PHY407 – University of Toronto Lecture 11: Monte Carlo Simulations

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Supporting textbook chapters for week 11: Chapters 10.3&4

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1 Previously, in PHY407...

Q on the chat last week: > is MonteCarlo used to find the normalization factor in QM? See here for applications of MC techniques in QM:

https://en.wikipedia.org/wiki/Quantum_Monte_Carlo

Last week: * How to draw random numbers: PRNGs * how to "fake" random draws (linear congruential ggenerator for illustration); * how to test: statistical properties of distributions; * Python's (pseudo) random number generator is the Mersenne Twister * Transformation of distributions, e.g., for uniformly distributed distribution $p(x) = a \exp(-ax)$ obtained from

$$x = -\frac{1}{a}\ln(1-z).$$

- Monte Carlo integration:
 - when functions are pathological (fast variations),
 - when integrating over a lot of dimensions,
 - when integration domains are complicated.
- MC integration techniques:

Importance sampling

- Hit or Miss integration and mean value method have errors that vary as $N^{-1/2}$
- Importance sampling chooses weights that favour largest integration values:

$$I = \int_a^b f(x) dx = \left\langle \frac{f(x)}{w(x)} \right\rangle_w \int_a^b w(x) dx,$$

$$\left\langle \frac{f(x)}{w(x)} \right\rangle_w = \frac{\int_a^b \left[\frac{f(x)}{w(x)} \right] w(x) dx}{\int_a^b w(x) dx} \approx \frac{1}{N} \sum_{i=1}^N \frac{f(x_i)}{w(x_i)},$$

Week 10, topics: * Monte Carlo simulation

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Monte Carlo simulations:

Any simulation that uses random numbers to simulate random physical processes to estimate something about the outcome of that process.

We focus on statistical mechanics here.

2 Statistical mechanics: a review

• For a system in equilibrium at temperature *T* (canonical ensemble), the probability of finding the system in any particular microstate *i* is given by the Boltzmann distribution,

$$P(E_i) = \frac{\exp[-E_i/(k_BT)]}{Z}, \quad Z = \sum_{i=1}^{ALL} \exp[-E_i/(k_BT)]$$

where E_i is the energy of microstate i, and k_B is Boltzmann's constant.

- System at temperature T undergoes transitions between microstates with probability of being in a particular microstate $P(E_i)$
- To calculate a macroscopic property during a measurement (total energy, magnetization...) ⇒ average over the many microstates that the system visits during the measurement.
- If we want to measure a quantity "X" over the macrostate:

$$\langle X \rangle = \sum_{i=1}^{ALL} X_i P(E_i)$$

where X_i is the value of the quantity in the ith microstate and P is the probability of finding the system in that microstate.

• Simple example: single mole of gas has $N_A \approx 6 \times 10^{23}$ molecules. Assume each molecule had only 2 possible quantum states (gross underestimation), then the total number of microstates of the mole of gas is 2^{N_A} , which is huge.

3 Monte Carlo simulation in Stat. Mech.

Recall
$$P(E_i) = \frac{\exp\left[-E_i/(k_BT)\right]}{Z}$$
, $Z = \sum_{i=1}^{ALL} \exp\left[-E_i/(k_BT)\right]$

3.1 Setting the problem

- Huge number of terms in sum ⇒ use Monte Carlo summation.
- Two difficulties to overcome:
 - 1. properly sampling which terms to sum over (solution: importance sampling),
 - 2. estimating *Z* (solution: Markov Chain Monte Carlo)

Difficulty #1: why do we have to choose which terms to sum over?

(We will get to difficulty #2 later)

• Randomly sample the terms in the sum and only use those as an estimate. Replace:

$$\langle X \rangle = \sum_{i=1}^{ALL} X_i P(E_i)$$

• with a sum over *N* randomly sampled microstates:

$$\langle X \rangle = \frac{\sum_{i=1}^{N} X_i P(E_i)}{\sum_{i=1}^{N} P(E_i)}$$

- the denominator is needed to ensure the total probability over the sampled states is 1.
- It is only worth keeping the big terms in the sum if we want to compute this:

$$\langle X \rangle = \sum_{i=1}^{ALL} X_i P(E_i)$$

• There are a lot of states with $P(E_i)$ really small, with $E_i \gg k_B T$, which is the case for most of the states:

$$P(E_i) = \frac{\exp\left[-E_i/(k_B T)\right]}{Z}$$

- To get a good estimate for the sum, need to preferentially choose terms where the integrand is non-negligible.
- So we should use importance sampling!

3.2 Importance sampling for Stat. Mech.

• For an integral

$$I = \int_a^b f(x) dx = \left\langle \frac{f(x)}{w(x)} \right\rangle_w \int_a^b w(x) dx \approx \frac{1}{N} \sum_{i=1}^N \frac{f(x_i)}{w(x_i)} \int_a^b w(x) dx,$$

• For a sum:

$$\langle X \rangle = \sum_{i=1}^{N} X_i P(E_i) \approx \frac{1}{N} \sum_{k=1}^{N} \frac{X_k P(E_k)}{w_k} \sum_{i=1}^{ALL} w_i.$$

- What to choose for weight w to reduce the variance?
- $P(E_i)$ of course!

$$\langle X \rangle \approx \frac{1}{N} \sum_{k=1}^{N} \underbrace{\frac{X_k P(E_k)}{P(E_k)}}_{=X_k} \underbrace{\sum_{i=1}^{ALL} P(E_i)}_{-1}.$$

$$\langle X \rangle \approx \frac{1}{N} \sum_{k=1}^{N} X_k.$$

- * Looks simple and no different from regular MC, * but recall that the X_k 's are drawn from non-uniform distribution: we randomly choose terms in the sum based on their Boltzmann probabilities.
 - One thing left to deal with: How do we pick states with probability $P(E_k)$? Recall:

$$P(E_i) = \frac{\exp[-E_i/(k_B T)]}{Z}, \quad Z = \sum_{i=1}^{ALL} \exp[-E_i/(k_B T)]$$

• To do it this way, we need *Z*, which is a sum over all states. But if we could do this, we wouldn't need Monte Carlo in the first place!

3.3 Markov chain method

3.3.1 Elevator Pitch

Mish-mashing https://en.wikipedia.org/wiki/Markov_chain https://en.wikipedia.org/wiki/Markov_property,

and

A Markov chain is a stochastic model describing a sequence of possible events in which the probability of each event depends only on the state attained in the previous event. [...] (sometimes characterized as "memorylessness"). In simpler terms, it is a process for which predictions can be made regarding future outcomes based solely on its present state [...]. In other words, conditional on the present state of the system, its future and past states are independent.

- Random walks (Brownian motion) are Markov chains.
- Here: events are jumps in energy states, one after another.
- Solution: Use the Markov chain method.
 - Text goes into details on how to implement this method with a Metropolis algorithm.
 - Crucial key: Metropolis does not compute probability to be in one state, but probability to transition between two states (*Z* cancels out in the process).
 - I will summarize it algorithmically first, then briefly outline why it works mathematically.



3.3.2 Algorithm

- 1. Choose a random starting state *i*
- 2. Calculate the energy of that state E_i
- 3. Choose a transition to a new state *j* uniformly at random from allowed set
- 4. Calculate the energy of this new state, E_i
- 5. Calculate the acceptance probability for this transition:

 - $P_a = \exp\left(-\frac{E_j E_i}{k_B T}\right)$ if $E_j > E_i$ (always accept a lower energy state) if $E_j > E_i$ (sometimes accept a higher energy state, more often for high T).
- 6. Accept/reject the move according to the acceptance probability
- 7. Measure the quantity *X* you want in its current state (new or old *i*) & store it
- 8. Repeat from step 2.
- How to implement the probability of the event in the previous slide?

 - $P_a = 1$ if $E_j \le E_i$ (always accept a lower energy state)

 $P_a = \exp\left(-\frac{E_j E_i}{k_B T}\right)$ if $E_j > E_i$ (sometimes accept a higher energy state, more often for hight T).
- Draw a random number in [0, 1). The statement

will introduce what to do if the move is accepted (elif will introduce what to do if rejected).

- E.g., at very high T, $\exp \approx 1$ and almost all moves are accepted.
- E.g., at low T, say, $\exp(-(E_i E_i)/(k_B T)) = 1\%$, then random() has 1% chance of drawing a number that is < 1%.
- If $E_i \leq E_i$, then $\exp \geq 1$ and if statement automatically accepts.

Why does it work? 3.3.3

- Why do the probability transitions move-by-move (Metropolis algorithm) end up creating a system where each microstate has a probability $P(E_i)$, the Boltzmann distribution?
- Let τ_{ij} a transition probability from μ -state i to μ -state j, such that

$$\frac{\tau_{ij}}{\tau_{ji}} = \frac{P(E_j)}{P(E_i)}.$$

For example, a small ratio above means that "i is much less probable than i" and equivalently, "probability of $j \to i$ is much higher than $i \to j$ ", in equal amounts.

- "In equal amounts" is crucial: it means that if you start from any initial state, your system will progressively evolve towards one where all μ -states follow Boltzmann.
- Does it always converge? Could it converge to another distribution? If you love linear algebra and eigenvectors, see proof in Appendix D of Newman (it is actually quite elegant).

3.4 Example: Ising model

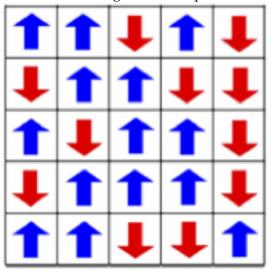
3.4.1 Elevator Pitch

- Simple model of ferromagnetism, but demonstrates many of the physical characteristics of fancier models.
- Assume an object is made up of a collection of dipoles (e.g. electron spins) and the net magnetization is the sum of the magnetization of all the spins
- Ising model:
 - assume the spins can only point up or down.
 - the spins interact and favor parallel alignment of pairs of spins
 - the interactions are non-zero only between nearest neighbours (i.e. distance dependent).
- The macroscopic energy *E* and magnetization *M* given by

$$E = -J \sum_{\langle ij \rangle} s_i s_j$$
 and $M = \sum_i s_i$

where s = +1 if spin is up & s = -1 if spin is down.

- Notice that the lowest energy occurs if the spins all line up.
- Spins can randomly flip as the system visits a set of allowable states given its temperature. At



any particular moment the system may look like

3.4.2 Example in 1D

- Create array of dipoles, initial state: random spin at each location.
- Calculate energy & magnetization of state
- Implement Metropolis algorithm:
 - create new state: flip 1 spin randomly
 - calculate new total energy
 - calculate acceptance probability
 - decide whether to accept or reject new state
 - store 'new' energy & magnetization

- repeat
- After this is a starter code for lab 11.

Oh, and by the way...

Fill out the online evaluations!!!

```
[]: # %load ising_1D_start.py

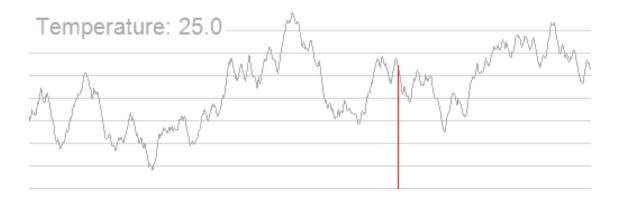
[]: import matplotlib.pyplot as plt
    # plot energy, magnetization
    fg, ax = plt.subplots(2, 1, sharex=True)
    ax[0].plot(magnet)
    ax[0].set_ylabel('Magnetization')
    ax[0].grid()
    ax[1].plot(energy)
    ax[1].set_xlabel('Number of flipping attempts')
    ax[1].set_ylabel('Energy')
    ax[1].grid()

plt.tight_layout()
    plt.show()
```

4 Simulated annealing

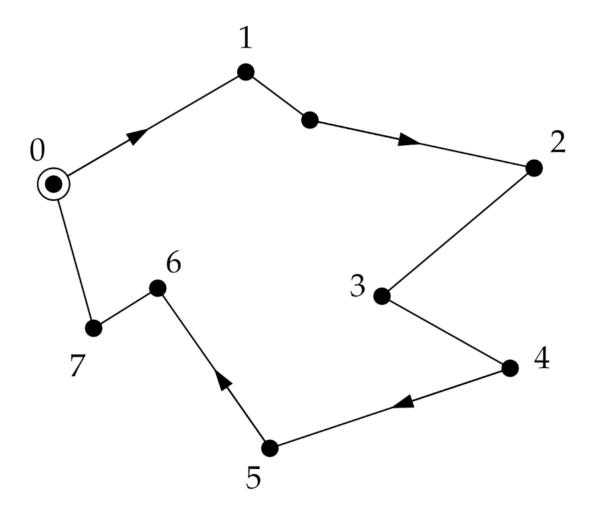
4.1 Elevator Pitch

- Using Monte Carlo simulations to find **global** minima/maxima.
- In week 4 we talked about ways of finding local minima (e.g., golden ratio search).
- How it works: rewrite max/min problem as looking for a "ground state energy" of a system.
 - Function *f* that you want the max/min of: make this the energy function.
 - how could you find ground state: reduce temperature until you reach the ground state.
- Issue: if you reduce temperature too quickly: might get caught in a local min instead of the global min.
- Solution: reduce temperature slowly. This way system has time to explore many microstates and find a good approximation to the global minimum.
- Visual Analogy: particle in a bumpy potential. Too low energy: get stuck in nearest local minimum. Keep low energy but allow some random 'kicks' in energy: can kick out of local minimum and continue heading to global minimum (see this figure).



4.2 Example: travelling salesman

- Famous NP-hard problem (https://en.wikipedia.org/wiki/NP-hardness): what is the shortest route to visit a given set of locations on a map?
- Want global minimum of distance
- Start with random route, swap 2 cities, use Metropolis algorithm to determine whether to keep the swap
- "energy" in this case is the total distance of the route
- You can explore this problem using code from the book (salesman.py).



Fill out the online evaluations!!!

[]: