

# Linear Algebra

①

A matrix  $A$  over a field  $K$  is a rectangular array of scalars usually presented in the following form

$$A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

The rows of such a matrix  $A$  are the  $m$  horizontal lists of scalars

$$(a_{11}, a_{12}, \dots, a_{1n}), (a_{21}, a_{22}, \dots, a_{2n}) \\ \dots, (a_{m1}, a_{m2}, \dots, a_{mn})$$

and the columns of  $A$  are the  $n$  vertical lists of scalars

$$\begin{bmatrix} a_{11} \\ a_{21} \\ \vdots \\ a_{m1} \end{bmatrix}, \begin{bmatrix} a_{12} \\ a_{22} \\ \vdots \\ a_{m2} \end{bmatrix}, \dots, \begin{bmatrix} a_{1n} \\ a_{2n} \\ \vdots \\ a_{mn} \end{bmatrix}$$

Note that the element  $a_{ij}$ , called the  $ij$ th element, appear in row  $i$  and column  $j$ . We frequently denote such a matrix by simply writing  $A = [a_{ij}]$

## Matrix Addition and Scalar Multiplication ②

Let  $A = [a_{ij}]$  and  $B = [b_{ij}]$  be two matrices with the same size, say  $m \times n$  matrices.

The sum of of A and B written  $A+B$ , is the matrix obtained by adding corresponding elements from A and B. That is,

$$A+B = \begin{bmatrix} a_{11}+b_{11} & a_{12}+b_{12} & \cdots & a_{1n}+b_{1n} \\ a_{21}+b_{21} & a_{22}+b_{22} & \cdots & a_{2n}+b_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1}+b_{m1} & a_{m2}+b_{m2} & \cdots & a_{mn}+b_{mn} \end{bmatrix}$$

The product of the matrix A by a scalar  $k$ , written  $k \cdot A$  or simply  $kA$ , is the matrix obtained by multiplying each element ~~log~~ of A by k. That is

$$kA = \begin{bmatrix} ka_{11} & ka_{12} & \cdots & ka_{1n} \\ ka_{21} & ka_{22} & \cdots & ka_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ ka_{m1} & ka_{m2} & \cdots & ka_{mn} \end{bmatrix}$$

We also observe that

$$-A = (-1)A, \quad A-B = A + (-B)$$

## Matrix multiplication

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The product of matrices A and B, written  
 $AB$  is

## Identity matrix

The unit matrix, denoted by  $I_n$  is the  $n$ -square matrix with 1's on the diagonal and 0's elsewhere. The identity matrix  $I$  is similar to the scalar 1 in that, for any  $n$ -square matrix A,

$$AI = IA = A$$

## Invertible Matrix

A square matrix A is said to be invertible or nonsingular if there exist a matrix B such that  $AB = BA = I$ .

In case  $|A| = 0$ , the matrix A is not invertible.

Find the inverse of  $A = \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix}$  (4)

$$|A| = 2 \times 5 - 4 \times 3 = -2$$

$|A| \neq 0$ , the matrix A is invertible

$$\text{and } A^{-1} = -\frac{1}{2} \begin{bmatrix} 5 & -3 \\ -4 & 2 \end{bmatrix} = \begin{bmatrix} -\frac{5}{2} & \frac{3}{2} \\ 2 & -1 \end{bmatrix}$$

### Transpose of a matrix A

The transpose of a matrix A, written  $A^T$ , is the matrix obtained by writing the columns of A, in order as rows.

For example

$$\begin{bmatrix} 1 & 2 & 3 \\ 4 & 5 & 6 \end{bmatrix}^T = \begin{bmatrix} 1 & 4 \\ 2 & 5 \\ 3 & 6 \end{bmatrix}$$

### Symmetric Matrices

A matrix A is symmetric if  $A^T = A$

Equivalently  $A = [a_{ij}]$  is symmetric if symmetric elements are equal -

that is if each  $a_{ij} = a_{ji}$ .

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A matrix A is said to be skew-symmetric if  $A^T = -A$ , or equivalently if each  $a_{ij} = -a_{ji}$ . Clearly the diagonal elements of such a matrix must be zero, because  $a_{ii} = -a_{ii}$  implies  $a_{ii} = 0$ .

Ex Show that

$$A = \begin{bmatrix} 1 & 0 & 2 \\ 2 & -1 & 3 \\ 4 & 1 & 8 \end{bmatrix} \text{ and } B = \begin{bmatrix} -11 & 2 & 2 \\ -1 & 0 & 1 \\ 6 & -1 & -1 \end{bmatrix}$$

are inverses.

$$AB = \begin{bmatrix} -11+0+12 & 2+0-2 & 2+0-2 \\ -22+1+18 & 4+0-3 & 4-1-3 \\ -14-1+18 & 8+0-8 & 8+1-8 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = I$$

$$AB = I$$

$\therefore A$  and  $B$  are inverses.

## Rank of a matrix

Let  $A$  be a non-zero matrix of order  $m \times n$ .  
 The rank of  $A$  is defined to be the greatest positive integer  $r$  such that  $A$  has at least one-zero minor of order  $r$ .  
 The rank of zero matrix  $\emptyset$  is defined to be 0.

The rank of  $A$  is also called the determinant rank of  $A$ .

If the rank of  $A$  is  $r$ , every minor of order  $r+1$  is zero.

For a non-zero  $m \times n$  matrix  $A$ ,  $0 \leq \text{rank } A \leq \min\{m, n\}$ .

For a square matrix  $A$  of order  $n$ , rank of  $A < n$ , or  $= n$  according as  $A$  is singular or non-singular.

$$1. \text{ Let } A = \begin{pmatrix} 1 & 0 & 3 \\ 4 & -1 & 5 \\ 2 & 0 & 6 \end{pmatrix}$$

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Since  $\det A = 0$ , rank of  $A < 3$  and since there is a second order minor

$$\begin{vmatrix} 1 & 0 \\ 4 & -1 \end{vmatrix} \neq 0, \text{ rank of } A = 2$$

$$2. \text{ Let } A = \begin{pmatrix} 2 & 3 & -1 & 1 \\ 3 & 0 & 4 & 2 \\ 6 & 9 & -3 & 3 \end{pmatrix}$$

Every minor of order 3 is zero, because the third row is a multiple of the first and therefore rank of  $A < 3$ .

There is a second order minor

$$\begin{vmatrix} 2 & 3 \\ 3 & 0 \end{vmatrix} \neq 0 \text{ and so rank of } A = 2$$

### Elementary Operations

An elementary operation on a matrix  $A$  is

1. Interchange of two rows (or columns) of  $A$



2. Multiplication of a row (or column) by a non-zero scalar  $c$ . ⑧
3. Addition of a scalar multiple of one row (or column) to another row (or column).

When applied to rows, the elementary operations are said to be elementary row operations. And when applied to columns they are said to be elementary column operations.

The interchange of the  $i$ th and  $j$ th row is denoted by  $R_{ij}$ .

Multiplication of the  $i$ th row by a non-zero scalar  $c$  denoted by  $cR_i$ .

Addition of  $c$  times the  $j$ th row to the  $i$ -th row is denoted by  $R_i + cR_j$ .

## Row equivalence, column & equivalence

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Let us consider the set  $S$  of all  $m \times n$  matrices over a field  $F$ . A matrix  $B$  in  $S$  is said to be row equivalent (column equivalent) to a matrix  $A$  in  $S$  if  $B$  can be obtained by successive application of a finite number of elementary row operations (column operations) on  $A$ .

Def An  $m \times n$  matrix  $A$  is called row reduced if

- a) the first non-zero element in each non-zero row is 1 (called the leading 1)
- b) in each column containing the leading 1 of some row, the leading 1 is the only non-zero element.

Def An  $m \times n$  matrix  $A$  is said to be a row-reduced echelon matrix

(or a row echelon matrix) if (10)

- A is row-reduced
- there is an integer  $r$  ( $0 \leq r \leq m$ ) such that the first  $r$  rows of A are non-zero rows and the remaining rows (if there be any) are all zero rows
- if the leading element of the  $i$ th non-zero row occurs in the  $k_i$ th column of A, then  $k_1 < k_2 < \dots < k_r$ .

Examples of row-reduced echelon matrix are

$$\left( \begin{array}{ccccc} 0 & 1 & 1 & 0 & 1 \\ 0 & 0 & 0 & 1 & 0 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right), \quad \left( \begin{array}{ccccc} 1 & 0 & 1 & 0 & 0 & 2 \\ 0 & 0 & 0 & 1 & 0 & 3 \\ 0 & 0 & 0 & 0 & 1 & 2 \\ 0 & 0 & 0 & 0 & 0 & 0 \end{array} \right)$$

Def The rank of a matrix is the number of non-zero rows (numbers of pivot) in its row reduced echelon form. (11)

$$\begin{pmatrix} 2 & 0 & 4 & 2 \\ 3 & 2 & 6 & 5 \\ 5 & 2 & 10 & 7 \\ 0 & 3 & 2 & 5 \end{pmatrix}$$

$$\xrightarrow{\frac{1}{2}R_1} \begin{pmatrix} 1 & 0 & 2 & 1 \\ 3 & 2 & 6 & 5 \\ 5 & 2 & 10 & 7 \\ 0 & 3 & 2 & 5 \end{pmatrix}$$

$$\xrightarrow{R_2 - 3R_1} \xrightarrow{R_3 - 5R_1} \begin{pmatrix} 1 & 0 & 2 & 1 \\ 0 & 2 & 0 & 2 \\ 0 & 2 & 0 & 2 \\ 0 & 3 & 2 & 5 \end{pmatrix}$$

$$\xrightarrow{\frac{1}{2}R_2} \begin{pmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 2 & 0 & 2 \\ 0 & 3 & 2 & 5 \end{pmatrix}$$

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$$\xrightarrow{R_3 - 2R_2} \begin{pmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 0 & 0 \\ 0 & 0 & 2 & 2 \end{pmatrix}$$

$$\xrightarrow{R_3 \leftrightarrow R_4} \begin{pmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 2 & 2 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{\frac{1}{2}R_3} \begin{pmatrix} 1 & 0 & 2 & 1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

$$\xrightarrow{R_1 - 2R_3} \begin{pmatrix} 1 & 0 & 0 & -1 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix}$$

Rank is 3.

Determine the rank of the matrix

①

$$A = \begin{pmatrix} 1 & 2 & 1 & 0 \\ 2 & 4 & 8 & 6 \\ 3 & 6 & 6 & 3 \end{pmatrix}$$

$$\xrightarrow{\begin{array}{l} R_2 - 2R_1 \\ R_3 - 3R_1 \end{array}} \begin{pmatrix} 1 & 2 & 10 & 0 \\ 0 & 0 & 6 & 6 \\ 0 & 0 & 3 & 3 \end{pmatrix} \xrightarrow{\frac{1}{6}R_2} \begin{pmatrix} 1 & 2 & 10 & 0 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 3 & 3 \end{pmatrix}$$
$$\xrightarrow{\begin{array}{l} R_1 - R_2 \\ R_3 - 3R_2 \end{array}} \begin{pmatrix} 1 & 2 & 0 & -1 \\ 0 & 0 & 1 & 1 \\ 0 & 0 & 0 & 0 \end{pmatrix} = R \text{ (say)}$$

R is a row-reduced echelon matrix and R has 2 non-zero rows. Therefore rank of R = 2

### System of Linear Equation

A linear equation in unknowns

$x_1, x_2, \dots, x_n$  is an equation that can be put in the standard form

$$a_1x_1 + a_2x_2 + \dots + a_nx_n = b \quad \text{--- } ①$$

where  $a_1, a_2, \dots, a_n$  and  $b$  are constants.

The constant  $a_k$  is called the coefficient of  $x_k$  and  $b$  is called the constant term

of the equation.

②

A solution of the linear equation ① is a list of values for the unknowns or equivalently a vector  $\mathbf{x} = [x_1, x_2, \dots, x_n]^T$  in  $K^n$ , say

$$x_1 = k_1, x_2 = k_2, \dots, x_n = k_n$$

such that  ~~$a_1k_1 + a_2k_2 + \dots + a_nk_n = b$~~

## System of Linear Equations

A system of linear equations is a list of linear equations with the same unknowns. In particular, a system of  $m$  linear equations  $L_1, L_2, \dots, L_m$  in  $n$  unknowns  $x_1, x_2, \dots, x_n$  can be put in the standard form

$$a_{11}x_1 + a_{12}x_2 + \dots + a_{1n}x_n = b_1$$

$$a_{21}x_1 + a_{22}x_2 + \dots + a_{2n}x_n = b_2$$

.....

$$a_{m1}x_1 + a_{m2}x_2 + \dots + a_{mn}x_n = b_m$$

②

where  $a_{ij}$  and  $b_i$  are constants. The number  $a_{ij}$  is the coefficient of the

of the unknowns  $x_j$  in the equation  $L_i$ ,  
and the number  $b_i$  is the constant of the  
equation  $L_i$ .

The system ② is called an  $m \times n$  system.  
It is called a square system if  $m=n$ —that  
is, if the number  $m$  of equations is equal  
to the number  $n$  of unknowns.

The system ② is said to be homogeneous  
if all the constant terms are zero—that  
is if  $b_1=0, b_2=0, \dots, b_m=0$ . Otherwise the  
system is said to be nonhomogeneous.

A solution of the system ② is a list  
of values for the unknowns or equivalently  
which is a solution of each of the  
equations of the system. The set of all  
solutions of the system is called the  
solution set or the general solution of  
the system.

The system ② of linear equations is  
said to be consistent if it has one or  
more solutions, and it is said to be  
inconsistent if it has no solution. (4)

Therefore the system of linear equations  
is either inconsistent or consistent.

If it is inconsistent then it has no  
solution. If it is consistent then it has  
either a unique solution or infinite  
number of solutions.

### Augmented and Coefficient Matrices of a system

Consider the general system ② of  $m$   
equations in  $n$  unknowns. Such a system  
has associated with it the following  
two matrices:

$$M = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & b_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & b_n \end{bmatrix} \quad \text{and } A = \begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix} \quad (5)$$

The matrix  $M$  is called augmented matrix of the system and the matrix  $A$  is called the coefficient matrix.

If Rank of  $M$  = Rank of  $A$

Then the system is consistent

i) If the system is consistent then if the number of equations is equal to the number of unknowns then it has unique solution.

ii) If the number of equation is  $< n$   
 That is there are more unknowns than equations. Then we can arbitrarily assign values to the  $n-m$  free variables and solve then and obtained  $\Rightarrow$  infinite no. of solutions.

1. 9) Solve each of the following system. ⑥

$$a) x_1 + x_2 - 2x_3 + 4x_4 = 5$$

$$2x_1 + 2x_2 - 3x_3 + x_4 = 3$$

$$3x_1 + 3x_2 - 4x_3 - 2x_4 = 1$$

Reduce its augmented matrix M to echelon form and then to row equivalent form as follows:

$$M = \left[ \begin{array}{cccc|c} 1 & 1 & -2 & 4 & 5 \\ 2 & 2 & -3 & 1 & 3 \\ 3 & 3 & -4 & -2 & 1 \end{array} \right]$$

$$\xrightarrow{R_2 - 2R_1} \left[ \begin{array}{cccc|c} 1 & 1 & -2 & 4 & 5 \\ 0 & 0 & 1 & -7 & -7 \\ 0 & 0 & 2 & -14 & -14 \end{array} \right]$$

$$\xrightarrow{R_3 - 2R_2} \left[ \begin{array}{cccc|c} 1 & 1 & 0 & -10 & -9 \\ 0 & 0 & 1 & -7 & -7 \\ 0 & 0 & 0 & 0 & 0 \end{array} \right]$$

Rank of M = Rank of A = 2

∴ The system is consistent.

Rewrite the row canonical form in terms  
of a system of linear equations to obtain  
the free variable form of the solution. ④

$$\text{That is } \begin{cases} x_1 + x_2 - 10x_4 = -9 \\ x_3 - 7x_4 = -7 \end{cases} \quad \begin{array}{l} \text{or } x_1 = -9 - x_2 + 10x_4 \\ x_3 = -7 + 7x_4 \end{array}$$

(The zero row is omitted in the solution).

Observe that  $x_1$  and  $x_3$  are the pivot  
variables and  $x_2$  and  $x_4$  are free variables.

So any arbitrary value of  $x_2$  and  $x_4$   
there exists infinite no. of solutions.

b)  $x_1 + x_2 - 2x_3 + 3x_4 = 1$

$$2x_1 + 3x_2 + 3x_3 - x_4 = 3$$

$$5x_1 + 7x_2 + 4x_3 + x_4 = 5$$

$$M = \left[ \begin{array}{ccccc} 1 & 1 & -2 & 3 & 4 \\ 2 & 3 & 3 & -1 & 3 \\ 5 & 7 & 4 & 1 & 5 \end{array} \right]$$

$$\xrightarrow{R_2 - 2R_1} \left[ \begin{array}{ccccc} 1 & 1 & -2 & 3 & 4 \\ 0 & 1 & 7 & -7 & -5 \\ 5 & 7 & 4 & 1 & 5 \end{array} \right]$$

~~$\xrightarrow{R_3 - 5R_1}$~~  REDUCE TO PRIME

(8)

$$\xrightarrow{R_3 - 2R_2} \left[ \begin{array}{ccccc|c} 1 & 1 & -2 & 3 & 1 & 4 \\ 0 & 1 & 7 & -7 & 1 & -5 \\ 0 & 0 & 0 & 0 & 1 & -5 \end{array} \right]$$

Rank of M = 3, Rank of A = 2

∴ The system is inconsistent  
i.e. it has no solution.

c)  $\left[ \begin{array}{ccc|c} 1 & 2 & 1 & 3 \\ 2 & 5 & -1 & -4 \\ 3 & -2 & -1 & 5 \end{array} \right]$

$$\begin{aligned} x + 2y + z &= 3 \\ 2x + 5y - z &= -4 \\ 3x - 2y - z &= 5 \end{aligned}$$

$$M = \left[ \begin{array}{cccc} 1 & 2 & 1 & 3 \\ 2 & 5 & -1 & -4 \\ 3 & -2 & -1 & 5 \end{array} \right]$$

$$\xrightarrow{\frac{R_2 - 2R_1}{R_3 - 3R_1}} \left[ \begin{array}{cccc} 1 & 2 & 1 & 3 \\ 0 & 1 & -3 & -10 \\ 0 & -8 & -4 & -4 \end{array} \right]$$

$$\xrightarrow{R_3 + 8R_2} \left[ \begin{array}{cccc} 1 & 2 & 1 & 3 \\ 0 & 1 & -3 & -10 \\ 0 & 0 & -28 & -84 \end{array} \right] \xrightarrow{R_3 + 9R_2} \left[ \begin{array}{cccc} 1 & 2 & 1 & 3 \\ 0 & 1 & -3 & -10 \\ 0 & 0 & 1 & 3 \end{array} \right]$$

$$\xrightarrow[R_2+3R_3]{R_1-2R_2} \left[ \begin{array}{cccc} 1 & 2 & 0 & 0 \\ 0 & 1 & 0 & -1 \\ 0 & 0 & 1 & 3 \end{array} \right] \quad \text{④}$$

Thus Rank of  $M = \text{Rank of } A = 3$

The system has the unique solution  $x = 2$ ,  
 $y = -1$ ,  $z = 3$

2. Determine whether or not each of the following homogeneous system has a non-zero solution.

$$x + y - z = 0$$

$$2x - 3y + z = 0$$

$$x - 4y + 2z = 0$$

(a)

$$x + y - z = 0$$

$$2x + 4y - z = 0$$

$$3x + 2y + 2z = 0$$

(b)

$$x_1 + 2x_2 - 3x_3 + 4x_4 = 0$$

$$2x_1 - 3x_2 + 5x_3 - 7x_4 = 0$$

$$5x_1 + 6x_2 - 9x_3 + 8x_4 = 0$$

(c)

a) Reduce the system to echelon form as follows.

$$x + y - z = 0$$

$$2y + z = 0$$

And then  $x + y - z = 0$

$$-5y + 3z = 0$$

The system has a nonzero solution, because  
there are only two equations in the three  
unknowns in echelon form. Here  $z$  is a  
free variable. Let us say  $z=5$ ,  
(10)

$$\therefore y=3, x=2$$

Thus  $(2, 3, 5)$  is a particular non-zero solution.

- b) Reduce the system to echelon form as follows:

$$\begin{array}{l} x+y-2=0 & x+y-z=0 \\ 2y+z=0 \quad \text{and} & 2y+z=0 \\ -y+5z=0 & 11z=0 \end{array}$$

In echelon form, there are three eqns  
in three variables. Thus the system has  
only the zero solution.

- c) The system must have a non-zero  
solution, because there are four unknowns  
but only three equations.

$$x + 2y - z = 3$$

$$y + 2z = 3$$

$$3z = 4$$

$$\therefore x = \frac{17}{3}, y = -\frac{2}{3}, z = \frac{4}{3}$$

Unique solution

b)  $M = \begin{bmatrix} 1 & -2 & 4 & 2 \\ 2 & -3 & 5 & 3 \\ 3 & -1 & 6 & 7 \end{bmatrix}$

$$\xrightarrow{\begin{array}{l} R_2 - 2R_1 \\ R_3 - 3R_1 \end{array}} \begin{bmatrix} 1 & -2 & 4 & 2 \\ 0 & 1 & -3 & -1 \\ 0 & 2 & -6 & 1 \end{bmatrix}$$

$$\xrightarrow{R_3 - 2R_2} \begin{bmatrix} 1 & -2 & 4 & 2 \\ 0 & 1 & -3 & -1 \\ 0 & 0 & 0 & +3 \end{bmatrix}$$

Rank of  $M = 3$ , Rank  $A = 2$

$$3 \neq 2$$

The system has no solution.

$$x + 2y - z = 3$$

$$y + 2z = 3$$

$$3z = 4$$

$$\therefore x = \frac{17}{3}, y = -\frac{2}{3}, z = \frac{4}{3}$$

Unique solution

b)  $M = \begin{bmatrix} 1 & -2 & 4 & 2 \\ 2 & -3 & 5 & 3 \\ 3 & -1 & 6 & 7 \end{bmatrix}$

$$\xrightarrow{\begin{array}{l} R_2 - 2R_1 \\ R_3 - 3R_1 \end{array}} \begin{bmatrix} 1 & -2 & 4 & 2 \\ 0 & 1 & -3 & -1 \\ 0 & 2 & -6 & 1 \end{bmatrix}$$

$$\xrightarrow{R_3 - 2R_2} \begin{bmatrix} 1 & -2 & 4 & 2 \\ 0 & 1 & -3 & -1 \\ 0 & 0 & 0 & +3 \end{bmatrix}$$

Rank of  $M = 3$ , Rank  $A = 2$

$$3 \neq 2$$

The system has no solution.

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$$c) M = \begin{bmatrix} 1 & 1 & 3 & 1 \\ 2 & 3 & -1 & 3 \\ 5 & 7 & 1 & 7 \end{bmatrix}$$

$$\xrightarrow{\frac{R_2 - 2R_1}{R_3 - 5R_1}} \begin{bmatrix} 1 & 1 & 3 & 1 \\ 0 & 1 & -7 & 1 \\ 0 & 2 & -14 & 2 \end{bmatrix}$$

$$\xrightarrow{\frac{R_3 - 2R_2}{R_1 - R_2}} \begin{bmatrix} 1 & 1 & 3 & 1 \\ 0 & 1 & -7 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$\text{Rank } M = \text{Rank } A = 2$$

The system is consistent

$$x + 10z = 0$$

$$y - 7z = 1$$

Here  $z$  is only free variable.

$$x = -10a, y = 1+7a, z = a$$

(14)

Solve

$$\underline{x_1 + 2x_2 - 3x_3 - 2x_4 + 4x_5 = 1}$$

$$2x_1 + 5x_2 - 8x_3 - x_4 + 6x_5 = 4$$

$$x_1 + 4x_2 - 7x_3 + 5x_4 + 2x_5 = 8$$

Solve each of the following system of

$$x + 2y - z = 3$$

$$x + 3y + z = 5$$

$$3x + 8y + 4z = 17$$

(a)

$$x - 2y + 1z = 2$$

$$2x - 3y + 5z = 3$$

$$3x - 4y + 6z = 7$$

(b)

$$x + y + 3z = 1$$

$$2x + 3y - z = 3$$

$$5x + 7y + 2z = 7$$

(c)

(a)

$$M = \begin{bmatrix} 1 & 2 & -1 & 3 \\ 1 & 3 & 1 & 5 \\ 3 & 8 & 4 & 17 \end{bmatrix} \xrightarrow{\substack{R_2 - R_1 \\ R_3 - 3R_1}} \begin{bmatrix} 1 & 2 & -1 & 3 \\ 0 & 1 & 2 & 2 \\ 0 & 2 & 1 & 7 \end{bmatrix}$$

$$\xrightarrow{R_3 - 2R_2} \begin{bmatrix} 1 & 2 & -1 & 3 \\ 0 & 1 & 2 & 2 \\ 0 & 0 & 3 & 4 \end{bmatrix}$$

Rank M = Rank A

So the system is consistent

## Vector Space

①

Def let  $V$  be a nonempty set with two operations:

i) Vector addition: This assigns to any  $u, v \in V$  a sum  $u+v \in V$ .

ii) Scalar Multiplication: This assigns to any  $u \in V$ ,  $k \in K$  a product  $ku \in V$ .

Then  $V$  is called a vector space (over the field  $K$ ) if the following axioms hold for any vectors  $u, v, w \in V$ :

①  $(u+v)+w = u+(v+w)$

② There is a vector in  $V$ , denoted by  $0$  and called the zero vector, such that, for any  $u \in V$ ,

$$u+0=0+u=u$$

③ For each  $u \in V$ , there is a vector in  $V$ , denoted by  $-u$ , and called the negative of  $u$  such that

$$u+(-u) = (-u)+u = 0$$

- ⑤  $k(u+v) = ku + kv$ , for any scalar  $k \in K$ . ②
- ⑥  $(a+b)u = au + bu$ , for any scalars  $a, b \in K$
- ⑦  $(ab)u = a(bu)$ , for any scalars  $a, b \in K$
- ⑧  $1u = u$  for the unit scalar  $1 \in K$ .

Th let  $V$  be a vector space over a field  $K$ .

- i) For any scalar  $k \in K$  and  $0 \in V$ ,  $k0 = 0$ .
- ii) For  $0 \in K$  and any vector vector  $u \in V$ ,  $0u = 0$
- iii) If  $ku = 0$ , where  $k \in K$  and  $u \in V$ ,  
then  $k = 0$  or  $u = 0$
- iv) For any  $k \in K$ , and any  $u \in V$ ,  
 $(-k)u = k(-u) = -ku$

### Polynomial space $P(t)$

Let  $P(t)$  be the set of all polynomials of the form

$$p(t) = a_0 + a_1 t + a_2 t^2 + \dots + a_s t^s \quad (s=1, 2, \dots)$$

where the coefficients  $a_i$  belong to a field  $K$ . Then  $P(t)$  is a vector space over  $K$

$$u = x u_1 + y u_2 + z u_3$$

$$u_1 = (1, 1, 1), \quad u_2 = (1, 2, 3), \quad u_3 = (2, 1, 1)$$

Linear combination of the vectors

④ Ex Express  $u = (1, -2, 5)$  in  $\mathbb{R}^3$  as a

$$u = a_1 u_1 + a_2 u_2 + \dots + a_m u_m$$

relation  $a_1, a_2, \dots, a_m$  in  $K$  such that  
of vectors  $u_1, u_2, \dots, u_m$  in  $V$  if there exist  
A vector  $v$  in  $V$  is a linear combination  
Let  $v$  be a vector space over a field  $K$ .

### Linear Combinations

The zero polynomial  $0$  is the zero vector in  $P(\mathbb{F})$ .

(ii) Scalar Multiplication: If there is  $p(t) \in P(\mathbb{F})$   
scalar  $p$  and a polynomial  $f(t)$   
in the usual operation of the field of a

polynomials.

In the usual operation of addition of

(i) Vector Addition: If there  $p(t) + q(t) \in P(\mathbb{F})$

Doing the following operations

$$A - \frac{1}{3}R_2$$

$$\frac{1}{3}R_3$$

Reducing the system by echelon form

$$x + 3y + z = 5$$

$$x + 2y - z = -2$$

$$x + y + 2z = 1$$

$$\begin{bmatrix} 1 & 1 & 2 & 1 \\ 1 & 2 & -1 & -3 \\ 1 & 2 & 1 & 1 \end{bmatrix} = x \begin{bmatrix} 1 \\ 1 \\ 1 \end{bmatrix} + y \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix} + z \begin{bmatrix} 1 \\ -1 \\ -2 \end{bmatrix}$$

④

(5)

$$x + y + 2z = 1$$

$$y - 3z = -3$$

$$5z = 10$$

$$\Rightarrow z = 2, y = 3, x = -6$$

$$\text{Thus } v = -6u_1 + 3u_2 + 2u_3$$

Ex2 Express  $v = (2, -5, 3)$  in  $\mathbb{R}^3$  as a linear combination of

$$u_1 = (1, -3, 2), u_2 = (2, -4, -1), u_3 = (1, -5, 7)$$

$$v = x u_1 + y u_2 + z u_3$$

$$\begin{bmatrix} 2 \\ -5 \\ 3 \end{bmatrix} = x \begin{bmatrix} 1 \\ -3 \\ 2 \end{bmatrix} + y \begin{bmatrix} 2 \\ -4 \\ -1 \end{bmatrix} + z \begin{bmatrix} 1 \\ -5 \\ 7 \end{bmatrix}$$

$$x + 2y + z = 2$$

$$-3x - 4y - 5z = -5$$

$$2x - y + 7z = 3$$

Reducing the system to echelon form yields  
the system

$$x + 2y + z = 2, 2y - 2z = 1, 0 = 3$$

The system is inconsistent and so it has

no solution.

Thus  $v$  cannot be written as a linear combination of  $u_1, u_2, u_3$ .

### Spanning Sets

Let  $V$  be a vector space over a field  $K$ . Vectors  $u_1, u_2, \dots, u_m$  in  $V$  are said to span  $V$  or to form a spanning set of  $V$  if there  $v$  in  $V$  is a linear combination of the vectors  $u_1, u_2, \dots, u_m$  - that is if there exist scalars  $a_1, a_2, \dots, a_m$  in  $K$  such that

$$v = a_1 u_1 + a_2 u_2 + \dots + a_m u_m$$

Remark 1: Suppose  $u_1, u_2, \dots, u_m$  span  $V$ .

Then for any vector  $w$ , the set  $w, u_1, u_2, \dots, u_m$  also spans  $V$ .

Remark 2: Suppose  $u_1, u_2, \dots, u_m$  span  $V$  and suppose  $u_b$  is a linear combination of some of the other  $u$ 's. Then the  $u$ 's

without  $u_k$  also span  $V$ . 7

Remark 3 Suppose  $u_1, u_2, \dots, u_m$  span  $V$  and suppose one of the  $u$ 's is the zero vector. Then the  $u$ 's without the zero vector also span  $V$ .

Example 1. The following vectors  $e_1 = (1, 0, 0)$ ,  $e_2 = (0, 1, 0)$ ,  $e_3 = (0, 0, 1)$  is a spanning set of  $V = \mathbb{R}^3$ .

Let  $v = (a, b, c)$  be any vector in  $\mathbb{R}^3$

$$\text{Then } v = a e_1 + b e_2 + c e_3$$

$$\text{For example } (5, -6, 2) = -5e_1 + (-6)e_2 + 2e_3$$

Subspaces:

Def Let  $V$  be a vector space over a field  $K$  and let  $W$  be a subset of  $V$ . Then  $W$  is a subspace of  $V$  if  $W$  is itself a vector space over  $K$  with respect to the operations of vectors addition and scalar multiplication on  $V$ .

Intersection of Subspaces

Let  $U$  and  $W$  be subspaces of a vector space  $V$ . We show that the intersection  $U \cap W$  is also a subspace of  $V$ .

Linear Dependence and Independence

Let  $V$  be a vector space over a field  $K$ . We say that the vectors  $v_1, v_2, \dots, v_m$  in  $V$  are linearly dependent if there exist scalars  $a_1, a_2, \dots, a_m$  in  $K$ , not all of them 0, such that

$$a_1 v_1 + a_2 v_2 + \dots + a_m v_m = 0$$

Otherwise, we say that the vectors are linearly independent.

A set  $S = \{v_1, v_2, \dots, v_m\}$  are linearly independent of vectors in  $V$  if linearly dependent or independent according to

the following linear combination where  
linearly dependent because we have

$u_1 = k u_2$ . Then the vectors would be  
linearly independent if the other, say  
 $u_m$  are also equal to zero in a

No. 3 Suppose two of the vectors  $u_1, u_2,$

be cause  $ku_2 = 0$ ,  $u_2 \neq 0$  so only one  $k = 0$   
Then  $u_1$  by itself is linearly independent

No. 2 Suppose  $v$  is a nonzero vector.

$$D = D + \dots + D + D + \dots + D = 1 \cdot D + \dots + 1 \cdot D = 10$$

where the coefficient of  $v$  is 10.  
We have the following linear combination  
would be linearly dependent, because  
 $u_1, u_2, \dots, u_m$  say  $u_1 = 0$ , then the vectors  
No. 1 Suppose  $v$  is one of the vectors

whether the vectors  $u_1, u_2, \dots, u_m$  are linearly  
dependent or independent.

the coefficients of  $v_1 \neq 0$ :

(10)

$$v_1 - kv_2 + 0v_3 + \dots + 0v_m = 0$$

Note 4 The vectors  $v_1$  and  $v_2$  are

linearly dependent if and only if one of them is a multiple of the other.

Note 5: If the set  $\{v_1, \dots, v_m\}$  is linearly independent, then any rearrangement of the vectors  $\{v_{i_1}, v_{i_2}, \dots, v_{i_m}\}$  is also linearly independent.

Note 6: If a set  $S$  of vectors is linearly independent, then any subset of  $S$  is linearly independent. Alternatively, if  $S$  contains a linearly dependent subset, then  $S$  is linearly dependent.

Ex1. Let  $u = (1, 1, 0)$ ,  $v = (1, 3, 2)$ ,  $w = (1, 9, 5)$  (11)

Then  $u, v, w$  are linearly dependent

because

$$3u + 5v + 2w = (0, 0, 0) = 0$$

Ex2 We show that the vectors

$u = (1, 2, 3)$ ,  $v = (2, 5, 7)$ ,  $w = (1, 3, 5)$  are linearly independent.

$$xu + yv + zw = 0$$

$$x + 2y + z = 0$$

$$2x + 5y + 3z = 0$$

$$3x + 7y + 5z = 0$$



$$x + 2y + z = 0$$

$$y + z = 0$$

$$2z = 0$$

$$x = 0, y = 0, z = 0$$

$$xu + yv + zw = 0$$

$$\Rightarrow x = 0, y = 0, z = 0$$

$\therefore u, v, w$  are linearly independent

Ex 3 Determine whether or not the vectors <sup>(12)</sup>  
 $u = (1, 1, 2)$ ,  $v = (2, 3, 1)$ ,  $w = (4, 5, 5)$  are  
linearly dependent

$$xu + yv + zw = 0$$

$$x + 2y + 4z = 0$$

$$x + 3y + 5z = 0$$

$$2x + y + 5z = 0$$

$$x + 2y + 4z = 0$$

$$y + z = 0$$

The echelon system has only two nonzero equations in three unknowns hence, it has a free variable and a non zero solution. Thus  $u, v, w$  are linearly dependent.

Ex 4 ~~a) b)~~ Determine whether or not not each of following set list of vectors in L.I.

(13)

a)  $u_1 = (1, 2, 5), u_2 = (1, 3, 1), \omega$

$u_3 = (2, 5, 7), u_4 = (3, 1, 4)$

b)  $u = (1, 2, 5), v = (2, 5, 1), \omega = (1, 5, 2)$

c)  $u = (1, 2, 3), v = (0, 0, 0), \omega = (1, 5, 6)$

Ex let  $V = \mathbb{R}^3$

Show that  $W$  is not a subspace of  $V$ ,  
where  $\text{①}$

a)  $W = \{(a, b, c) : a \geq 0\}$  b)  $W = \{(a, b, c) : a^2 + b^2 + c^2 \leq 1\}$

Sol a)  $W$  consists of those vectors whose first entry is nonnegative. Thus  $v = (1, 2, 3)$  belongs to  $W$ . Let  $k = -3$ . Then  $kv = (-3, -6, -9)$  does not belong to  $W$ , because  $-3$  is negative. Thus  $W$  is not a subspace of  $V$ .

b)  $W$  consists of vectors whose length does not exceed 1. Hence  $u = (1, 0, 0)$  and  $v = (0, 1, 0)$  belong to  $W$ , but  $u+v = (1, 1, 0)$  does not belong to  $W$ , because  $1^2 + 1^2 + 0^2 = 2 > 1$ . Thus  $W$  is not a subspace of  $V$ .

Ex let  $V = P(t)$ , the vector space of real polynomials. Determine whether or not  $W$  is a subspace of  $V$ .

- (2)
- $W$  consists of all polynomials with integral coefficients.
  - $W$  consists of all polynomials with degree  $\geq 6$  and the zero polynomial.

Ans: a) No, because scalar multiple of polynomials in  $W$  do not always belong to  $W$ . For example

$$f(t) = 3 + 6t + 7t^2 \in W$$

$$\text{but } \frac{1}{2}f(t) = \frac{3}{2} + 3t + \frac{7}{2}t^2 \notin W$$

b) Yes, in each case  $W$  consists of the zero polynomial, and sums and scalar multiples of polynomials in  $W$  belong to  $W$ .

### Linear span

Show that the vectors  $u_1 = (1, 1, 1)$ ,  $u_2 = (1, 2, 3)$ ,  $u_3 = (1, 5, 8)$  span  $\mathbb{R}^3$ .

Sol<sup>n</sup> We need to show that an arbitrary vector  $v = (a, b, c)$  in  $\mathbb{R}^3$  is a linear combination of  $u_1, u_2, u_3$ . ③

So let  $v = xu_1 + yu_2 + zu_3$

$$\text{That is } (a, b, c) = x(1, 1, 1) + y(1, 2, 3) + z(1, 5, 8)$$

$$= (x+y+z, x+2y+5z, x+3y+8z)$$

$$\begin{array}{l} \therefore x+y+z = a \\ x+2y+5z = b \\ x+3y+8z = c \end{array} \left. \begin{array}{l} x+y+z = a \\ y+4z = b-a \\ 2y+7z = c-a \end{array} \right\} \text{ or } \begin{array}{l} x+y+z = a \\ y+4z = b-a \\ -z = c-2b+a \end{array}$$

$$\text{or } \begin{array}{l} x+y+z = a \\ y+4z = b-a \\ -z = c-2b+a \end{array}$$

The above system is in echelon form  
and is consistent

$$\begin{aligned} x &= -a+5b+3c, \quad y = 3a-7b+4c, \\ z &= a+2b-c \end{aligned}$$

is a solution.

Thus  $u_1, u_2, u_3$  span  $\mathbb{R}^3$ .

Ex Find conditions on  $a, b, c$  so that (4)  
 $v = (a, b, c)$  in  $\mathbb{R}^3$  belongs to  $N = \text{span}(u_1, u_2, u_3)$

where  $u_1 = (1, 2, 0)$ ,  $u_2 = (-1, 1, 2)$ ,  $u_3 = (3, 0, -1)$

$$a, b, c = x(1, 2, 0) + y(-1, 1, 2)$$

$$+ z(3, 0, -1)$$

$$\left. \begin{array}{l} x+y+3z=a \\ 2x+y=b \\ 2y-4z=c \end{array} \right\} \text{or} \quad \left. \begin{array}{l} x-y+3z=a \\ 3y-6z=b-2a \\ 2y-4z=c \end{array} \right\}$$

$$\text{or } x-y+3z=a$$

$$3y-6z=b-2a$$

$$0 = 4a-2b+3c$$

The vector  $v = (a, b, c)$  belongs to  $N$   
iff the system is consistent and it's  
consistent iff  $4a-2b+3c=0$

$\therefore u_1, u_2, u_3$  do not span the whole  
space  $\mathbb{R}^3$ .



Def<sup>n</sup>: A set  $S = \{u_1, u_2, \dots, u_n\}$  of vectors is a basis of  $V$  if it has the following two properties ①  $S$  is linearly independent ②  $S$  spans  $V$ .

Def<sup>n</sup>: A set  $S = \{u_1, u_2, \dots, u_n\}$  of vectors is a basis of  $V$  if every  $v \in V$  can be written uniquely as a linear combination of the basis vectors.

Th let  $V$  be a vector space such that one basis has  $m$  elements and another basis has  $n$  elements then  $m=n$ .

A vector space  $V$  is said to be of finite dimension  $n$  or  $n$  dimensional, written  $\dim V = n$

The vector space  $\{0\}$  is defined to have dimension 0.

⑥

Suppose a vector space  $V$  does not have a finite basis. Then  $V$  is said to be of infinite dimension or to be infinite-dimensional.

Lemma Suppose  $\{v_1, v_2, \dots, v_n\}$  spans  $V$  and suppose  $\{w_1, w_2, \dots, w_m\}$  is linearly independent. Then  $m \leq n$  and  $V$  is spanned by a set of the form  $\{w_1, w_2, \dots, w_m, v_{i_1}, v_{i_2}, \dots, v_{i_{n-m}}\}$

Thus in particular,  $n+1$  or more vectors in  $V$  are linearly dependent.

### Theorem on Bases

Th Let  $V$  be a vector space of finite dimension  $n$ . Then

- Any  $n+1$  or more vectors in  $V$  are linearly dependent.
- Any linearly independent set  $S = \{v_1, v_2, \dots, v_n\}$  with  $n$  elements is a basis for  $V$ .

(iii) Any spanning set  $T = \{v_1, v_2, \dots, v_n\}$  of  $\mathbb{V}$  with  $n$  elements is a basis of  $\mathbb{V}$ .  $\oplus$

Th Suppose  $S$  spans a vector space  $\mathbb{V}$ .

Then

- i) Any maximum number of linearly independent vectors in  $S$  form a basis of  $\mathbb{V}$ .
- ii) Suppose one deletes from  $S$  every vector that is a linear combination of preceding vectors in  $S$ . Then the remaining vectors form a basis of  $\mathbb{V}$ .

Th Let  $\mathbb{V}$  be a vector space of finite dimension and let  $S = \{u_1, u_2, \dots, u_r\}$  be a set of linearly independent vectors in  $\mathbb{V}$ . Then  $S$  is a part of a basis of  $\mathbb{V}$ , that is,  $S$  may be extended to a basis of  $\mathbb{V}$ .

Th Let  $W$  be a subspace of a real vector space  $\mathbb{V}$  of  $n$  dimensional. Then  $\dim W \leq n$ .  
On particular, if  $\dim W = n$ , then  $W = \mathbb{V}$ .

Example Suppose the vectors  $u, v, w$  are ③  
linearly independent. Show that the  
vectors  $u+v, u-v, u-2v+w$  are also linearly  
independent.

Soln  $x(u+v) + y(u-v) + z(u-2v+w) = 0$

$$\text{or } (x+y+z)u + (x-y-2z)v + zw = 0$$

Because  $u, v, w$  are linearly independent

Hence  $x+y+z=0$

$$x-y-2z=0$$

$$z=0$$

The only solution is  $x=0, y=0, z=0$

Thus  $u+v, u-v, u-2v+w$  are linearly independent.

Determine whether or not each of the following is a basis of  $\mathbb{R}^3$ .

a)  $(1, 1, 1), (1, 0, 1)$

b)  $(1, 2, 3), (1, 3, 5), (1, 9, 1)$

c)  $(2, 3, 0), (1, 1, 1), (1, 2, 3), (2, -1, 1)$

(d)  $(1, 1, 2), (1, 2, 5), (5, 3, 4)$

⑨

(e) and (b) No, because a basis of  $\mathbb{R}^3$  must contain exactly three elements because  $\dim \mathbb{R}^3 = 3$

c) The three vectors form a basis iff. they are linearly independent. Thus the matrix whose rows are the given vectors, and row reduce the matrix to echelon form

$$\left[ \begin{array}{ccc} 1 & 1 & 1 \\ 1 & 2 & 3 \\ 2 & -1 & 1 \end{array} \right] \sim \left[ \begin{array}{ccc} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & -3 & -1 \end{array} \right] \sim \left[ \begin{array}{ccc} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 5 \end{array} \right]$$

The echelon matrix has no zero rows.

Hence the three vectors are linearly independent and so they do form a basis of  $\mathbb{R}^3$ .

d) Form the matrix whose rows are the given vectors, and row reduce the matrix to echelon form:

$$\left[ \begin{array}{ccc} 1 & 1 & 2 \\ 1 & 2 & 5 \\ 5 & 3 & 4 \end{array} \right] \sim \left[ \begin{array}{ccc} 1 & 1 & 2 \\ 0 & 1 & 3 \\ 0 & -2 & -6 \end{array} \right] \sim \left[ \begin{array}{ccc} 1 & 1 & 2 \\ 0 & 1 & 3 \\ 0 & 0 & 0 \end{array} \right]$$

The echelon matrix has a zero row hence  
 the three vectors are linearly dependent and  
 so they do not form a basis of  $\mathbb{R}^3$ . (10)

### Example

Determine whether  $(1, 1, 1, 1)$ ,  $(1, 2, 3, 2)$ ,  
 $(2, 5, 6, 4)$ ,  $(2, 6, 8, 5)$  form a basis of  
 $\mathbb{R}^4$ . If not find the dimension of  
 the subspace they span.

$$B = \left[ \begin{array}{cccc} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 2 \\ 2 & 5 & 6 & 4 \\ 2 & 6 & 8 & 5 \end{array} \right] \sim \left[ \begin{array}{cccc} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 1 \\ 0 & 3 & 4 & 2 \\ 0 & 4 & 6 & 3 \end{array} \right]$$

$$\sim \left[ \begin{array}{cccc} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & -2 & -1 \\ 0 & 0 & -2 & -1 \end{array} \right] \sim \left[ \begin{array}{cccc} 1 & 1 & 1 & 1 \\ 0 & 1 & 2 & 1 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{array} \right]$$

The echelon matrix has a zero row.

Hence the four vectors are ~~not~~ linearly

dependent and do not form a basis of  $\mathbb{R}^4$ .<sup>(1)</sup>  
Because the echelon matrix has three non-zero rows, the four vectors span a subspace of dimension 3.

Ex Find a basis and dimension of the subspace  $W$  of  $\mathbb{R}^4$  where

a)  $W = \{(a, b, c) : a+b+c=0\}$

b)  $W = \{(a, b, c) : (a=b=c)\}$

a) Note that  $W \neq \mathbb{R}^3$ , because for example  $(1, 2, 3) \notin W$ . Then  $\dim W < 3$ .

Note that  $u_1 = (1, 0, -1)$  and  $u_2 = (0, 1, -1)$  are two independent vectors in  $W$ . Thus  $\dim W = 2$  and  $u_1, u_2$  form a basis of  $W$ .

b) The vector  $u = (1, 1, 1) \in W$ . Any vector  $w \in W$  has the form  $w = (k, k, k)$ .

Hence  $w = k u$ . Thus  $u$  spans  $W$  and  $\dim W = 1$ .

Ex Find the dimension and a basis of the solution space  $N$  of each homogeneous system. (12)

$$a) x + 2y + 2z - s + 3t = 0$$

$$x + 2y + 3z + s + t = 0$$

$$2x + 6y + 8z + s + 5t = 0$$

Reduce the system to echelon form

$$\begin{aligned} x + 2y + 2z - s + 3t &= 0 \\ z + 2s - 2t &= 0 \\ 2z + 4s - 4t &= 0 \end{aligned} \quad \left. \begin{array}{l} \\ \\ \end{array} \right\}$$

or,  $x + 2y + 2z - s + 3t = 0$

$$z + 2s - 2t = 0$$

The system in echelon form has two equations in five unknowns. Hence the system has  $5-2=3$  free variable.

which are  $y, s, t$ . Thus  $\dim N = 3$ .

We obtain a basis for  $N$ :

① Set  $y=1, s=0, t=0$ ,  $v_1 = (-2, 1, 0, 0, 0)$

② Set  $y=0, s=1, t=0$ ,  $v_2 = (5, 0, -2, 1, 0)$

③ Set  $y=0, s=0, t=1$ ,  $v_3 = (-7, 0, 2, 0, 1)$

The set  $\{u_1, u_2, u_3\}$  is a basis of the solution space  $\mathcal{W}$ .

b)  $x + 2y + 2 - 2t = 0$   
 $2x + 4y + 4z - 3t = 0$   
 $3x + 6y + 7z - 4t = 0$

Here the coefficient matrix A

$$= \begin{bmatrix} 1 & 2 & 1 & -2 \\ 2 & 4 & 4 & -3 \\ 3 & 6 & 7 & -4 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 2 & 1 & -2 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 4 & 2 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 1 & -2 \\ 0 & 0 & 2 & 1 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

The corresponding system is

$$x + 2y + 2 - 2t = 0$$

$$2z + t = 0$$

The free variable are  $y, t$   $\dim \mathcal{W} = 2$

i) set  $y=1, z=0, u_1 = (-2, 1, 0, 0)$

ii) set  $y=0, z=2, u_2 = (6, 0, -1, 2)$

Then  $\{u_1, u_2\}$  is a basis of  $W$ . (14)

c)  $x + 2y + 2z = 0$   
 $2x + 3y + 3z = 0$   
 $x + 3y + 5z = 0$

The coefficient matrix is

$$A = \left[ \begin{array}{ccc} 1 & 1 & 2 \\ 2 & 3 & 3 \\ 1 & 3 & 5 \end{array} \right] \sim \left[ \begin{array}{ccc} 1 & 1 & 2 \\ 0 & 1 & -1 \\ 0 & 2 & 3 \end{array} \right]$$

$\sim$

$$\left[ \begin{array}{ccc} 1 & 1 & 2 \\ 0 & 1 & -1 \\ 0 & 0 & 5 \end{array} \right]$$

Here no free variable. Thus  $\dim W = 0$

## Linear Mapping (Linear Transformation)

Def Let  $V$  and  $U$  be vector spaces over the same field  $K$ . A mapping  $F: V \rightarrow U$  is called a linear mapping, or linear transformation if

① For any vectors  $u, w \in V$ ,

$$F(u+w) = F(u) + F(w)$$

② For any scalar  $k$  and vector

$$v \in V, F(kv) = kF(v)$$

Note  $F(0) = 0$ . Thus every linear mapping takes the zero vector into the zero vector.

More generally For any scalars

$a_i \in K$  and any vectors  $v_i \in V$

$$F(a_1 v_1 + a_2 v_2 + \dots + a_m v_m) = a_1 F(v_1)$$

$$+ a_2 F(v_2) + \dots + a_m F(v_m)$$

### Example

1. Let  $F: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be the mapping defined by  $F(x, y, z) = (x, y, 0)$ . We show that  $F$  is linear.

(2)

Let  $v = (a, b, c)$  and  $w = (a', b', c')$

$$\text{Then } F(v+w) = F(a+a', b+b', c+c')$$

$$= (aa', bb', cc')$$

$$= (a, b, c) + (a', b', c')$$

$$= F(v) + F(w)$$

and for any scalar  $k$ ,

$$F(kv) = F(ka, kb, kc) = (ka, kb, kc)$$

$$= k(a, b, c)$$

$$= kF(v)$$

Thus  $F$  is linear.

Example 2 : Let  $G_2: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by

$$G_2(x, y) = (x+1, y+2)$$

$$G_2(0) = G_2(0, 0) = (1, 2) \neq 0$$

Thus the zero vector is not mapped into the zero vector. Hence  $G_2$  is not linear



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## Kernel and Image of a linear mapping. ③

Def Let  $F: V \rightarrow U$  be a linear mapping.

The kernel of  $F$ , written  $\text{Ker } F$ , is the set of elements of  $V$  that map into the zero vector  $0$  in  $U$ .

$$\text{That is } \text{Ker } F = \{v \in V : F(v) = 0\}$$

The image (or range) of  $F$ , written in  $\text{Im } F$ , is the set of image points in  $U$ .

$$\text{That is } \text{Im } F = \{u \in U : \text{there exists } v \in V \text{ for which } F(v) = u\}$$

Th Let  $F: V \rightarrow U$  be a linear mapping.

Then the kernel of  $F$  is a subspace of  $V$  and the image of  $F$  is a subspace of  $U$ .

## Rank and Nullity of Linear Mapping

Let  $F: V \rightarrow U$  be a linear mapping. The rank of  $F$  is defined to be the dimension of its image and the nullity of  $F$  is



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defined to be the dimension of its kernel; (4)  
namely,

$$\text{rank}(F) = \dim(\text{Im } F) \quad \text{and} \quad \text{Nullity}(F) = \dim(\text{Ker } F)$$

Th Let  $V$  be of finite dimension, and let  
 $F: V \rightarrow V$  be linear. Then

$$\begin{aligned}\dim V &= \dim(\text{Ker } F) + \dim(\text{Im } F) \\ &= \text{nullity}(F) + \text{rank}(F)\end{aligned}$$

Ex Let  $F: \mathbb{R}^4 \rightarrow \mathbb{R}^3$  be the linear mapping defined by

$$F(x, y, z, t) = (x-y+z+t, 2x-2y+3z+4t, 3x-3y+4z+5t)$$

a) Find a basis and the dimension of the image of  $F$ .

First find the image of the usual basis vectors of  $\mathbb{R}^4$ .

$$F(1, 0, 0, 0) = (1, 2, 3), \quad F(0, 1, 0, 0) = (-1, -2, -3)$$

$$F(0, 0, 1, 0) = (1, 3, 4), \quad F(0, 0, 0, 1) = (1, 4, 5)$$



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The image vectors span  $\text{Im } F$ . Hence  
 form the matrix  $M$  whose rows are these  
 image vectors and row reduce to echelon  
 form :

$$M = \begin{bmatrix} 1 & 2 & 3 \\ -1 & -2 & -3 \\ 1 & 3 & 4 \\ 1 & 4 & 5 \end{bmatrix} \sim \begin{bmatrix} 1 & 2 & 3 \\ 0 & 0 & 0 \\ 0 & 1 & 1 \\ 0 & 2 & 2 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 2 & 3 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Thus  $(1, 2, 3), (0, 1, 1)$  form a basis of  $\text{Im } F$ .  
 Hence  $\dim(\text{Im } F) = 2, \text{rank } F = 2$

b) Find a basis and the dimension of the kernel of the mapping  $F$ :

Set  $F(v) = 0$  where  $v = (x, y, z, t)$

$$\begin{aligned} F(x, y, z, t) &= (x-y+z+t, 2x-2y+3z+4t, 3x-3y \\ &\quad +4z+5t) \\ &= (0, 0, 0) \end{aligned}$$



Set corresponding components equal to ⑥ each other to form the following homogeneous system whose solution space is  $\text{Ker } F$ :

$$\left. \begin{array}{l} x-y+z+t=0 \\ 2x-2y+3z+4t=0 \\ 3x-3y+4z+5t=0 \end{array} \right\} \text{ or } \left. \begin{array}{l} x-y+z+t=0 \\ z+2t=0 \\ z+2t=0 \end{array} \right\}$$

or

$$\left. \begin{array}{l} x-y+z+t=0 \\ z+2t=0 \end{array} \right.$$

The free variables are  $y$  and  $t$ ,

Hence  $\dim(\text{Ker } F) = 2$  or  $\text{Nullity}(F) = 2$

i) Set  $y=1, t=0$  to obtain the solution  $(-1, 1, 0, 0)$

ii) Set  $y=0, t=1$  to obtain the solution  $(1, 0, -2, 1)$

Thus  $(-1, 1, 0, 0)$  and  $(1, 0, -2, 1)$  form a basis for  $\text{Ker } F$ .

As expected  $\dim(\text{Ker } F) + \dim(\text{Im } F) = 4 = \dim(\mathbb{R}^4)$

The The dimension of the solution space  $N$  of a homogeneous system  $AX=0$  of linear equations is  $s=n-r$ , where  $n$  is the number

number of unknowns and  $r$  is the rank of the coefficient matrix  $A$ . ⑦

## Singular and Non-singular Linear mappings

Let  $F: V \rightarrow U$  be a linear mapping.

Recall that  $F(0) = 0$ .  $F$  is said to be singular if the image of some nonzero vector

$v$  is  $0$  — that is if there exists  $v \neq 0$  such that  $F(v) = 0$ . Thus  $F: V \rightarrow U$  is nonsingular if the zero vector  $0$  is the only vector whose image under  $F$  is  $0$  or in other words; if  $\ker F = \{0\}$ .

Th Let  $F: V \rightarrow U$  be a nonsingular linear mapping. Then the image of any linearly independent set is linearly independent.

Th A linear mapping  $F: V \rightarrow U$  is one to one iff if  $F$  is nonsingular.

Ex Suppose the mapping  $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  is defined by  $F(x, y) = (x+y, x)$ . Show that  $F$  is linear. ⑧

An: We need to show that  $F(v+w) = F(v) + F(w)$  and  $F(kv) = k F(v)$ , where  $v$  and  $w$  are any elements of  $\mathbb{R}^2$  and  $k$  is any scalar.

$$\text{Let } v = (a, b), w = (a', b')$$

$$v+w = (a+a', b+b')$$

$$kv = (ka, kb)$$

$$F(v) = (a+b, a), F(w) = (a'+b', a')$$

$$F(v+w) = F(a+a', b+b')$$

$$= (a+a'+b+b', a+a')$$

$$= (a+b, a) + (a'+b', a')$$

$$= F(v) + F(w)$$

$$\text{and } F(kv) = F(ka, kb)$$

$$= (ka+kb, ka) = k(a+b, a)$$

$$= k F(v)$$

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Because  $v, w, k$  were arbitrary,  $F$  is linear. ⑨

Ex Suppose  $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by

$F(x, y, z) = (x+y+z, 2x-3y+4z)$ . Show that  
 $F$  is linear.

Ex Show that the following mappings  
are not linear.

a)  $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by  $F(x, y) = (xy, x)$

b)  $F : \mathbb{R}^2 \rightarrow \mathbb{R}^2$  defined by  $F(x, y) = (x+3, 2y, x+y)$

c)  $F : \mathbb{R}^3 \rightarrow \mathbb{R}^2$  defined by  $F(x, y, z) = (|x|, y+z)$

a) Let  $v = (1, 2)$ ,  $w = (3, -1)$

$$v+w = (4, 1)$$

$$F(v) = (1 \cdot 2, 1) = (2, 1) \quad F(w) = (3 \times 4, 3) = (12, 3)$$

$$\text{Hence } F(v+w) = (4 \cdot 1, 1) = (4, 1) \neq (24, 6)$$

$$\neq F(v) + F(w)$$

b) Because  $F(0, 0) = (3, 0, 0) \neq (0, 0, 0)$

$\therefore F$  is not linear.



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(10)

$$c) \text{ Let } v = (1, 2, 3), \quad k = -3$$

$$kv = (-3, -6, -9)$$

$$F(v) = (1, 5) \text{ and } kF(v) = -3(1, 5) \\ = (-3, -15)$$

$$\text{Thus } F(kv) = F(-3, -6, -9) = (+3, -15) \\ \neq kF(v)$$

$\therefore F$  is not linear

Ex Let  $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be the linear mapping for which  $F(1, 2) = (2, 3)$ ,  $F(0, 1) = (1, 4)$

Let  $(a, b)$  as a linear combination of  $(1, 2)$  and  $(0, 1)$ .

$$(a, b) = x(1, 2) + y(0, 1) \\ = (x, 2x+y)$$

$$\therefore x=a, \quad b=2x+y, \quad y=-2a+b$$

$$F(a, b) = xF(1, 2) + yF(0, 1) = a(2, 3) + (-2a+b)(1, 4)$$

$$= (b, -5a+1b)$$

(1D)

Kernal and Image of the linear mapping

Ex 201 Let  $F: \mathbb{R}^4 \rightarrow \mathbb{R}^3$  be the linear mapping

defined by

$$F(x, y, z, t) = (x-y+z+t, x+2z-t, x+y+3z-3t)$$

Find a basis and the dimension of  
a) the image of  $F$  (b) the kernel of  $F$ .

a) Find the images of the usual  
basis of  $\mathbb{R}^4$

$$F(1, 0, 0, 0) = (1, 1, 1), \quad F(0, 0, 1, 0) = (1, 2, 3)$$

$$F(0, 1, 0, 0) = (-1, 0, 1), \quad F(0, 0, 0, 1) = (1, -1, -3)$$

$$\begin{bmatrix} 1 & 1 & 1 \\ -1 & 0 & 1 \\ 1 & 2 & 3 \\ 1 & -1 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 1 & 2 \\ 0 & -2 & -4 \end{bmatrix}$$

$$\sim \begin{bmatrix} 1 & 1 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix}$$

Thus  $(1, 1, 1)$  and  $(0, 1, 2)$   
form a basis for  $\text{Im } F$ .  
Hence  $\dim(\text{Im } F) = 2$



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b) Set  $F(v) = 0$  where  $v = (x, y, z, t)$  ⑫

$$F(x, y, z, t) = (x-y+z+t, x+2z-t, x+y+3z-2t) \\ = (0, 0, 0)$$

$$\left. \begin{array}{l} x-y+z+t=0 \\ x+2z-t=0 \\ x+y+3z-2t=0 \end{array} \right\} \text{or} \quad \left. \begin{array}{l} x-y+z+t=0 \\ y+2z-2t=0 \\ 2y+2z-4t=0 \end{array} \right\} \text{or}$$

$$x-y+z+t=0$$

$$y+2z-2t=0$$

The free variables are  $z$  and  $t$

Hence  $\dim(\ker F) = 2$

i) Set  $z=1, t=0$ , the solution is  $(2, 1, -1, 0)$

ii) Set  $z=0, t=1$ , the solution is  $(1, 2, 0, 1)$

Thus  $(2, 1, -1, 0), (1, 2, 0, 1)$  form a basis  
of  $\ker F$ .

$$\dim(\ker F) + \dim(\text{Im } F) = 2+2=4 \\ = \dim \mathbb{R}^4$$

Ex Let  $\alpha: \mathbb{R}^3 \rightarrow \mathbb{R}^3$  be the linear mapping ⑬  
defined by

$$\alpha(x, y, z) = (x+2y-z, y+z, x+y-2z)$$

Find a basis and the dimension of (a)  
the image of  $\alpha$  (b) the kernel of  $\alpha$ .

a) Find the images of the usual  
basis of  $\mathbb{R}^3$

$$\alpha(1, 0, 0) = (1, 0, 1), \quad \alpha(0, 1, 0) = (2, 1, 1)$$

$$\alpha(0, 0, 1) = (-1, 1, -2)$$

$$M = \begin{bmatrix} 1 & 0 & 1 \\ 2 & 1 & 1 \\ -1 & 1 & -2 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 1 & -1 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$$

Thus  $(1, 0, 1)$  and  $(0, 1, -1)$  form a basis  
for  $\text{Im } \alpha$ . Hence  $\dim(\text{Im } \alpha) = 2$

b) Set  $\alpha(v) = 0$  where  $v = (x, y, z)$

$$\alpha(x, y, z) = (x+2y-z, y+z, x+y-2z) = (0, 0, 0)$$



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(4)

Set corresponding

$$\left. \begin{array}{l} x+2y-2=0 \\ y+2=0 \\ x+y-2z=0 \end{array} \right\} \quad \begin{array}{l} x+2y-2=0 \\ y+2=0 \end{array}$$

$\therefore \dim(\ker \alpha) = 1$ , set  $z=1, y=-1, x=3$

Then  $(3, -1, 1)$  is a basis of  $\ker \alpha$ .

## Linear Mappings and Matrices

### Matrix Representation of a Linear Operator

Let  $T$  be a linear transformation from a vector space  $V$  into itself and suppose

$S = \{u_1, u_2, \dots, u_n\}$  is a basis of  $V$ . Now

$T(u_1), T(u_2), \dots, T(u_n)$  are vectors in  $V$ , and so each is a linear combination of the vectors in the basis  $S$ ; say

$$T(u_1) = a_{11}u_1 + a_{12}u_2 + \dots + a_{1n}u_n$$

$$T(u_2) = a_{21}u_1 + a_{22}u_2 + \dots + a_{2n}u_n$$

— — — — — — —

$$T(u_n) = a_{n1}u_1 + a_{n2}u_2 + \dots + a_{nn}u_n$$

Def<sup>n</sup>: The transpose of the above matrix of coefficients, denoted by  $m_S(T)$  or  $[T]_S$ , is called the matrix representation of  $T$  relative to the basis  $S$  or simply the matrix of  $T$  in the basis  $S$ .

Using the coordinate vector notation, the <sup>②</sup>  
matrix representation of  $T$  may be written  
in the form

$$m_s(T) = [T]_s = \left[ \begin{bmatrix} T(u_1) \\ T(u_2) \end{bmatrix}_s, \dots, \begin{bmatrix} T(u_n) \\ T(u_n) \end{bmatrix}_s \right].$$

Prob: Let  $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be the linear operator  
defined by  $F(x, y) = (2x+3y, 4x-5y)$

Find the matrix representation of  $F$   
relative to the basis  $S = \{u_1, u_2\}$

$$= \{(1, 2), (2, 5)\}.$$

$$\begin{aligned} F(u_1) &= F(1, 2) = (8, -6) \\ &= x(1, 2) + y(2, 5) \end{aligned}$$

$$\therefore x+2y = 8$$

$$2x+5y = -6$$

Solve the system to obtain  $x = 52, y = -22$

$$\therefore F(u_1) = 52u_1 - 22u_2$$

$$F(u_2) = F(2, 5) = (19, -17)$$

$$= x(1, 2) + y(2, 5)$$

(3)

$$x+2y = 19$$

$$2x+5y = -17$$

$$\therefore x = 129, y = -55$$

$$F(u_2) = 129u_1 - 55u_2$$

Now write the coordinates of  $F(u_1)$  and  $F(u_2)$  as column we obtain the matrix

$$[F]_S = \begin{bmatrix} 52 & 129 \\ 22 & -55 \end{bmatrix}$$

Prob: Let  $F: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  be defined by

$F(x, y) = (2x+3y, 4x-5y)$ . Find the matrix representation  $[F]_S$  of  $F$  relative to the basis  $S = \{u_1, u_2\} = \{(1, -2), (2, -5)\}$

$$\begin{aligned} \text{Ans: } F(u_1) &= F(1, -2) = (4, 14) \\ &= x(1, -2) + y(2, -5) \\ &= 8u_1 + 6u_2 \end{aligned}$$

$$F(u_2) = F(2, -5) = (11, 33)$$

$$= 11u_1 - 11u_2$$

$$[F]_S = \begin{bmatrix} 8 & 11 \\ -6 & -11 \end{bmatrix}$$



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Prob Let  $F: \mathbb{R}^3 \rightarrow \mathbb{R}^2$  be the linear mapping (4)  
defined by  $F(x, y, z) = (3x+2y-4z, x-5y+3z)$

a) Find the matrix of  $F$  in the following  
bases of  $\mathbb{R}^3$  and  $\mathbb{R}^2$

$$S = \{\omega_1, \omega_2, \omega_3\} = \{(1, 1, 1), (1, 1, 0), (1, 0, 0)\}$$

$$\text{and } S' = \{u_1, u_2\} = \{(1, 3), (2, 5)\}$$

$$\underline{\text{Sol'n}} \quad (a, b) = (-5a+2b)u_1 + (3a-b)u_2$$

$$F(\omega_1) = F(1, 1, 1) = (1, -1) = -7u_1 + 4u_2$$

$$F(\omega_2) = F(1, 1, 0) = (5, -4) = -33u_1 + 19u_2$$

$$F(\omega_3) = F(1, 0, 0) = (3, 1) = -13u_1 + 8u_2$$

$$[F]_{S, S'} = \begin{bmatrix} -7 & -33 & -13 \\ 4 & 19 & 8 \end{bmatrix}$$

Prob: Consider the linear transformation  
 $T$  on  $\mathbb{R}^2$  defined by  $T(x, y) = (2x-3y, x+4y)$  and  
the following bases of  $\mathbb{R}^2$ :

$$E = \{e_1, e_2\} = \{(1, 0), (0, 1)\} \text{ and}$$

$$S = \{u_1, u_2\} = \{(1, 3), (2, 5)\}$$

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a) Find the matrix A representing T relative to the bases E and S

b) Find the matrix B representing T relative to the bases S and E.

$$\begin{aligned} a) \quad (\underline{a}, b) &= (-5a+2b)u_1 + xu_1 + yu_2 \\ &= (-5a+2b)u_1 + (3a-b)u_2 \end{aligned}$$

$$T(e_1) = T(1, 0) = (2, 1) = -8u_1 + 5u_2$$

$$T(e_2) = T(0, 1) = (-3, 4) = 23u_1 + 13u_2$$

$$A = \begin{bmatrix} -8 & 23 \\ 5 & -13 \end{bmatrix}$$

$$b) \quad T(u_1) = T(1, 3) = (-7, 13) = -7e_1 + 13e_2$$

$$T(u_2) = T(2, 5) = (-11, 12) = -11e_1 + 22e_2$$

$$B = \begin{bmatrix} -7 & -11 \\ 13 & 22 \end{bmatrix}$$

Rub Let  $F: \mathbb{R}^3 \rightarrow \mathbb{R}^2$  be defined by  $F(x, y, z)$   
 $= (2x+y-z, 3x-2y+4z)$ . Find the matrix A

of  $f$  relative to the bases

$S = \{(1,1,1), (1,1,0), (1,0,0)\}$  and  $S' = \{(1,3), (1,4)\}$  ⑥

## Characteristic Polynomial, Cayley-Hamilton

### Theorem

Let  $A = [a_{ij}]$  be an  $n$ -square matrix. The matrix  $M = A - tI_n$ , where  $I_n$  is the  $n$ -square identity matrix and  $t$  is an indeterminate, may be obtained by subtracting  $t$  down the diagonal of  $A$ . The negative of  $M$  is the matrix  $tI_n - A$ , and its determinant

$$\Delta(t) = \det(tI_n - A) = (-1)^n \det(A - tI_n)$$

which is a polynomial in  $t$  of degree  $n$  and is called the characteristic polynomial of  $A$ .

### Cayley Hamilton

Every matrix  $A$  is a root of its characteristic polynomial.

Ex Let  $A = \begin{bmatrix} 1 & 3 \\ 4 & 5 \end{bmatrix}$ . Its characteristic polynomial is

$$\Delta(t) = |tI - A| = \begin{vmatrix} t-1 & -3 \\ -4 & t-5 \end{vmatrix} = (t-1)(t-5) - 12 = t^2 - 6t - 7$$

The Cayley-Hamilton theorem,  $A$  is a root of  $\Delta(t)$ .

$$\begin{aligned}\Delta(A) &= A^2 - 6A - 7I \\ &= \begin{bmatrix} 13 & 18 \\ 24 & 37 \end{bmatrix} + \begin{bmatrix} -6 & -18 \\ -24 & -30 \end{bmatrix} + \begin{bmatrix} -7 & 0 \\ 0 & -7 \end{bmatrix} \\ &= \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}\end{aligned}$$

Ex Find the characteristic polynomial of  $A$

$$= \begin{bmatrix} 1 & 1 & 2 \\ 0 & 3 & 2 \\ 1 & 3 & 9 \end{bmatrix}$$

$$\Delta(t) = t^3 - 13t^2 + 31t - 17$$

Eigenvalue

Let  $A$  be any square matrix. A scalar  $\lambda$  is called an eigenvalue of  $A$  if there exists a non-zero vector  $v$  such that

$$22 \quad Av = \lambda v$$

(8)

The An  $n$ -square matrix  $A$  is similar to a diagonal matrix  $D$  iff  $A$  has  $n$  linearly independent eigenvectors. In this case, the diagonal elements of  $D$  are the characteristic corresponding eigen values and  $D = P^{-1}AP$ , where  $P$  is the matrix whose columns are the eigenvectors.

Q. Let  $A = \begin{bmatrix} 3 & -1 \\ 2 & -6 \end{bmatrix}$

- Find all eigenvalues and eigenvectors.
  - Find matrices  $P$  and  $D$  such that  $P$  is nonsingular and  $D = P^{-1}AP$  is diagonal.
- Ans: a) First find the characteristic polynomial of  $A$

$$\begin{aligned}\Delta(t) &= t^2 - \text{tr}(A) + |A| \\ &= t^2 + 3t - 10 = (t+2)(t-5)\end{aligned}$$

The roots  $\lambda = 2, \lambda = -5$

Eigen values are 2, 5.



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i) Subtract  $\lambda = 2$  down the diagonal of  $A$  to obtain the matrix  $M = A - 2I$ , where the corresponding homogeneous system  $Mx = 0$  yields the eigenvectors corresponding to  $\lambda = 2$ . We have

$$M = \begin{bmatrix} 1 & -4 \\ 2 & -8 \end{bmatrix} \quad \text{corresponding to } \begin{cases} x - 4y = 0 \\ 2x - 8y = 0 \end{cases}$$

$$\text{or, } x - 4y = 0$$

The system has only one free variable, and  $v_1 = (4, 1)$  is a nonzero solution. Thus,  $v_1 = (4, 1)$  is an eigenvector belonging to  $\lambda = 2$ .

ii) Subtract  $\lambda = -5$

$$M = \begin{bmatrix} 8 & -4 \\ 2 & -1 \end{bmatrix} \quad \begin{cases} 8x - 4y = 0 \\ 2x - y = 0 \end{cases} \quad \text{or } 2x - y = 0$$

The system has only one free variable and  $v_1 = (1, 2)$  is a nonzero solution.

Thus  $v_2 = (1, 2)$  is an eigenvector belonging

b) Let  $P$  be the matrix whose columns are  $v_1$  and  $v_2$ . Then

$$P = \begin{bmatrix} 4 & 1 \\ 1 & 2 \end{bmatrix} \text{ and } D = P^{-1}AP = \begin{bmatrix} 2 & 0 \\ 0 & -5 \end{bmatrix}$$

Note that  $D$  is the diagonal matrix whose entries are the eigenvalues of  $A$  corresponding to the eigenvectors appearing in  $P$ .

Q3 Prob Let  $A = \begin{bmatrix} 2 & 2 \\ 1 & 3 \end{bmatrix}$

eigenvalues and

a) Find all eigenvectors

b) Find a nonsingular matrix  $P$  such that  $D = P^{-1}AP$  is diagonal. and  $P^{-1}$

The eigen values are  $\lambda = 1, \lambda = 4$

$$\begin{aligned} x+2y=0 \\ x+2y=0 \end{aligned} \quad \left. \begin{array}{l} \\ \end{array} \right\} \text{ or } x+2y=0$$

$(2, -1)$ ,  $v_1 = (2, -1)$  is an eigenvector

belonging to 1.

ii) Subtract  $\lambda = 4$  (iv)

$$M = \begin{bmatrix} -2 & 2 \\ 1 & -1 \end{bmatrix} \quad \begin{cases} -2x+2y=0 \\ x-y=0 \end{cases} \quad x-y=0$$

$x=1, y=1, v_2 = (1, 1)$  is an eigen vector belonging  $\lambda = 4$ .

b) Let  $P$  be the matrix whose columns are  $v_1$  and  $v_2$ . Then

$$P = \begin{bmatrix} 2 & 1 \\ -1 & 1 \end{bmatrix} \quad D = P^{-1} A P \\ = \begin{bmatrix} 1 & 0 \\ 0 & 4 \end{bmatrix}$$

where  $P^{-1} = \begin{bmatrix} \frac{1}{3} & -\frac{1}{3} \\ \frac{1}{3} & \frac{2}{3} \end{bmatrix}$