KU LEUVEN

Multi-agent systems based solution for Pickup-and-delivery

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1 Problem definition - Setting

- Pizzeria chain RoboPizza
- Pizza delivery using robots (AGVs)
- RoboPizza receives pizza delivery requests (tasks), robots deliver the pizzas
- Manhattan style city blocks

Problem definition - Robots

- Can move from and to any location in the city
- Have maps and can compute paths between locations
- Can carry up to 5 pizzas at once
- Can only communicate with entities that are close to them

1 Problem definition - Tasks

- Consist of pickup up (multiple) pizzas and deliver them to a location before a certain timepoint.
- ▶ If there are more than 5 pizzas in a task, it will have to be split up.
- Will be created every time step with low probability.
 - Delivery time window based on distance from pizzeria + randomness.
 - Amount of pizzas from Gaussian distribution.
 - Delivery location uniformly random in city.

1 Problem definition - World

Dynamism

- Streets can become closed off due to road works
- Amount of pizerrias

Potential AGV crashes

- Running out of battery
- **▶** ?

Efficiency measure

► Total waiting time for task

Charging

- Happens on one location.
- Charging station can only serve a limited amount of robots.

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2 Objectives

► Analyze performance of BDI & delegate MAS algorithm in a city setting

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3 Research questions (1)

- ► What is the relation between the amount of requests that RoboPizza receives and the waiting time for customers?
- ► Are robots on the road more when there are more requests in the system?
- Does increasing the amount of robots decrease the customer waiting time when there are many requests?
- ► How does the amount of robots impact the workload (occupancy rate) of the charging station?

3 Research questions (2)

- ▶ What is the relation between the amount of charging robots and the amount of clients we have to decline?
- How do waiting times change as the amount of road works change (dynamism)?
- ► How do waiting times change as the amount of pickup locations change (dynamism)?

- 4 Hypotheses

4 Hypotheses (1)

- ► What is the relation between the amount of requests that RoboPizza receives and the waiting time for customers?
 - H_1 : The waiting time increases with the amount of requests.
 - H_0 : The waiting time does **not** increase with the amount of requests.
- Are robots on the road more when there are more requests in the system?
 - H₁: Robots are on the road more when there are more requests in the system.
 - H₀: Robots are **not** on the road more when there are more requests in the system.

4 Hypotheses (2)

- Does increasing the amount of robots decrease the customer waiting time when there are many requests?
 - H_1 : Increasing the amount of robots decreases the customer waiting time when there are many requests.
 - H₀: Increasing the amount of robots does not decrease the customer waiting time when there are many requests.
- ► How does the amount of robots impact the workload (occupancy rate) of the charging station?
 - H_1 : A larger amount of robots increases the workload of the charging station.
 - H₀: A larger amount of robots does **not** increase the workload of the charging station.

4 Hypotheses (3)

- ▶ What is the relation between the amount of charging robots and the amount of clients we have to decline?
 - H₁: The amount of charging robots has no influence on the amount of clients that have to be declined.
 - H₀: The amount of charging robots influences on the amount of clients that have to be declined.
- How do waiting times change as the amount of road works change (dynamism)?
 - H_1 : Waiting times increase as the amount of road works increase.
 - H₀: Waiting times do **not** increase as the amount of road works increase.

4 Hypotheses (4)

- ▶ How do waiting times change as the amount of pickup locations change (dynamism)?
 - H_1 : Waiting times decrease as the amount of pickup locations increase.
 - H₀: Waiting times do **not** decrease as the amount of pickup locations increase.

- 6 Variables

5 Independent variables

- $ightharpoonup n_{robots} = ext{amount of delivery robots}$
- $p_{request} = \text{probability for a new request}$
- $\mu_{pizza}, \sigma_{pizza} =$ Gaussian distribution parameters for amount of pizzas
- $lacktriangledown p_{pizzeria_closes} = {
 m probability} \ {
 m for a pickup location to close}$
- $lacktriangledown p_{pizzeria_opens} = {
 m probability} \ {
 m for a pickup location to open}$
- $lacktriangledown p_{road_works_start} = {
 m probability} \ {
 m for} \ {
 m road} \ {
 m works} \ {
 m to} \ {
 m start}$
- $lacktriangledown p_{road_works_finish} = ext{probability for existing road works to finish}$

5 Dependent variables

- $ightharpoonup t_{wait} = {\sf cumulative}$ waiting time for customers
- lacktriangledown $t_{robots_driving} = \mathsf{time}\ \mathsf{robots}\ \mathsf{spent}\ \mathsf{driving}$
- t_{idle_time} = time where robots are idle
- $ightharpoonup n_{deliveries} = \text{amount of finished deliveries}$
- $ightharpoonup n_{road_works} = \text{amount of road works}$
- $lacktriangleq n_{requests} = {\sf cumulative} \ {\sf amount} \ {\sf of} \ {\sf requests} \ {\sf in} \ {\sf the} \ {\sf system}$
- lacktriangledown $n_{robots_charging} =$ workload of the charging station
- $ightharpoonup avg_{pizzas} = ext{average amount of pizzas carried by robots}$
- $lacktriangledown avg_{pizzeria} = {\sf average amount of pizzeria open}$
- $ightharpoonup avg_{requests} = ext{average amount of requests in the system}$

5 Other variables

- speed = moving speed of the robots
- baking time = how fast can a pizzeria cook a pizza
- battery size = the capacity of a battery
- charging time = the amount of time it takes to recharge a battery

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6 Plan

- Create a map
- Generate pizzeria and charging station
- Create random delivery tasks
- Implement task-allocation & route planning
- Calculate statistics
- Report results 6

