Calculator

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Note: remove/add ";" in order to see/hide the output of the desired cell

Derivatives

```
In[1]= (*Function to derive*) f = Tan[Log[x^{\wedge}(-1/3)]]; Print["The function to derive is: ", f]  (*1st \text{ derivative*})  S = D[f, x]; Print["The 1st derivative of ", f, " is: ", S]  (*2nd \text{ derivative*})  S2 = D[D[f, x], x]; Print["The 2nd derivative of ", f, " is: ", S2]  

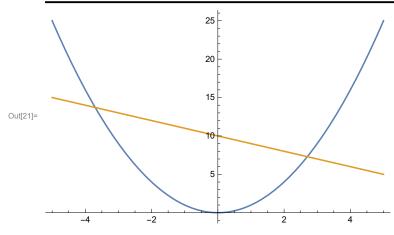
The function to derive is: Tan[Log[\frac{1}{x^{1/3}}]] The 1st derivative of Tan[Log[\frac{1}{x^{1/3}}]] is:  -\frac{Sec[Log[\frac{1}{x^{1/3}}]]^2}{3x}  The 2nd derivative of Tan[Log[\frac{1}{x^{1/3}}]] is:  \frac{Sec[Log[\frac{1}{x^{1/3}}]]^2}{3x^2} + \frac{2 Sec[Log[\frac{1}{x^{1/3}}]]^2 Tan[Log[\frac{1}{x^{1/3}}]]}{9x^2}
```

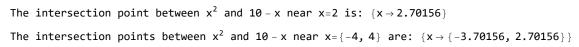
Integrals

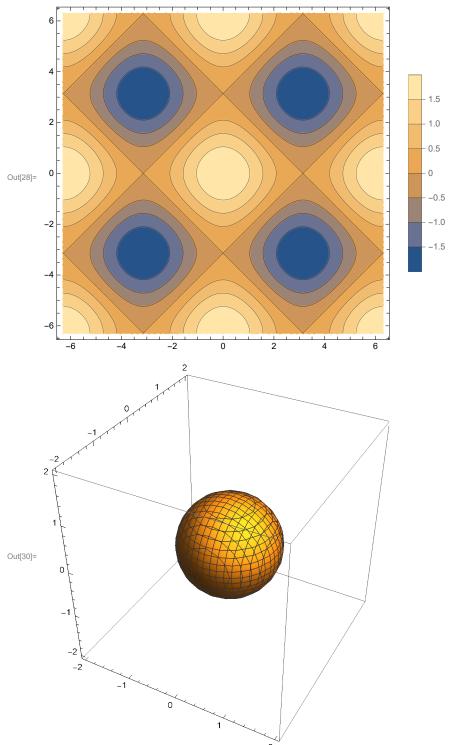
```
In[7]= (*Function to integrate*)
    f = 1 / (x^2 + 1);
    Print["The function to integrate is: ", f]
    (*Indefinite integral*)
    S = Integrate[f, x];
    Print["The integral of ", f, " is: ", S]
    (*Definite integral a → b*)
    a = 0;
    b = 1;
    S2 = Integrate[f, {x, a, b}];
    Print["The integral of ", f, " between ", a, " and ", b, " is: ", S2]
    (*Wavefunction normalization*)
    c = Infinity;
    S3 = Integrate[f * Conjugate[f], {x, -c, c}];
    Print["The normalization factor of the wavefunction ", f, " is: ", S3]
```

Plots

```
In[18]:= (*1st function to plot*)
     f1 = x^2;
     (*1st function to plot*)
     f2 = 10 - x;
     (*Plot range*)
     a = 5;
     (*2D Plot*)
     Plot[{f1, f2}, {x, -a, a}]
     (*Approx. value of intersection between functions*)
     b = 2;
     (*Find the exact intersection point value*)
     S = FindRoot[f1 = f2, \{x, b\}];
     Print["The intersection point between ", f1, " and ", f2, " near x=", b, " is: ", S]
     (*FOR Loop*)
     b = Table [4 * (-1 + 2 * n), \{n, 0, 1\}];
     S2 = FindRoot[f1 == f2, {x, b}];
     Print["The intersection points between ", f1, " and ", f2, " near x=", b, " are: ", S2]
     (*2D Plot*)
     ContourPlot[Cos[x] + Cos[y], {x, -2 Pi, 2 Pi}, {y, -2 Pi, 2 Pi}, PlotLegends → Automatic]
     (*3D Plot (sphere example)*)
     f = x^2 + y^2 + z^2;
     ContourPlot3D[f == 1, \{x, -2, 2\}, \{y, -2, 2\}, \{z, -2, 2\}]
```







Eigenvalue problems

```
In[31]:= (*Matrix*)
         0 1 2
    H = -4 1 4;
        -5 1 7
     H2 = MatrixForm[H];
     Print["Matrix: ", H2]
     (*En = eigenvalues (Energy)*)
     (*c = eigenvectors*)
     {En, c} = Eigensystem[H];
     c = c[[Ordering[En]]];
     En = En[[Ordering[En]]];
     TableForm[En];
     c = Transpose[c];
     MatrixForm[c];
     Print["1st eigenvalue: ", Part[En, 1]]
     Print["1st eigenvector: ", Part[c, 1]]
     Print["2nd eigenvalue: ", Part[En, 2]]
     Print["2nd eigenvector: ", Part[c, 2]]
     Print["3rd eigenvalue: ", Part[En, 3]]
     Print["3rd eigenvector: ", Part[c, 3]]
              0 1 2
     Matrix:
```

```
Matrix: \begin{pmatrix} 0 & 1 & 2 \\ -4 & 1 & 4 \\ -5 & 1 & 7 \end{pmatrix}

1st eigenvalue: 1

1st eigenvector: {1, 1, 1}

2nd eigenvalue: 2

2nd eigenvector: {-1, 0, 1}

3rd eigenvalue: 5

3rd eigenvector: {1, 1, 2}
```

Matrix operations

```
5 0 0
In[46]:= A = 0 1 0;
         2 0 1
         2 0 0
     B = 0 2 0;
         0 0 1
     (*Addition*)
     S = MatrixForm[A + B];
     (*Multiplication*)
     S2 = MatrixForm[A.B];
     (*Normalization*)
     S3 = MatrixForm[Normalize[B, Norm]];
     (*Transpose*)
     S4 = MatrixForm[Transpose[A]];
     (*Determinant*)
     S5 = Det[A];
     (*Inverse*)
     S6 = MatrixForm[Inverse[A]];
     (*Characteristic Polynomial*)
     S7 = CharacteristicPolynomial[A, x];
```

Systems of equations

```
In[55]:= (*Solve single equation*)
         Solve [x^2 + x = 0, x]
         (*System to solve*)
         (* X + Y + Z = 1 *)
         (* 2x + 9y + 2z = 0 *)
         (* 3x + 4y + 5z = 2 *)
               1 1 1
         A = 2 9 2;
               3 4 5
         (*Variable names*)
        V = y;
         (*Right part of the equations*)
         S = 0;
         (*With FindRoot*)
         Pr = FindRoot [A.V == S, {V, 1}]
         (*With Solve*)
         Solve [x + y + z == 1 & 2 & 2 & x + 9 & y + 2 & z == 0 & 3 & 3 & x + 4 & y + 5 & z == 2, \{x, y, z\}]
Out[55]= \{\{x \rightarrow -1\}, \{x \rightarrow \emptyset\}\}
\text{Out[59]= } \{\,\{\,\{\,x\,\}\,\text{, }\{\,y\,\}\,\text{, }\{\,z\,\}\,\}\,\,\rightarrow\,\,\{\,\{\,1.64286\,\}\,\text{, }\{\,-\,0.285714\,\}\,\text{, }\{\,-\,0.357143\,\}\,\}\,\}\,
Out[60]= \left\{\left\{x \rightarrow \frac{23}{14}, y \rightarrow -\frac{2}{7}, z \rightarrow -\frac{5}{14}\right\}\right\}
```