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ !



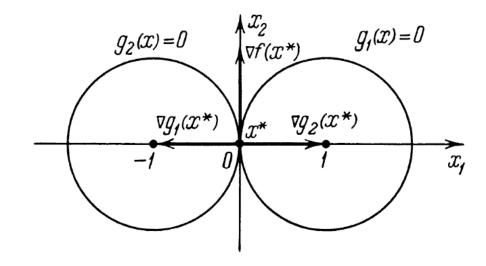
### Exemplu minim neregulat

$$\min x_2$$
s.l. $(x_1 - 1)^2 + x_2^2 = 1$ 
 $(x_1 + 1)^2 + x_2^2 = 1$ 

$$\nabla \mathbf{g_1}(\mathbf{0},\mathbf{0}) = \begin{bmatrix} -2\\ \mathbf{0} \end{bmatrix}$$

$$\nabla g_2(0,0) = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

Concluzie: minim neregulat  $\begin{bmatrix} 0 \\ 0 \end{bmatrix}$ !



### Conditii necesare de ordin I

THEOREM 2 (The rule of Lagrange multipliers). If  $x^*$  is a regular minimum point, then we can find  $y_1^*$ , ...,  $y_m^*$  such that

$$\nabla f(x^*) + \sum_{i=1}^m y_i^* \nabla g_i(x^*) = 0.$$
 (2)

Echivalent cu  $\nabla_x L(x^*, \lambda^*) = 0$  (conditii de optimalitate, caz neconstrans!)  $\lambda^*$  se numesc Multiplicatori Lagrange!

Pentru simplitate pp. ca  $x^*$  minim unic si global in vecinatatea  $V(x^*)$ .

Formam functia penalitate:  $f_{\rho}(x) = f(x) + \frac{\rho}{2} ||g(x)||^2$  (param.  $\rho$  de penalitate); O noua problema:

$$\min_{\mathbf{x} \in V(x^*)} f_{\rho}(x) = f(x) + \frac{\rho}{2} ||g(x)||^2$$

cu solutia  $x^{\rho}$ . Observam ca:

$$f(x^{\rho}) + \frac{\rho}{2} ||g(x^{\rho})||^{2} = f_{\rho}(x^{\rho}) \le f_{\rho}(x^{*}) = f(x^{*}) + \frac{\rho}{2} ||g(x^{*})||^{2} = f(x^{*})$$
$$||g(x^{\rho})||^{2} \le \frac{2}{\rho} (f(x^{*}) - f(x^{\rho}))$$

Termenul  $\frac{2}{\rho} (f(x^*) - f(x^\rho)) \to 0$  cand  $\rho \to \infty$   $(x^\rho \in V(x^*))$ 

$$\min_{\mathbf{x} \in V(x^*)} f_{\rho} (\mathbf{x}) = f(\mathbf{x}) + \frac{\rho}{2} ||g(\mathbf{x})||^2$$

cu solutia  $x^{\rho}$ . Observam ca:

$$f(x^{\rho}) + \frac{\rho}{2} ||g(x^{\rho})||^{2} = f_{\rho}(x^{\rho}) \le f_{\rho}(x^{*}) = f(x^{*}) + \frac{\rho}{2} ||g(x^{*})||^{2} = f(x^{*})$$
$$||g(x^{\rho})||^{2} \le \frac{2}{\rho} (f(x^{*}) - f(x^{\rho}))$$

Termenul  $\frac{2}{\rho} (f(x^*) - f(x^\rho)) \to 0$  cand  $\rho \to \infty$   $(x^\rho \in V(x^*))$ 

Deci  $g(x^{\rho}) \to 0$  cand  $\rho \to \infty$ . Orice pct. limita  $x^{\rho_k} \to \bar{x}$  are  $g(\bar{x}) = 0$ .

Din inegalitatea de mai sus:  $f(\bar{x}) \le f(x^*)$ , dar si  $f(\bar{x}) \ge f(x^*)$ , deci  $\bar{x} = x^*$ 

$$\min_{\mathbf{x} \in V(x^*)} f_{\rho}(\mathbf{x}) = f(\mathbf{x}) + \frac{\rho}{2} ||g(\mathbf{x})||^2$$

cu solutia  $x^{\rho}$ .

Cand  $\rho \to \infty$ ,  $x^{\rho} = x^*$ , deci pt  $\rho$  suf. de mare avem  $x^{\rho}$  in interiorul lui  $V(x^*)$ 

Pe de alta parte  $x^{\rho}$  satisfice  $\nabla f_{\rho}(x^{\rho}) = 0$ , echivalent

$$\nabla f(x^{\rho}) + \rho \sum_{i} g_{i}(x^{\rho}) \nabla g_{i}(x^{\rho}) = 0$$

Impartim prin  $1 + \rho \sum_{i} g_{i}(x^{\rho})$  (suma tuturor ponderilor) si obtinem:

$$\lambda_0^{\rho} \nabla f(x^{\rho}) + \sum_i \lambda_i^{\rho} \nabla g_i(x^{\rho}) = 0$$

Pentru ca  $\sum_i (\lambda_i^{\rho})^2 = 1$ , deci  $\lambda^{\rho}$  marginit, are un pct limita  $\lambda^*$ , care confirma:

$$\lambda_0^* \nabla f(x^*) + \sum_i \lambda_i^* \nabla g_i(x^*) = 0$$

$$\nabla f(x^*) + \sum_{i} \frac{\lambda_i^*}{\lambda_0^*} \nabla g_i(x^*) = 0$$

### Metoda penalitate

$$x^{k} = \arg\min f_{\rho_{k}}(x) = f(x) + \frac{\rho_{k}}{2} ||g(x)||^{2}$$
  
 $\rho_{k+1} = 2\rho_{k}$ 

C.N. ordin I sugereaza:  $x^k \rightarrow x^*$  (punct stationar)