

# Sensing Tree Automata as a Model of Syntactic Dependencies

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#### The Talk in One Minute

#### The research program

a tight upper bound to the complexity of natural language dependencies?

#### In this talk

- Sensing tree automata as a uniform upper bound
- MG dependency trees

#### **Spoilers**

- ► A (linguistically) natural perspective!
- Empirically attested restrictions on movement
- Head-argument relations
- C-command and licensing conditions

### Outline

- 1 Preliminaries
- 2 Merge and Move via STA
- 3 Licensing Conditions
- 4 Conclusion & Open Questions

### Computational Theories of Language

#### The subregular program

Can we provide tight complexity characterizations for natural language?

- Particularly successful in phonology (Heinz et al. 2011; Chandlee 2014; Jardine 2016; McMullin 2016; Graf 2017; Graf and Mayer 2018)
- Some results for syntax
  - regular tree languages (Michaelis 2004; Kobele et al. 2007; Graf 2012)
  - subregular operations? (Graf 2012, 2018)
  - subregular dependencies? (Vu 2018; Vu et al. 2019)
  - subregular constraints? (Shafiei and Graf 2019)

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Can we gain a unified perspective for syntax?

### Syntax?

#### We need a formal model of syntactic structures.

- ► Minimalist grammars (MGs) are a formalization of Minimalist syntax. (Stabler 1997, 2011)
- Operations:
  - Merge

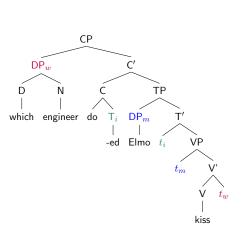
```
category feature N^-, D^-, ... selector feature N^+, D^+, ...
```

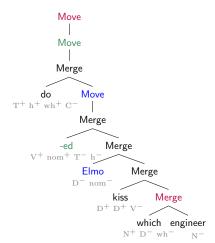
Move

```
licensee feature wh<sup>-</sup>, nom<sup>-</sup>, ... licensor feature wh<sup>+</sup>, nom<sup>+</sup>, ...
```

- Adopt Chomsky-Borer hypothesis: Grammar is just a finite list of feature-annotated lexical items
- ► The set of derivation trees is a regular tree language. (Michaelis 2004; Kobele et al. 2007; Graf 2012)

### MG Syntax: Derivation Trees



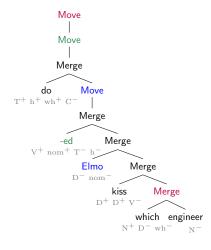


#### Phrase Structure Tree

#### **Derivation Tree**

### MG Syntax: Dependency Trees

**Preliminaries** 



$$do :: T^+ h^+ wh^+ C^-$$

$$-ed :: V^+ nom^+ T^- h^-$$

$$-ed :: V^+ nom^+ T^- h^-$$

$$kiss :: D^+ D^+ V^-$$

$$Elmo :: D^- nom^- which :: N^+ D^- wh^-$$

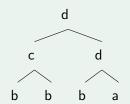
$$-engineer :: N^-$$

**Derivation Tree** 

**Dependency Tree** 

#### Sensing Tree Automata (STA)

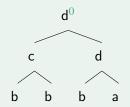
Deterministic top-down tree automata with finite look-ahead of 1.



- ightharpoonup 0(b) o b; 1(b) o b
- ightharpoonup 1(a) 
  ightharpoonup a

#### Sensing Tree Automata (STA)

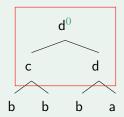
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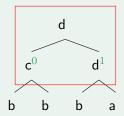
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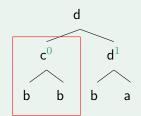
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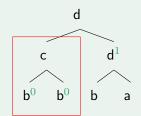
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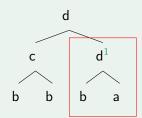
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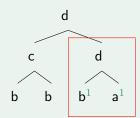
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#### Sensing Tree Automata (STA)

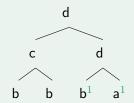
Deterministic top-down tree automata with finite look-ahead of 1.



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#### Sensing Tree Automata (STA)

Deterministic top-down tree automata with finite look-ahead of 1.



- ightharpoonup 0(b) o b; 1(b) o b
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  ightharpoonup a

### Interim Summary

#### We are looking for a complexity upper bound for syntax...

- MG dependency trees (MDEP)
- STA

- ► MDEP[merge] ⊆ STA
- MDEP[merge, move] ⊆ STA iff we restrict move

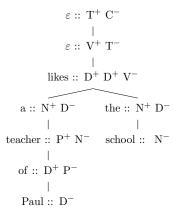
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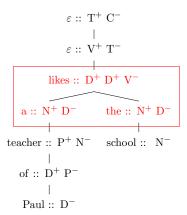
#### **Upcoming**

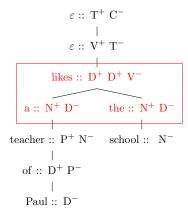
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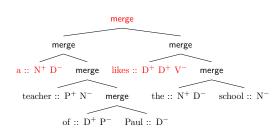


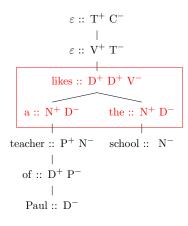
```
\varepsilon :: T^+ C^-
           likes :: D^+ D^+ V^-
   a::\ N^+\ D^- \qquad \quad the::\ N^+\ D^-
teacher :: P<sup>+</sup> N<sup>-</sup> school :: N<sup>-</sup>
   of :: D+ P-
    Paul :: D^-
```

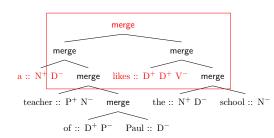
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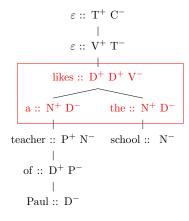


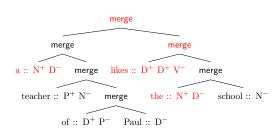


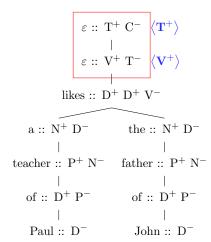












$$\varepsilon :: \mathbf{T}^{+} \ \mathbf{C}^{-} \ \left\langle \mathbf{T}^{+} \right\rangle$$

$$\varepsilon :: \mathbf{V}^{+} \ \mathbf{T}^{-} \ \left\langle \mathbf{V}^{+} \right\rangle$$

$$| \mathbf{V}^{+} \ \mathbf{V}^{-} \ \left\langle \mathbf{D}^{+} \mathbf{D}^{+} \right\rangle$$

$$| \mathbf{D}^{+} \ \mathbf{V}^{-} \ \left\langle \mathbf{D}^{+} \mathbf{D}^{+} \right\rangle$$

$$| \mathbf{D}^{+} \ \mathbf{V}^{-} \ \mathbf{D}^{+} \mathbf{D}^{-}$$

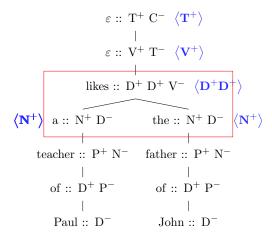
$$| \mathbf{D}^{+} \ \mathbf{V}^{-} \ \mathbf{D}^{+} \mathbf{D}^{-}$$

$$| \mathbf{D}^{+} \ \mathbf{V}^{-} \ \mathbf{D}^{+} \mathbf{D}^{-}$$

$$| \mathbf{D}^{+} \ \mathbf{D}^{-} \ \mathbf{D}^{+} \ \mathbf{D}^{-}$$

$$| \mathbf{D}^{-} \ \mathbf{D}^{+} \ \mathbf{D}^{-} \ \mathbf{D}^{-}$$

$$| \mathbf{D}^{-} \ \mathbf{D}^{-} \ \mathbf{D}^{-} \ \mathbf{D}^{-}$$

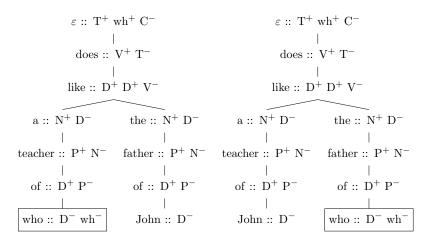


```
\varepsilon :: T^+ C^- \langle T^+ \rangle
                                  \varepsilon :: V^+ T^- \langle V^+ \rangle
                           likes :: D^+ D^+ V^- \langle D^+ D^+ \rangle
    \langle \mathbf{N}^+ \rangle a :: N<sup>+</sup> D<sup>-</sup> the :: N<sup>+</sup> D<sup>-</sup> \langle \mathbf{N}^+ \rangle
\langle \mathbf{P}^+ \rangle teacher :: P^+ N^- father :: P^+ N^- \langle \mathbf{P}^+ \rangle
                of :: D^+ P^- of :: D^+ P^-
                 Paul :: D^- John :: D^-
```

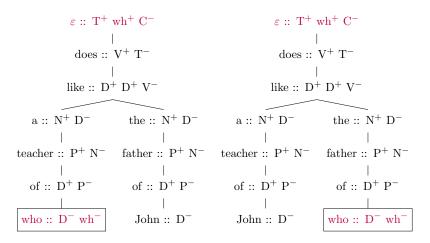
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    \langle \mathbf{D}^+ \rangle of :: D^+ P^- of :: D^+ P^- \langle \mathbf{D}^+ \rangle
           \langle \varepsilon \rangle Paul :: D<sup>-</sup> John :: D<sup>-</sup> \langle \varepsilon \rangle
```

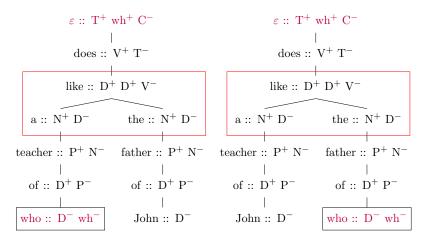
### MDEP[merge,move]

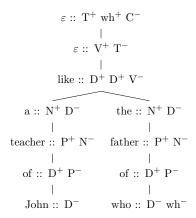


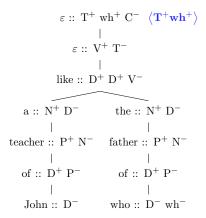
# MDEP[merge,move]

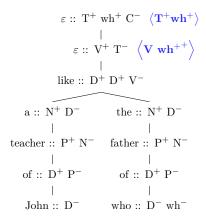


# MDEP[merge, move]







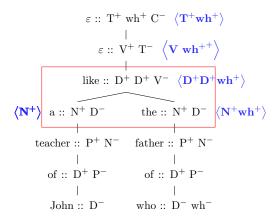


$$\varepsilon :: T^{+} \text{ wh}^{+} C^{-} \left\langle \mathbf{T}^{+} \mathbf{wh}^{+} \right\rangle$$

$$\varepsilon :: V^{+} T^{-} \left\langle \mathbf{V} \mathbf{wh}^{++} \right\rangle$$

$$\begin{vmatrix} \text{like} :: D^{+} D^{+} V^{-} \left\langle \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{wh}^{+} \right\rangle \\ & \\ 1 & \\$$

# MDEP[merge,move] ⊈ STA



$$\varepsilon :: \mathbf{T}^{+} \ \mathbf{wh}^{+} \ \mathbf{C}^{-} \ \left\langle \mathbf{T}^{+} \mathbf{wh}^{+} \right\rangle$$

$$\varepsilon :: \mathbf{V}^{+} \ \mathbf{T}^{-} \ \left\langle \mathbf{V} \ \mathbf{wh}^{++} \right\rangle$$

$$| \mathbf{kke} :: \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{V}^{-} \ \left\langle \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{P}^{+} \rangle \ \text{ a } :: \mathbf{N}^{+} \ \mathbf{D}^{-} \ \text{ the } :: \mathbf{N}^{+} \ \mathbf{D}^{-} \ \left\langle \mathbf{N}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{P}^{+} \rangle \ \text{ teacher } :: \mathbf{P}^{+} \ \mathbf{N}^{-} \ \text{ father } :: \mathbf{P}^{+} \ \mathbf{N}^{-} \ \left\langle \mathbf{P}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{P}^{+} \rangle \ \text{ of } :: \mathbf{D}^{+} \ \mathbf{P}^{-} \ \text{ of } :: \mathbf{D}^{+} \ \mathbf{P}^{-}$$

$$| \mathbf{P}^{-} \rangle \ \text{ who } :: \mathbf{D}^{-} \ \text{ who } :: \mathbf{D}^{-} \ \text{ who } = \mathbf{P}^{-}$$

# MDEP[merge,move] ⊈ STA

$$\varepsilon :: \mathbf{T}^{+} \ \mathbf{wh}^{+} \ \mathbf{C}^{-} \ \left\langle \mathbf{T}^{+} \mathbf{wh}^{+} \right\rangle$$

$$\varepsilon :: \mathbf{V}^{+} \ \mathbf{T}^{-} \ \left\langle \mathbf{V} \ \mathbf{wh}^{++} \right\rangle$$

$$| \mathbf{kke} :: \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{V}^{-} \ \left\langle \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{M}^{+} \rangle \ \mathbf{a} :: \mathbf{N}^{+} \ \mathbf{D}^{-} \qquad \mathbf{the} :: \mathbf{N}^{+} \ \mathbf{D}^{-} \ \left\langle \mathbf{N}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{P}^{+} \rangle \ \text{ teacher} :: \mathbf{P}^{+} \ \mathbf{N}^{-} \qquad \mathbf{father} :: \mathbf{P}^{+} \ \mathbf{N}^{-} \ \left\langle \mathbf{P}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{D}^{+} \rangle \ \mathbf{of} :: \mathbf{D}^{+} \ \mathbf{P}^{-} \qquad \mathbf{of} :: \mathbf{D}^{+} \ \mathbf{P}^{-} \ \left\langle \mathbf{D}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{D}^{-} \rangle \ \mathbf{who} :: \mathbf{D}^{-} \ \mathbf{who} :: \mathbf{D}^{-} \ \mathbf{wh}^{-}$$

# MDEP[merge,move] ⊈ STA

$$\varepsilon :: \mathbf{T}^{+} \ \mathbf{wh}^{+} \ \mathbf{C}^{-} \ \left\langle \mathbf{T}^{+} \mathbf{wh}^{+} \right\rangle$$

$$\varepsilon :: \mathbf{V}^{+} \ \mathbf{T}^{-} \ \left\langle \mathbf{V} \ \mathbf{wh}^{++} \right\rangle$$

$$| \mathbf{v}^{+} \mathbf{v}^{-} \ \left\langle \mathbf{V} \ \mathbf{vh}^{++} \right\rangle$$

$$| \mathbf{v}^{+} \mathbf{v}^{-} \mathbf{v}^{-} \mathbf{vh}^{+} \mathbf{v}^{-} \rangle$$

$$| \mathbf{v}^{+} \mathbf{v}^{-} \mathbf{v}^{-} \mathbf{vh}^{+} \mathbf{v}^{-} \rangle$$

$$| \mathbf{v}^{+} \mathbf{v}^{-} \mathbf{vh}^{+} \mathbf{vh}^{+} \rangle$$

$$| \mathbf{v}^{-} \mathbf{vh}^{+} \mathbf{vh}^{-} \rangle$$

$$| \mathbf{v}^{+} \mathbf{v}^{-} \mathbf{vh}^{-} \mathbf{vh}^{-} \rangle$$

$$| \mathbf{v}^{+} \mathbf{vh}^{-} \mathbf{vh}^{-} \rangle$$

$$| \mathbf{v}^{-} \mathbf{vh}^{-} \mathbf{vh}^{-} \rangle$$

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$$\varepsilon :: \mathbf{T}^{+} \ \mathbf{wh}^{+} \ \mathbf{C}^{-} \ \left\langle \mathbf{T}^{+} \mathbf{wh}^{+} \right\rangle$$

$$\varepsilon :: \mathbf{V}^{+} \ \mathbf{T}^{-} \ \left\langle \mathbf{V} \ \mathbf{wh}^{++} \right\rangle$$

$$\lim_{} \mathbf{ke} :: \mathbf{D}^{+} \ \mathbf{D}^{+} \ \mathbf{V}^{-} \ \left\langle \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{wh}^{+} \right\rangle$$

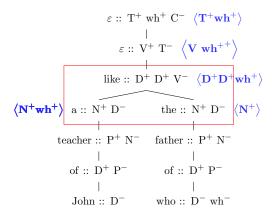
$$a :: \mathbf{N}^{+} \ \mathbf{D}^{-} \qquad \text{the} :: \mathbf{N}^{+} \ \mathbf{D}^{-}$$

$$\text{teacher} :: \mathbf{P}^{+} \ \mathbf{N}^{-} \qquad \text{father} :: \mathbf{P}^{+} \ \mathbf{N}^{-}$$

$$\text{of} :: \mathbf{D}^{+} \ \mathbf{P}^{-} \qquad \text{of} :: \mathbf{D}^{+} \ \mathbf{P}^{-}$$

$$\text{John} :: \mathbf{D}^{-} \qquad \text{who} :: \mathbf{D}^{-} \ \mathbf{wh}^{-}$$

# MDEP[merge,move] ⊈ STA



```
\varepsilon :: \mathbf{T}^+ \text{ wh}^+ \mathbf{C}^- \langle \mathbf{T}^+ \mathbf{wh}^+ \rangle
                                                \varepsilon :: \stackrel{\mid}{V^{+}} T^{-} \left\langle \mathbf{V} \mathbf{w} \mathbf{h}^{++} \right\rangle
                                            like :: D^+ D^+ V^- \langle D^+ D^+ wh^+ \rangle
     \langle \mathbf{N^+ w h^+} \rangle a :: \mathbf{N^+} D<sup>-</sup> the :: \mathbf{N^+} D<sup>-</sup> \langle \mathbf{N^+} \rangle
\langle \mathbf{P^+ w h^+} \rangle teacher :: P^+ N^- father :: P^+ N^- \langle \mathbf{P}^+ \rangle
                            of :: D^+ P^- of :: D^+ P^-
                              John :: D^- who :: D^- wh
```

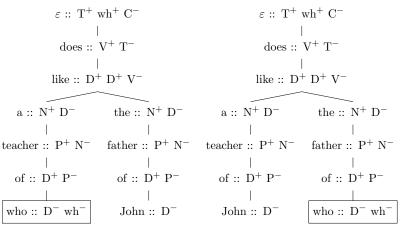
# MDEP[merge,move] ⊈ STA

```
\varepsilon :: \mathbf{T}^+ \text{ wh}^+ \mathbf{C}^- \langle \mathbf{T}^+ \mathbf{wh}^+ \rangle
                                                     \varepsilon :: \stackrel{\mid}{V^{+}} T^{-} \left\langle \mathbf{V} \mathbf{w} \mathbf{h}^{++} \right\rangle
                                                like :: D^+ D^+ V^- \langle D^+ D^+ wh^+ \rangle
      \langle \mathbf{N^+ wh^+} \rangle a :: \hat{\mathbf{N^+}} D<sup>-</sup> the :: \hat{\mathbf{N^+}} D<sup>-</sup> \langle \mathbf{N^+} \rangle
\langle \mathbf{P^+ w h^+} \rangle teacher :: P^+ N^- father :: P^+ N^- \langle \mathbf{P}^+ \rangle
     \langle \mathbf{D^+ wh^+} \rangle of :: \mathbf{D^+ P^-} of :: \mathbf{D^+ P^-} \langle \mathbf{D^+} \rangle
                                 John :: D^- who :: D^- wh
```

# MDEP[merge,move] ⊈ STA

```
\varepsilon :: \mathbf{T}^+ \text{ wh}^+ \mathbf{C}^- \langle \mathbf{T}^+ \mathbf{wh}^+ \rangle
                                                                 \varepsilon :: V^+ T^- \left\langle \mathbf{V} \ \mathbf{wh}^{++} \right\rangle
                                                           like :: D^+ D^+ V^- \langle D^+ D^+ wh^+ \rangle
       \langle \mathbf{N^+ wh^+} \rangle a :: \mathbf{N^+} D<sup>-</sup> the :: \mathbf{N^+} D<sup>-</sup> \langle \mathbf{N^+} \rangle
\langle \mathbf{P^+ w h^+} \rangle teacher :: P^+ N^- father :: P^+ N^- \langle \mathbf{P}^+ \rangle
     \left\langle \mathbf{D^+ w h^+} \right\rangle \  \, \mathrm{of} \  \, :: \stackrel{\stackrel{\cdot}{\mathrm{D}^+}}{\mathrm{P}^-} \  \, \qquad \quad \, \mathrm{of} \  \, :: \stackrel{\mid}{\mathrm{D}^+} \mathrm{P}^- \  \, \left\langle \mathbf{D}^+ \right\rangle
                \langle \mathbf{wh^+} \rangle John :: D<sup>-</sup> who :: D<sup>-</sup> wh<sup>-</sup> \langle \mathbf{wh^-} \rangle
```

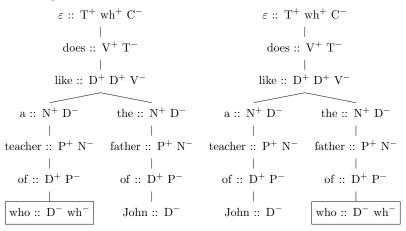
### Restricting move



The Specifier Island Constraint (SpIC)

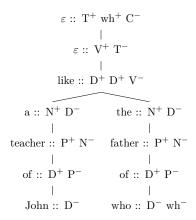
1 \*Who does a teacher of \_\_ like the father of John

### Restricting *move*



### The Specifier Island Constraint (SpIC)

\*Who does a teacher of \_\_ like the father of John?



$$\varepsilon :: T^{+} \text{ wh}^{+} C^{-} \left\langle T^{+} \text{wh}^{+} \right\rangle$$

$$\varepsilon :: V^{+} T^{-} \left\langle V \text{ wh}^{++} \right\rangle$$

$$\text{like} :: D^{+} D^{+} V^{-}$$

$$\text{a} :: N^{+} D^{-} \text{ the} :: N^{+} D^{-}$$

$$\text{teacher} :: P^{+} N^{-} \text{ father} :: P^{+} N^{-}$$

$$\text{of} :: D^{+} P^{-} \text{ of} :: D^{+} P^{-}$$

$$\text{John} :: D^{-} \text{ who} :: D^{-} \text{ wh}^{-}$$

$$\varepsilon :: T^{+} \text{ wh}^{+} C^{-} \left\langle \mathbf{T}^{+} \mathbf{wh}^{+} \right\rangle$$

$$\varepsilon :: V^{+} T^{-} \left\langle \mathbf{V} \mathbf{wh}^{++} \right\rangle$$

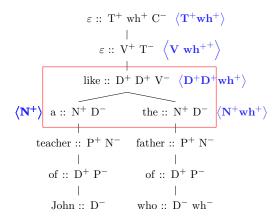
$$| \text{like} :: D^{+} D^{+} V^{-} \left\langle \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{wh}^{+} \right\rangle$$

$$a :: N^{+} D^{-} \qquad \text{the} :: N^{+} D^{-}$$

$$| \text{teacher} :: P^{+} N^{-} \qquad \text{father} :: P^{+} N^{-}$$

$$| \text{of} :: D^{+} P^{-} \qquad \text{of} :: D^{+} P^{-}$$

$$| \text{John} :: D^{-} \qquad \text{who} :: D^{-} \text{wh}^{-}$$



$$\varepsilon :: \mathbf{T}^{+} \ \mathbf{wh}^{+} \ \mathbf{C}^{-} \ \left\langle \mathbf{T}^{+} \mathbf{wh}^{+} \right\rangle$$

$$\varepsilon :: \mathbf{V}^{+} \ \mathbf{T}^{-} \ \left\langle \mathbf{V} \ \mathbf{wh}^{++} \right\rangle$$

$$| \mathbf{kke} :: \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{V}^{-} \ \left\langle \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{ke} :: \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{V}^{-} \ \left\langle \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{ke} :: \mathbf{D}^{+} \mathbf{D}^{-} \ \mathbf{ke} :: \mathbf{N}^{+} \mathbf{D}^{-} \ \left\langle \mathbf{N}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{ke} :: \mathbf{D}^{+} \mathbf{V}^{-} \ \left\langle \mathbf{P}^{+} \mathbf{wh}^{+} \right\rangle$$

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$$| \mathbf{h}^{-} \ \left\langle \mathbf{P}^{+} \mathbf{Wh}^{-} \right\rangle$$

$$\varepsilon :: \mathbf{T}^{+} \ \mathbf{wh}^{+} \ \mathbf{C}^{-} \ \left\langle \mathbf{T}^{+} \mathbf{wh}^{+} \right\rangle$$

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$$| \mathbf{kke} :: \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{V}^{-} \ \left\langle \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{M}^{+} \rangle \ \mathbf{a} :: \mathbf{N}^{+} \ \mathbf{D}^{-} \qquad \mathbf{the} :: \mathbf{N}^{+} \ \mathbf{D}^{-} \ \left\langle \mathbf{N}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{P}^{+} \rangle \ \text{ teacher} :: \mathbf{P}^{+} \ \mathbf{N}^{-} \qquad \mathbf{father} :: \mathbf{P}^{+} \ \mathbf{N}^{-} \ \left\langle \mathbf{P}^{+} \mathbf{wh}^{+} \right\rangle$$

$$| \mathbf{D}^{+} \rangle \ \mathbf{of} :: \mathbf{D}^{+} \ \mathbf{P}^{-} \qquad \mathbf{of} :: \mathbf{D}^{+} \ \mathbf{P}^{-} \ \left\langle \mathbf{D}^{+} \mathbf{wh}^{+} \right\rangle$$

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$$\varepsilon :: \mathbf{T}^{+} \ \mathbf{wh}^{+} \ \mathbf{C}^{-} \ \left\langle \mathbf{T}^{+} \mathbf{wh}^{+} \right\rangle$$

$$\varepsilon :: \mathbf{V}^{+} \ \mathbf{T}^{-} \ \left\langle \mathbf{V} \ \mathbf{wh}^{++} \right\rangle$$

$$\left| \mathbf{kh}^{+} \right\rangle = \left| \mathbf{kh}^{+} \ \mathbf{v}^{-} \ \left\langle \mathbf{D}^{+} \mathbf{D}^{+} \mathbf{wh}^{+} \right\rangle$$

$$\left\langle \mathbf{N}^{+} \right\rangle = \left| \mathbf{kh}^{+} \ \mathbf{v}^{-} \ \mathbf{vh}^{+} \right\rangle$$

$$\left\langle \mathbf{P}^{+} \right\rangle = \left| \mathbf{vh}^{+} \ \mathbf{vh}^{-} \right\rangle = \left| \mathbf{vh}^{+} \ \mathbf{vh}^{+} \right\rangle$$

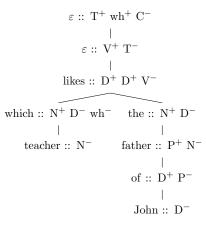
$$\left| \mathbf{vh}^{+} \right\rangle = \left| \mathbf{vh}^{+} \ \mathbf{vh}^{-} \right\rangle$$

$$\left\langle \mathbf{D}^{+} \right\rangle = \left| \mathbf{vh}^{+} \ \mathbf{vh}^{-} \right\rangle$$

$$\left| \mathbf{vh}^{-} \ \mathbf{vh}^{-} \right\rangle = \left| \mathbf{vh}^{-} \ \mathbf{vh}^{-} \right\rangle$$

$$\left\langle \varepsilon \right\rangle = \left| \mathbf{vh}^{-} \ \mathbf{vh}^{-} \right\rangle = \left| \mathbf{vh}^{-} \ \mathbf{vh}^{-} \right\rangle$$

$$\left\langle \varepsilon \right\rangle = \left| \mathbf{vh}^{-} \ \mathbf{vh}^{-} \right\rangle = \left| \mathbf{vh}^{-} \ \mathbf{vh}^{-} \right\rangle$$



```
likes :: D^+ D^+ V^- \langle D^+ D^+ w h^+ \rangle
which :: N^+ D^- wh^- the :: N^+ D^-
   teacher :: N^- father :: P^+ N^-
                      of :: D^+ P^-
                       John :: D^-
```

```
\varepsilon :: \mathbf{T}^+ \mathbf{w} \mathbf{h}^+ \mathbf{C}^- \left\langle \mathbf{T}^+ \mathbf{w} \mathbf{h}^+ \right\rangle
                             \varepsilon :: V^+ T^- \left\langle \mathbf{V} \mathbf{w} \mathbf{h}^{++} \right\rangle
                       likes :: D^+ D^+ V^- \langle D^+ D^+ wh^+ \rangle
which :: N^+ D^- wh^- the :: N^+ D^-
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                                                  of :: D<sup>+</sup> P<sup>-</sup>
                                                    John :: D^-
```

```
likes :: D^+ D^+ V^- \langle D^+ D^+ w h^+ \rangle
\langle \mathbf{D}^+ \rangle which :: N<sup>+</sup> D<sup>-</sup> wh<sup>-</sup> the :: N<sup>+</sup> D<sup>-</sup> \langle \mathbf{N}^+ \rangle
                teacher :: N^- father :: P^+ N^-
                                                 of :: D<sup>+</sup> P<sup>-</sup>
                                                  John :: D^-
```

```
likes :: D^+ D^+ V^- \langle D^+ D^+ w h^+ \rangle
\langle \mathbf{D}^+ \rangle which :: N^+ D^- wh^- the :: N^+ D^- \langle \mathbf{N}^+ \rangle
          \langle \varepsilon \rangle teacher :: N<sup>-</sup> father :: P<sup>+</sup> N<sup>-</sup> \langle \mathbf{P}^+ \rangle
                                                 of :: D^+ P^-
                                                  John :: D^-
```

```
\begin{array}{ccccc} \varepsilon :: & T^+ & \mathbf{w}\mathbf{h}^+ & C^- & \left\langle \mathbf{T}^+\mathbf{w}\mathbf{h}^+ \right\rangle \\ & & & & & \\ \varepsilon :: & V^+ & T^- & \left\langle \mathbf{V} & \mathbf{w}\mathbf{h}^{++} \right\rangle \end{array}
                                                           likes :: D^+ D^+ V^- \langle D^+ D^+ w h^+ \rangle
\langle \mathbf{D}^+ \rangle which :: N<sup>+</sup> D<sup>-</sup> wh<sup>-</sup> the :: N<sup>+</sup> D<sup>-</sup> \langle \mathbf{N}^+ \rangle
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                                                                                                     of :: D^+ P^- \langle D^+ \rangle
                                                                                                       John :: D^-
```

```
\begin{array}{ccccc} \varepsilon :: & \mathbf{T^+} \ \mathbf{w} \mathbf{h^+} \ \mathbf{C^-} & \left\langle \mathbf{T^+} \mathbf{w} \mathbf{h^+} \right\rangle \\ & & & & & \\ \varepsilon :: & \mathbf{V^+} \ \mathbf{T^-} & \left\langle \mathbf{V} \ \mathbf{w} \mathbf{h^{++}} \right\rangle \end{array}
                                                                likes :: D^+ D^+ V^- \langle D^+ D^+ w h^+ \rangle
\langle \mathbf{D}^+ \rangle which :: N<sup>+</sup> D<sup>-</sup> wh<sup>-</sup> the :: N<sup>+</sup> D<sup>-</sup> \langle \mathbf{N}^+ \rangle
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                                                                                                             of :: D^+ P^- \langle D^+ \rangle
                                                                                                                John :: D^- \langle \varepsilon \rangle
```

# Interim Summary [2]

We are looking for a complexity upper bound for syntax...

#### The road so far

- ▶ MDEP[merge] ⊆ STA
- MDEP[merge,move] ⊈ STA
- But MDEP[merge,move] 

  STA if we restrict move Movement constraints follow naturally: SpIC, CSC, ...

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**But** syntax is not just about core operations!

# **Licensing Conditions**

### Syntax is not just about Merge and Move...

#### NPI licensing

- 1a) \*Every student said that the train **ever** arrives on time.
- 1b) No student said that the train ever arrives on time.

#### Principle A

- 2a) \*John said that Mary likes himself
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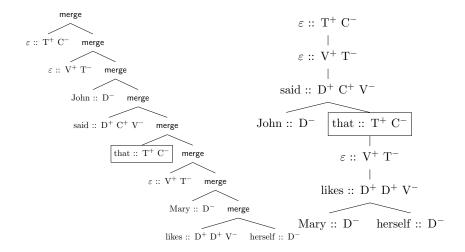
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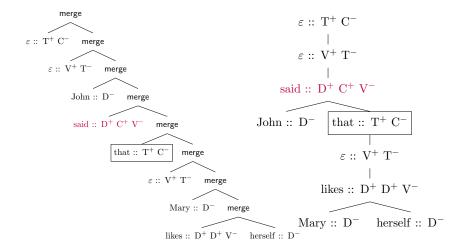
### Principle A

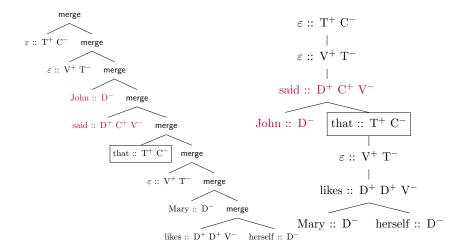
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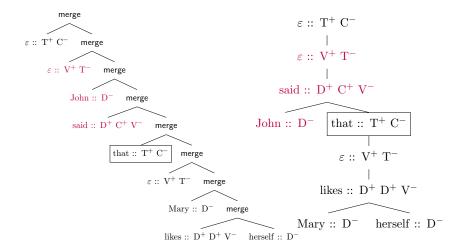
# Graf and Shafiei (2019)

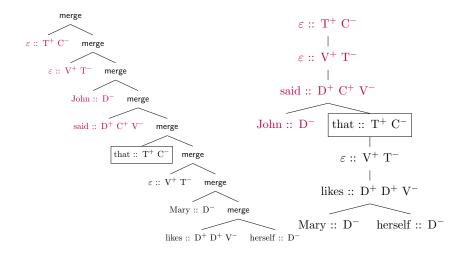
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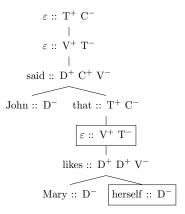






# Enforcing Principle A with an STA

# Principle A



# Principle A

$$\varepsilon :: T^+ C^- \langle \varepsilon \rangle$$

$$\varepsilon :: V^+ T^-$$

$$said :: D^+ C^+ V^-$$

$$John :: D^- \quad that :: T^+ C^-$$

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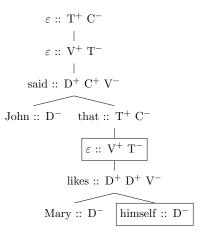
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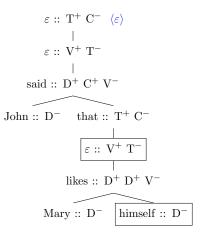
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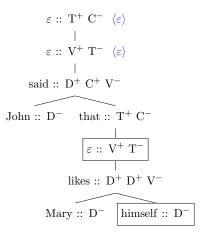
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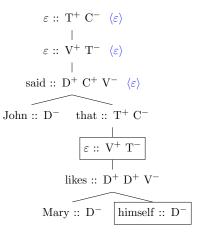
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# In Sum

- MDEP[merge,move] ⊆ STA if we restrict move Movement constraints follow naturally: SpIC, CSC, ...
- STA and C-Command Conditions

#### Taking a step back

Different perspectives on subregular syntax:

- Core operations? → derivation trees (Graf 2012, 2018)
- ▶ licensing conditions? → derivation trees/c-command strings (Vu 2018; Vu et al. 2019)
- ► constraints? → c-command strings (Shafiei and Graf 2019)

STA as an upper bound for syntax

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### STA as an upper bound for syntax

# What Do We Get?

# Merge, Move, Licensing conditions enforced by the same subregular machinery!

- ► MDEP a natural encoding of head-argument relations
- Naturalness of c-command
- ightharpoonup STA-recognition pprox syntactically motivated restrictions
- interaction of movement and licensing is expected

# Conclusion?

# STA as a uniform upper bound. But:

- ► Too permissive: Enforce arbitrary regular constraints
- ► Too restrictive? Licensing + c-command...

### **Expanding the Core Results**

- Movement + licensing
- Subcommand
- Adjunct Island Constraint, Coordinate Structure Constraint, ...
- MG derivation trees?
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 $\langle Thank\ you! \rangle$ 

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# References II

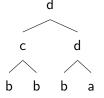
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# The Spine of a Node

Example: spine(a)

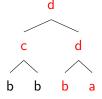


### STAs and spine closure (?

A regular tree language  ${\cal L}$  belongs to the class STA iff  ${\cal L}$  is spine closed.

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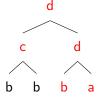


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# The Spine of a Node

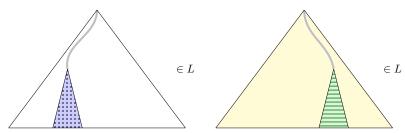
Example: spine(a)

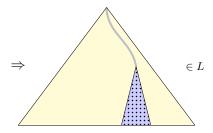


# STAs and spine closure (?)

A regular tree language  ${\cal L}$  belongs to the class STA iff  ${\cal L}$  is spine closed.

# Spine Closure





# Subregular Complexity in Phonology

► Subregular phonology has proved to be a fruitful enterprise (Heinz et al. 2011; Chandlee 2014; Jardine 2016; McMullin 2016; Graf 2017; Graf and Mayer 2018)

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