

view_frames Result
Recorded at time: 81.972

map

Broadcaster: /amcl
Average rate: 10.206 Hz
Most recent transform: 82.461 (-0.489 sec old)
Buffer length: 4.801 sec

odom

Broadcaster: /gazebo
Average rate: 30.208 Hz
Most recent transform: 81.961 (0.011 sec old)
Buffer length: 4.800 sec

base_footprint

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (81.972 sec old)
Buffer length: 0.000 sec

base_link

Broadcaster: /gazebo
Average rate: 60.196 Hz
Most recent transform: 81.962 (0.010 sec old)
Buffer length: 4.801 sec

right_wheel

Broadcaster: /gazebo
Average rate: 60.196 Hz
Most recent transform: 81.962 (0.010 sec old)
Buffer length: 4.801 sec

left_wheel

Broadcaster: /robot_state_publisher
Average rate: 10000.000 Hz
Most recent transform: 0.000 (81.972 sec old)
Buffer length: 0.000 sec

rplidar_link