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1 Data Structures

1.1 Sets

1.1.1 Union-Find Disjoint Sets

build O(n)

```
int un [MAXV];
int rnk [MAXV];

void setUn(){
  for(int i = 0; i < MAXV; ++i)
    un[i] = i;
}</pre>
```

Initializes each value as member of its own set

```
build \approx O(1)
```

```
1 int find(int a){
2   return un[a] == a? a : un[a] = find(un[a]);
3 }
```

Tells the set a belongs to.

 $merge \approx O(1)$

```
bool merge(int a, int b){
1
2
      x = find(a);
      y = find(b);
3
      if(x != y){
4
        if (rnk[x] > rnk[y]) un[y] = x;
5
        else {
6
           \operatorname{un}[x] = y;
7
           if(rnk[x] = rnk[y]) rnk[y]++;
8
9
10
        {\bf return\ true}\,;
11
      return false;
12
13
```

Merge the sets in which a and b belong to.

1.2 Trees

1.2.1 Segment Tree

build O(n)

```
ll arr [MAXN];
1
2
   11 tree [MAXN*4];
3
   void build(int node, int 1, int r){
4
     if(1 > r) return;
5
     if(1 = r)
6
7
        tree[node] = arr[1];
8
       return;
9
     build (node *2, 1, (l+r)/2);
10
     build (node *2+1, 1+(1+r)/2, r);
11
      tree[node] = tree[node*2] + tree[node*2+1];
12
13
```

Stores the values of arr in tree, each node stores the operation on a different interval of values. Root of tree is 1.

query $O(\log n)$

```
11 query(int node, int 1, int r, int a, int b){
1
2
     if(1 > r | | 1 > b | | r < a) return 0;
3
     if(1) = a \&\& r <= b)
        return tree [node];
4
5
     11 \text{ temp1} = \text{query}(\text{node}*2, 1, (1+r)/2, a, b);
6
7
      11 \text{ temp2} = \text{query}(\text{node}*2+1, 1+(1+r)/2, r, a, b);
8
     return temp1 + temp2;
9
```

Returns the given operation on the range [a, b].

update O(n)

```
1
   void update(int node, int 1, int r, int a, int b, 11 p){
2
      if(1 > r \mid | 1 > b \mid | r < a) return;
3
      if(l = r){
4
        tree[node] += p;
5
       return;
6
     }
7
     update(node*2, 1, (l+r)/2, a, b, p);
     update(node*2+1, 1+(1+r)/2, r, a, b, p);
8
9
      tree[node] = tree[node*2] + tree[node*2+1];
10
```

Increments every value in the range [a, b] in p units, can be modified to change all values in the range to p by changing increment operator by assignation.

propagate O(1)

```
1
   void prop(int node, int l, int r){
2
      if(lazy[node]){
3
        tree [node] += lazy [node];
        if ( l!=r ) {
4
          lazy[node*2] += lazy[node];
5
          lazy [node*2+1] += lazy [node];
6
7
8
        lazy[node] = 0;
9
10
```

Updates the value on *node* and propagates the lazy value to its children.

lazy update $O(\log n)$

```
void update(int node, int l, int r, int a, int b, ll p){
1
2
     prop(node, l, r);
     if(l > r \mid | l > b \mid | r < a) return;
3
4
      if(1) = a \&\& r <= b)
        tree[node] += p;
5
        if (1!=r) {
6
7
          lazy [node*2] += p;
          lazy [node*2+1] += p;
8
9
10
        return;
11
12
     update(node*2, 1, (l+r)/2, a, b, p);
     update(node*2+1, 1+(1+r)/2, r, a, b, p);
13
      tree[node] = min(tree[node*2], tree[node*2+1]);
14
15
```

Increments every value in the range [a, b] in p units, lazy values are stored in lazy, updates on demand.

```
lazy query O(\log n)
```

```
11 query(int node, int 1, int r, int a, int b){
1
2
      if(l > r \mid | l > b \mid | r < a) return INF;
      prop(node, left, right);
3
      if(l) = a \&\& r <= b)
4
        return tree [node];
5
6
7
      11 \text{ temp1} = \text{query}(\text{node}*2, 1, (1+r)/2, a, b);
8
      11 temp2 = query (node * 2+1, 1+(1+r)/2, r, a, b);
      return min(temp1, temp2);
9
10
```

Computes the value of the operation in the range [a, b], updates on demand.

2 Graphs

2.1 MST

2.1.1 Kruskal

Kruskal $O(|E| \log |V|)$

```
vector< tuple < double, int, int >> edges;
1
2
   int MST(int t){
3
4
     setUn();
      sort(edges.begin(), edges.end());
5
     int cost = 0;
6
      for(int i = 0; i < (int) edges.size(); ++i)
7
        bool f = merge(get < 1 > (edges[i]), get < 2 > (edges[i]));
8
9
        cost += (get < 0 > (edges[i])) * f;
10
11
      return cost;
12
```

Computes the Minimum Spanning Tree of a graph with E = edges.

2.2 SSSP

2.2.1 Dijkstra

Dijkstra $O(|E| + |V| \log |V|)$

```
int d[MAXV];
1
2
3
    void dijkstra(int s, int e){
4
      priority_queue<ii> q;
5
      q.push({0,s});
      d[s] = 0;
6
7
      while (!q.empty()) {
         int w = -q.top().first;
8
9
         int u = q.top().second;
10
         if(u == e) return w;
11
         q.pop();
         if(w > d[u]) continue;
12
13
         for (auto &t: graph [u]) {
           int nw = t.first + w;
14
            \label{eq:cond} \mbox{init} \ \ v \, = \, t \, . \, \mbox{second} \, ;
15
            if(nw < d[v])
16
              d[v] = nw;
17
              q.push(\{-nw, v\});
18
19
         }
20
21
22
      return INF;
23
```

Computes the shortest distance d[u] from vertex s to every vertex u, stops after finding min distance to e.

3 Math

3.1 Series

3.1.1 Aritmetic Progression

$$S_n = a_1 + (a_1 + d) + (a_1 + 2d) + \dots + (a_1 + (n-1)d)$$

$$S_n = \frac{n}{2}(2a_1 + (n-1)d)$$