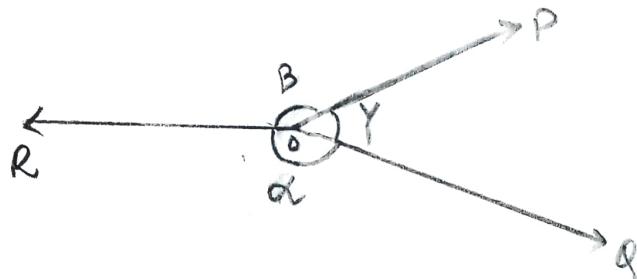


University Roll No. - T91/ECE/204058Subject - Engineering MechanicsSemester - 2ndPaper Code - ME 203Date of Examination - 14-08-2021

- ① a) LAMI'S THEOREM: It states that; if a particle is under the action of three coplanar concurrent forces, all of them acting either towards or away from point of concurrency be in equilibrium , then , each force is proportional to sine of the angle between the other two forces .



let, at point O, 3 coplanar concurrent forces (say) \vec{P} , \vec{Q} and \vec{R} be acting such that the angle formed between P & Q is Y , R & Q is β d , Q & R is β , then,

Lami's Theorem states that :-

$$\frac{P}{\sin \alpha} = \frac{Q}{\sin \beta} = \frac{R}{\sin Y}$$

where, P , Q , R are the magnitudes of the respective forces .

b)

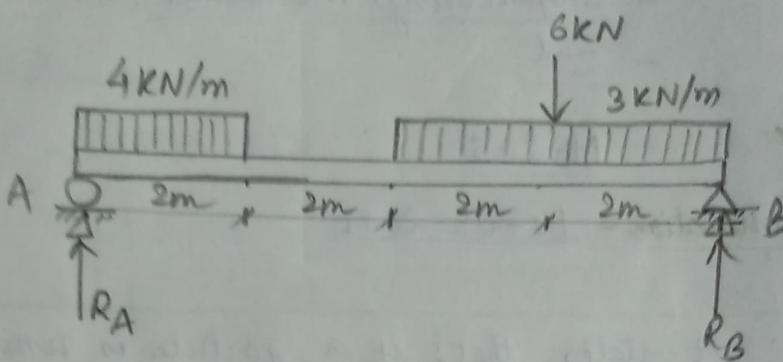
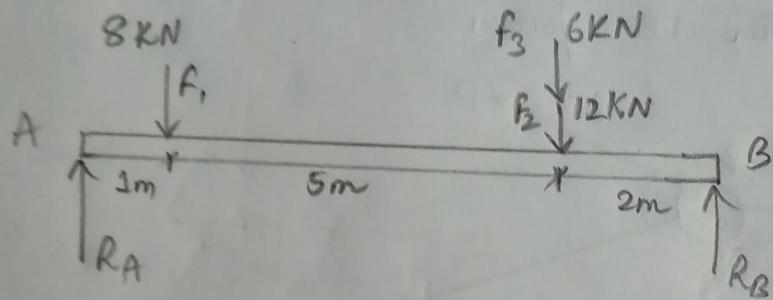


Figure 1

Given, AB is a supported beam of length 8m.

To find, the reaction at A and B.

Sol:



Let, R_A and R_B be the reactions at hinge points, A and B respectively.

The force, f_1 at point 1m from A $\Rightarrow f_1 = 4\text{KN/m} \times 2\text{m}$
 $= \underline{\underline{8\text{KN}}}$

likewise, the force, f_2 at 2m from B $\Rightarrow f_2 = 3\text{KN/m} \times 2\text{m}$
 $= \underline{\underline{6\text{KN}}}$

And, force, $f_3 = 6\text{KN}$ (given)

Now, By taking the moments at point B;

$$\sum M_B = 0$$

$$\Rightarrow -R_A \times 8 + \cancel{8 \times f_1} + (f_2 + f_3) \times 2 = 0$$

$$\Rightarrow -R_A \times 8 + 8 \times \cancel{f_1} + 18 \times 2 = 0$$

$$\Rightarrow 8 R_A = \cancel{10 + 36} 56 + 36$$

$$\Rightarrow R_A = \frac{92}{8} \text{ kN}$$

$$\Rightarrow R_A = 11.5 \text{ kN}$$

Similarly, By taking moment at A, we get,

$$\sum M_A = 0$$

$$\Rightarrow R_B \times 8 - f_1 \times 1 - (f_2 + f_3) \times 6 = 0$$

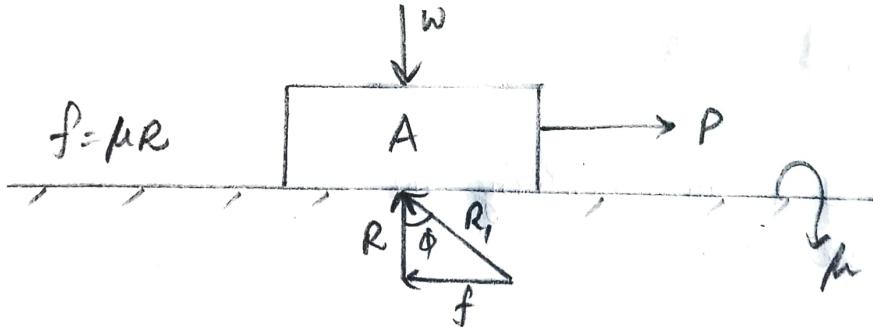
$$\Rightarrow 8R_B - 8 - 18 \times 6 = 0$$

$$\Rightarrow 8R_B = 8 + 108 \rightarrow R_B = \frac{116}{8} = 14.5 \text{ kN}$$

$$\Rightarrow R_B = \frac{108}{8} = 10 \text{ kN}$$

Thus the values of reaction forces at A is 11.5 kN vertically upwards & the value of reaction forces at B is 14.5 kN, vertically upwards.

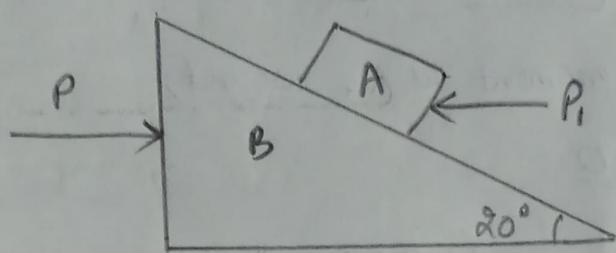
Q) a) LIMITING ANGLE OF FRICTION: This is the angle between resultant force of friction and the normal reaction made with normal reaction.



In the above figure, let, a force, P be acting on a body A of weight w kept on a friction plane with coefficient of friction, μ . Then, the normal reaction, R acts vertically upwards and frictional force, f acts in opp. direction of P ; $f = \mu R$

$$\text{Then, } \tan \phi = \frac{f}{R} = \frac{\mu R}{R} = \mu \rightarrow \phi = \tan^{-1} \mu$$

b)



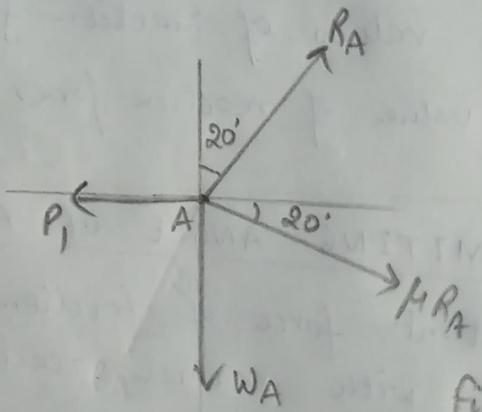
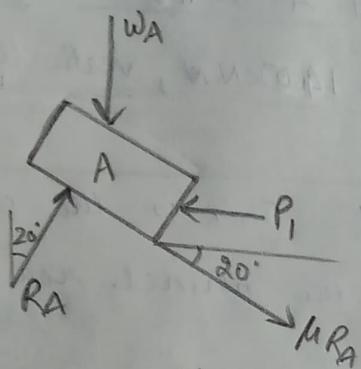
Given; weight of body A $\Rightarrow w_A = 20 \text{ kN}$.

coefficient of friction, $\mu = 0.25$ (for all surfaces).

angle of inclination, $\theta = 20^\circ$

To find; value of P and P_1 ; for the system to be in equilibrium.

Solⁿ:



FBD of body A Fig 1.

For body A:

Considering the FBD of A and resolving the forces horizontally and vertically at A, we get;

$$\sum Y = 0$$

$$R_A \cos 20^\circ - \mu R_A \sin 20^\circ - w_A = 0$$

$$\text{or, } R_A \cos 20^\circ - 0.25 R_A \sin 20^\circ - 20,000 = 0$$

$$\text{or, } R_A (\cos 20^\circ - 0.25 \times \sin 20^\circ) = 20,000$$

$$\text{or, } R_A (0.93969 - 0.08550) = 20,000$$

$$\text{or, } R_A = \frac{20,000}{0.854185} \text{ N} = 23414.1315 \text{ N} \approx 23414.13 \text{ N}$$

Resolution of forces at A.

By $\sum X = 0$, we get,

$$P_1 = R_A \sin 20^\circ + \mu R_A \cos 20^\circ = 0$$

$$\text{Or, } P_1 = R_A (\sin 20^\circ + \mu \cos 20^\circ)$$

$$\text{Or, } P_1 = 23414.13x (\sin 20^\circ + 0.25 \times \cos 20^\circ)$$

$$\text{Or, } P_1 = 23414.13x (0.342020 + 0.23492)$$

$$\text{Or, } P_1 = 23414.13x 0.576943$$

$$\text{Or, } P_1 = 13508.522N$$

$$\text{Or, } \underline{P_1 \approx 13508.522N}$$

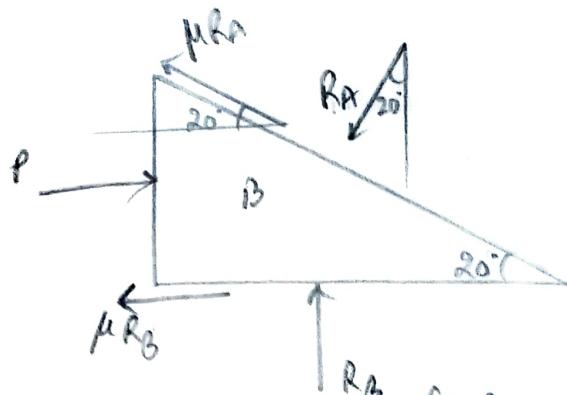
for body B,

Fig 3.

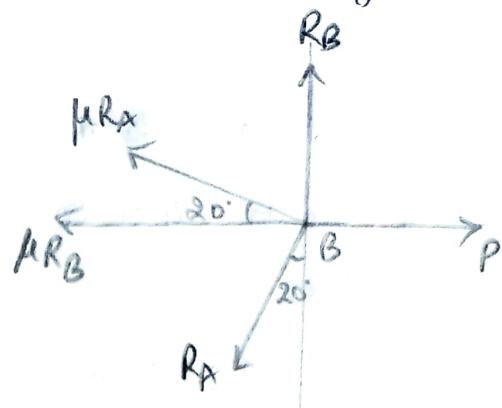
FBD of B:

Fig 4.

Resolution of forces on B

Here, friction force acts on 2 surfaces, one at inclined surface and the other at horizontal surface.

On considering the FBD of B and resolution of forces on body B, we get:

$$\sum Y = 0,$$

$$\Rightarrow R_B - R_A \cos 20^\circ + \mu R_A \sin 20^\circ = 0$$

$$\Rightarrow R_B = R_A (\cos 20^\circ - \mu \sin 20^\circ) = 0$$

$$\Rightarrow R_B = 23414.13 \times (0.93969 - 0.25 \times 0.342020)$$

$$\Rightarrow R_B = 23414.13 \times (0.93969 - 0.085505)$$

$$\Rightarrow R_B = 23414.13 \times 0.854185 \Rightarrow R_B = 19999.9986 \text{ N}$$

$$\Rightarrow R_B = 20,000.0498 \text{ N} \quad \cancel{\Rightarrow 20,000.05 \text{ N}} \Rightarrow R_B \approx 20,000 \text{ N}.$$

By, $\sum X = 0$, we get:

$$P = \mu R_B + \mu R_A \cos 20^\circ + R_A \sin 20^\circ$$

$$\text{or, } P = \mu R_B + R_A (\sin 20^\circ + \mu \cos 20^\circ)$$

$$\text{or, } P = (0.25 \times 20,000.00 + 13508.62)$$

$$\text{or, } P = (5000.00 + 13508.62) \text{ N}$$

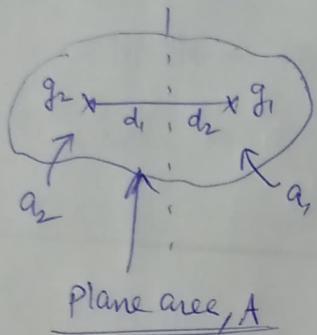
$$\Rightarrow P = 18508.62 \text{ N} \Rightarrow P = 18,508.62 \text{ N}$$

Thus the value of $P = 18508.62 \text{ N}$ & $P_1 = 13508.62 \text{ N}$

④ Centroid: In mechanics, for plane areas body with negligible thickness, we assume the total area to be concentrated at a single point and such a ~~per~~ single point is called the centroid of the plane area.

$$\Rightarrow \bar{x} = \frac{\sum A_i x_i}{\sum A_i}, \quad \bar{y} = \frac{\sum A_i y_i}{\sum A_i}, \quad \bar{z} = \frac{\sum A_i z_i}{\sum A_i}$$

→ Centroid is a point in a plane area, where the moment of areas about an axis through the centroid is zero.



$$\text{Here, } a_1 d_1 - a_2 d_2 = 0.$$

→ Centroid is denoted (normally) by G.

Radius of gyration: It is defined as the radial distance to a point which would have a moment of inertia the same as the body's actual distribution of mass, if the total mass of the body were concentrated there. It is denoted by k.

→ Consider an area, A, with moment of inertia, I_x .

$$\text{Then, } I_x = k^2 A$$

$$\therefore k_x = \sqrt{\frac{I_x}{A}}$$

(where, k_x is the radius of gyration wrt. x-axis)

4A).

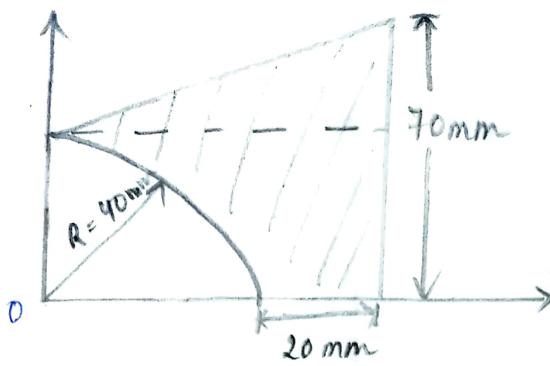


Fig 4A.

Calculation for centroid of the lamina :

This has 3 components (basically): Quarter circle, triangular part & rectangular part; which can be formetted in the below table.

Q. Let,

$$\text{Here, } x_2 = 40, y_2 = 50$$

For quarter circle:-

$$x_3 = 30, y_3 = 20$$

$$x_1 = \frac{4 \times 40}{3\pi} = \frac{160}{3\pi} = 16.976.$$

Components	Area (mm ²)	X (mm)	Y (mm)	$a_i x_i$	$a_i y_i$
1. Quarter Circle	-1256.64	16.97	16.97	-21325.2	-21325.2
2. Triangle	900	40	50	36000	45000
3. Rectangle	2400	30	20	72000	48000

$$\text{Thus, } \bar{x} = \frac{-A_1 x_1 + A_2 x_2 + A_3 x_3}{-A_1 + A_2 + A_3}$$

$$\Rightarrow \bar{x} = \frac{\sum a_i x_i}{\sum a_i} = \frac{-21325.2 + 36000 + 72000}{-1256.64 + 900 + 2400} = \frac{86674.82}{2043.36}$$

$$\therefore \bar{x} = 42.42 \text{ mm}$$

$$\text{Again, } \bar{y} = \frac{\sum a_i y_i}{\sum a_i} = \frac{-21325.2 + 45000 + 48000}{2043.36} = \frac{71674.82}{2043.36}$$

$$\therefore \bar{y} = 35.08 \text{ mm}$$

$$\text{Thus, } \bar{x} = 42.42 \text{ mm} \quad \& \quad \bar{y} = 35.08 \text{ mm} \quad \checkmark$$

(4B)

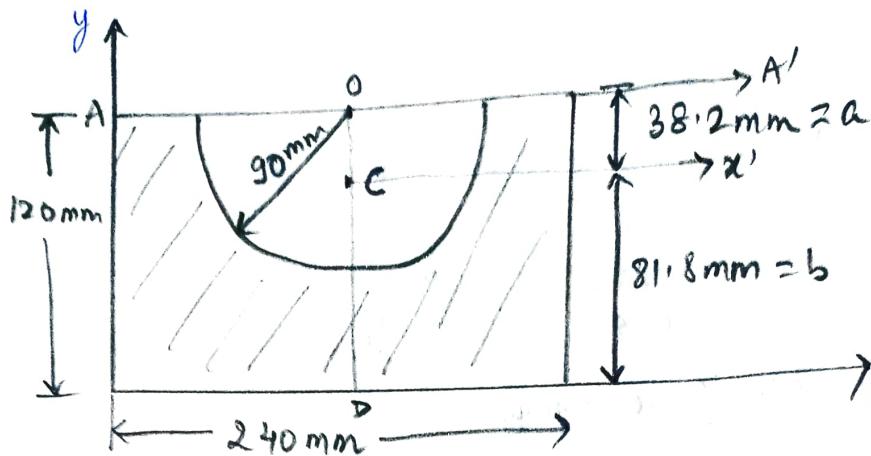


Fig 4B

This has basically 2 components :-

- i) Rectangular
- ii) Circular

For (i) :

$$\text{Moment of inertia along } x, I_x = \frac{1}{3} b h^3 = \frac{1}{3} (240)(120)^3 \text{ mm}^4.$$

$$\Rightarrow I_{x'} = 138.2 \times 10^6 \text{ mm}^4 \quad \text{--- (1)}$$

For (ii) :

Now, let, C be the centroid of the circular region.

$$\text{Then, } OC = a \text{ (say)} = \frac{4R}{3\pi} = \frac{4 \times 90}{3\pi} = 38.2 \text{ mm}$$

$$\& OD = b \text{ (say)} = 120 - a = 81.8 \text{ mm}$$

$$\text{Then, area, } A_c = \frac{1}{2}\pi R^2 = \frac{1}{2}\pi(90)^2 = 12.72 \times 10^3 \text{ mm}^2$$

Now, moment of inertia about AA' is :-

$$I_{AA'} = \frac{1}{8}\pi R^4 = \frac{1}{8}\pi(90)^4 = 25.76 \times 10^6 \text{ mm}^4.$$

→ moment of inertia w.r.t x' is :-

$$\Rightarrow I_{x'} = I_{AA'} - A_c a^2 \quad (\text{Parallel axis theorem})$$

$$\begin{aligned} \Rightarrow I_{x'} &= (25.76 \times 10^6) - (12.72 \times 10^3)(38.2)^2 \\ &= 7.20 \times 10^6 \text{ mm}^4 \end{aligned}$$

Now, moment of inertia about x is :-

$$\Rightarrow I_{x_2} = I_{x'} + A b^2 \quad (\text{parallel axis theorem})$$

$$\Rightarrow I_{x_2} = (7.20 \times 10^6) + (12.72 \times 10^3)(81.8)^2$$

$$\Rightarrow I_{x_2} = 92.3 \times 10^6 \text{ mm}^4 \quad \text{--- (11)}$$

Thus, for the given figure ; we have :- (using eqⁿ ② & ⑪)

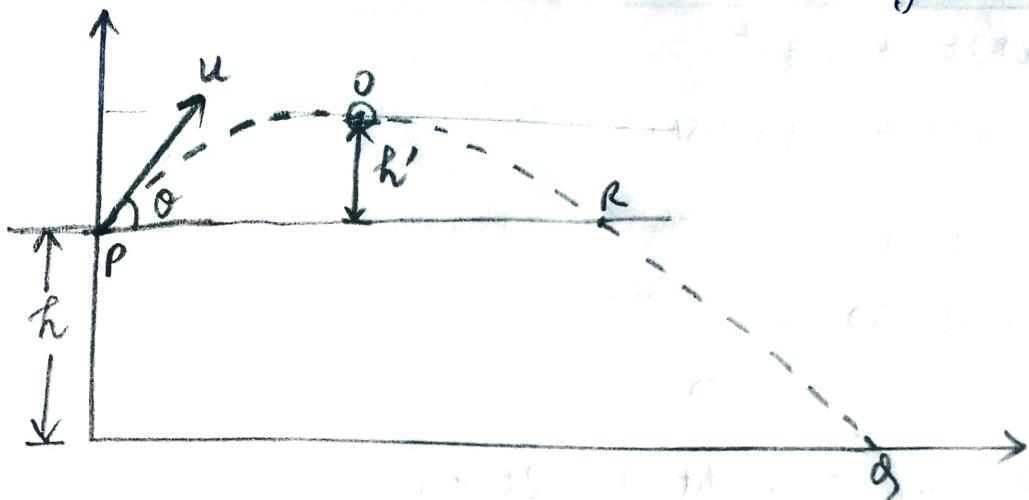
$$\Rightarrow I_x = I_{x'} - I_{x_2}$$

$$\Rightarrow I_x = 138.2 \times 10^6 \text{ mm}^4 - 92.3 \times 10^6 \text{ mm}^4$$

$$\Rightarrow I_x = 45.9 \times 10^6 \text{ mm}^4$$

Thus, the moment of inertia of the composite figure is $45.9 \times 10^6 \text{ mm}^4$
about the x-axis .

(5) a)



Given, { the initial velocity, $u = 100 \text{ m/s}$
 angle of projection, $\theta = 30^\circ$ (with horizontal)
 height of tower, $h = 100 \text{ m/s}$

Solⁿ: (i) let, the total time of flight is T sec.

(ii) Consider, the projectile covers, h' m above the tower to reach its peak and the corresponding time is t' and during the fall, it covers h m in t sec.

Thus, we conclude that : $T = 2t' + t$

On applying first equation of motion from pt. P to Q, we get:

$$v = u + at$$

$$\therefore u \sin \theta - gt' = 0 \quad (\because v = 0)$$

$$\therefore 2t' = 2 \times \frac{u \sin \theta}{g}$$

$$\therefore 2t' = \frac{2 \times 100 \times \sin 30^\circ}{9.81} = 10.194 \text{ sec.} \quad \text{--- (1)}$$

Further, applying second equation of motion from pt. R to Q,

$$h = ut + \frac{1}{2}at^2$$

$$\Rightarrow h^* = (u \sin \theta) t + \frac{1}{2} g t^2$$

$$\Rightarrow 50 = (100 \sin 30) t + \frac{1}{2} \times 9.81 t^2$$

$$\Rightarrow 50 = 50t + 4.905 t^2$$

$$\Rightarrow 4.9 t^2 + 50t - 50 = 0$$

$$\Rightarrow t = 0.92 \text{ sec.} \quad \text{--- (1)}$$

Thus, the total time of flight, $T = 2t' + t$

$$= (10.194 + 0.92) \text{ sec.} \quad \left\{ \text{using (1) \& (1)} \right.$$

$$= \underline{11.114} \text{ sec}$$

Note

$$(i) \text{ horizontal range, } R = (u \cos \theta) T$$

$$= (100 \cos 30) \times 11.114 \text{ m}$$

$$= \underline{962.5} \text{ m}$$

(ii) Using third eqⁿ of motion from h to Q,

$$V^2 - U^2 = 2ah$$

$$\Rightarrow 0 = (u \sin \theta)^2 - 2gh'$$

$$\Rightarrow h' = \frac{(100 \sin 30)^2}{2g} = \frac{(100 \times \sin 30)^2}{2 \times 9.81} = 127.42 \text{ m}$$

so, the total height, H = h' + h

$$= (127.42 + 50) \text{ m}$$

$$= \underline{177.42} \text{ m}$$

(b)

iv) Since, $t' = 5.097 \text{ sec}$.

So, after $t = 6 \text{ sec}$, the projectile is on its downward movement from the peak height.

Thus, the vertically downward component of velocity after 6 sec, is denoted by : ~~$v_{v,6}$~~

$$\begin{aligned} V_{v,6} &= 0 + g_x(6 - 5.097) \\ &= 9.81 \times 0.903 \\ &= 8.858 \text{ m/s.} \end{aligned}$$

The horizontal component remains unchanged.

$$\Rightarrow V_{H,6} = u \cos \theta = 100 \cos 30^\circ \\ = 86.6 \text{ m/s.}$$

Thus the resultant velocity, V_6 is given by :-

$$\Rightarrow V_6 = \sqrt{(V_{H,6})^2 + (V_{v,6})^2}$$

$$\Rightarrow V_6 = \sqrt{(86.6)^2 + (8.858)^2} = 87.05 \text{ m/s.}$$

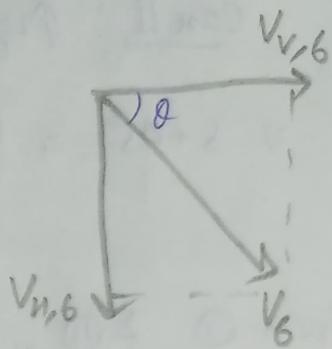
$$\text{and } \tan \theta = \frac{V_{H,6}}{V_{v,6}} = \frac{86.6}{8.858} \quad \textcircled{*}$$

$$\Rightarrow \theta = \tan^{-1} \left(\frac{86.6}{8.858} \right) = 84.16^\circ.$$

⑥ ~~Given~~, let, s be the distance of the target from the point of projection and u be the velocity of projection;

then, By using the expression of range of projection, we get,

$$R = \frac{u^2 \sin 2\alpha}{g}$$



Now, Case I: projectile falls 12 m short at $\alpha = 15^\circ$.

$$\Rightarrow S - 12 = \frac{u^2 \sin(2 \times 15^\circ)}{g} = \frac{u^2}{2g} \quad \text{--- (i)}$$

②

Case II: Projectile overshoots by 24 m at $\alpha = 45^\circ$.

$$\Rightarrow S + 24 = \frac{u^2 \sin(2 \times 45^\circ)}{g} = \frac{u^2}{g} \quad \text{--- (ii)}$$

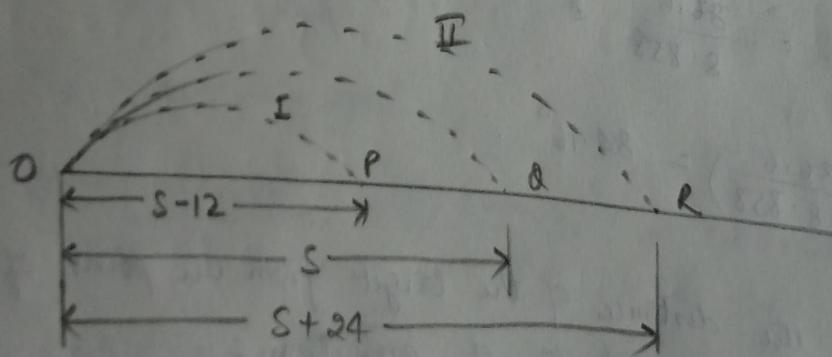
From ① & ②, we get,

$$\Rightarrow S + 24 = 2(S - 12)$$

$$\Rightarrow S = 24 + 2 \times 12$$

$$\Rightarrow \boxed{S = 48 \text{ m}}$$

Now, let, the angle of projection be α .



$$\text{Then, } S = 48 = \frac{u^2 \sin 2\alpha}{g} \quad \text{--- (iii)}$$

From ① & ③, we get,

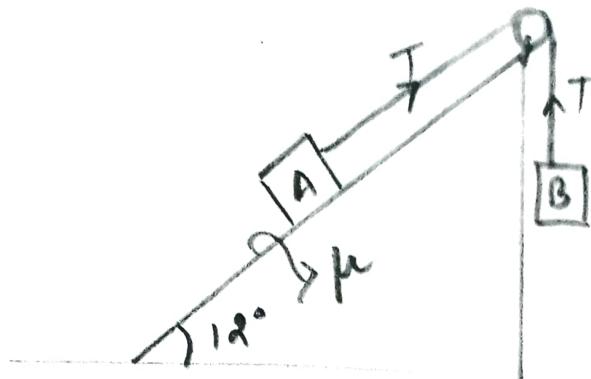
$$\Rightarrow 48 = 72 \sin 2\alpha$$

$$\Rightarrow \sin 2\alpha = \frac{48}{72} = 0.67 \rightarrow 2\alpha = \sin^{-1}(0.67) = 41.81^\circ$$

$$\Rightarrow \alpha = 20.905^\circ$$

Thus, the angle of projection, to hit the target is 20.905° .

(6)



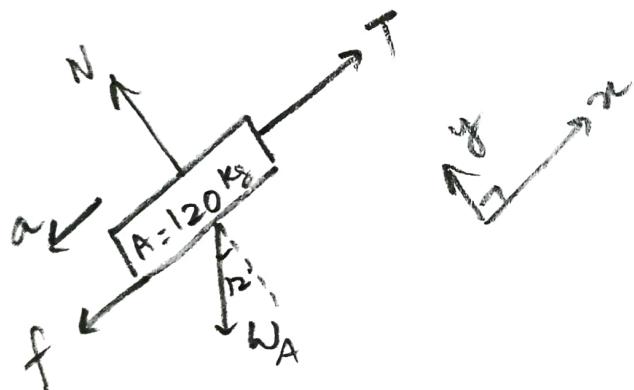
Given, mass of body, A , $m_A = 125 \text{ kg}$.

angle of inclination, $\theta = 12^\circ$

mass of body B , $m_B = 81.5 \text{ kg}$.

coefficient of friction, $\mu = 0.25$

Sol²: i) Let, the tension in the rope be T .



FBD of A

let, the normal from surface be N .
& frictional force, $f = \mu N$

Along y axis,

$$N = W_A \cos 12^\circ$$

$$= 125g \cos 12^\circ$$

$$\approx 125g \cos 12^\circ$$

$$\Rightarrow N = w_A \cos 12^\circ$$

$$\Rightarrow N = 125 \times 9.81 \times \cos 12^\circ$$

$$\Rightarrow N = 1199.45 \text{ N}$$

$$\Rightarrow N \approx 1199.45 \text{ N}$$

$$\begin{aligned} \Rightarrow f &= \mu N \\ &= 0.25 \times 1199.45 \\ &= 299.86 \text{ N} \end{aligned}$$

$$\Rightarrow \sum F_x = 0$$

$$\Rightarrow T - f - w \sin 12^\circ - 120 \times a = 0$$

$$\Rightarrow T - 299.86 - 125 \times 9.81 \times \sin 12^\circ - 120a = 0$$

$$\Rightarrow T = 120a + (254.95 + 299.86)$$

$$\Rightarrow T = 120a + 554.812 \quad \text{--- (1)}$$

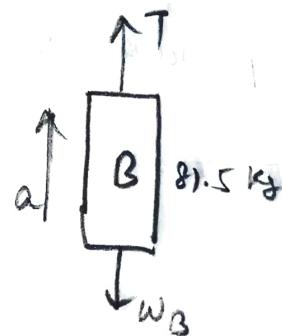
For body B, $m = 81.5 \text{ kg}$

$$\Rightarrow m_2 g - T - m_2 a = 0$$

$$\Rightarrow 81.5 \times 9.81 - T - 81.5a = 0$$

$$\Rightarrow 799.52 - T - 81.5a = 0$$

$$\Rightarrow T = 799.52 - 81.5a \quad \text{--- (2)}$$



FBD of body B

From (1) & (2), we get;

$$\Rightarrow 120a + 554.812 = -81.5a + 799.52$$

$$\Rightarrow 201.5a = 244.708$$

$$\Rightarrow a = 6.356 \text{ m/s}^2$$

$$\Rightarrow a = 1.2144 \text{ m/s}^2 \quad \text{--- (3)}$$

Putting this value in (1),

$$T = 120 \times 1.2144 + 554.812$$

$$T = 799.52 - 81.5 \times 1.2144$$

$$T = 700.55 \text{ N}$$

ii) Thus, from solving ① & ②, we get from eq⁵ ③,

$$a = 1.2144 \text{ m/s}^2$$

$$\Rightarrow a \approx 1.21 \text{ m/s}^2$$

iii)^(b) distance moved by body in 3 sec after starting from rest be s.

$$\text{Then, } s = ut + \frac{1}{2}at^2$$

$$\text{or, } s = 0 + \frac{1}{2} \times 1.2144 \times 3^2$$

$$\text{or, } s = \frac{1}{2} \times 1.2144 \times 9$$

$$\text{or, } s = 1.2144 \times 4.5$$

$$\text{or, } s = 5.4648 \text{ m}$$

$$\text{or, } s \approx \underline{5.465 \text{ m}}$$

③ a) Truss: A plane truss is defined as a structure made up of several bars hinged/joined together to form a framed structure to take loads.

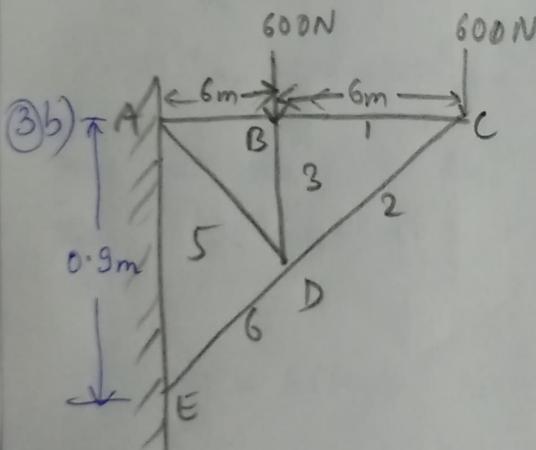
Trusses are classified into 2 different types:-

i) Perfect Frame ($n = 2j - 3$) $[n = \text{no. of members}]$
 $[j = \text{no. of joints}]$

ii) Imperfect frame ($n \neq 2j - 3$)

Imperfect frames are of 2 types:-

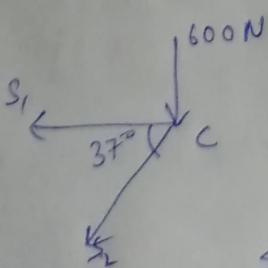
- a) Deficient b) Redundant
 $(n < 2j - 3)$ $(n > 2j - 3)$



$$\Rightarrow \tan \theta = AE/AC \\ = \frac{0.9}{1.2} = 0.75$$

$$\Rightarrow \theta = \tan^{-1}(0.75) \\ = 37^\circ.$$

$$\Rightarrow \cos \theta = 0.8 \quad \& \quad \sin \theta = 0.6.$$



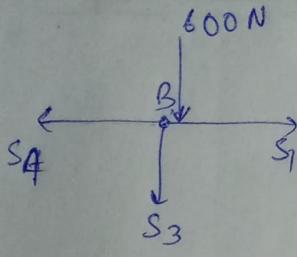
Isolating the joint C as a free body diagram and resolving vertically and horizontally.

$$\sum Y = 0, \quad \cancel{S_1} - S_2 \sin 37^\circ = -600$$

$$S_2 = -1000 \text{ N} \quad (\text{Ans})$$

$$\sum X = 0, \quad -S_1 - S_2 \cos 37^\circ = 0$$

$$S_1 = 1000 \times 0.8 = 800 \text{ N} \quad (\text{Ans})$$



Isolating the joint B as a FBD and resolving the forces vertically & horizontally, we get;

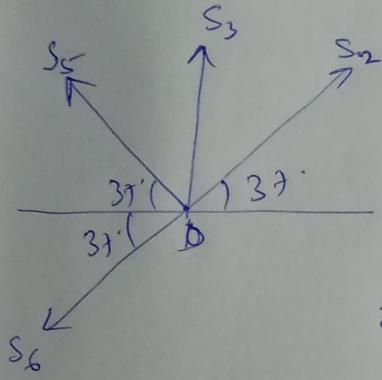
$$\sum Y = 0$$

$$\Rightarrow -S_3 - 600 = 0 \rightarrow S_3 + 600 N = -600 N \text{ (Ans)}$$

$$\sum X = 0$$

$$\Rightarrow S_1 - S_4 = 0$$

$$\Rightarrow S_4 = S_1 = 800 N \text{ (Ans)}$$



FBD of D.

On resolving forces, we get ;-

$$\sum X = 0, S_2 \cos 37^\circ - S_5 \cos 37^\circ - S_6 \cos 37^\circ = 0$$

$$\Rightarrow S_5 + S_6 = S_2 = -1000 N \quad \textcircled{1}$$

$$\sum Y = 0, S_3 + S_2 \sin 37^\circ + S_5 \sin 37^\circ - S_6 \sin 37^\circ = 0$$

$$\Rightarrow S_5 - S_6 = \frac{600}{\sin 37^\circ} + 1000 = 2000 N \quad \textcircled{2}$$

From ① & ②,

$$2S_5 = 1000 N, S_5 = 500 N \text{ (Ans)}$$

$$\therefore S_6 = -1500 N \text{ (Ans)}$$

Hence, $\begin{cases} S_1 = 800 N, S_2 = -1000 N, S_3 = -600 N, \\ S_4 = 800 N, S_5 = 500 N, S_6 = -1500 N \end{cases} \text{ (Ans)}$