

ALGORITHM IC DIFFERENTI ATION

using the Taylor
method for high-
accuracy integration
of non-stiff problems

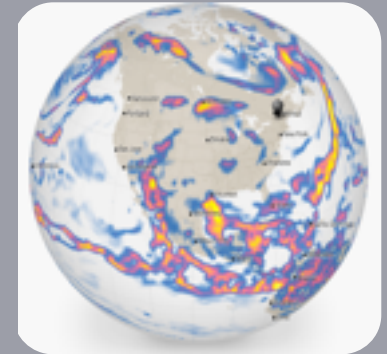
#DIFFERENTIATEEVERYTHING

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DEPARTMENT OF MATH
UNIVERSITY OF VERMONT

MAIN IDEAS

ALGORITHMIC DIFFERENTIATION

The basics, main theorem, example



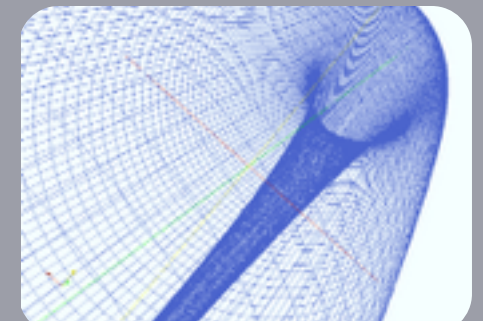
ADVANTAGES AND DISADVANTAGES

Why do we want to use this



IMPLEMENTATION DETAILS

Operator overloading and source code transformation



MAIN RESULTS: 3-BODY PROBLEM

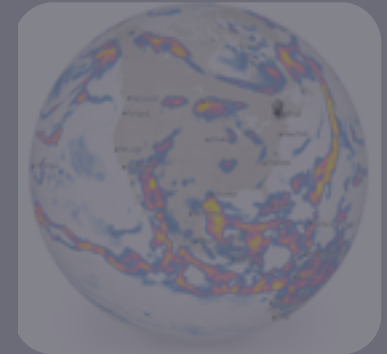
Comparing a high-order Taylor method



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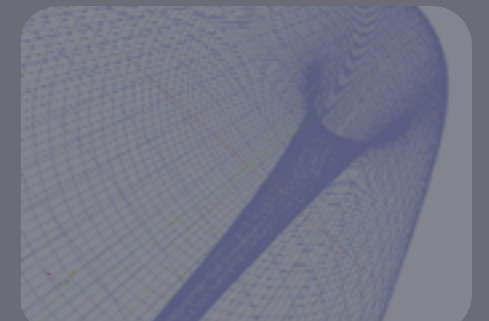
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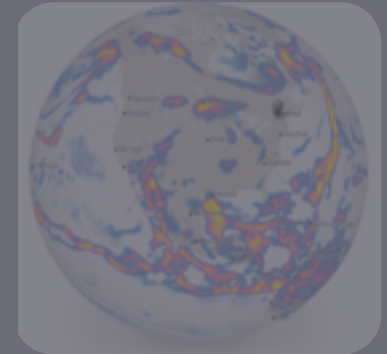
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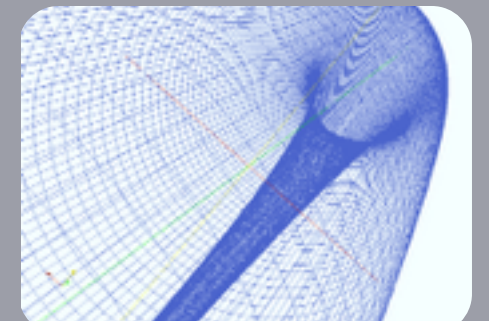
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```

VACC happy%
VACC happy% cat tbp.in
/* ODE specification: tbp
   Two body problem, discretized into
   a set of four ODE's.  */

diff(x1, t)= x3;
diff(x2, t)= x4;
diff(x3, t)= -x1/((x1^2+x2^2)^(3/2));
diff(x4, t)= -x2/((x1^2+x2^2)^(3/2));

ecc = 0.6; /* 1-ecc, 0, 0, -sqrt((1+ecc)/(1-ecc)); */

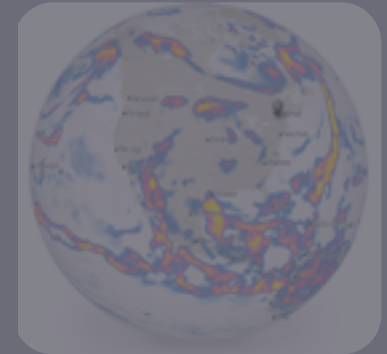
initial_values= 0.4, 0, 0, -2;
start_time= 0.0;
stop_time = 500.0;
absolute_error_tolerance = 0.1e-16;
relative_error_tolerance = 0.1e-16;
VACC happy% cat make.sh
# make the executable
./taylor -name tbp -o tbp.c -jet -step tbp.in
./taylor -name tbp -o taylor.h -header
./taylor -name tbp -o main_tbp.c -main_only tbp.in
gcc -O3 main_tbp.c tbp.c -lm -sVACC happy%
VACC happy% █

```


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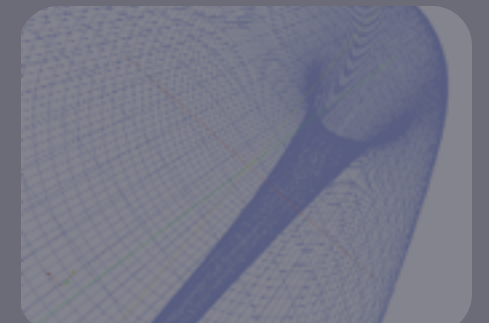
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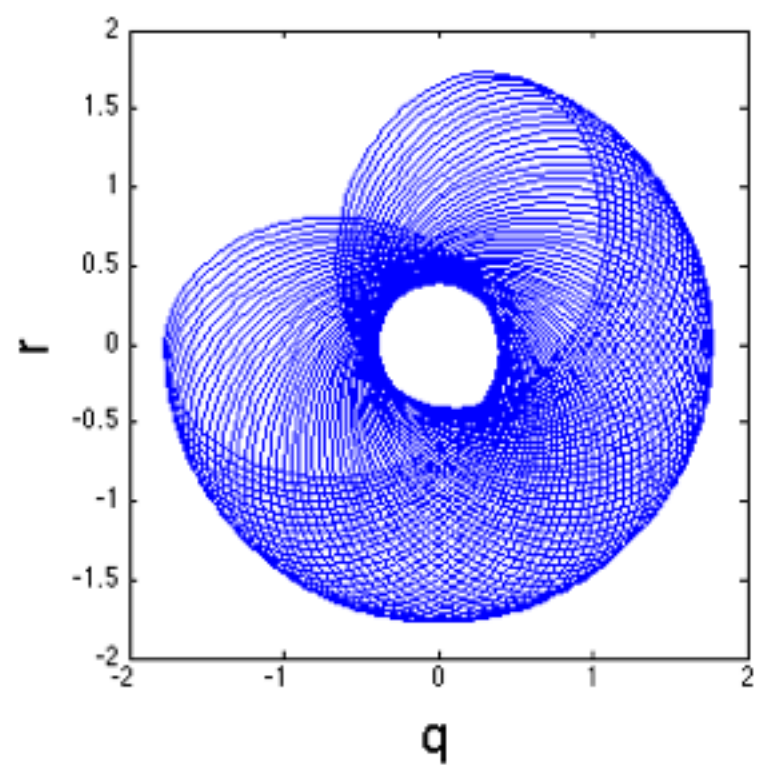
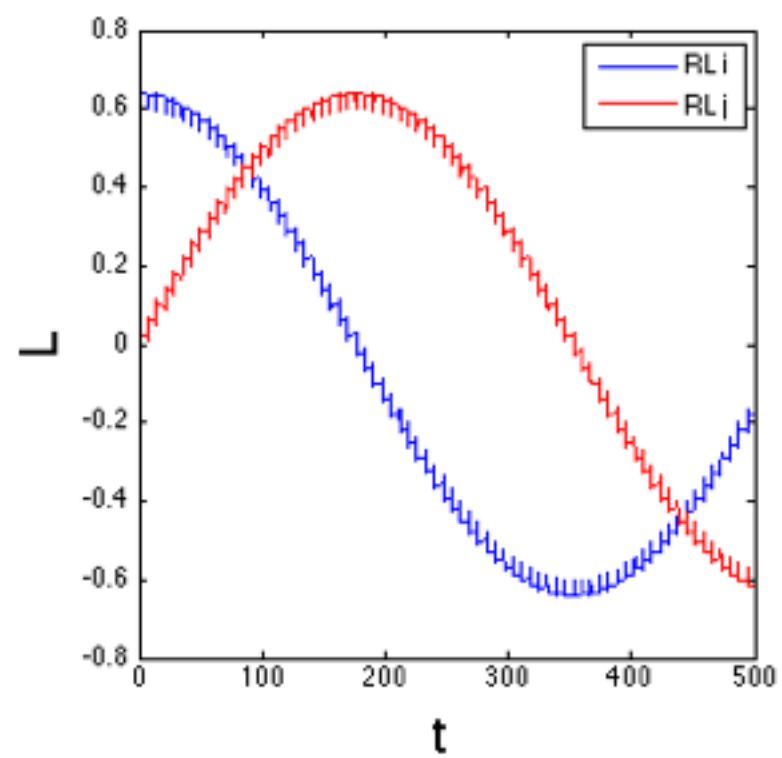
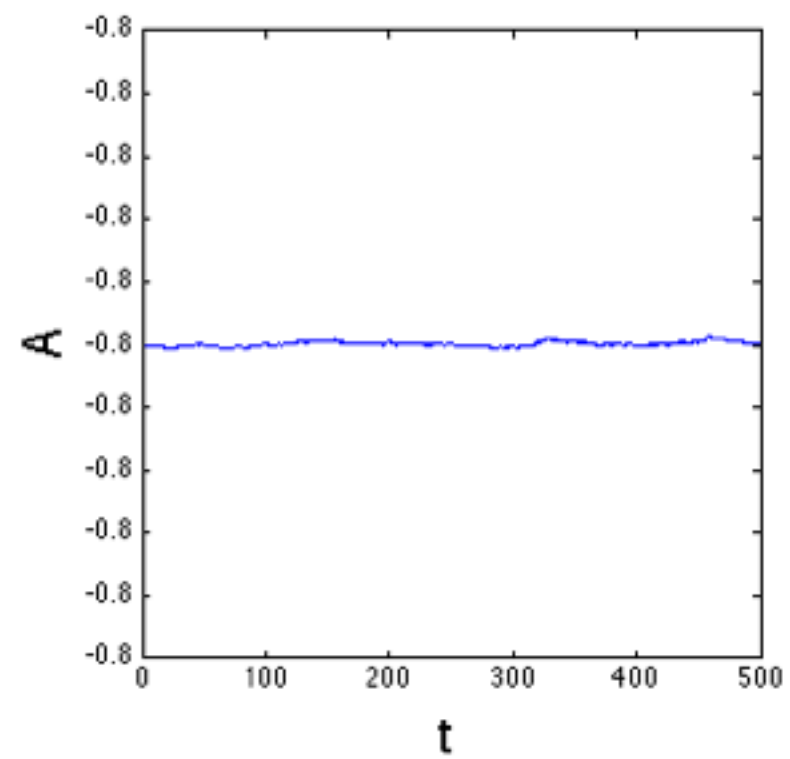
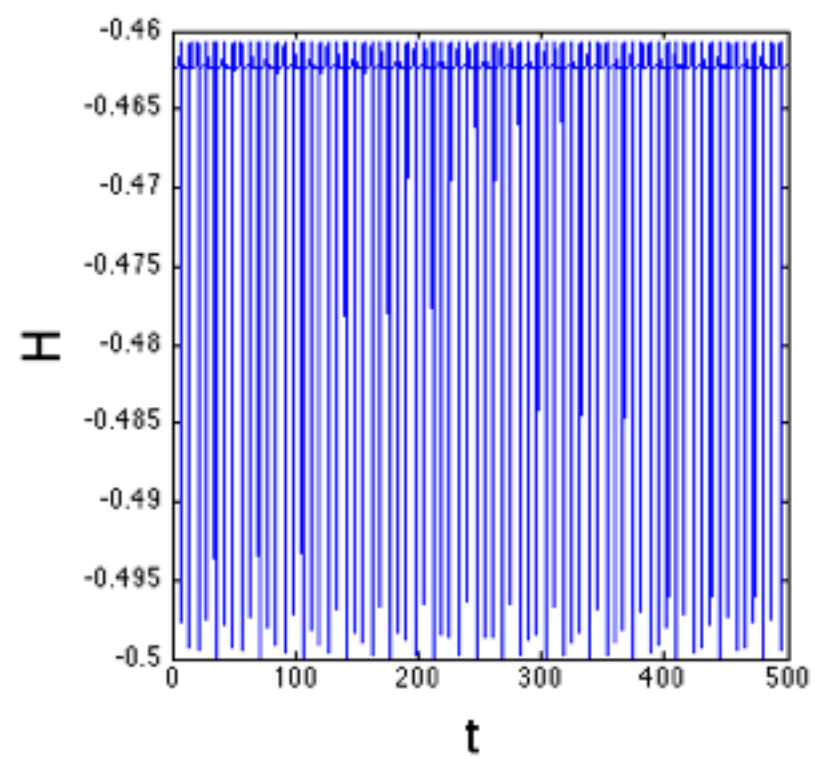
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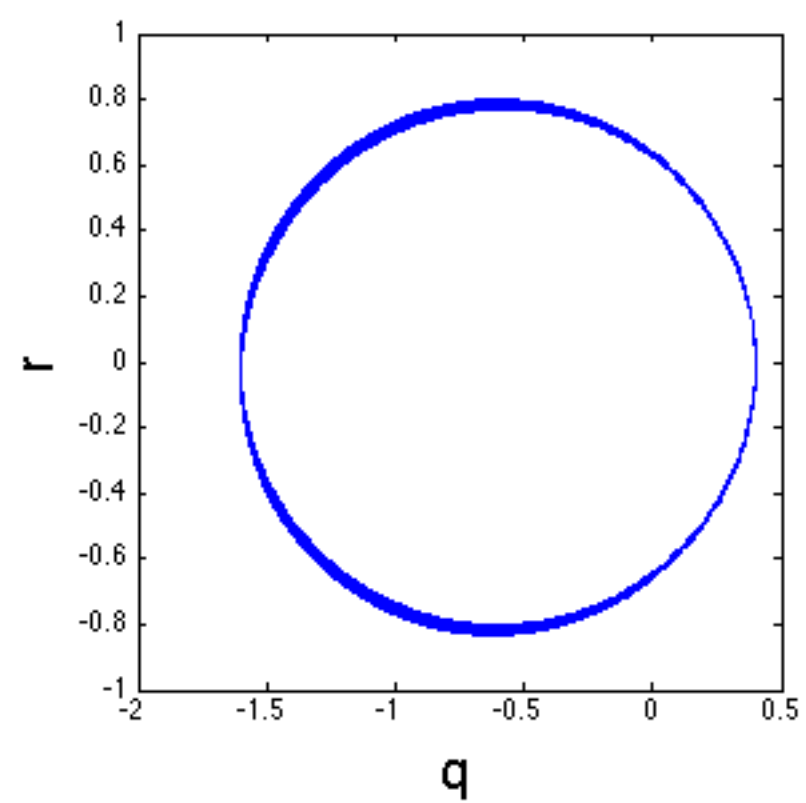
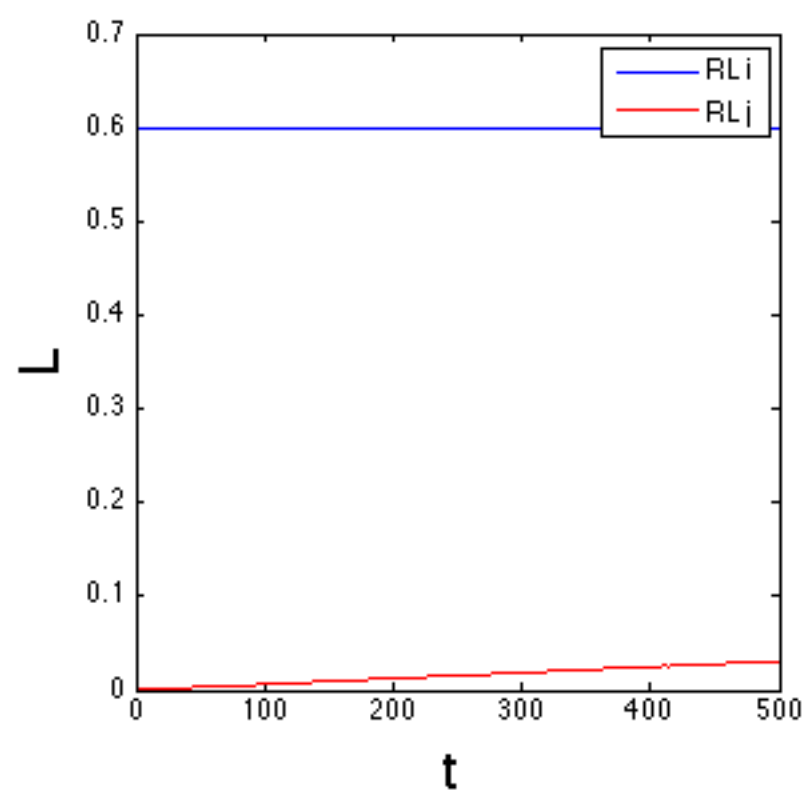
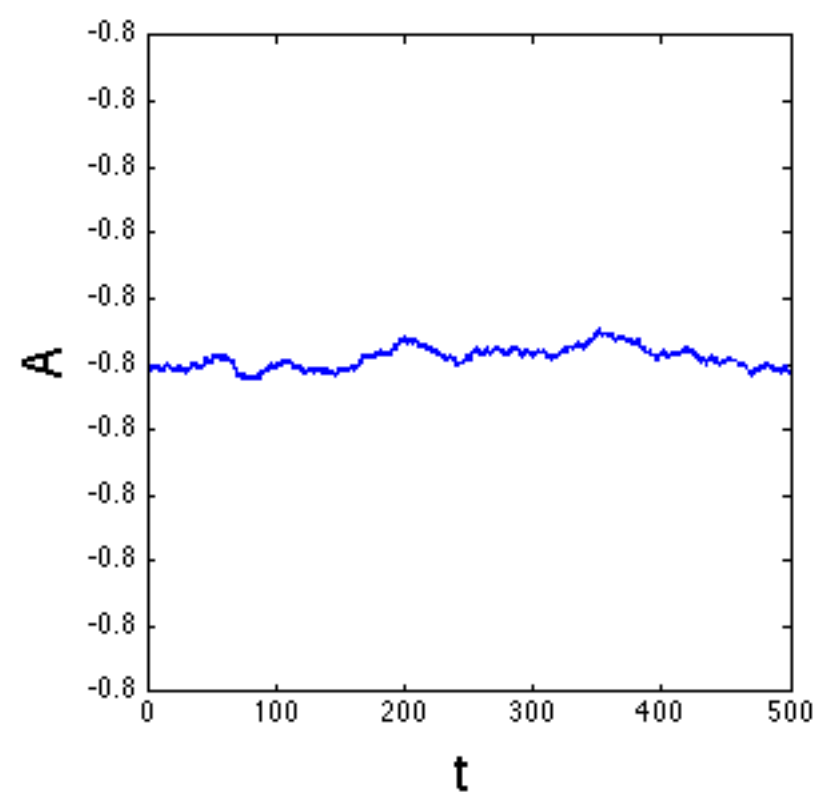
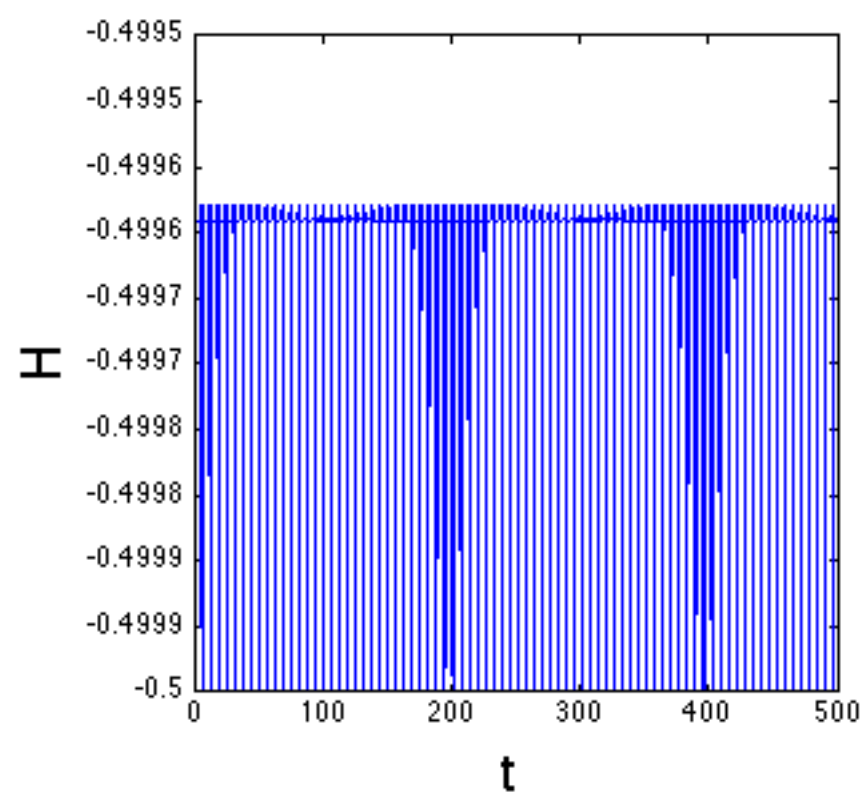


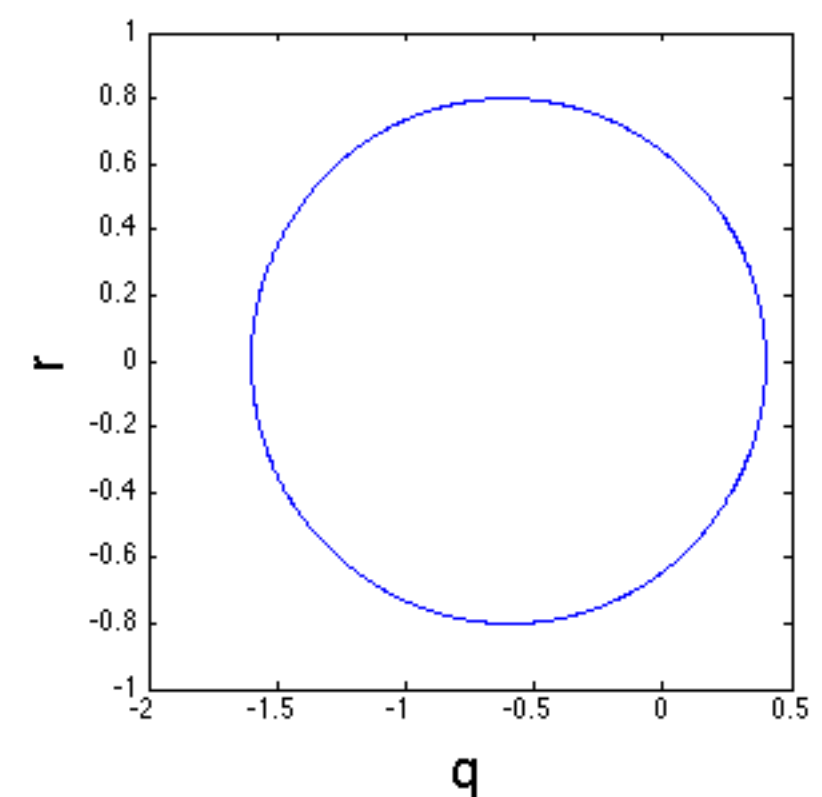
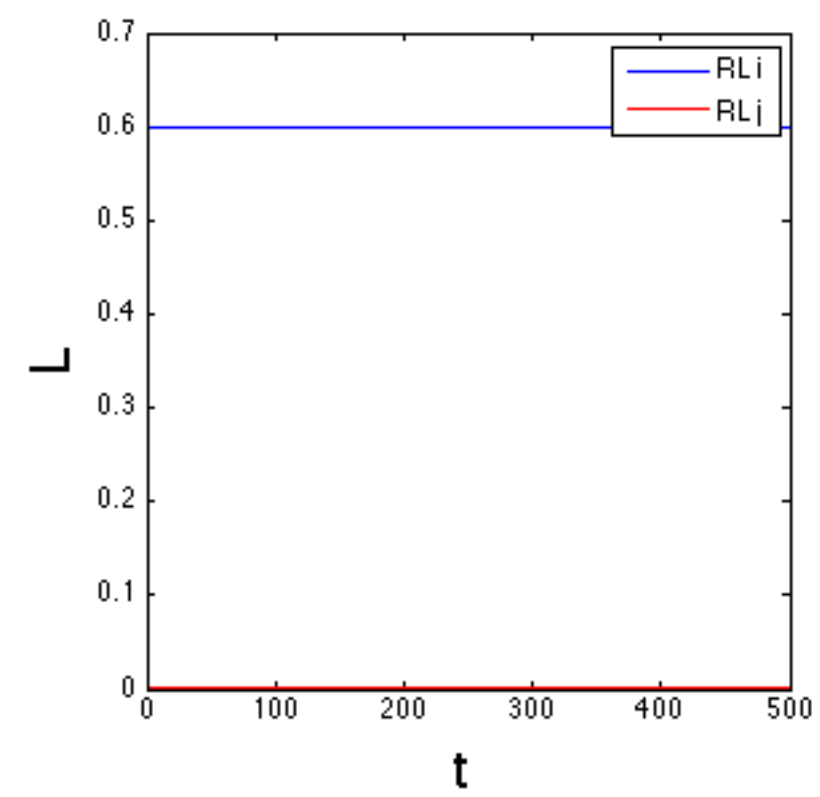
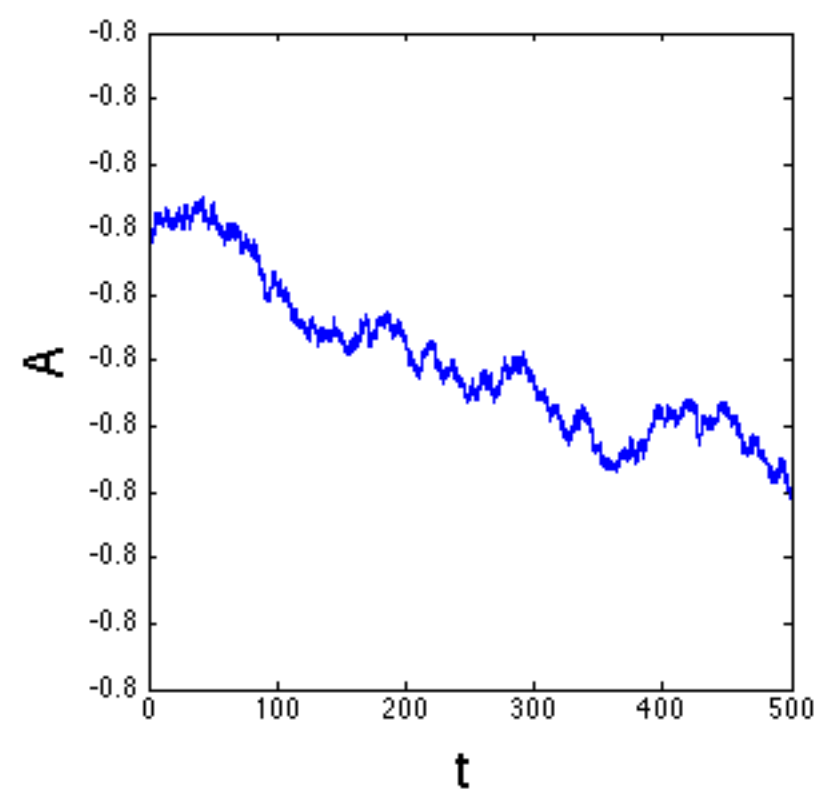
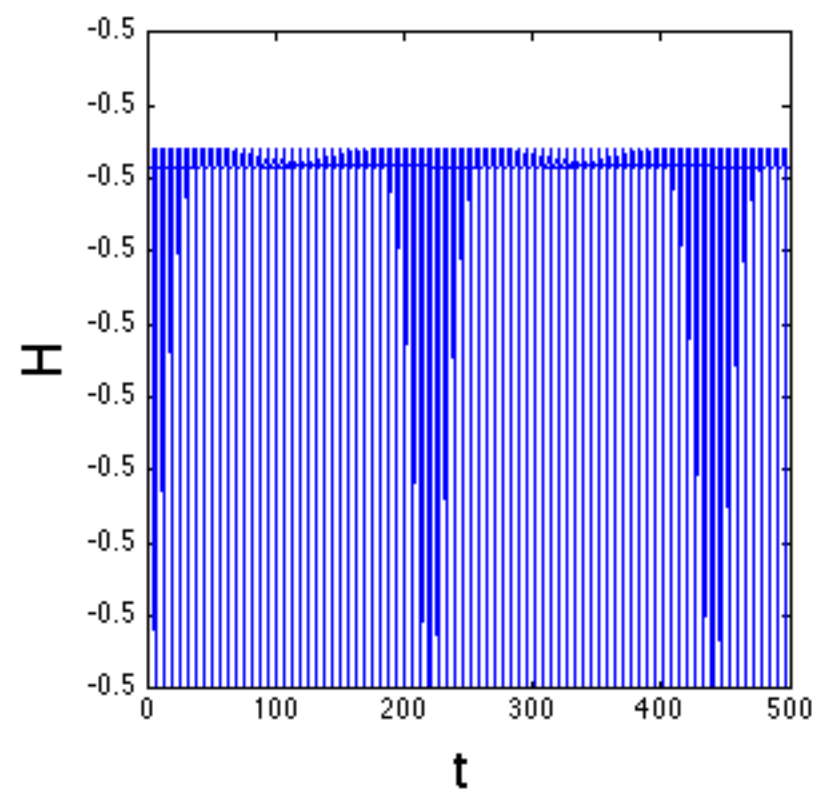
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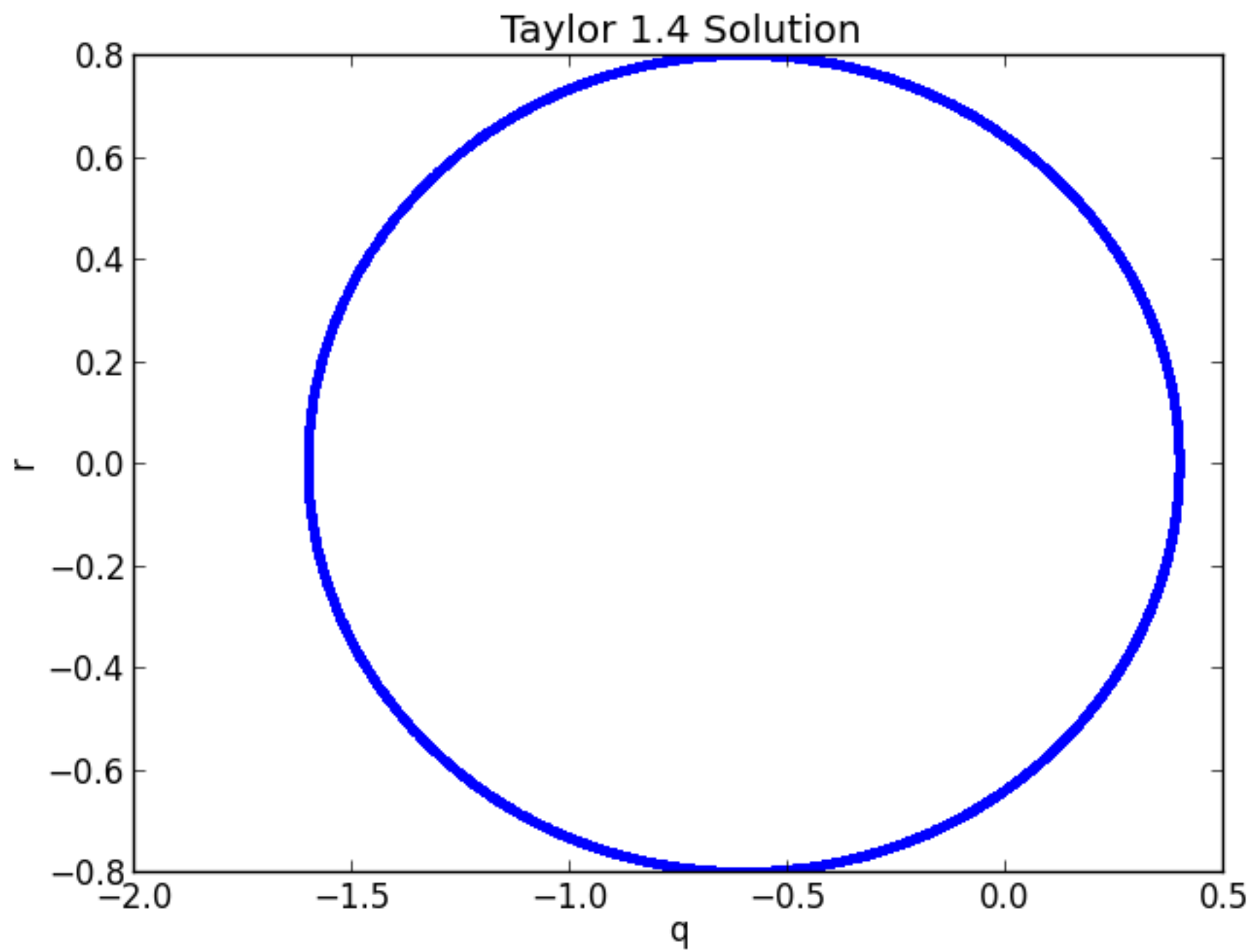
Comparing a high-order Taylor method











THANK YOU