

Reducing error in open-ocean acoustic measurements

Tim Ryan, Ryan Downie, Rudy Kloser and Gordon Keith

CSIRO Marine and Atmospheric Research

WGFAST Brest, 2012

Integrated Marine Observing System (IMOS)

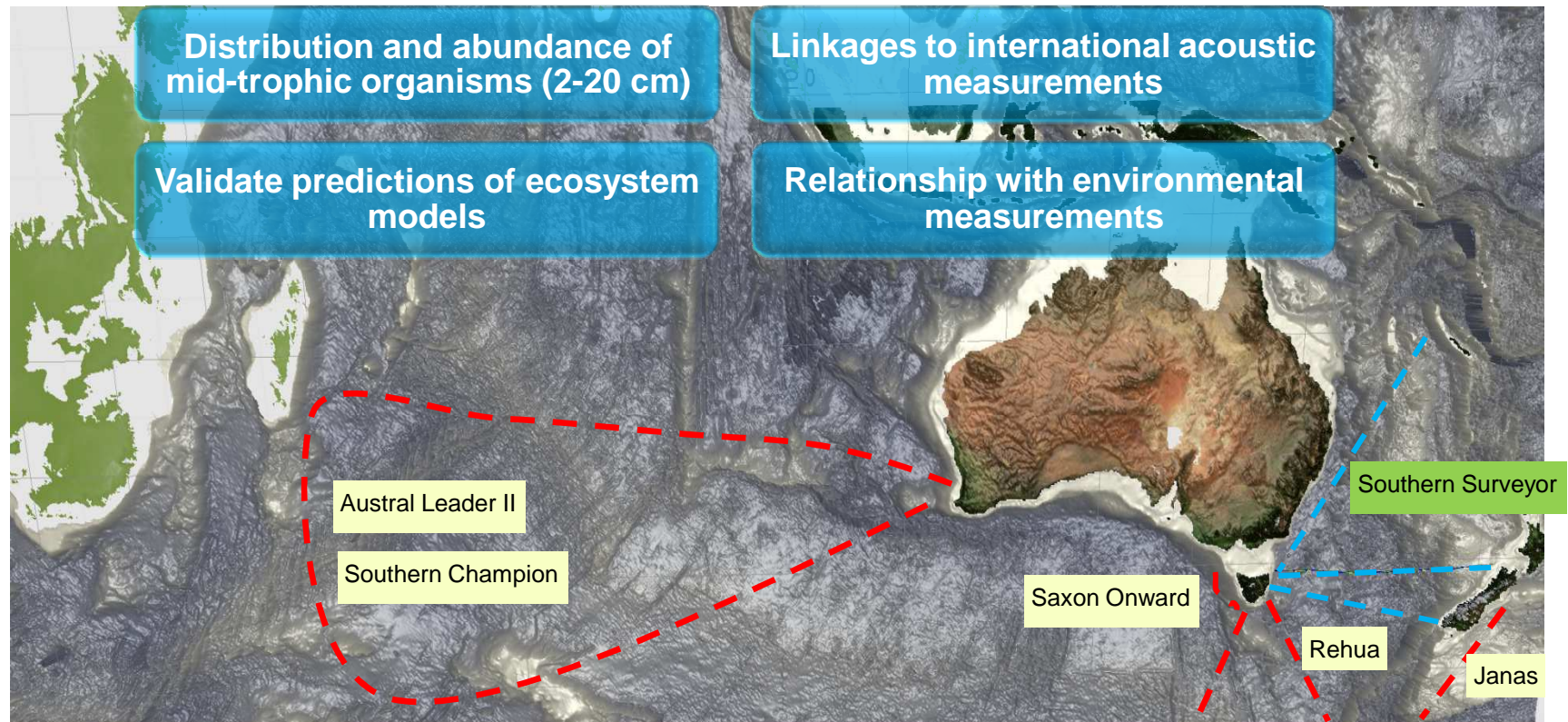
“IMOS is a distributed set of equipment and data-information services which collectively contribute to meeting the needs of marine climate research in Australia”



Facilities

Argo
Moorings
Gliders
AUVs
Ocean Radar
Satellite Remote Sensing
Animal tagging
Marine information (emII)
Ships of opportunity (SOOP)
• **Bio-acoustics**

Bio-Acoustic Ship of Opportunity sub-facility (BASOOP)



Commercial and research vessels
with calibrated digital echosounders

Vessel track : existing — — — —
: new — — — —

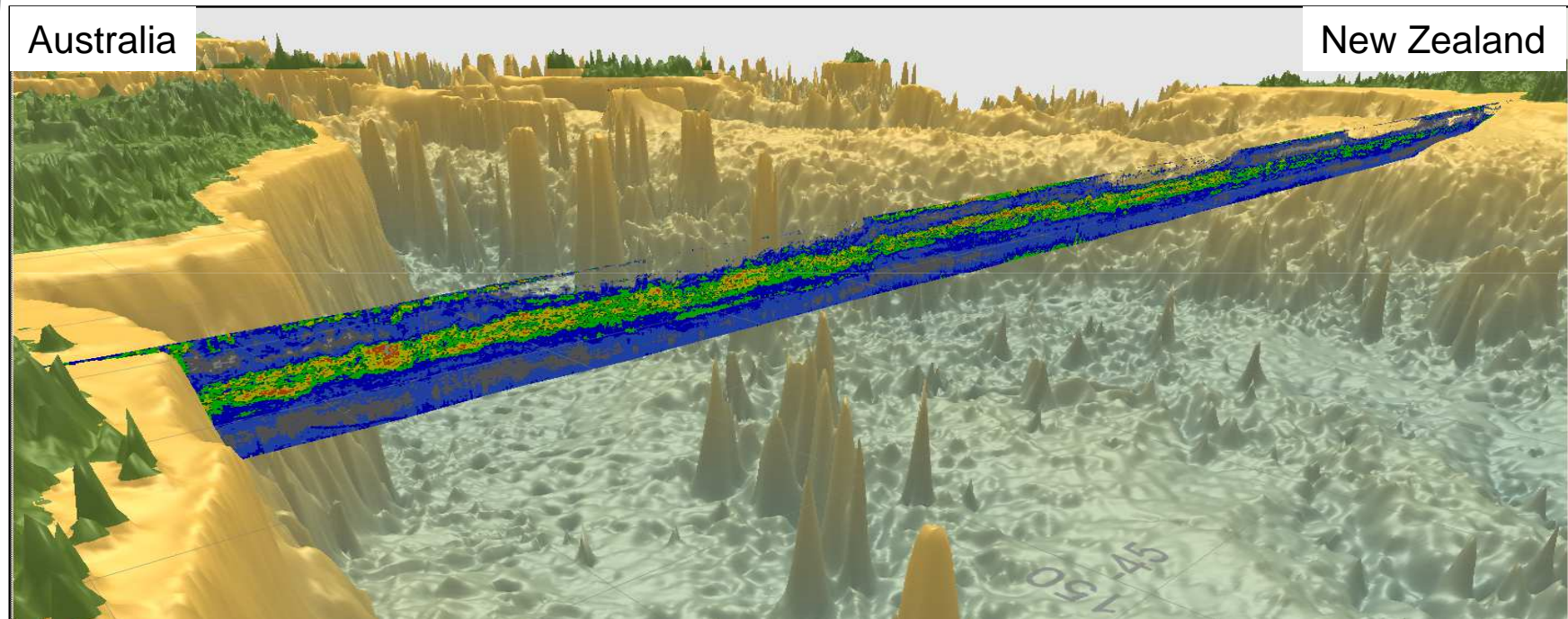


National Research
FLAGSHIPS
Wealth from Oceans



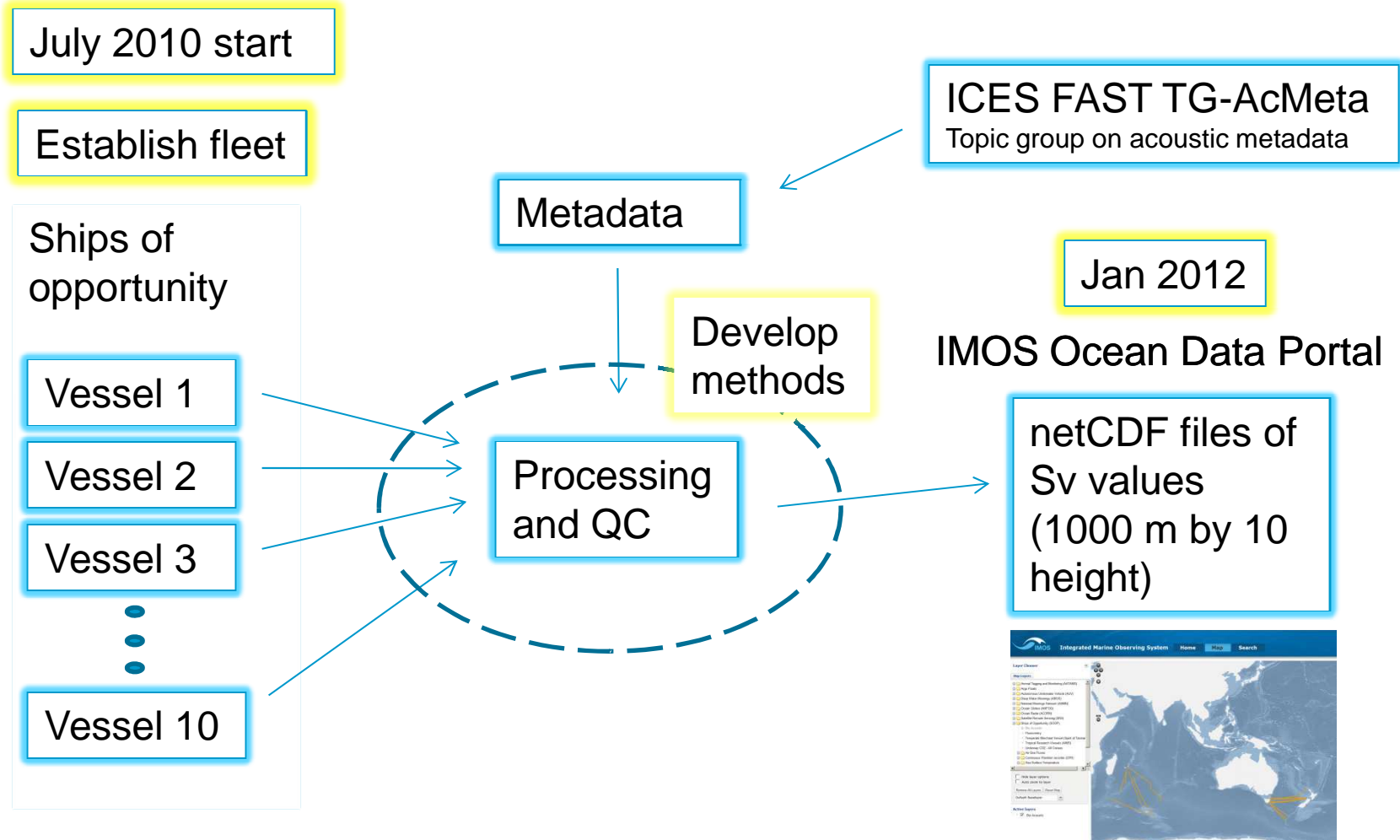
Biological acoustics ocean observing objective

To provide calibrated quality controlled measures of acoustic backscatter at ocean basin scales

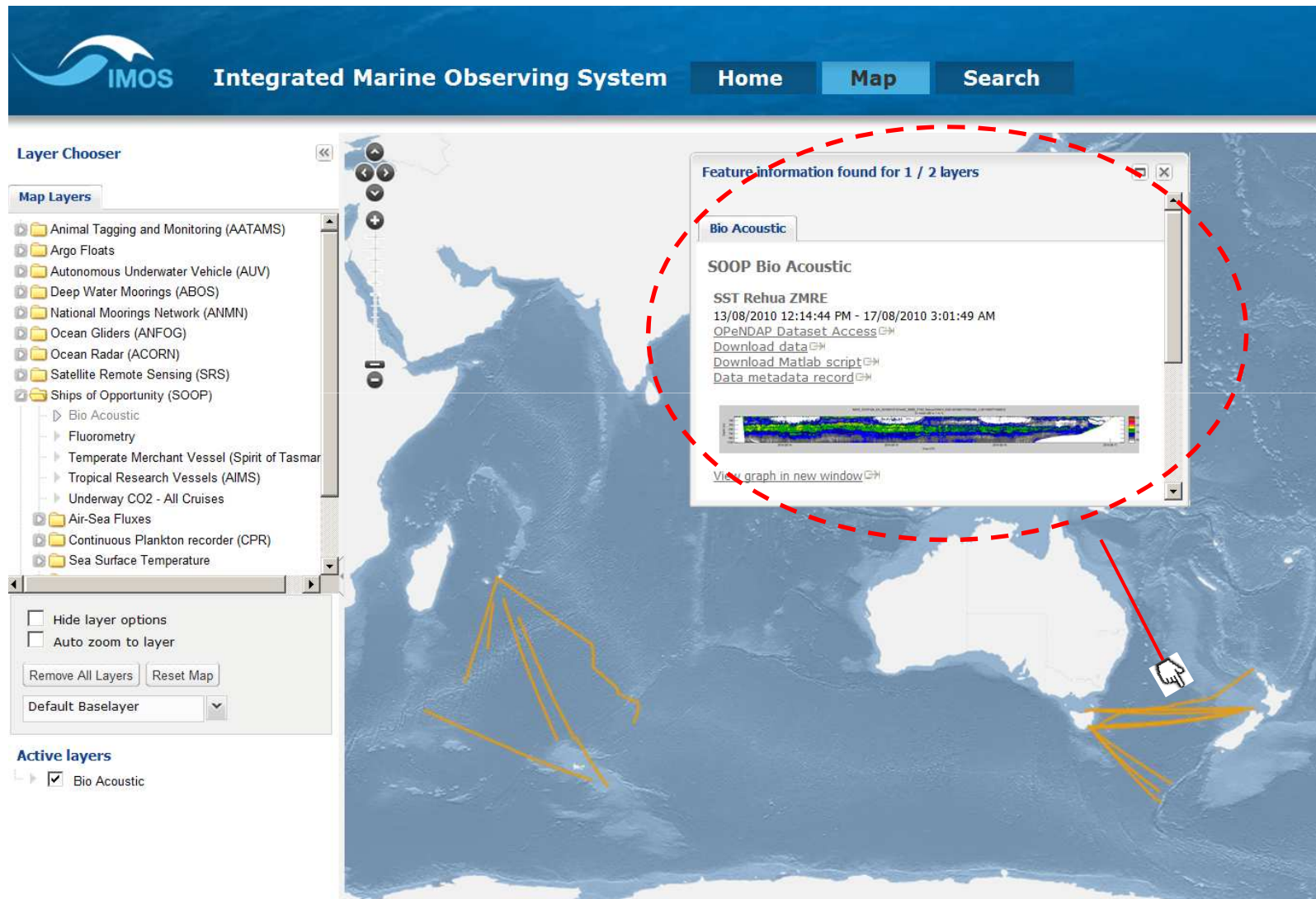


Visualisation of 38 kHz volume backscatter (Sv) collected by FV Rehua Australia during a 4 day transit from New Zealand to Australia, August 2010

Project data flow structure



IMOS Ocean Portal



<http://imos.aodn.org.au/webportal/>

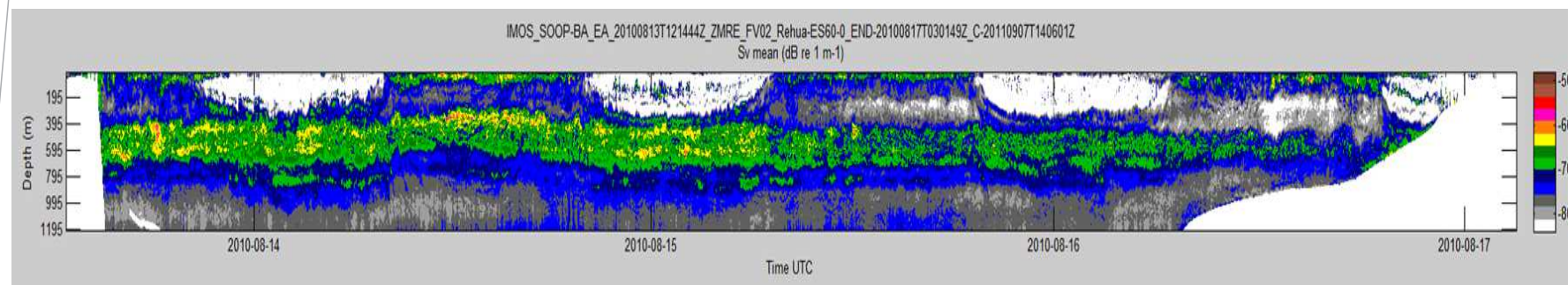
National Research
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IMOS Ocean Portal



- OPeNDAP Data Access
- Download data (netCDF)
- Matlab viewing script
- Metadata record
- Summary graphic



First iteration error corrections

July 2010 start

Establish fleet

Ships of
opportunity

Vessel 1

Vessel 2

Vessel 3



Vessel 10

Metadata

Develop
methods

Processing
and QC

ICES FAST TG-AcMeta
Topic group on acoustic metadata

Jan 2012

IMOS Ocean Data Portal

netCDF files of
Sv values
(1000 m by 10
height)



First iteration error corrections

Vessel calibration



Raw data

Filter
stages

Spike

(Anderson et al. 2005)

Attenuated signal

Ryan (2011)

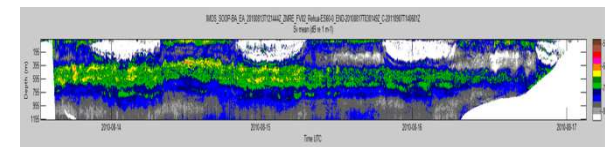
Persistent
intermittent noise

Ryan (2011)

Background noise

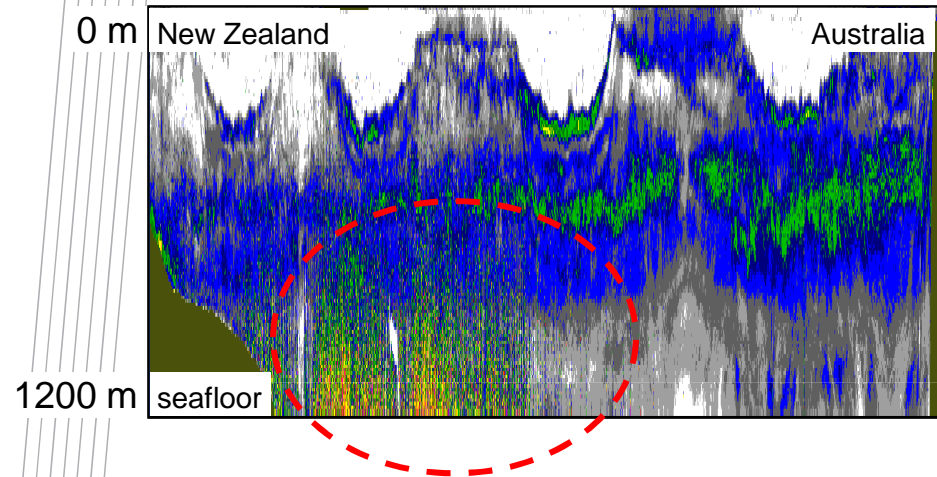
(de Robertis 2007)

Processed data

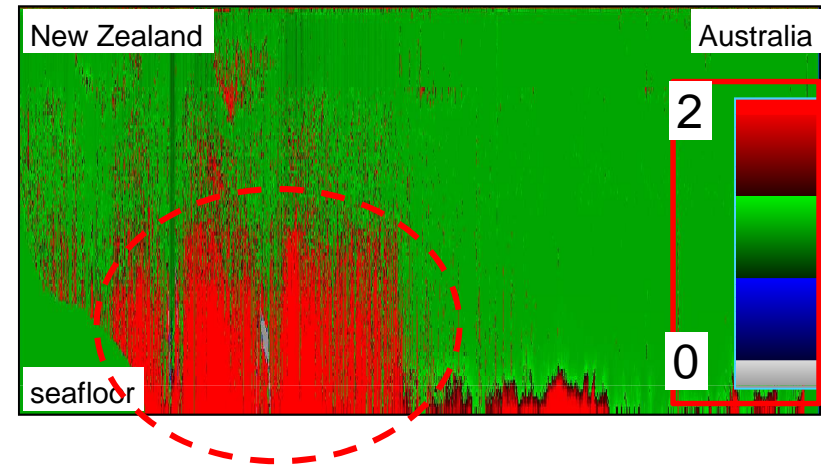


First iteration error corrections

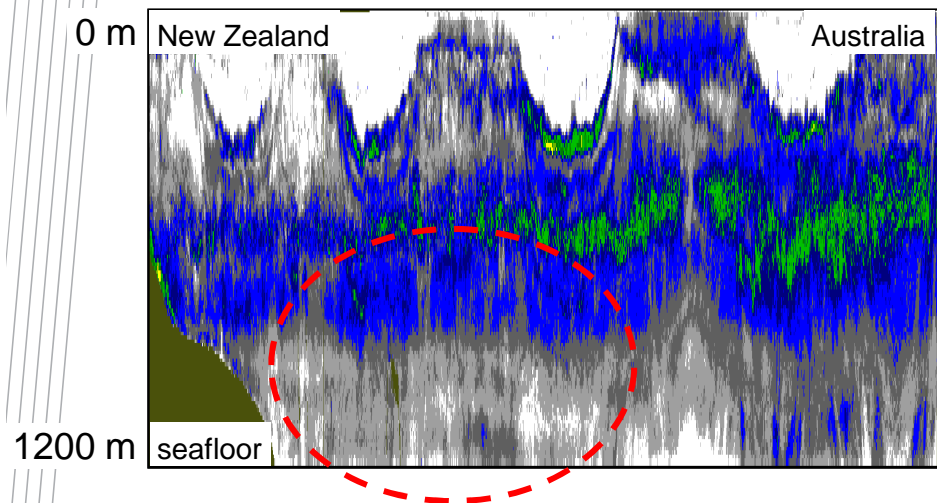
Unfiltered echointegrated data (1 km by 10 m cells)



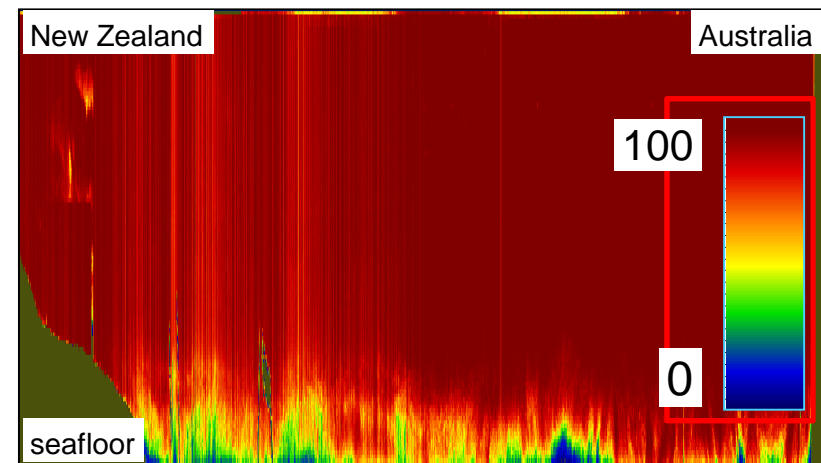
NASC Ratio: Unfiltered/filtered data



Filtered echointegrated data (1 km by 10 m cells)

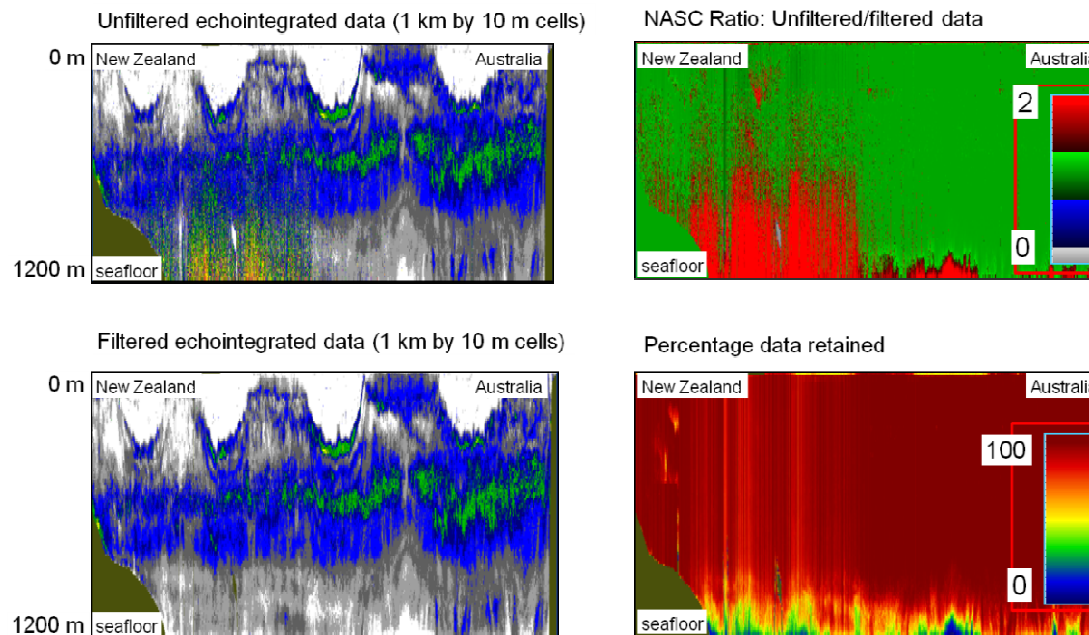


Percentage data retained

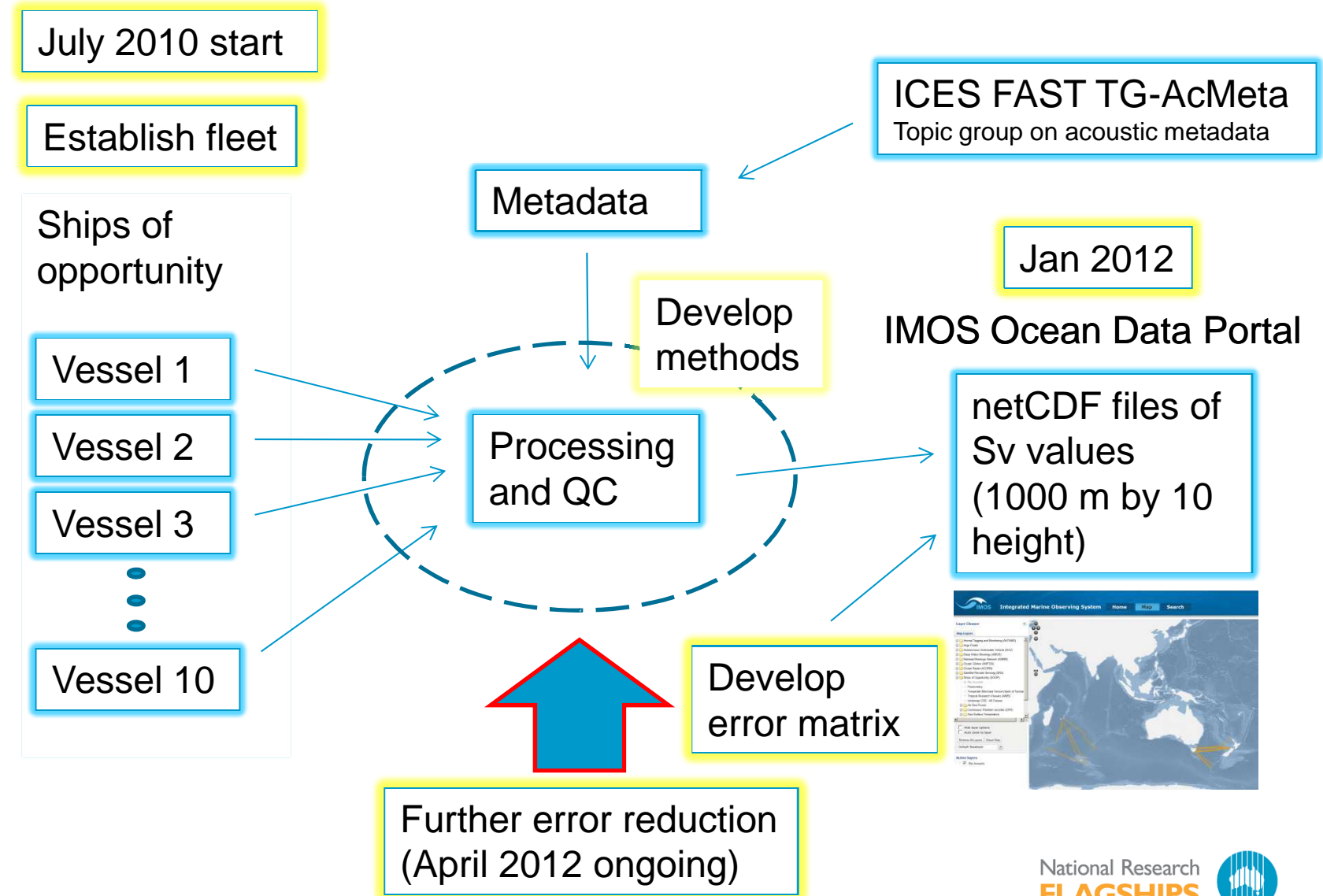


First iteration error corrections

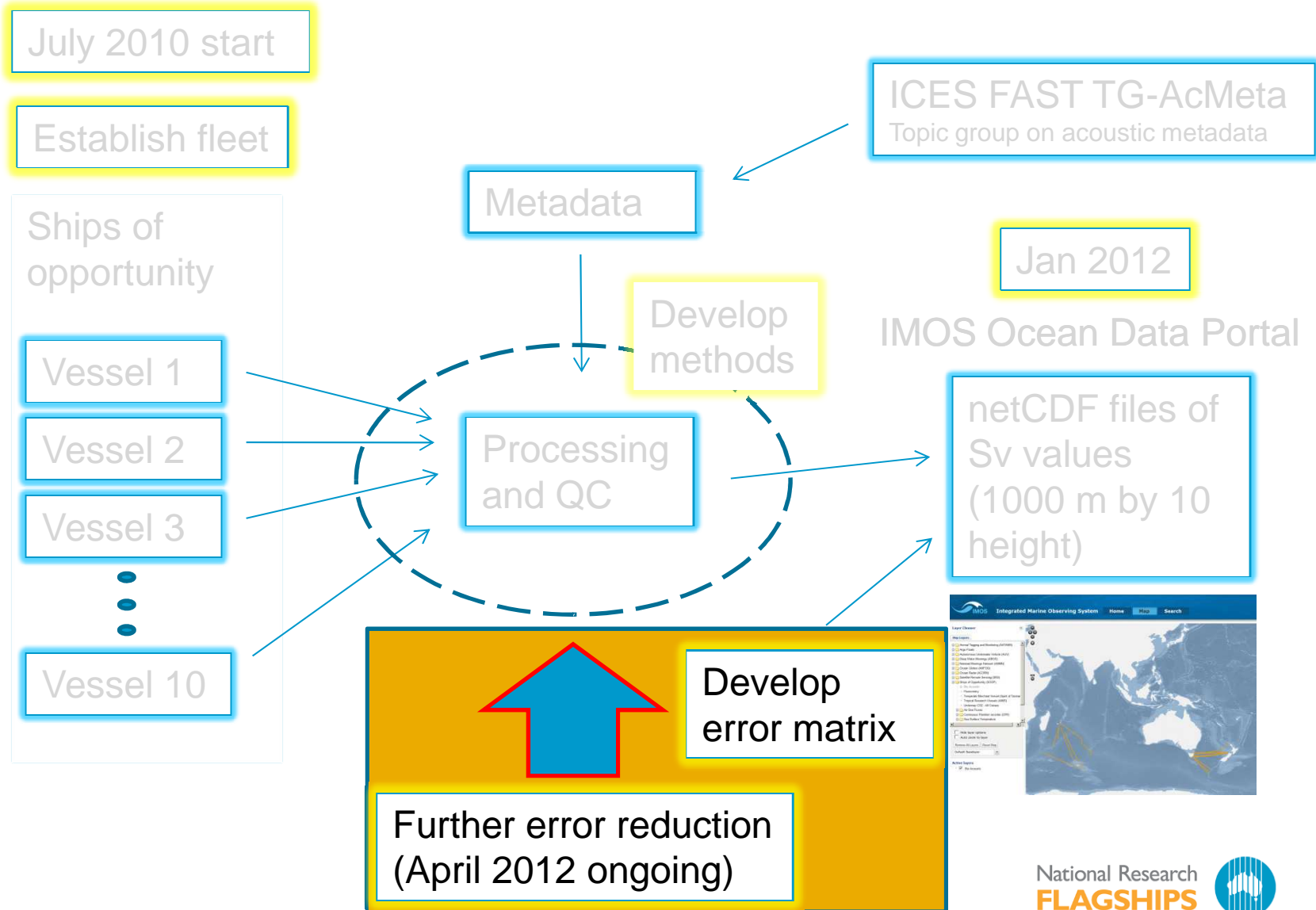
- Filters effective at reducing gross errors
- Below threshold noise and attenuation will pass through filters leaving a residual error
- Difficult to quantify this residual error when signal characteristics are similar to valid data



Project data flow structure

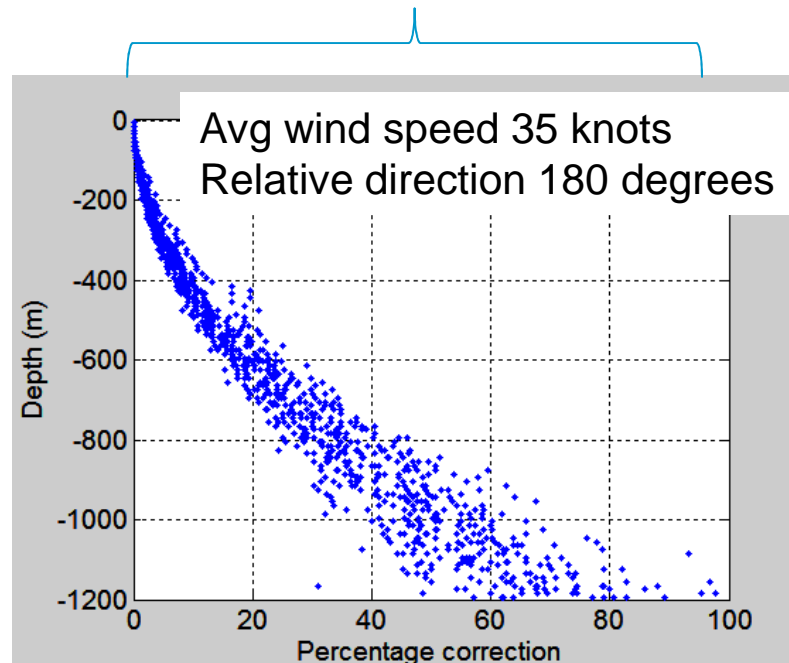
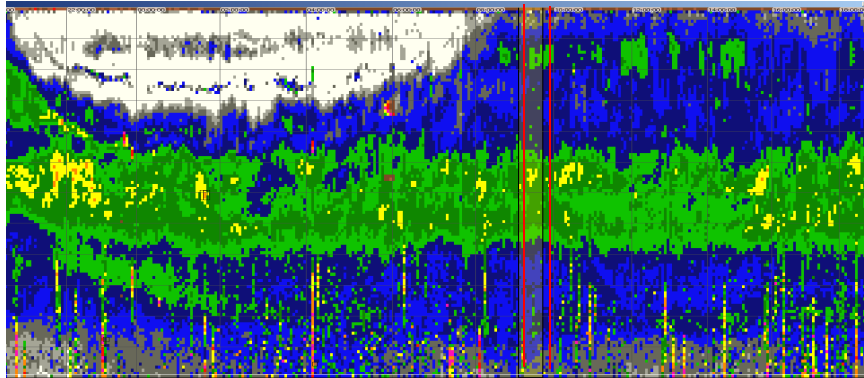


Project data flow structure



Further error reduction – Motion correction

Southern Surveyor 38 kHz 2- August 2011



Motion correction
(Stanton 1982,
Dunford 2005)

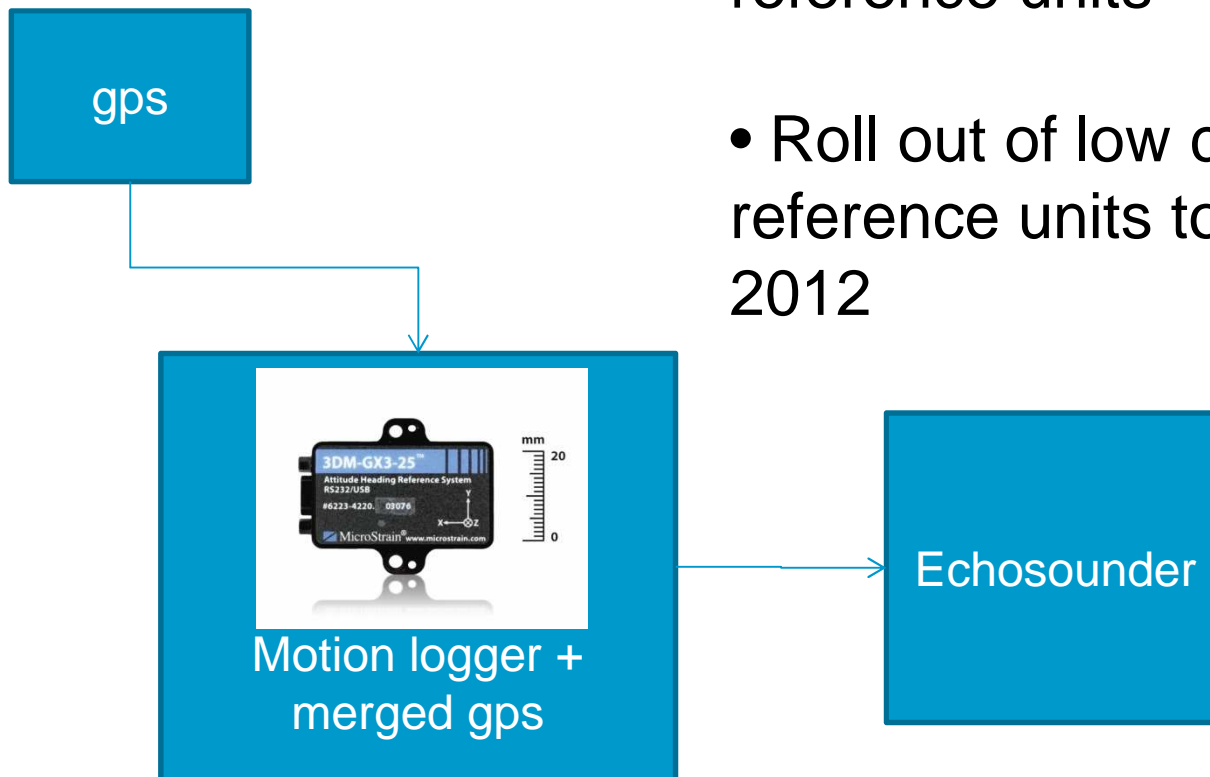
Can be significant at
deeper depths

e.g. 20% at 600 m
40% at 800 m

Further error reduction – Motion correction

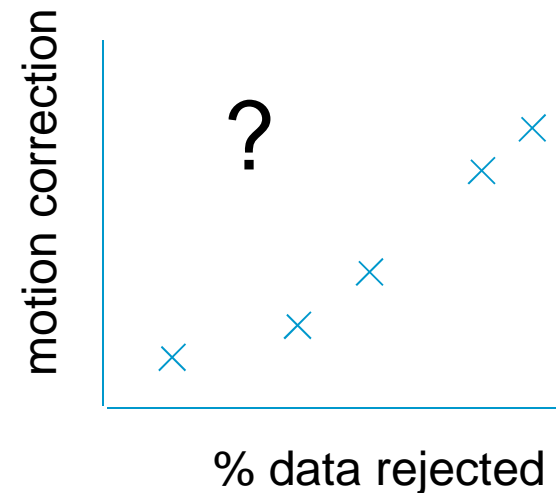
- 2 out of 10 participating vessels presently have motion reference units

- Roll out of low cost motion reference units to vessels in 2012



Further error reduction – can we infer motion correction?

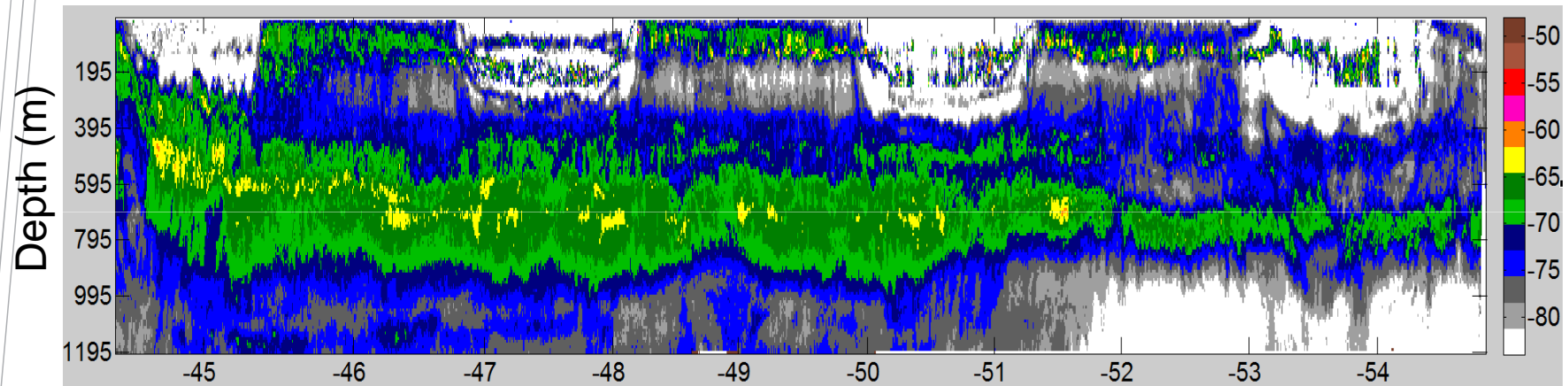
- For each vessel collect acoustic data with mru in a range of conditions.
- Process data using noise and attenuation filters.
- Establish relationship between percentage data rejected and magnitude of motion correction.
- For historic data without mru, infer motion correction from percentage data retained.



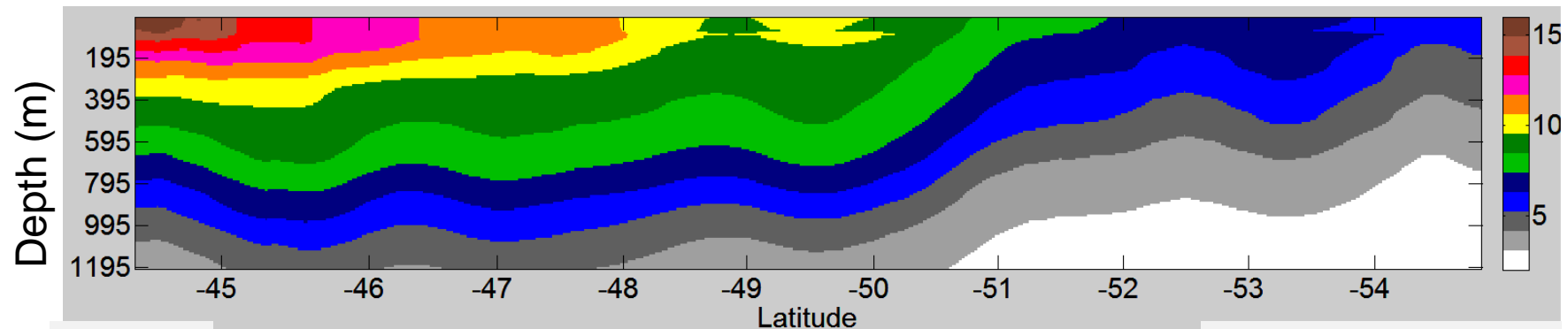
Corrections for environmental conditions

Open-ocean transects may pass through very different water masses.

FV Janas – Hobart to 55 degrees South



Along-transect temperature (synTS model)



Hobart

Macquarie Island

Corrections for environmental conditions

- Link open-ocean acoustic transect positions to satellite adjusted climatology model (synTS)
- Calculate absorption and sound speed
- Calculate Sv' (corrected Sv)

$$Sv' = Sv + 30 * \log\left(\frac{c}{c_o}\right) + 2 * R_o(\alpha * \frac{c}{c_o} - \alpha_o)$$

α_o = nominal absorption c_o = nominal sound speed

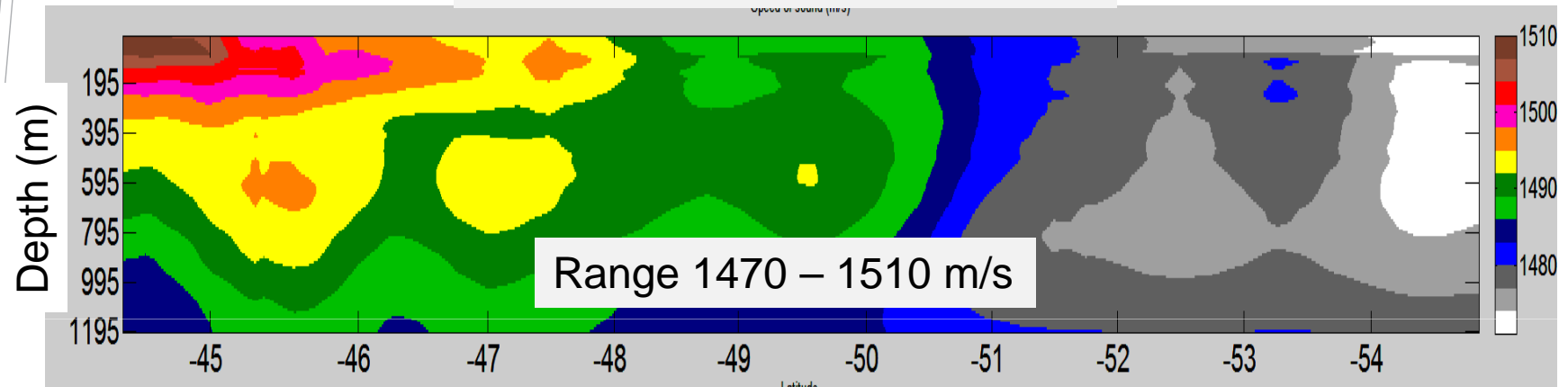
c = estimated sound speed α = estimated absorption

R_o = nominal sample depth

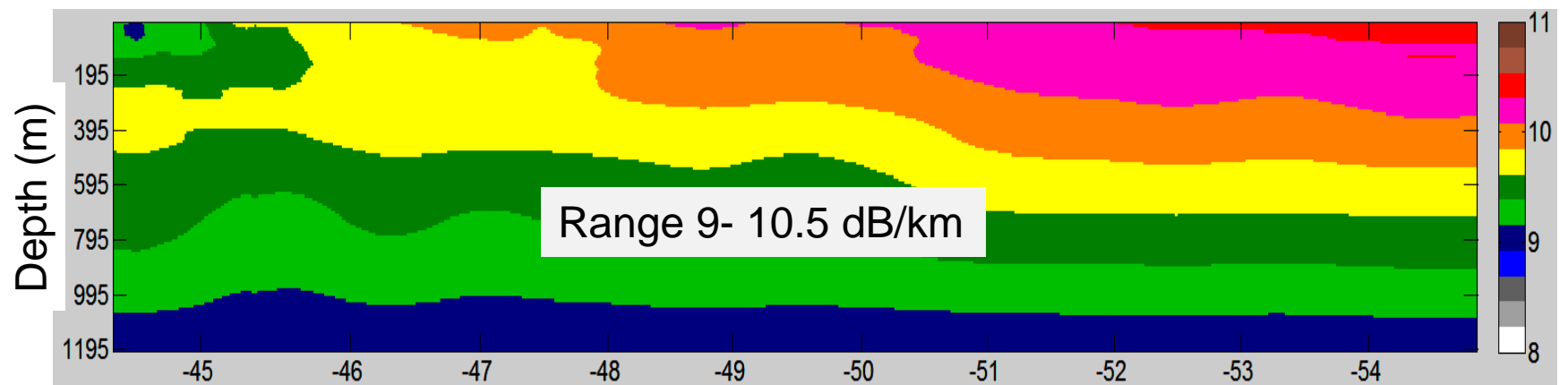
Corrections for environmental conditions

Absorption and sound speed estimates

Sound speed (Mackenzie, 1981)



Absorption (Francoise and Garrison 1982)



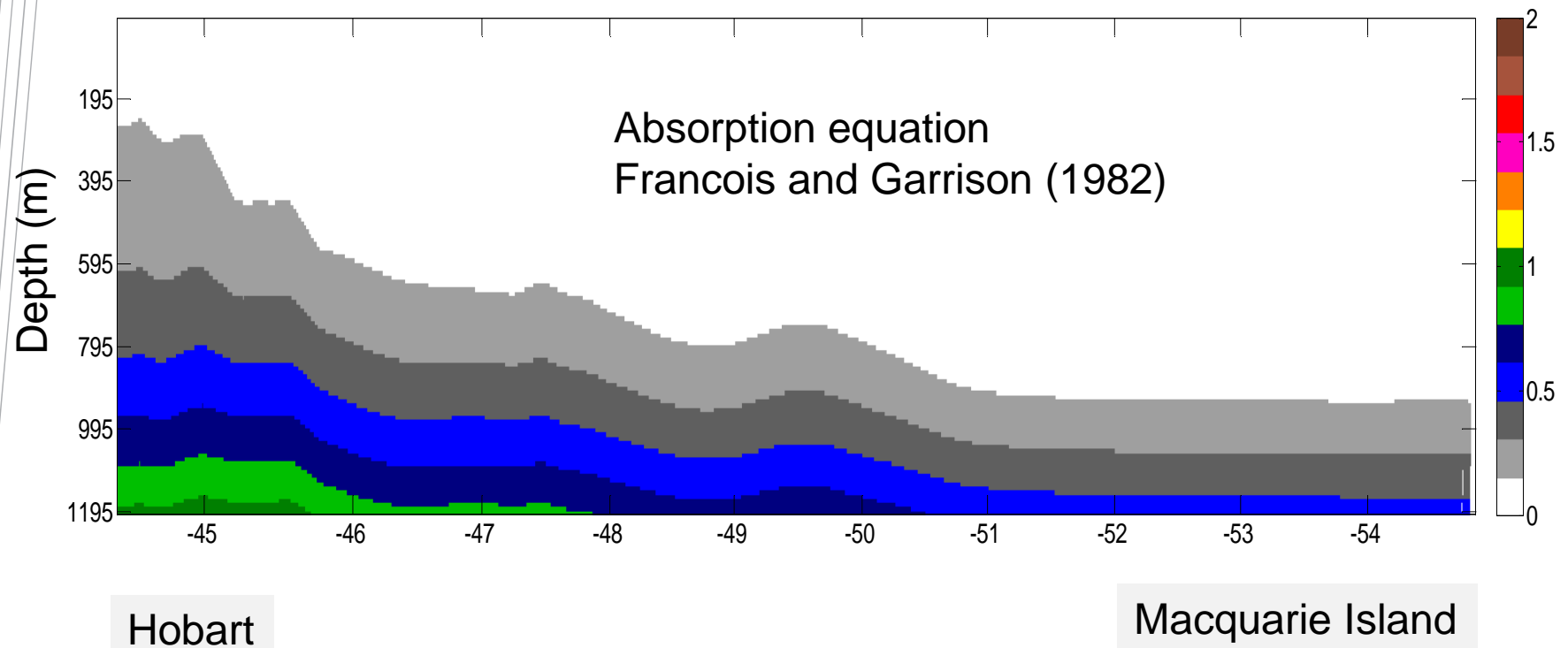
Hobart

Macquarie Island

Corrections for environmental conditions

Absorption and sound speed estimates

Difference between corrected and uncorrected Sv in dB



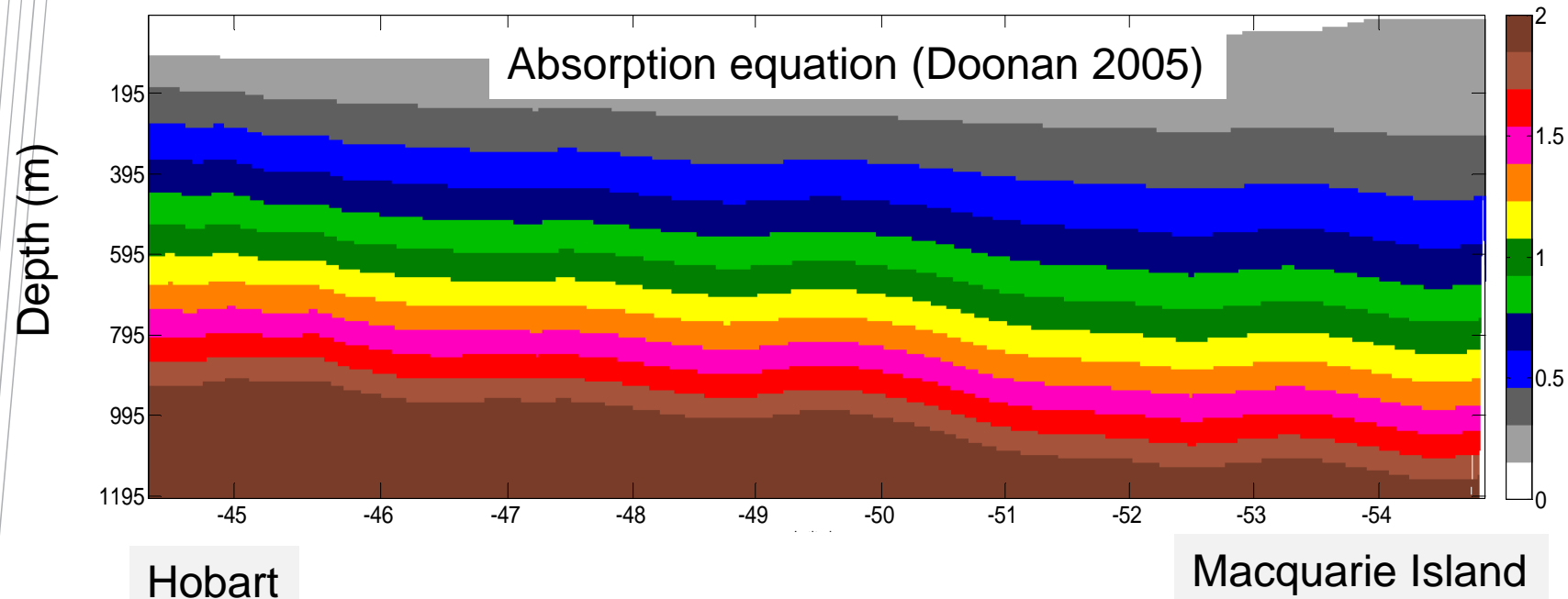
Changes in absorption and sound speed have opposing effects on Sv correction

→ Small difference between corrected and uncorrected Sv (typically <0.3 dB or less)

Corrections for environmental conditions

Absorption and sound speed estimates

Difference between corrected and uncorrected Sv in dB



Larger difference between corrected and uncorrected Sv (up to 2 dB)

Corrections for environmental conditions

Absorption and sound speed estimates

Conclusion:

Choice of absorption equation is having a larger effect than the changes temperature and salinity parameters

Summary

- Quality controlled data posted with first order errors removed
- Future data will be motion corrected, uncorrected historic data will require larger error term
- Environmental corrections sensitive to choice of equations
- Future work: Matrix of error estimates to accompany each Sv value