Dip Switch Config for Mr. Roboto

Test Modes										
Function	1	2	3	4	5	6	7	8	9	10
Do nothing	1	0	0	0	0	0	0	0	0	0
Run Motor Tests	1	1	Χ	Χ	Χ	Χ	Χ	Х	Х	Х
Run 7-segment Tests	1	0	1	Х	Х	Х	Χ	Χ	Х	Х
Run IR Tests	1	0	0	1	Χ	Χ	Χ	Х	Х	Х
Run Reflectivity Sensor Tests	1	0	0	0	1	Χ	Χ	Х	Х	Х
Run Camera Tests	1	0	0	0	0	1	Χ	Χ	Χ	Х
Run Gyro Tests	1	0	0	0	0	0	1	Χ	Χ	Χ
Run EM Detector Tests	1	0	0	0	0	0	0	1	Χ	Χ

Special Autonomous Modes										
Function	1	2	3	4	5	6	7	8	9	10
Roomba Mode	0	1	1	Χ	Х	Х	Χ	Χ	Χ	Х
Line Following - straight tendency	0	1	0	1	Х	Х	Χ	Χ	Х	Х
Line Following - left tendency	0	1	0	0	1	Χ	Χ	Х	Χ	Х
Line Following - right tendency	0	1	0	0	0	1	Χ	Χ	Х	Х
Room Search - Door begin	0	1	0	0	0	0	1	Χ	Χ	Х
Hazard Detection - Door Begin	0	1	0	0	0	0	0	1	Χ	Х
Victim Status Identification	0	1	0	0	0	0	0	0	1	Х

Autonomous Operation										
Function	1	2	3	4	5	6	7	8	9	10
Autonomous Operation (AO)	0	0	1	Χ	Х	Х	Χ	Χ	Х	Χ
Cut Max speed by half	0	0	1	1	Χ	Χ	Χ	Χ	Χ	Χ
Use AAOE for Line following	0	0	1	Χ	1	Х	Χ	Χ	Х	Χ
Use EM Field Sensor	0	0	1	Χ	Χ	1	Χ	Χ	Χ	Χ
Use LCD display	0	0	1	Χ	Χ	Χ	1	Χ	Χ	Χ

Glossary						
AAOE	Accumlating Average with Outlier Elimination					

Legend

1	Closed
0	Open
Х	Don't Care