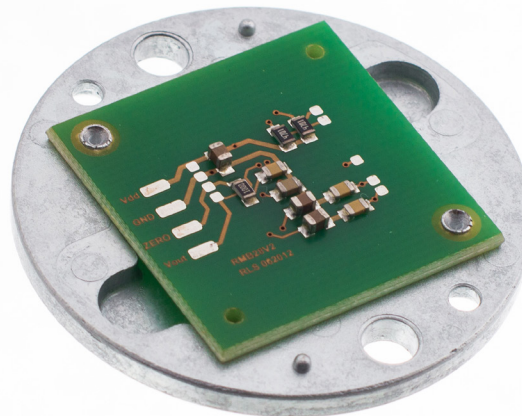
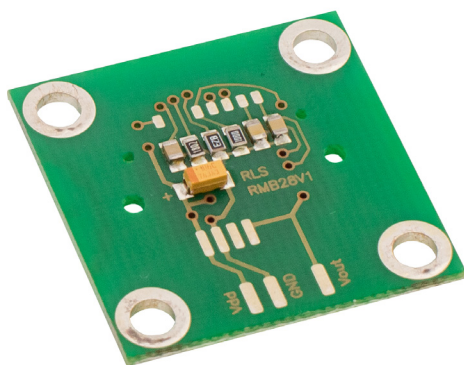


RMB28 / RMF44 angular magnetic encoder modules



The images do not represent all variants.

The RMB28 encoder module is designed for direct integration to high volume OEM applications. The low cost 28 mm square PCB can also be provided with a connector or as RMF44 on a 44 mm diameter metal flange for easy installation.

The encoder module consists of a magnetic actuator and a separate sensor board. Rotation of the magnetic actuator is sensed by a custom encoder chip mounted on the sensor board, and processed to give the required output format. Output signals are provided in industry standard absolute, incremental, analogue or linear voltage output formats.

The RMB28 and RMF44 encoder modules can be used in a wide range of OEM applications including motor control and industrial automation.

Product range

RMB28AC / RMF44AC

Analogue sinusoidal output with a single sine/cosine period per revolution.

RMB28I / RMF44I

Incremental with 80 to 2,048 pulses per revolution (320 to 8,192 counts per revolution with x4 evaluation).

RMB28MD / RMF44MD

Sine/Cosine + Absolute binary synchro-serial + Incremental, 5V.

RMB28SC / RMF44SC

Synchro serial interface (SSI) with 32 to 8,192 positions per revolution.

RMB28SI / RMF44SI

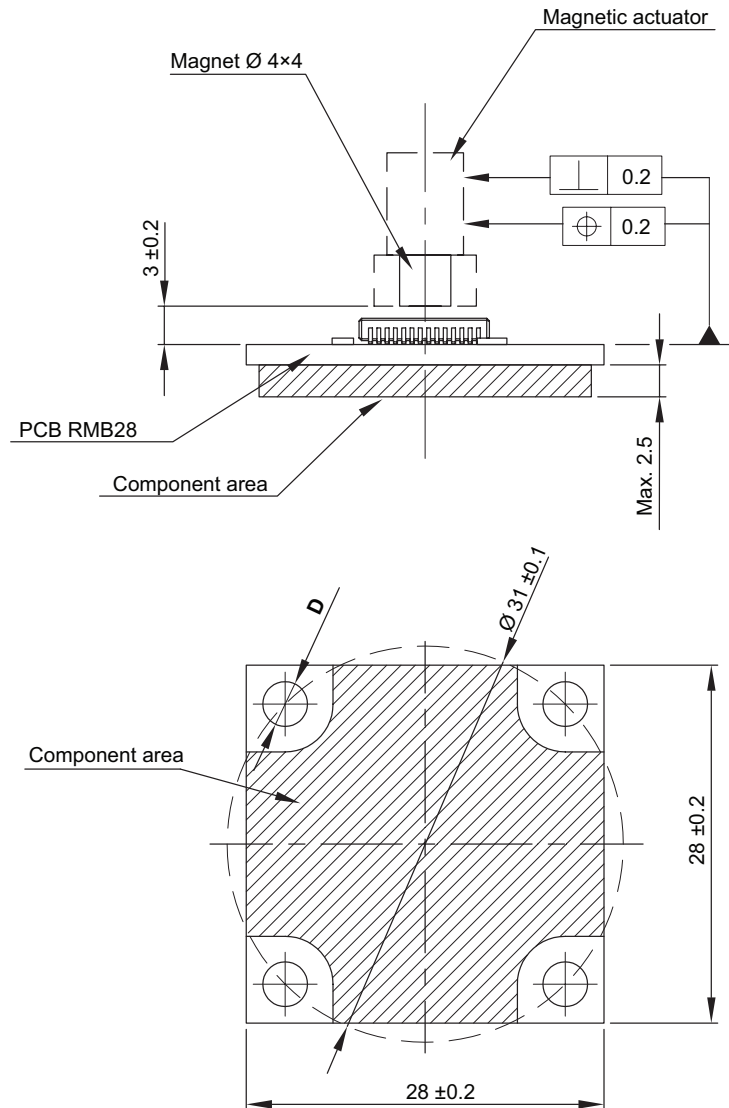
Synchro serial interface (SSI) and incremental outputs.

RMB28Vx / RMF44Vx

Linear voltage output in a range of variants.

- 28 mm square module with the option of 44 mm diameter metal flange
- Low cost for OEM integration
- 24 V and 5 V power supply versions
- High speed operation to 60,000 rpm
- Absolute - to 13 bit resolution (8,192 counts per revolution)
- Industry standard absolute, incremental, analogue, commutation and linear voltage output formats
- Accuracy to $\pm 0.5^\circ$
- RoHS compliant (lead free) - see Declaration of conformity

RMB28 installation drawing



Output type	Hole diameter (D)
RMB28AC	2.5 ± 0.1
RMB28IC	2.5 ± 0.1
RMB28IB	3.5 ± 0.1
RMB28IE	3.5 ± 0.1
RMB28MD	3.5 ± 0.1
RMB28SC	2.5 ± 0.1
RMB28SI	2.5 ± 0.1
RMB28Vx	3.5 ± 0.1



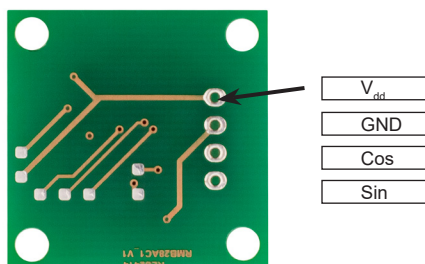
Clockwise (CW) rotation of magnet

RMB28AC / RMF44AC – Analogue sinusoidal

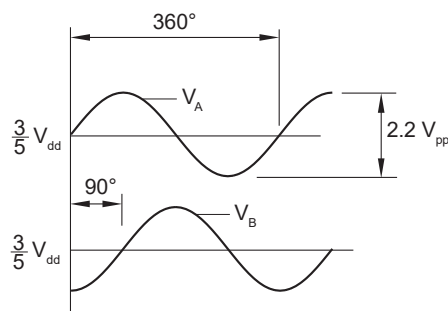
2 channels VA VB sinusoids (90° phase shifted, single ended)

Power supply	$V_{dd} = 5\text{ V} \pm 5\%$
Resolution	One sine/cosine wave per revolution
Current consumption	13 mA
Sin/Cos outputs	Signal amplitude: $1.1\text{ V} \pm 0.2\text{ V}$ Signal offset: $V_{dd}/2 \pm 5\text{ mV}$
Maximum speed	60,000 rpm
Operating temperature	$-40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$

Connections



Timing diagram

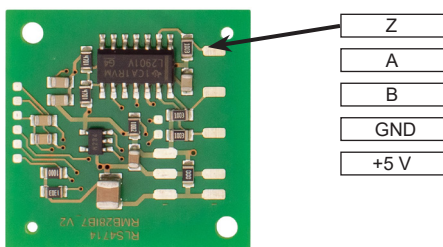


RMB28IE / RMF44IE – Incremental, Open Collector, NPN

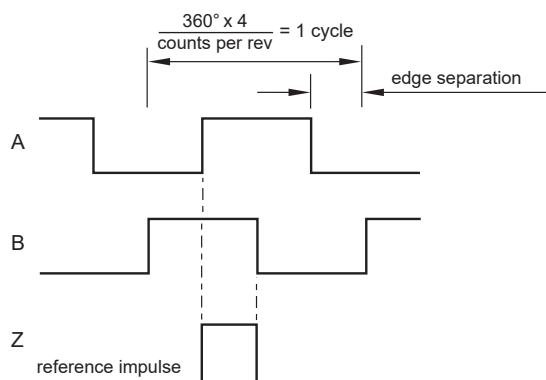
Low cost alternative for ball bearing encoders

Power supply	$V_{dd} = 5\text{ V} \pm 5\%$
Current consumption	35 mA (not loaded)
Output signals	A, B, Z
Maximum output load	20 mA
Accuracy	Typ. $\pm 0.5^{\circ}$
Hysteresis	0.18°
Resolution	80 to 2,048 pulses per revolution (320, 400, 500, 512, 800, 1,000, 1,024, 1,600, 2,000, 2,048, 4,096, 8,192 counts per revolution)
Maximum speed	30,000 rpm
Temperature Operating and storage	$-40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$

Connections

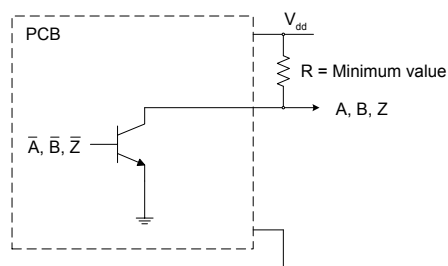


Timing diagram



B leads A for clockwise rotation of magnet.

Recommended signal termination

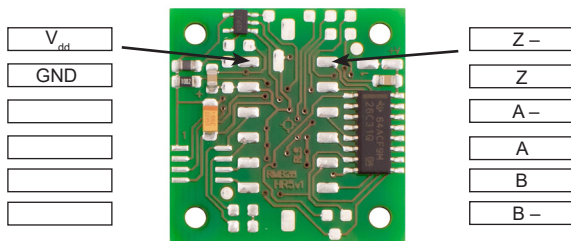


RMB28IC / RMF44IC– Incremental, RS422

Square wave differential line driver to RS422

Power supply	$V_{dd} = 5\text{ V} \pm 5\%$
Current consumption	Max. 35 mA
Output signals	A, B, Z, A–, B–, Z– (RS422)
Accuracy	Typ. $\pm 0.5^\circ$
Hysteresis	0.18°
Resolution	80 to 2,048 pulses per revolution (320, 400, 500, 512, 800, 1,000, 1,024, 1,600, 2,000, 2,048, 4,096, 8,192 counts per revolution)
Maximum speed	30,000 rpm
Temperature	-40°C to $+125^\circ\text{C}$
Operating and storage	-40°C to $+105^\circ\text{C}$ (with connector)

Connections

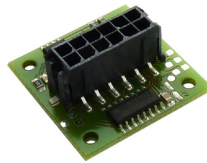


Connector type

Molex 43045-1219

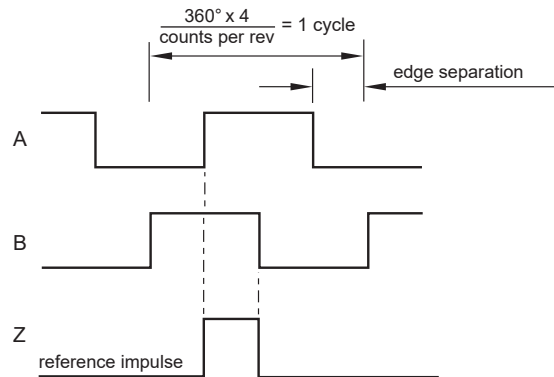
Mating connector (Not provided)

Molex 43025-1200 (crimp terminal 43030-xxxx)



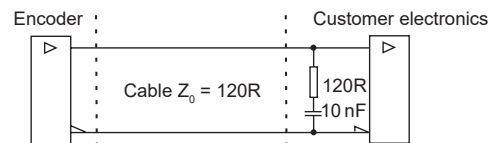
Timing diagram

Complementary signals not shown



B leads A for clockwise rotation of magnet.

Recommended signal termination

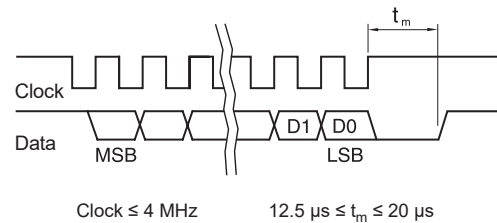


RMB28SC / RMF44SC – Absolute binary synchro-serial (SSI), RS422

Serial encoded absolute position measurement

Output code	Natural binary
Power supply	$V_{dd} = 5\text{ V} \pm 5\%$
Current consumption	Max. 35 mA
Data output	Serial data (RS422)
Data input	Clock (RS422)
Accuracy	Typ. $\pm 0.5^\circ$
Hysteresis	0.18°
Resolution	320, 400, 500, 512, 800, 1,000, 1,024, 1,600, 2,000, 2,048, 4,096, 8,192 counts per revolution
Maximum speed	30,000 rpm
Temperature	-40°C to $+125^\circ\text{C}$
Operating and storage	-40°C to $+105^\circ\text{C}$ (with connector)

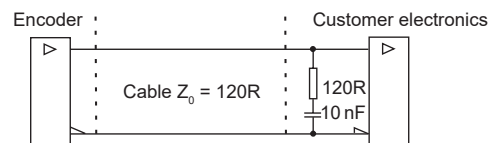
Timing diagram



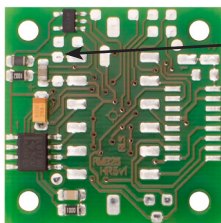
Position increases for clockwise rotation of magnet.

Recommended signal termination

For data output lines only



Connections



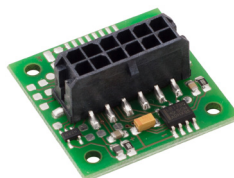
V_{dd}
GND
Clock
Clock -
Data -
Data

Connector type

Molex 43045-1219

Mating connector (Not provided)

Molex 43025-1200 (crimp terminal 43030-xxxx)

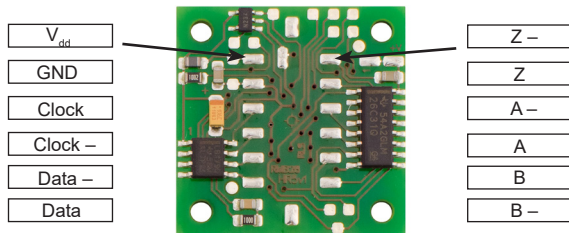


RMB28SI / RMF44SI – Absolute binary synchro-serial (SSI) + Incremental, RS422

Complex feedback device for absolute position at start up as well as during operation + incremental outputs.
Both the incremental and the SSI output always have the same fixed resolution.

Output code	Natural binary
Power supply	$V_{dd} = 5\text{ V} \pm 5\%$
Current consumption	Max. 35 mA
Incremental outputs	A, B, Z, A–, B–, Z– (RS422)
Data output	Serial data (RS422)
Data input	Clock (RS422)
Accuracy	Typ. $\pm 0.5^\circ$
Hysteresis	0.18°
Resolution	80 to 2,048 pulses per revolution (320, 400, 500, 512, 800, 1,000, 1,024, 1,600, 2,000, 2,048, 4,096, 8,192 counts per revolution)
Maximum speed	30,000 rpm
Temperature	-40°C to $+125^\circ\text{C}$
Operating and storage	-40°C to $+105^\circ\text{C}$ (with connector)

Connections

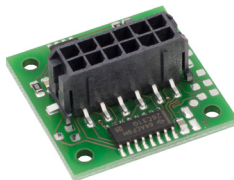


Connector type

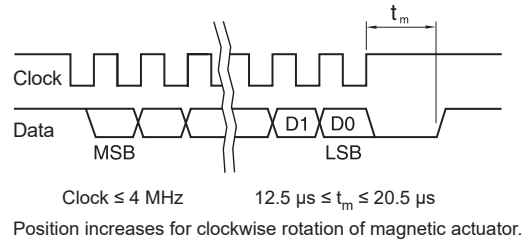
Molex 43045-1219

Mating connector (Not provided)

Molex 43025-1200 (crimp terminal 43030-xxxx)

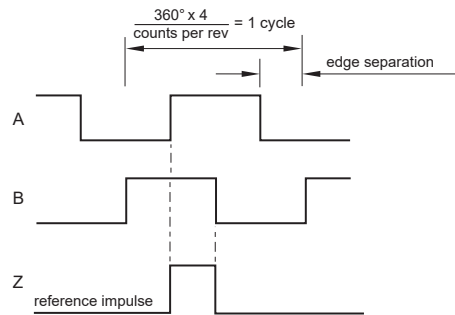


Timing diagram - SSI



Timing diagram - Incremental

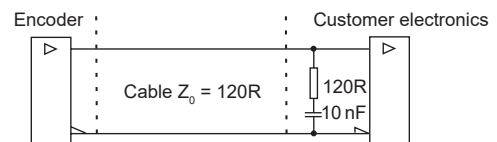
Complementary signals not shown



B leads A for clockwise rotation of magnetic actuator.

Recommended signal termination

For incremental signals + SSI data output lines only

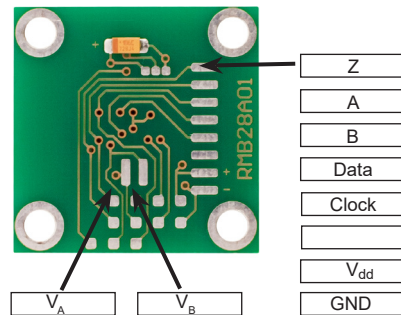


RMB28MD / RMF44MD – Sine/Cosine + Absolute binary synchro-serial (SSI) + Incremental

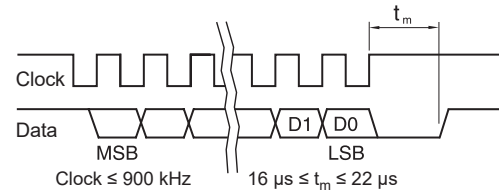
Complex feedback device for absolute position at start-up as well as during operation + incremental outputs

Output code	Natural binary
Power supply	$V_{dd} = 5\text{ V} \pm 5\%$
Current consumption	13 mA – incremental and SSI (not loaded)
Incremental outputs	A, B, Z
Sin/Cos outputs	Signal amplitude: $1.1\text{ V} \pm 0.2\text{ V}$ Signal offset: $V_{dd}/2 \pm 5\text{ mV}$
Data output	Serial data
Data input	Clock
Accuracy	$\pm 0.7^\circ$
Hysteresis	0.45°
Resolution	8 bit + 64 ppr (256 cpr) + one sine/ cosine period per revolution
Maximum speed	60,000 rpm
Temperature	-40°C to $+125^\circ\text{C}$
Operating and storage	

Connections

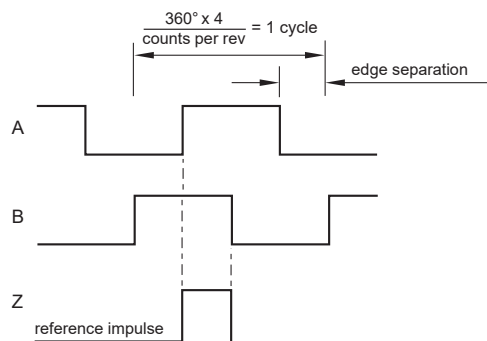


Timing diagram - SSI



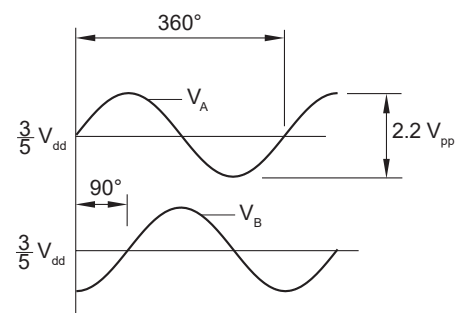
Position increases for clockwise rotation of magnet.

Timing diagram - Incremental



B leads A for clockwise rotation of magnet.

Timing diagram - Sine/Cosine

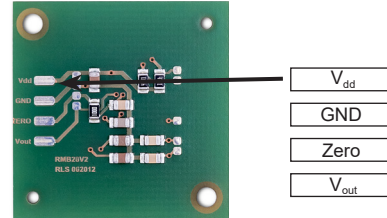


RMB28Vx / RMF44Vx – Linear voltage output

Alternative for potentiometers

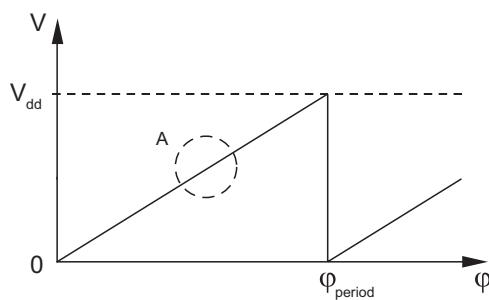
Power supply	$V_{dd} = 5\text{ V} \pm 5\%$
Current consumption	Typ. 26 mA
Output voltage	0 V to V_{dd}
Output loading	Max. 2 mA
Nonlinearity	1 %
Resolution of DAC	10 bit
Maximum speed	30,000 rpm
Temperature	$-40\text{ }^{\circ}\text{C}$ to $+125\text{ }^{\circ}\text{C}$
Operating and storage	

Connections

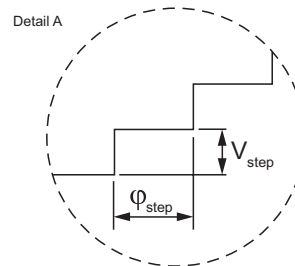


The digital relative angular position information is converted into linear voltage with a built-in 10 bit D/A converter. The linear output voltage swing ranges from 0 V and V_{dd} (5 V). The number of periods within one revolution (N_{period}) can be 1, 2, 4 or 8, representing one full swing over an angle (ϕ_{period}) of 360° , 180° , 90° or 45° respectively. The signal is made up of steps which represent the angular movement needed to register a change in the position (ϕ_{step}) and the resulting change in the output voltage (V_{step}). The number of steps in one period (N_{step}) is given in the table below.

For clockwise rotation of the magnetic actuator, the output voltage increases. For counterclockwise rotation, the output voltage decreases.



Timing diagram for linear voltage output



$$\phi_{\text{step}} = \frac{\phi_{\text{period}}}{N_{\text{step}}} \quad V_{\text{step}} = \frac{V_{dd}}{N_{\text{step}}}$$

ϕ_{period} = Angle covered in one period (one sawtooth)

V_{period} = Output voltage range for one period

ϕ_{step} = Step angle (angular movement needed to register a change in the position)

V_{step} = Output voltage range for one step

N_{period} = Number of periods in one revolution

N_{step} = Number of steps in one period

ϕ_{period}	N_{period}	N_{step}	ϕ_{step}
360°	1	1024	0.35°
180°	2	1024	0.18°
90°	4	1024	0.09°
45°	8	512	0.09°

Output type and electrical variant

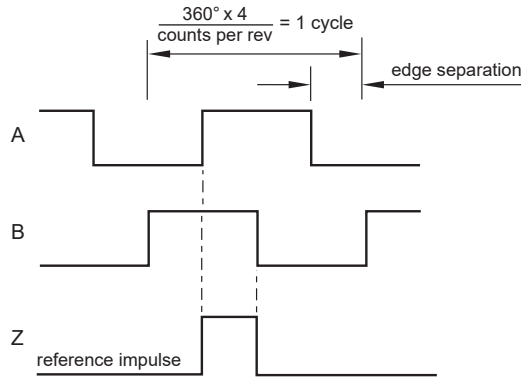
ϕ_{period}	360°	180°	90°	45°
Rotation				
Clockwise	VA	VB	VC	VD
Counterclockwise	VE	VF	VG	VH

RMB28IB / RMF44IB – Incremental, Open Collector, NPN

Square wave output

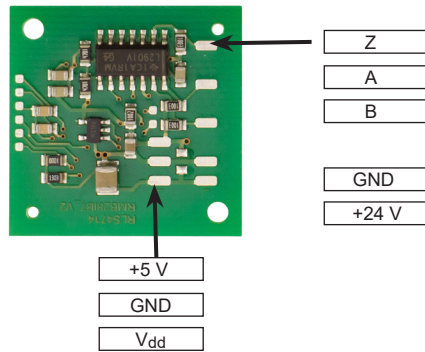
Power supply	$V_{dd} = 8 \text{ V to } 26 \text{ V}$
Current consumption	50 mA
Output signals	A, B, Z
Maximum output load	20 mA
Accuracy	Typ. $\pm 0.5^\circ$
Hysteresis	0.18°
Resolution	80 to 2,048 pulses per revolution (320, 400, 500, 512, 800, 1,000, 1,024, 1,600, 2,000, 2,048, 4,096, 8,192 counts per revolution)
Maximum speed	30,000 rpm
Temperature Operating and storage	$-40^\circ \text{C to } +125^\circ \text{C}$

Timing diagram

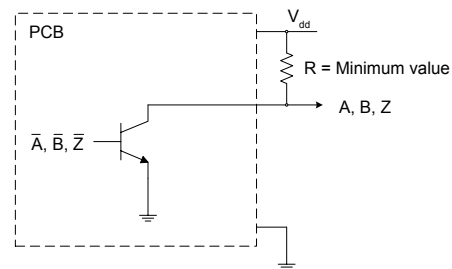


B leads A for clockwise rotation of magnet.

Connections

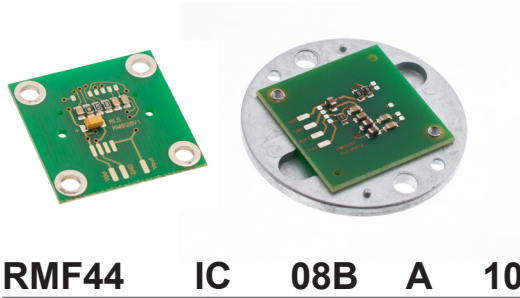


Recommended signal termination



NOTE: RMB28IB / RMF44IB boards need 2 power supplies; pad V_{dd} needs 24 V and pad +5 V needs 5 V. Pads V_{in} , GND and +5 V have been provided to allow easy connection to a 3 terminal voltage regulator to generate 5 V from 24 V.

Part numbering



Series

RMB28

RMF44 - RMB28 encoder module
on 44 mm diameter metal flange

Output type

AC - Sine/Cosine output

IB - Incremental, open collector, NPN, 24 V

IC - Incremental, RS422, 5 V

IE - Incremental, open collector, NPN, 5 V

MD - SSI + Incremental + Analogue sinusoidal, 5 V

SC - Absolute binary synchro-serial (SSI), RS422, 5 V

SI - SSI + Incremental, RS422, 5 V

Vx - Linear voltage

Linear voltage output 0 - 5 V, supply 5 V DC

	360°	180°	90°	45°
CW	VA	VB	VC	VD
CCW	VE	VF	VG	VH

NOTE: Not all combinations are valid.

RMF44 IC 08B A 10

Special requirements

10 - No special requirements (standard)

11 - With Molex connector (for **IC**, **SC** and **SI**)

Shape

S - Square (for RMB28)

A - Standard 44 mm diameter aluminium flange (for RMF44)

Resolution

For **AC**:

01S - One sine/cosine wave per revolution

For **MD**:

08B - 256 counts or positions per revolution

For **IB**, **IC**, **IE**, **SC** and **SI** (counts/positions per revolution):

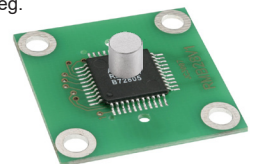
Decimal		
D32 - 320	D80 - 800	2D0 - 2000
D40 - 400	1D0 - 1000	
D50 - 500	1D6 - 1600	

Binary		
07B - 128	10B - 1024	13B - 8192
08B - 256	11B - 2048	
09B - 512	12B - 4096	

For **Vx**:

10B - 1,024 steps per revolution

* For sample quantities of RMB28 supplied with a magnet please add "KIT" to the end of the required RMB28 part number, eg. RMB28IC09BS10KIT.



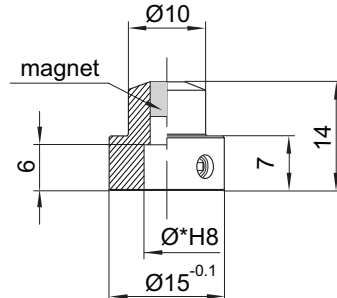
Series	Output type	Resolution	Shape	Special requirements
RMB28 / RMF44	AC	01S	S / A	10
	MD	08B		
	Vx	10B		
	IB	2D0 / 1D6 / 1D0 / D80 / D50 / D40 / D32 / 13B / 12B / 11B / 10B / 09B / 08B / 07B		
	IE			
	IC			
	SC			
	SI			

Magnetic actuator and magnet ordering information

Actuator for integration onto shaft



Shaft = $\varnothing \times h7$
Fixing: Grub screw provided



Part numbers:

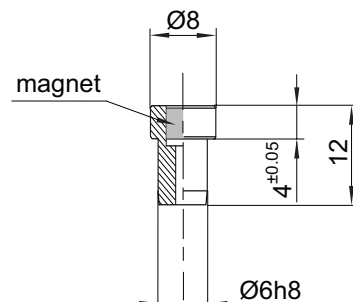
For resolutions up to 9 bit absolute (512 cpr incremental)

RMA04A2A00 – Ø4 mm shaft	RMA10A2A00 – Ø10 mm shaft
RMA05A2A00 – Ø5 mm shaft	RMA19A2A00 – Ø3/16" shaft
RMA06A2A00 – Ø6 mm shaft	RMA25A2A00 – Ø1/4" shaft
RMA08A2A00 – Ø8 mm shaft	RMA37A2A00 – Ø3/8" shaft

For resolutions from 10 bit absolute (800 cpr incremental) and above

RMA04A3A00 – Ø4 mm shaft	RMA10A3A00 – Ø10 mm shaft
RMA05A3A00 – Ø5 mm shaft	RMA19A3A00 – Ø3/16" shaft
RMA06A3A00 – Ø6 mm shaft	RMA25A3A00 – Ø1/4" shaft
RMA08A3A00 – Ø8 mm shaft	RMA37A3A00 – Ø3/8" shaft

Actuator for integration into shaft



Part numbers:

For resolutions up to 9 bit absolute (512 cpr incremental)

RMH06A2A00

For resolutions from 10 bit absolute (800 cpr incremental) and above

RMH06A3A00

With N-pole marker scribed to a $\pm 5^\circ$ accuracy:

For resolutions up to 9 bit absolute (512 cpr incremental)

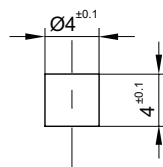
RMH06A2A02

For resolutions from 10 bit absolute (800 cpr incremental) and above

RMH06A3A02

Hole = Ø6G7
Fixing: Glue (recommended – LOCTITE 648 or LOCTITE 2701)

Magnet for direct recessing in non-ferrous shafts



Fixing: Glue (recommended – LOCTITE 648 or LOCTITE 2701)

Part numbers:

For resolutions up to 9 bit absolute (512 cpr incremental)

RMM44A2A00 (individually packed) – for sample quantities only
RMM44A2C00 (packed in tubes)

For resolutions from 10 bit absolute (800 cpr incremental) and above

RMM44A3A00 (individually packed) – for sample quantities only
RMM44A3C00 (packed in tubes)

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Document issues

Issue	Date	Page	Amendments done
9	8. 3. 2017	General	RMF44 added
10	1. 2. 2018	3	RMF44 installation drawing amended
11	18. 5. 2018	3	RMF44 installation drawing amended
		4 - 6, 8, 9	Resolutions amended
12	27. 7. 2018	General	Resolution amended
13	17. 9. 2018	3	RMF44 installation drawing amended
14	29. 8. 2019	3	RMF44 installation drawing amended

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