

Final Project

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1 Motivation

1. What is the problem you would like to solve?

Recently increase use of location-aware devices (such as GPS, Smart-phones and RFID tags) has allowed the collection of a vast amount of data with a spatial component linked to them. Different studies have focused in analyzing and mining this kind of collections [Leung, 2010][Miller and Han, 2001]. In this area, trajectory datasets have emerged as an interesting field where diverse kind of patterns can be identified [Zheng and Zhou, 2011][Vieira and Tsotras, 2013]. For instance, authors have proposed techniques to discover motion spatial patterns such as moving clusters[Kalnis et al., 2005], convoys[Jeung et al., 2008] and flocks [Benkert et al., 2006][Gudmundsson and van Kreveld, 2006]. In particular, [Vieira et al., 2009] and [Turdukulov et al., 2014] propose two novel algorithms to find moving flock patterns in very large spatio-temporal datasets.

2. Why is it important?

A flock pattern is defined as a group of entities which move together for a defined lapse of time [Benkert et al., 2006]. Applications to this kind of patterns are diverse and range from surveillance to integrated transport systems. For example, [Turdukulov et al., 2014] explore the finding of this class of patterns to discover similarities between tropical cyclone paths. Also, [Calderon Romero, 2011] finds moving flock patterns in iceberg trajectories to understand their movement behavior and how they related to changes in ocean's currents.

3. What is your plan/outline of your solution?

The algorithms proposed by [Vieira et al., 2009] and [Turdukulov et al., 2014] share the same initial strategy to detect flock patterns. In that, first they find clusters of points which could be close enough to initiate a flock for each time interval. This is a costly operation due to the large number of points and intervals to be analyzed. The technique uses a grid-based index and a stencil (see figure 1) to speed up the process but the complexity is still high. My plan is to allow individual threads to compute each of the stencils in the grid in parallel.

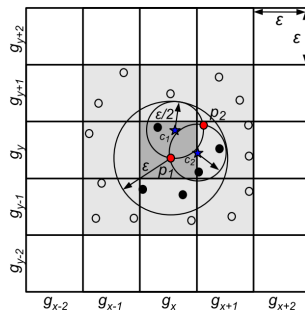
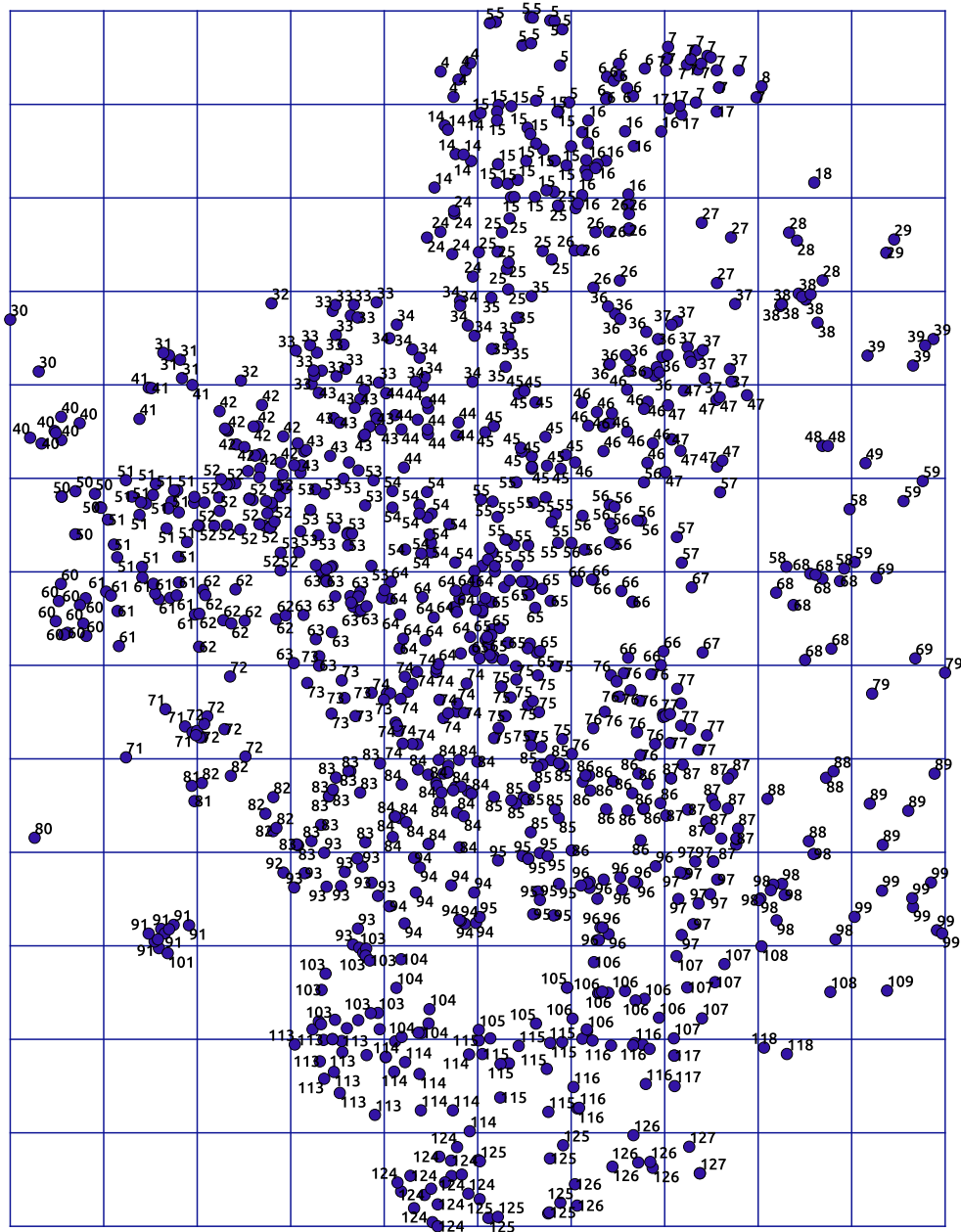


Figure 1: Grid-based index used in [Vieira et al., 2009].

2 Data



3 Code

Full code and other materials are available at Calderon Romero [2015].

3.1 bfe.cu

```
1  #include <stdio.h>
2  #include <stdlib.h>
3  #include <thrust/sort.h>
4  #include <thrust/functional.h>
5  #include <thrust/device_vector.h>
6  #include <thrust/host_vector.h>
7  #include "bfe.h"
8  #include "kernel.cu"
9
10 int main(int argc, char *argv[]){
11     if(argc != 4){
12         printf("Usage: %s TIMESTAMP EPSILON MU", argv[0]);
13         return 1;
14     }
15     const int TIMESTAMP = atoi(argv[1]);
16     const int EPSILON = atoi(argv[2]);
17     const int E2 = EPSILON * EPSILON;
18     const int MU = atoi(argv[3]);
19     cudaError_t cuda_ret;
20
21     FILE *in;
22     FILE *out;
23     in = fopen("oldenburg.csv", "r");
24     out = fopen("output.csv", "w");
25     fprintf(out, "oid;time;lat;lon;grid_id\n");
26     char line[1024];
27     int n = 0;
28     short time;
29     int lat; int lon;
30     int max_lat = INT_MIN; int min_lat = INT_MAX;
31     int max_lon = INT_MIN; int min_lon = INT_MAX;
32     int M = 0;
33     int N = 0;
34     while (fgets(line, 1024, in)){
35         atoi(strtok(line, ";"));
36         if(atoi(strtok(NULL, ";")) > TIMESTAMP) continue;
37         lat = atoi(strtok(NULL, ";"));
38         if(lat > max_lat) max_lat = lat;
39         if(lat < min_lat) min_lat = lat;
40         lon = atoi(strtok(NULL, ";"));
41         if(lon > max_lon) max_lon = lon;
42         if(lon < min_lon) min_lon = lon;
43         n++;
44     }
45     int *x;
46     x = (int*) malloc( sizeof(int) * n);
47     int *y;
48     y = (int*) malloc( sizeof(int) * n);
49     int *g;
50     g = (int*) malloc( sizeof(int) * n);
51     int *i;
52     i = (int*) malloc( sizeof(int) * n);
53     printf("Min and max latitude:\t(%d, %d)\n", min_lat, max_lat);
54     printf("Min and max longitude:\t(%d, %d)\n", min_lon, max_lon);
55     M = (max_lat - min_lat) / EPSILON + 1;
56     N = (max_lon - min_lon) / EPSILON + 1;
57     rewind(in);
58     int j = 0;
59     while (fgets(line, 1024, in)){
60         atoi(strtok(line, ";"));
61         time = atoi(strtok(NULL, ";"));
62         if(time > TIMESTAMP) continue;
63         lat = atoi(strtok(NULL, ";"));
64         lon = atoi(strtok(NULL, ";"));
```

```

65     g[j] = M * ((N - 1) - ((lon - min_lon) / EPSILON)) + ((lat - min_lat) / EPSILON);
66     x[j] = lat;
67     y[j] = lon;
68     i[j] = j;
69     //printf("%d;%hi;%d;%d;%d\n", oid, time, lat, lon, g[j]);
70     j++;
71 }
72 printf("Number of points:\t%d\n", n);
73 printf("M x N : %d x %d\n", M, N);
74 int c = M * N;
75 //int r = createGrid("grid.shp", EPSILON, min_lat, max_lat, min_lon, max_lon);
76 printf("Sorting arrays...\n");
77 thrust::device_vector<int> d_x(x, x + n);
78 thrust::device_vector<int> d_y(y, y + n);
79 thrust::device_vector<int> d_g(g, g + n);
80 thrust::device_vector<int> d_i(i, i + n);
81 thrust::sort_by_key(d_g.begin(), d_g.end(), d_i.begin());
82 thrust::gather(d_i.begin(), d_i.end(), d_x.begin(), d_x.begin());
83 thrust::gather(d_i.begin(), d_i.end(), d_y.begin(), d_y.begin());
84 thrust::copy(d_g.begin(), d_g.end(), g);
85 thrust::copy(d_i.begin(), d_i.end(), i);
86 thrust::copy(d_x.begin(), d_x.end(), x);
87 thrust::copy(d_y.begin(), d_y.end(), y);
88
89 printf("Counting point indices...\n");
90 int *a;
91 a = (int*) malloc(sizeof(int) * c);
92 int *b;
93 b = (int*) malloc(sizeof(int) * c);
94 a[0] = g[0];
95 b[0] = 0;
96 int k = 0;
97 for(j = 0; j < n; j++){
98     if(g[j] != a[k]){
99         k++;
100         a[k] = g[j];
101         b[k] = j;
102     }
103 }
104 b[++k] = n;
105
106 int *x_d, *y_d, *g_d;
107 int *a_d, *b_d;
108 unsigned long *N_DISKS;
109 unsigned long *result;
110
111 result = (unsigned long*) malloc(sizeof(long) * c);
112
113 printf("cudaMalloc and cudaMemcpy stage...\n");
114 cuda_ret = cudaMalloc((void **) &x_d, sizeof(int) * n);
115 if(cuda_ret != cudaSuccess){
116     printf("\nChecking cudaMalloc for x ... %s in %s at line %d\n", cudaGetErrorString(cuda_ret),
117         ↪ __FILE__, __LINE__);
118     exit(EXIT_FAILURE);
119 }
120 cuda_ret = cudaMalloc((void **) &y_d, sizeof(int) * n);
121 if(cuda_ret != cudaSuccess){
122     printf("\nChecking cudaMalloc for y ... %s in %s at line %d\n", cudaGetErrorString(cuda_ret),
123         ↪ __FILE__, __LINE__);
124     exit(EXIT_FAILURE);
125 }
126 cuda_ret = cudaMalloc((void **) &g_d, sizeof(int) * n);
127 if(cuda_ret != cudaSuccess){
128     printf("\nChecking cudaMalloc for g ... %s in %s at line %d\n", cudaGetErrorString(cuda_ret),
129         ↪ __FILE__, __LINE__);
130     exit(EXIT_FAILURE);
131 }
132 cuda_ret = cudaMalloc((void **) &N_DISKS, sizeof(long) * c);
133 if(cuda_ret != cudaSuccess){
134     printf("\nChecking cudaMalloc for N_DISKS ... %s in %s at line %d\n", cudaGetErrorString(cuda_ret),
135         ↪ __FILE__, __LINE__);

```

```

132     exit(EXIT_FAILURE);
133 }
134 cuda_ret = cudaMalloc((void **) &a_d, sizeof(int) * c);
135 if(cuda_ret != cudaSuccess){
136     printf("\nChecking cudaMalloc for a ... %s in %s at line %d\n", cudaGetErrorString(cuda_ret),
137         ↪ __FILE__, __LINE__);
138     exit(EXIT_FAILURE);
139 }
140 cuda_ret = cudaMalloc((void **) &b_d, sizeof(int) * c);
141 if(cuda_ret != cudaSuccess){
142     printf("\nChecking cudaMalloc for b ... %s in %s at line %d\n", cudaGetErrorString(cuda_ret),
143         ↪ __FILE__, __LINE__);
144     exit(EXIT_FAILURE);
145 }
146 cudaDeviceSynchronize();
147 cuda_ret = cudaMemcpy(x_d, x, sizeof(int) * n, cudaMemcpyHostToDevice);
148 if(cuda_ret != cudaSuccess){
149     printf("\nChecking cudaMemcpy for x_d... %s in %s at line %d\n", cudaGetErrorString(cuda_ret),
150         ↪ __FILE__, __LINE__);
151     exit(EXIT_FAILURE);
152 }
153 cuda_ret = cudaMemcpy(y_d, y, sizeof(int) * n, cudaMemcpyHostToDevice);
154 if(cuda_ret != cudaSuccess){
155     printf("\nChecking cudaMemcpy for y_d... %s in %s at line %d\n", cudaGetErrorString(cuda_ret),
156         ↪ __FILE__, __LINE__);
157     exit(EXIT_FAILURE);
158 }
159 cuda_ret = cudaMemcpy(g_d, g, sizeof(int) * n, cudaMemcpyHostToDevice);
160 if(cuda_ret != cudaSuccess){
161     printf("\nChecking cudaMemcpy for g_d... %s in %s at line %d\n", cudaGetErrorString(cuda_ret),
162         ↪ __FILE__, __LINE__);
163     exit(EXIT_FAILURE);
164 }
165 cuda_ret = cudaMemcpy(a_d, a, sizeof(int) * c, cudaMemcpyHostToDevice);
166 if(cuda_ret != cudaSuccess){
167     printf("\nChecking cudaMemcpy for a_d... %s in %s at line %d\n", cudaGetErrorString(cuda_ret),
168         ↪ __FILE__, __LINE__);
169     exit(EXIT_FAILURE);
170 }
171 cuda_ret = cudaMemcpy(b_d, b, sizeof(int) * c, cudaMemcpyHostToDevice);
172 if(cuda_ret != cudaSuccess){
173     printf("\nChecking cudaMemcpy for b_d... %s in %s at line %d\n", cudaGetErrorString(cuda_ret),
174         ↪ __FILE__, __LINE__);
175     exit(EXIT_FAILURE);
176 }
177 cudaDeviceSynchronize();
178 const dim3 grid(1, 1, 1);
179 const dim3 block(k, 1, 1);
180
181 // Calling the kernel...
182 printf("Running the kernel...\nk=%d\n", k);
183 parallelBFE<<<grid, block>>>(x_d, y_d, g_d, a_d, b_d, n, k, M, N, E2, N_DISKS);
184
185 cuda_ret = cudaDeviceSynchronize();
186 if(cuda_ret != cudaSuccess){
187     printf("\nError lunning kernel... %s in %s at line %d\n", cudaGetErrorString(cuda_ret), __FILE__,
188         ↪ __LINE__);
189     exit(EXIT_FAILURE);
190 }
191
192 cuda_ret = cudaMemcpy(result, N_DISKS, sizeof(long) * c, cudaMemcpyDeviceToHost);
193 if(cuda_ret != cudaSuccess){
194     printf("\nChecking cudaMemcpy for result... %s in %s at line %d\n", cudaGetErrorString(cuda_ret),
195         ↪ __FILE__, __LINE__);
196     exit(EXIT_FAILURE);
197 }
198 cudaDeviceSynchronize();
199
200 printf("\n");
201 for(int j = 0; j < k; j++){

```

```

193     if(j % M == 0) printf("\n");
194     if(result[j] >= MU){
195         printf("%3d->%3li  ", a[j], result[j]);
196     }
197 }
198 printf("\n");
199
200 cudaFree(x_d);
201 cudaFree(y_d);
202 cudaFree(g_d);
203 cudaFree(N_DISKS);
204
205 free(x);
206 free(y);
207 free(g);
208 free(i);
209 free(result);
210
211 return 0;
212 }

```

3.1.1 kernel.cu

```

1  #include <stdio.h>
2
3  __device__ int distance(int x1, int y1, int x2, int y2){
4      int dx = x2 - x1;
5      int dy = y2 - y1;
6      return (dx * dx) + (dy * dy);
7  }
8
9  __device__ int findPosition(const int *a, int k, int b, int top){
10     if(b < 0){
11         return -1;
12     }
13     if(b > top){
14         return -2;
15     }
16     for(int i = 0; i < k; i++){
17         if(a[i] == b){
18             return i;
19         }
20     }
21     return -3;
22 }
23
24 __global__ void parallelBFE(const int *x, const int *y, int *g, const int *a, const int *b, int n, int k,
    ↪ int M, int N, int E, unsigned long *N_DISKS){
25     int t = threadIdx.x;
26     //int px[250];
27     //int py[250];
28     //int h;
29     unsigned long j = 0;
30
31     // Center-Medium
32     int cm = a[t];
33     for(int i = b[t]; i < b[t + 1]; i++){
34         //px[j] = x[i];
35         //py[j] = y[i];
36         j++;
37     }
38     //h = j;
39
40     // Left-Medium
41     int lm;
42     if(cm % M == 0){
43         lm = -1;
44     } else {
45         lm = findPosition(a, k, cm - 1, M*N);
46     }

```

```

47  if(lm >= 0){
48      for(int i = b[lm]; i < b[lm + 1]; i++){
49          //px[j] = x[i];
50          //py[j] = y[i];
51          j++;
52      }
53  }
54  // Right-Medium
55  int rm;
56  if(cm % M == M - 1){
57      rm = -1;
58  } else {
59      rm = findPosition(a, k, cm + 1, M*N);
60  }
61  if(rm >= 0){
62      for(int i = b[rm]; i < b[rm + 1]; i++){
63          //px[j] = x[i];
64          //py[j] = y[i];
65          j++;
66      }
67  }
68  // Center-Up
69  int cu = cm - M;
70  cu = findPosition(a, k, cu, M*N);
71  if(cu >= 0){
72      for(int i = b[cu]; i < b[cu + 1]; i++){
73          //px[j] = x[i];
74          //py[j] = y[i];
75          j++;
76      }
77  }
78  // Left-Up
79  int lu;
80  if(cm % M == 0){
81      lu = -1;
82  } else {
83      lu = findPosition(a, k, cm - M - 1, M*N);
84  }
85  if(lu >= 0){
86      for(int i = b[lu]; i < b[lu + 1]; i++){
87          //px[j] = x[i];
88          //py[j] = y[i];
89          j++;
90      }
91  }
92  // Right-Up
93  int ru;
94  if(cm % M == M - 1){
95      ru = -1;
96  } else {
97      ru = findPosition(a, k, cm - M + 1, M*N);
98  }
99  if(ru >= 0){
100     for(int i = b[ru]; i < b[ru + 1]; i++){
101         //px[j] = x[i];
102         //py[j] = y[i];
103         j++;
104     }
105 }
106 // Center-Down
107 int cd = cm + M;
108 cd = findPosition(a, k, cd, M*N);
109 if(cd >= 0){
110     for(int i = b[cd]; i < b[cd + 1]; i++){
111         //px[j] = x[i];
112         //py[j] = y[i];
113         j++;
114     }
115 }
116 // Left-Down

```

```

117     int ld;
118     if(cm % M == 0){
119         ld = -1;
120     } else {
121         ld = findPosition(a, k, cm + M - 1, M*N);
122     }
123     if(ld >= 0){
124         for(int i = b[ld]; i < b[ld + 1]; i++){
125             //px[j] = x[i];
126             //py[j] = y[i];
127             j++;
128         }
129     }
130     // Right-Down
131     int rd;
132     if(cm % M == M - 1){
133         rd = -1;
134     } else {
135         rd = findPosition(a, k, cm + M + 1, M*N);
136     }
137     if(rd >= 0){
138         for(int i = b[rd]; i < b[rd + 1]; i++){
139             //px[j] = x[i];
140             //py[j] = y[i];
141             j++;
142         }
143     }
144     N_DISKS[t] = j;
145 }

```

4 Output

```

1  =====
2  === Increasing number of points =====
3  =====
4  storm.ee.ucr.edu /home/tempmaj/classacc2391/PhD/Y1Q1/GPU/project $ time ./bfe 0 2000 100
5  Min and max latitude: (1314, 21542)
6  Min and max longitude: (4391, 30096)
7  Number of points: 700
8  M x N : 11 x 13
9  Sorting arrays...
10 Counting point indices...
11 cudaMalloc and cudaMemcpy stage...
12 Running the kernel...
13 k=100
14
15
16
17
18 47->102
19 57->109 58->118 59->122 60->105
20 69->115 70->132 71->123
21 80->101 81->134 82->133 83->103
22 92->104 93->116 94->101
23
24
25
26
27 real 0m1.616s
28 user 0m1.375s
29 sys 0m0.115s
30 =====
31 storm.ee.ucr.edu /home/tempmaj/classacc2391/PhD/Y1Q1/GPU/project $ time ./bfe 1 2000 100
32 Min and max latitude: (1314, 21542)
33 Min and max longitude: (4297, 30161)
34 Number of points: 1700
35 M x N : 11 x 13
36 Sorting arrays...
37 Counting point indices...

```



```

38  cudaMalloc and cudaMemcpy stage...
39  Running the kernel...
40  k=104
41
42
43      5->127      6->139      15->112      16->178      17->187      18->119
44      26->147      27->185      28->186      29->127      35->112      36->148      37->175
45      38->175      39->174      40->135      45->160      46->238      47->251      48->239      49->204
46      50->186      51->132      56->192      57->263      58->283      59->302      60->257      61->205
47      62->107      67->166      68->224      69->267      70->310      71->288      72->218      73->104
48      79->139      80->238      81->313      82->309      83->242      84->136
49      90->107      91->190      92->243      93->266      94->231      95->167      96->107
50      101->105      102->158      103->200      104->207      105->194      106->163      107->102      113->105
51      114->147      115->156      116->149      117->128      125->142      126->154      127->120
52      137->110
53
54  real    0m0.145s
55  user    0m0.024s
56  sys     0m0.081s
57
58  =====
59  storm.ee.ucr.edu /home/tempmaj/classacc2391/PhD/Y1Q1/GPU/project $ time ./bfe 5 2000 100
60  Min and max latitude: (858, 21542)
61  Min and max longitude: (4297, 30800)
62  Number of points: 5652
63  M x N : 11 x 14
64  Sorting arrays...
65  Counting point indices...
66  cudaMalloc and cudaMemcpy stage...
67  Running the kernel...
68  k=112
69
70
71      5->138      6->233      15->198      16->377      17->473      18->316      19->137      26->300      27->565      28->655
72      ↪ 29->436
73      30->183      36->169      37->395      38->588      39->622      40->469      41->234      42->127      45->179      46->319
74      47->463      48->583      49->622      50->601      51->481      52->297      53->137      55->180      56->412      57->724
75      58->842      59->862      60->713      61->652      62->488      63->312      64->140      66->243      67->528      68->874
76      ↪ 69->994
77      70->1147      71->953      72->768      73->381      74->221      75->110      77->191      78->462      79->761      80->882
78      81->1135      82->1011      83->863      84->377      85->217      86->101      89->255      90->453      91->714
79      92->1057      93->1073      94->932      95->497      97->125      100->158      101->320      102->553      103->768
80      104->879      105->847      106->622      107->396      108->159      112->299      113->508      114->644
81      115->696      116->655      117->575      118->366      119->163      124->361      125->485      126->519      127->503
82      128->425      129->261      130->110      135->298      136->427      137->475      138->405      139->288      140->136      147->260
83      ↪ 148->327
84      149->283      150->174
85
86  real    0m0.133s
87  user    0m0.029s
88  sys     0m0.082s
89  =====
90  storm.ee.ucr.edu /home/tempmaj/classacc2391/PhD/Y1Q1/GPU/project $ time ./bfe 10 2000 100
91  Min and max latitude: (858, 21542)
92  Min and max longitude: (4297, 30838)
93  Number of points: 10257
94  M x N : 11 x 14
95  Sorting arrays...
96  Counting point indices...
97  cudaMalloc and cudaMemcpy stage...
98  Running the kernel...
99  k=112
100
101
102      5->255      6->430      15->362      16->657      17->810      18->534      19->239      26->557      27->1012      28->1145
103      ↪ 29->764
104      30->330      36->288      37->692      38->1063      39->1077      40->815      41->400      42->232      44->140      45->309
105      ↪ 46->555
106      47->792      48->1048      49->1167      50->1118      51->874      52->521      53->250      55->290      56->673      57->1275
107      58->1507      59->1641      60->1354      61->1218      62->857      63->551      64->255      66->384      67->866      68->1604
108      ↪ 69->1893

```

```

103 70->2281 71->1833 72->1459 73->672 74->415 75->205 76->122 77->292 78->733 79->1382
    ↳ 80->1718
104 81->2306 82->1967 83->1607 84->638 85->384 86->183 87->123 88->157 89->418 90->815
    ↳ 91->1370
105 92->2072 93->2089 94->1742 95->888 97->215 98->106 99->138 100->272 101->547 102->1003
    ↳ 103->1434
106 104->1663 105->1538 106->1109 107->699 108->267 109->131 110->120 111->161 112->537 113->919
    ↳ 114->1174
107 115->1278 116->1190 117->1038 118->666 119->281 120->137 122->112 124->677 125->894 126->938
    ↳ 127->887
108 128->745 129->474 130->184 135->563 136->766 137->835 138->697 139->513 140->240 147->445
    ↳ 148->580
109 149->476 150->306
110
111 real 0m0.129s
112 user 0m0.040s
113 sys 0m0.068s
114 =====
115 === Decresing Epsilon =====
116 =====
117 storm.ee.ucr.edu /home/tempmaj/classacc2391/PhD/Y1Q1/GPU/project $ time ./bfe 120 2000 600
118 Min and max latitude: (292, 22279)
119 Min and max longitude: (4191, 30838)
120 Number of points: 54636
121 M x N : 11 x 14
122 Sorting arrays...
123 Counting point indices...
124 cudaMalloc and cudaMemcpy stage...
125 Running the kernel...
126 k=114
127
128
129 5->812 6->1519 16->2051 17->3383 18->2539 19->1715 27->3859 28->5951 29->4225 30->3087
130 31->1009 37->3615 38->5042 39->7109 40->4787 41->4166 42->1947 43->978 45->716
131 46->1686 47->2853 48->6760 49->8164 50->9590 51->6328 52->4845 53->2096 54->1057
    ↳ 56->1501
132 57->4009 58->6181 59->10052 60->10847 61->10877 62->6956 63->4445 64->2029 65->1092
    ↳ 66->624 67->1948
133 68->5098 69->8395 70->13333 71->13782 72->11823 73->6131 74->3186 75->1516 76->946
    ↳ 78->1830 79->4624
134 80->8111 81->12517 82->12670 83->10082 84->4725 85->2434 86->1309 87->875 89->1326
    ↳ 90->3001
135 91->6641 92->10940 93->11795 94->9268 95->5152 96->3469 97->2137 98->943 100->1078
    ↳ 101->2144
136 102->5218 103->7631 104->9223 105->7499 106->5986 107->4180 108->2522 109->983 111->723 112->1505
137 113->3897 114->5943 115->7895 116->6758 117->6013 118->4105 119->2558 120->945 123->828 124->2612
    ↳ 125->3970
138 126->5608 127->4831 128->4050 129->2463 130->1197 135->1427 136->2431 137->3799 138->3648
    ↳ 139->2784 140->1247
139 147->1195 148->1878 149->1785 150->1243
140
141 real 0m0.131s
142 user 0m0.044s
143 sys 0m0.070s
144 =====
145 storm.ee.ucr.edu /home/tempmaj/classacc2391/PhD/Y1Q1/GPU/project $ time ./bfe 120 1000 600
146 Min and max latitude: (292, 22279)
147 Min and max longitude: (4191, 30838)
148 Number of points: 54636
149 M x N : 22 x 27
150 Sorting arrays...
151 Counting point indices...
152 cudaMalloc and cudaMemcpy stage...
153 Running the kernel...
154 k=385
155
156
157 33->668 34->694 35->709 36->851 37->802 54->728 55->968 56->885 57->1114 58->1361
    ↳ 59->1250 60->644 76->924 77->1253 78->1160 79->1492
158 80->1498 81->1165 98->1049 99->1476 100->1265 101->1744 102->1532 103->1117 120->1555
    ↳ 121->2080 122->1653 123->2024 124->1542 125->1102

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159 128->616 142->1901 143->2389 144->1923 145->1946 146->1462 149->840 150->906
160 163->729 164->2318 165->2647 166->2281 167->1787 168->1454 169->1480 170->851 171->1199 172->1307
    ↳ 173->763 184->817
161 185->962 186->2752 187->2948 188->2874 189->2178 190->1937 191->2024 192->991 193->1003 194->983
    ↳ 195->627 203->920 204->1217 205->1759 206->1789 207->2149
162 208->2989 209->3451 210->3223 211->3021 212->2288 213->1998 214->847 215->719 216->694 224->972
    ↳ 225->1528 226->2140 227->3008 228->2921 229->3008 230->2751
163 231->3753 232->3469 233->3535 234->2196 235->1647 246->833 247->1654 248->2703 249->3818 250->3250
    ↳ 251->3088 252->2902 253->4207 254->3923 255->3323
164 256->1785 257->1014 267->771 268->1180 269->1749 270->2533 271->3644 272->3404 273->3264 274->3881
    ↳ 275->4653 276->4080 277->2224 278->1152 279->720 280->624 282->695
165 289->617 290->749 291->1152 292->1792 293->2915 294->2794 295->2960 296->4659 297->5043 298->4345
    ↳ 299->1502 300->831 303->619 304->820 305->630
166 312->772 313->957 314->1231 315->2394 316->2719 317->2986 318->4283 319->4151 320->3610 321->1147
    ↳ 322->771
167 335->653 336->1075 337->1935 338->2305 339->2432 340->3057 341->3273 342->2894 343->1464 344->1004
    ↳ 345->730 357->813 358->1187 359->1690 360->2206 361->2726
168 362->2608 363->2586 364->2158 365->1844 366->1574 367->1420 368->1134 369->613 379->731 380->1054
    ↳ 381->1359 382->2234 383->3015 384->2904 385->2843 386->2184 387->2121 388->1503
169 389->1501 390->1545 391->1245 392->899 402->679 403->1034 404->1991 405->2765 406->2833 407->2467
    ↳ 408->2116 409->2043 410->1695 411->1552 412->1681 413->1489 414->1190
170 415->668 425->962 426->1941 427->2539 428->2371 429->1965 430->1800 431->1714 432->1374 433->1189
    ↳ 434->1294 435->1370 436->1185 437->731
171 448->1502 449->1825 450->1391 451->1233 452->1252 453->1393 454->1355 455->1065 456->920 457->843
    ↳ 458->699 469->943 470->1332 471->1673 472->1133 473->1144
172 474->1341 475->1644 476->1452 477->994 478->645 479->626 491->683 492->1148 493->1300 494->1098
    ↳ 495->994 496->1324 497->1532 498->1443 499->811
173 514->999 515->1278 516->1212 517->927 518->1253 519->1328 520->1316 521->668 536->614 537->884
    ↳ 538->1014 539->665 540->823 541->774 542->937 560->633
174 562->642 563->617 564->669
175
176 real 0m0.133s
177 user 0m0.044s
178 sys 0m0.074s
179 =====
180 storm.ee.ucr.edu /home/tempmaj/classacc2391/PhD/Y1Q1/GPU/project $ time ./bfe 120 800 600
181 Min and max latitude: (292, 22279)
182 Min and max longitude: (4191, 30838)
183 Number of points: 54636
184 M x N : 28 x 34
185 Sorting arrays...
186 Counting point indices...
187 cudaMalloc and cudaMemcpy stage...
188 Running the kernel...
189 k=580
190
191
192 70->628 73->685 74->756 75->711 97->637 98->701 101->974 102->1096 103->880
193 125->752 126->725 127->646 128->838 129->1135 130->1027 131->724 152->602 153->762 154->621
    ↳ 155->795 156->1101 157->1184 158->897 180->778 181->1100 182->1054 183->1222
194 184->1414 185->1358 186->844 208->939 209->1325 210->1415 211->1196 212->1514 213->1406 214->937
    ↳ 237->1576 238->1813 239->1176
195 240->1231 241->1289 242->1041 246->706 247->623 264->712 265->1700 266->1864 267->1290 268->708
    ↳ 269->1036 270->1024 271->622 273->790
196 274->1021 275->865 293->1865 294->2038 295->1820 297->1212 298->1246 299->1039 301->821 302->798
    ↳ 303->701
197 318->670 319->918 320->948 321->2349 322->2444 323->2289 324->1303 325->1695 326->1717 327->1296
    ↳ 328->696 329->671 330->638
198 342->650 343->889 344->1058 345->1270 346->1386 347->1717 348->1565 349->2158 350->2329 351->2391
    ↳ 352->2173 353->1992 354->1668 355->1077
199 371->1022 372->1564 373->2199 374->2350 375->2473 376->1815 377->1821 378->2379 379->2471
    ↳ 380->2513 381->1630 382->1291 383->724 398->941 399->1468 400->2058 401->2656
200 402->2317 403->2162 404->1345 405->1822 406->2222 407->2687 408->2397 409->1496 410->879 425->872
    ↳ 426->1124 427->1578 428->2026 429->2678 430->2243 431->2054 432->1508 433->2694 434->3175
201 435->3131 436->2009 437->1071 438->761 453->653 454->853 455->1347 456->1628 457->2300 458->1948
    ↳ 459->1965 460->1687 461->3550 462->3476 463->3139 464->1248 465->852
202 483->725 484->1084 485->2029 486->2030 487->2030 488->1666 489->3609 490->3751 491->3136 492->908
203 512->645 513->1668 514->1793 515->1804 516->1200 517->3003 518->2884 519->2580 520->701
204 540->746 541->1467 542->1554 543->1504 544->1100 545->2170 546->2352 547->2153 548->1060 549->755
    ↳ 550->700 568->732 569->1184 570->1626 571->1583 572->1547 573->1526 574->1807

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205 575->1533 576->1188 577->913 578->1015 579->851 595->675 596->796 597->1038 598->1397 599->1671
    ↳ 600->2043 601->1609 602->1728 603->1265 604->1326 605->896 606->976 607->1117 608->1069
    ↳ 609->807
206 624->616 625->749 626->1113 627->1909 628->2305 629->2055 630->1727 631->1653 632->1544 633->1192
    ↳ 634->884 635->1085 636->1121 637->1119 638->801
207 653->723 654->1012 655->1859 656->2022 657->1928 658->1416 659->1539 660->1482 661->1215 662->778
    ↳ 663->847 664->1079 665->1261 666->1026 667->723 681->609 682->1159 683->1647 684->1654
    ↳ 685->1387 686->1173 687->1321
208 688->1239 689->1032 690->750 691->732 692->852 693->823 694->716 710->1197 711->1350 712->1242
    ↳ 713->851 714->803 715->808 716->969 717->928 718->781 719->705 720->784 721->621 722->600
209 737->677 738->1036 739->1114 740->954 741->694 742->612 743->665 744->852 745->902 746->699
    ↳ 747->641 765->681 766->928 767->1053 768->772 769->604 771->884
210 772->1179 773->1216 774->810 794->753 795->904 796->820 797->663 799->822 800->1009 801->1033
    ↳ 802->760 823->963 824->927
211 825->737 827->849 828->1018 829->960 830->694 851->705 852->794 853->784 855->637
212
213
214 real 0m0.135s
215 user 0m0.049s
216 sys 0m0.075s
217 =====
218 storm.ee.ucr.edu /home/tempmaj/classacc2391/PhD/Y1Q1/GPU/project $ time ./bfe 120 600 600
219 Min and max latitude: (292, 22279)
220 Min and max longitude: (4191, 30838)
221 Number of points: 54636
222 M x N : 37 x 45
223 Sorting arrays...
224 Counting point indices...
225 cudaMalloc and cudaMemcpy stage...
226 Running the kernel...
227 k=932
228
229
230 136->634 172->673
231 208->645 209->725 245->661 246->612 280->640 281->681
232 282->694 313->621 314->662 317->666 318->851 319->760 350->832 351->968 352->658 353->704
    ↳ 354->677 355->959 356->841 357->666
233 387->970 388->1160 389->922 390->630 392->917 393->853 394->764 424->1061 425->1289 426->1274
    ↳ 429->635 430->821 431->754
234 461->786 462->1193 463->1340 464->627 467->717 468->720 474->637
235 499->1348 500->1472 501->1044 504->763 505->805 506->622
236 536->1364 537->1562 538->1500 541->963 542->962 543->768 571->630 572->817 573->1620 574->1815
    ↳ 575->1598 576->652 577->871 578->1328 579->1334
237 580->871 602->632 603->736 604->836 605->883 606->960 607->1047 608->1146 609->1172 610->1262
    ↳ 611->1477 612->1507 613->1253 614->1276 615->1396 616->1193 617->761
238 639->789 640->975 641->1073 642->1283 643->1253 644->1337 645->1178 646->1214 648->1402 649->1511
    ↳ 650->1571 651->1134 652->1045 653->895
239 675->768 676->821 677->1197 678->1470 679->1821 680->1503 681->1330 682->951 683->761 685->1185
    ↳ 686->1611 687->1635 688->1015 689->700 712->682 713->930 714->1252 715->1505 716->1541
    ↳ 717->1129 718->975
240 720->667 721->1019 722->1643 723->1864 724->1338 725->903 726->647 750->905 751->1323 752->1689
    ↳ 753->1499 754->1076 755->786 756->695 757->934 758->1819 759->2171 760->2202 761->1236
    ↳ 762->887 763->641
241 787->880 788->1154 789->1408 790->1338 791->1140 792->955 793->1021 794->1258 795->2417 796->2365
    ↳ 797->2235 798->920 799->651
242 825->690 826->1123 827->1438 828->1350 829->1022 830->1030 831->1375 832->2658 833->2548 834->2111
    ↳ 863->871
243 864->1320 865->1242 866->1105 867->915 868->1218 869->2409 870->2250 871->1895 900->698 901->1057
    ↳ 902->967 903->887 905->942 906->1959 907->2014 908->1656
244 938->1032 939->979 940->941 942->672 943->1329 944->1598 945->1419 946->683
245 975->989 976->1026 977->982 978->613 979->727 980->990 981->1229 982->964 983->680 1012->801
    ↳ 1013->1005 1014->946 1015->904 1016->745 1017->790 1018->972 1019->884 1020->805 1024->720
246 1050->824 1051->966 1052->1337 1053->1087 1054->859 1055->700 1056->771 1057->898 1061->709
    ↳ 1062->775 1063->732
247 1087->752 1088->1223 1089->1586 1090->1391 1091->1017 1092->856 1093->1070 1094->1039 1095->840
    ↳ 1098->612 1099->726 1100->777 1101->728 1102->609 1125->1289 1126->1504 1127->1405 1128->864
    ↳ 1129->827
248 1130->1078 1131->1000 1132->851 1137->774 1138->861 1139->735 1161->713 1162->1228 1163->1260
    ↳ 1164->1094 1165->705 1166->827 1167->980 1168->908 1169->790 1175->628
249 1176->641 1198->786 1199->969 1200->852 1201->721 1205->643 1206->613 1234->614

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250 1235->876 1236->841 1237->683 1238->621 1243->618 1271->618 1272->822 1273->675 1280->601
251 1309->663 1346->608
252 1390->718 1391->711 1392->618
253 1427->654 1428->628 1459->625 1464->688
254
255
256
257 real 0m0.147s
258 user 0m0.045s
259 sys 0m0.084s

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5 Profiler

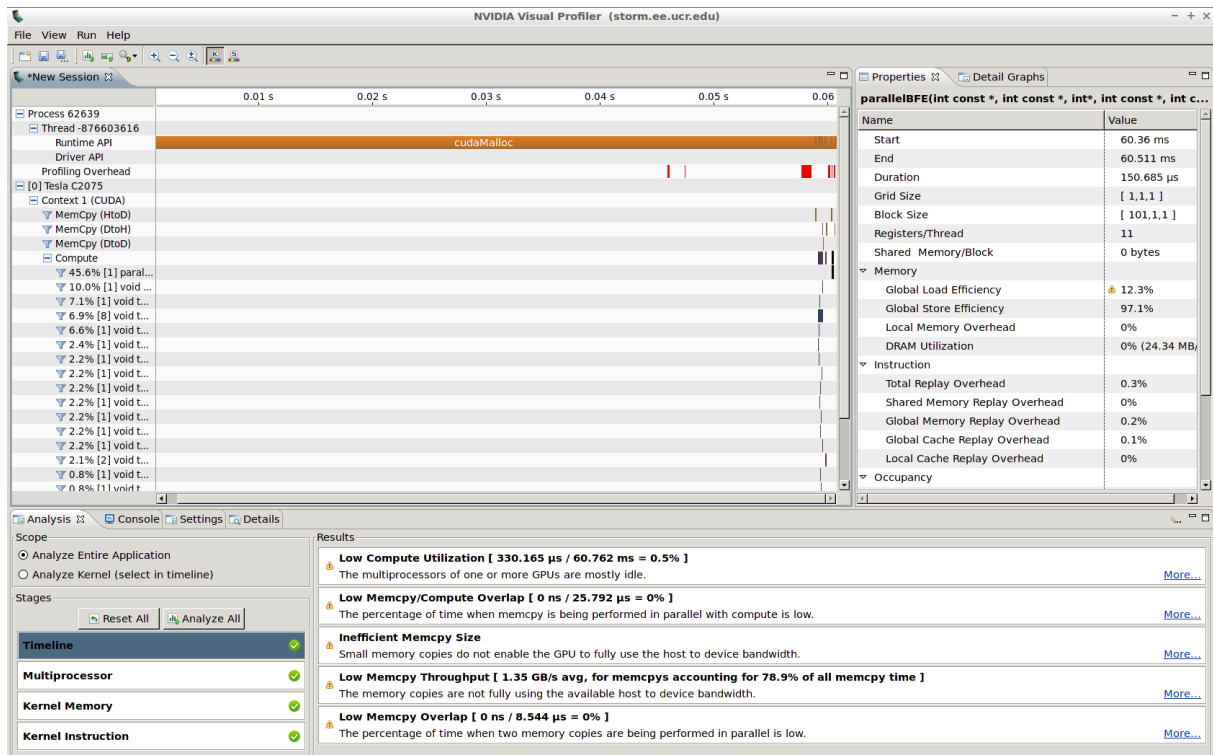


Figure 2: NVVP performance analysis for T1-E2K-M100.

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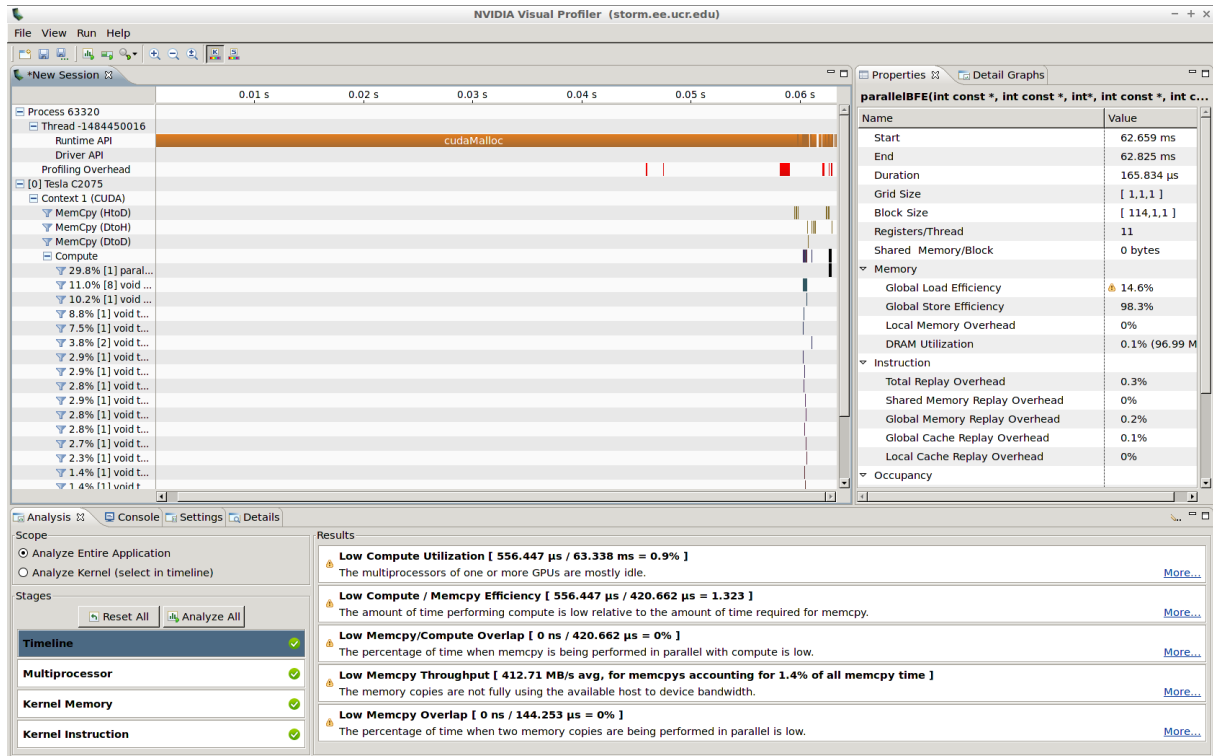


Figure 3: NVVP performance analysis for T120-E2K-M100.

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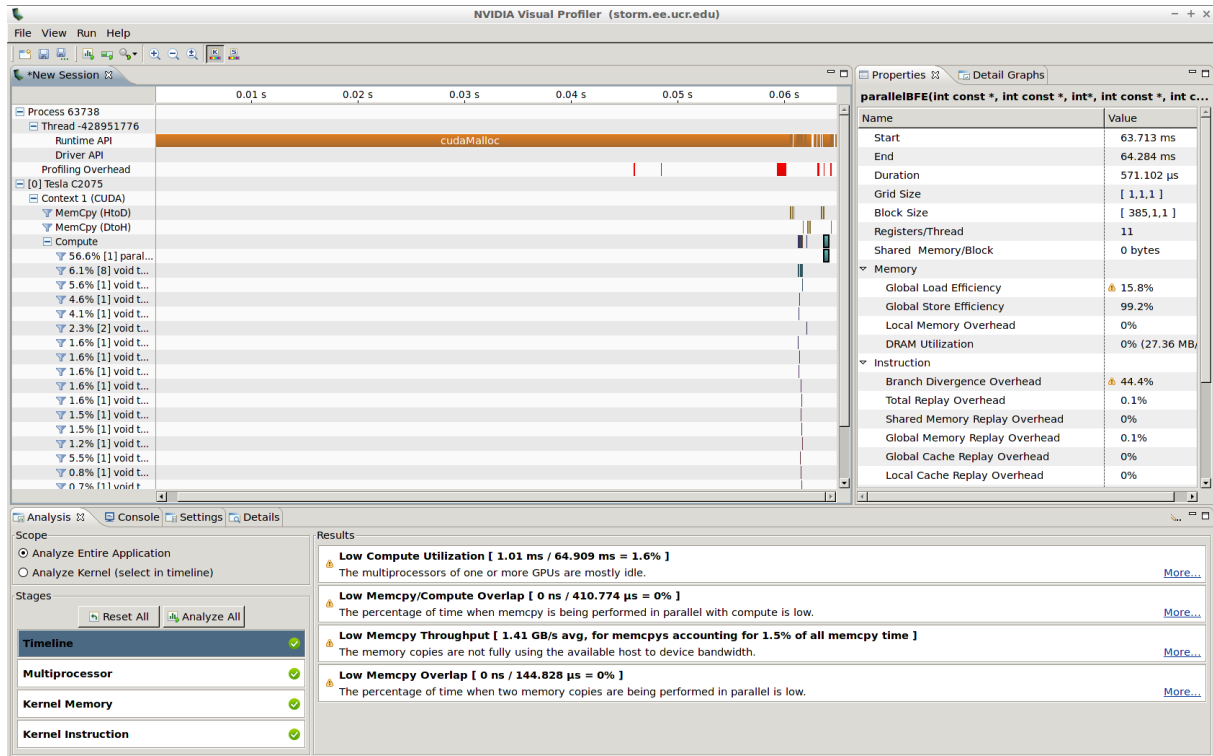


Figure 4: NVVP performance analysis for T120-E1K-M100.

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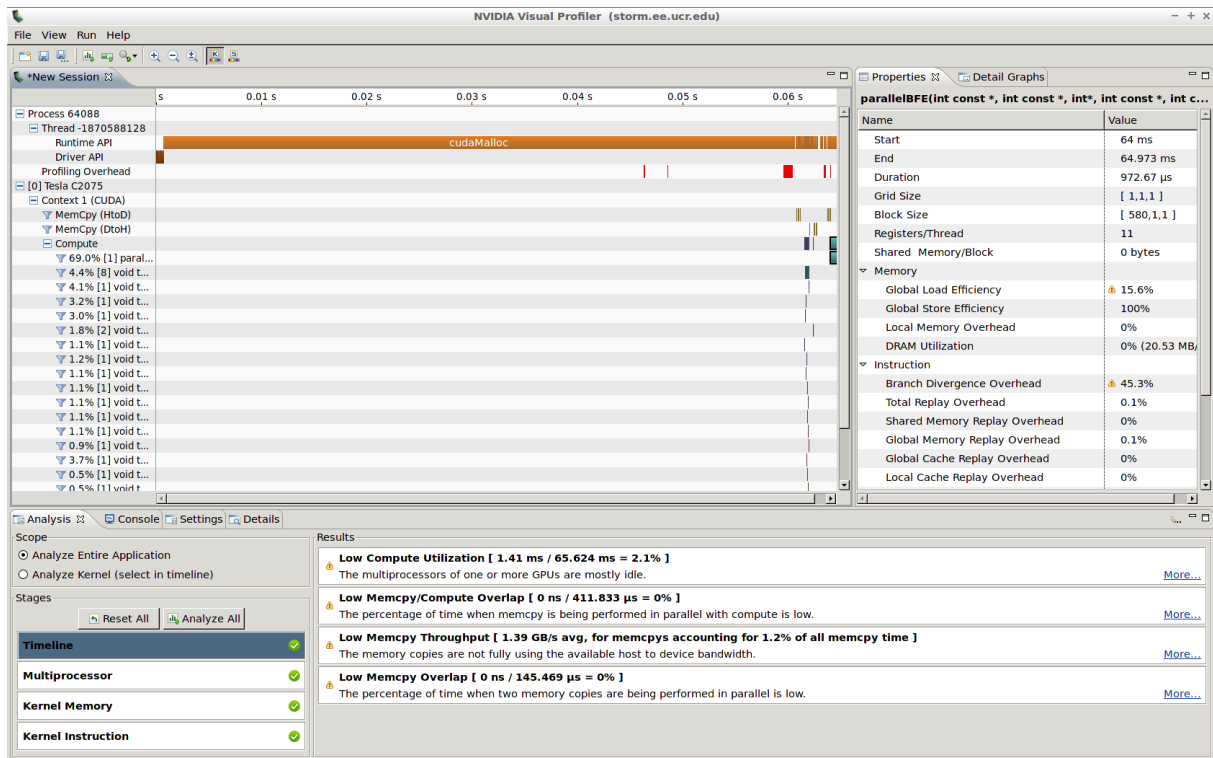


Figure 5: NVVP performance analysis for T120-E800-M100.

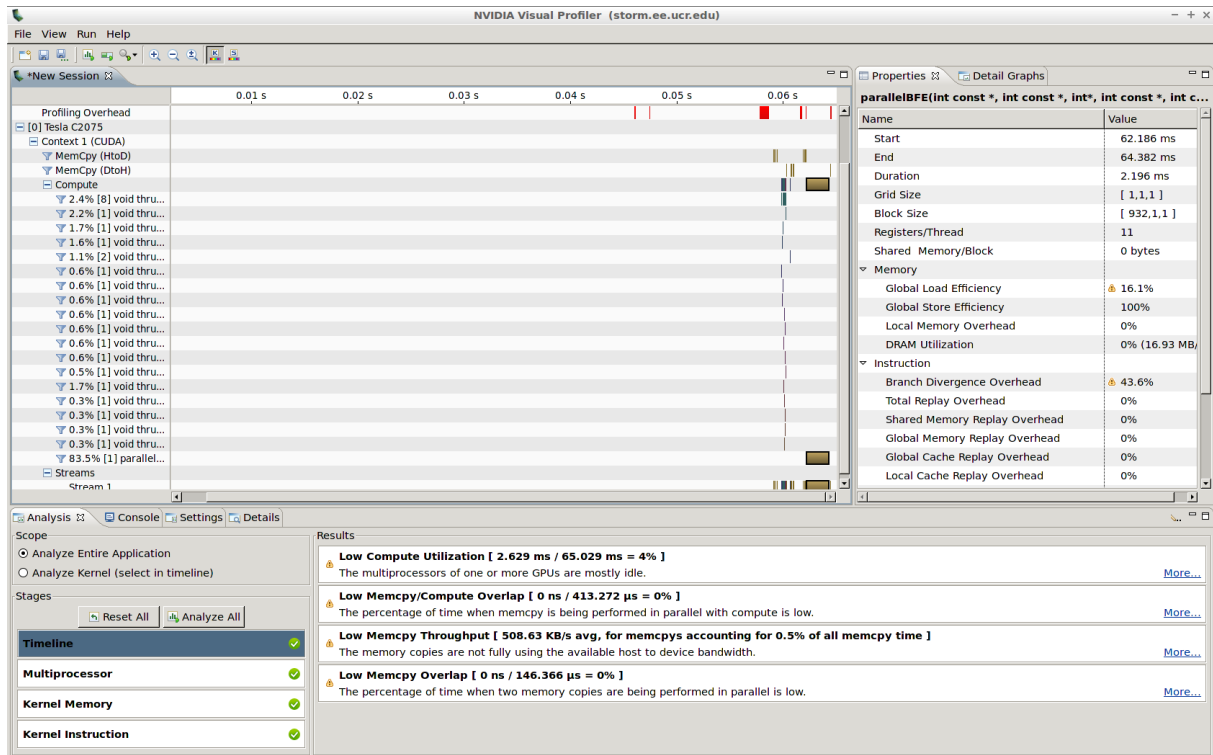


Figure 6: NVVP performance analysis for T120-E600-M100.