

# Towards Parallel Detection of Moving Flock Patterns in Large Spatio-temporal Datasets

Final report

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## 1 Introduction

Spatio-temporal data is ubiquitous nowadays. Thanks to new technologies and location devices (such as Internet of Things, Remote Sensing, Smart phones, GPS, RFID, etc.), the collection of huge amount of spatio-temporal data is now possible. With the appearance of this datasets also appears the need of new techniques which allow the analysis and detection of useful patterns.

Applications for this kind of information are diverse and interesting, in particular if they come in the way of trajectory datasets [Jeung et al., 2011; hua, 2015]. Case of studies range from transportation system management [Di Lorenzo et al., 2016; Johansson and others, 2015] to Ecology [Johnston et al., 2015; La Sorte et al., 2016]. For instance, Turdukulov et al. [2014] explore the finding of complex motion patterns to discover similarities between tropical cyclone paths. Similarly, Amor et al. [2016] use eye trajectories to understand which strategies people use during a visual search. Also, Holland et al. [1999] track the behavior of tiger sharks in the coasts of Hawaii in order to understand their migration patters.

Recently, there has been an increasing interest in exploiting more complex movement patterns in spatio-temporal datasets. Traditional range and nearest neighbor queries do not capture the collective behavior of moving objects. Moving cluster (Kalnis et al. [2005]), convoys (Jeung et al. [2008]) and flock patterns (Benkert et al. [2008]; Gudmundsson and van Kreveld [2006]) are new movement patterns which unveil how entities move together during a minimum time interval.

In particular, a moving flock pattern show how objects move close enough during a given period of time. A better understanding on how entities move in space is of special interest in areas such as sports (Iwase and Saito [2002]), surveillance and security (Makris

and Ellis [2002]; Piciarelli et al. [2005]), urban development (Huang et al. [2016]; Long and Thill [2015]) and socio-economic geography (Frank et al. [2000]).

Despite the fact that much more data become available, state-of-the-art techniques to mine complex movement patterns still depict low scalability and poor performance in big spatial data. The present work aims to find an initial solution to implement a parallel method to discover moving flock patterns in large spatio-temporal datasets. It is thought that new trends in distributed in-memory framework for spatial operations could help to speed up the detection of this kind of patterns.

The following section will state the related work in the area. Section 3 will explain the details of the implementation of the proposed solution while section 4 will present their experimental results. Finally, section 5 will discuss some conclusions and future work.

## 2 Related work

Recently increase use of location-aware devices (such as GPS, Smart-phones and RFID tags) has allowed the collection of a vast amount of data with a spatial component linked to them. Different studies have focused in analyzing and mining this kind of collections [Leung, 2010][Miller and Han, 2001]. In this area, trajectory datasets have emerged as an interesting field where diverse kind of patterns can be identified [Zheng and Zhou, 2011][Vieira and Tsotras, 2013]. For instance, authors have proposed techniques to discover motion spatial patterns such as moving clusters [Kalnis et al., 2005], convoys [Jeung et al., 2008] and flocks [Benkert et al., 2008; Gudmundsson and van Kreveld, 2006]. In particular, Vieira et al. [2009] and Turdukulov et al. [2014] propose two novel algorithms to find moving flock patterns in very large spatio-temporal datasets.

A flock pattern is defined as a group of entities which move together for a defined lapse of time [Benkert et al., 2008]. Applications to this kind of patterns are rich and diverse. For example, [Calderon, 2011] finds moving flock patterns in iceberg trajectories to understand their movement behavior and how they related to changes in ocean's currents.

The algorithms proposed by [Vieira et al., 2009] and [Turdukulov et al., 2014] share the same initial strategy to detect flock patterns. In that, first they find disks with a predefined diameter where moving entities could be close enough at a given time interval. This is a costly operation due to the large number of points and intervals to be analyzed ( $\mathcal{O}(2n^2)$  per time interval). The technique uses a grid-based index and a stencil (see figure 1) to speed up the process but the complexity is still high.

A recent research [Tanaka et al., 2016] introduce the use of plane sweeping along with binary signatures and inverted indexes to speedup the process but still keep the same strategy to find the disks at each interval. Similarly, [Arimura et al., 2014] and [Geng et al., 2014] use depth-first algorithms to analyze the time intervals of trajectories to report maximal duration flocks. However, these techniques are not suitable to find patterns in an on-line fashion.

Given the high complexity of the task, it should not be surprising the use of parallelism

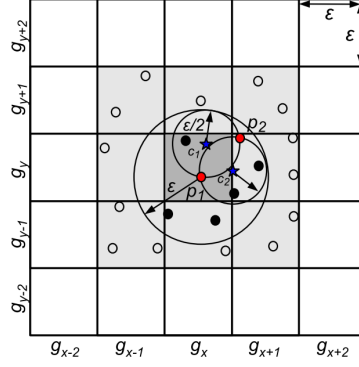


Figure 1: Grid-based index used in Vieira et al. [2009].

to increase performance. Fort et al. [2014] use extremal and intersection sets to report maximal, longest and largest flocks on the GPU with the limitations of its memory model.

Indeed, despite the popularity of cluster computing frameworks, in particular those supporting spatial capabilities [Eldawy, 2014; Yu et al., 2016; Hughes et al., 2015; Xie et al., 2016], there are not significant advances in this area. At the best of our knowledge, this work is the first to explore in-memory distributed systems towards the detection of moving flock patterns.

### 3 Parallelizing flock detection

### 4 Experiments

### 5 Conclusions and future work

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