# **Final Project**

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## 1 Data

## 2 Code

Full code and other materials are available at [?].

## 2.1 bfe.cu

```
#include <stdio.h>
    #include <thrust/sort.h>
    #include <thrust/functional.h>
    #include <thrust/device_vector.h>
    #include <thrust/host_vector.h>
    #include "bfe.h"
    int main(){
9
      const int TIMESTAMP = 1;
         const int EPSILON = 2000;
10
11
      FILE *in;
12
          FILE *out;
13
          in = fopen("oldenburg.csv", "r");
out = fopen("output.csv", "w");
15
          fprintf(out, "oid;time;lat;lon;grid_id\n");
16
      char line[1024];
17
      int n = 0;
18
      long grid_id;
19
      int oid; short time;
20
      int lat; int lon;
21
      int max_lat = INT_MIN; int min_lat = INT_MAX;
      int max_lon = INT_MIN; int min_lon = INT_MAX;
23
      int M = 0;
24
      int N = 0;
          while (fgets(line, 1024, in)){
26
               atoi(strtok(line, ";"));
        if(atoi(strtok(NULL, ";\n")) != TIMESTAMP) continue;
28
              lat = atoi(strtok(NULL, ";\n"));
29
               if(lat > max_lat) max_lat = lat;
               if(lat < min_lat) min_lat = lat;</pre>
31
               lon = atoi(strtok(NULL, ";\n"));
32
               if(lon > max_lon) max_lon = lon;
               if(lon < min_lon) min_lon = lon;</pre>
34
35
36
      int x[n];
37
      int y[n];
      int g[n];
39
      int i[n];
```

Figure 1: Data points.

```
printf("Min and max latitude:\t(%d, %d)\n", min_lat, max_lat);
41
      printf("Min \ and \ max \ longitude:\t(\d, \d)\n", \ min\_lon, \ max\_lon);
42
      M = (max_lat - min_lat) / EPSILON + 1;
43
      N = (max_lon - min_lon) / EPSILON + 1;
44
      rewind(in):
45
       int j = 0;
46
           while (fgets(line, 1024, in)){
47
               oid = atoi(strtok(line, ";"));
48
49
               time = atoi(strtok(NULL, ";\n"));
         if(time != TIMESTAMP) continue;
50
         lat = atoi(strtok(NULL, ";\n"));
51
               lon = atoi(strtok(NULL, ";\n"));
52
               g[j] = M * ((N - 1) - ((lon - min_lon) / EPSILON)) + ((lat - min_lat) / EPSILON);
53
         y[j] = lon;
55
         i[j] = j;
56
57
         j++;
               //fprintf(out, \ ''%d;\%hi;\%d;\%d;\%li\n'', \ oid, \ time, \ lat, \ lon, \ grid\_id);
58
59
      printf("Number of points:\t%d\n", n);
60
       printf("M x N : %d \times %d\n", M, N);
61
62
       //int \ r = createGrid("grid.shp", EPSILON, min_lat, max_lat, min_lon, max_lon);
63
64
       thrust::device_vector<int> d_x(x, x + n);
       thrust::device_vector<int> d_y(y, y + n);
65
       thrust::device_vector<int> d_g(g, g + n);
66
       thrust::device_vector<int> d_i(i, i + n);
67
       thrust::sort_by_key(d_g.begin(), d_g.end(), d_i.begin());
68
      thrust::gather(d_i.begin(), d_i.end(), d_x.begin(), d_x.begin());
69
       thrust::gather(d_i.begin(), d_i.end(), d_y.begin(), d_y.begin());
71
72
       for(j = 0; j < n; j++)
         std::cout << g[j] << "-" << i[j] << "(" << x[j] << "," << y[j] << ")";
73
       std::cout << std::endl;</pre>
74
75
       std::cout << std::endl;
       thrust::copy(d_g.begin(), d_g.end(), g);
76
      thrust::copy(d_i.begin(), d_i.end(), i);
77
       thrust::copy(d_x.begin(), d_x.end(), x);
      thrust::copy(d_y.begin(), d_y.end(), y);
79
80
      for(j = 0; j < n; j++)
        std::cout << g[j] << "-" << i[j] << "(" << x[j] << "," << y[j] << ")";
81
       std::cout << std::endl;
82
      std::cout << std::endl;</pre>
83
       //thrust::copy(d_x.begin(), d_x.end(), std::ostream_iterator<int>(std::cout, ","));
84
      //std::cout << std::endl;</pre>
85
      return 0;
87
```

#### 2.1.1 kernel.cu

# 3 Output

# 4 Output

### References

[1] Andres Calderon. GitHub Personal Repository, 2015. https://github.com/aocalderon/PhD/tree/master/Y1Q1/GPU/lab3.

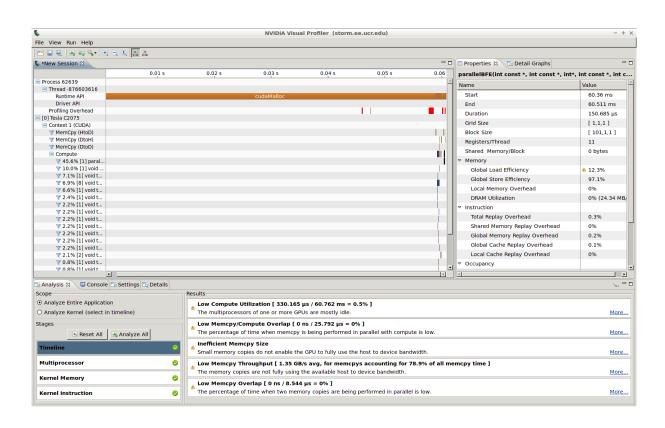


Figure 2: NVVP performance analysis for T1-E2K-M3.