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Getting the clowns out of the Mandelbrot

### Overview

optimisation	time	change
baseline	1	
parallelise	0.34752	+188%
dynamic distribution	0.27227	+28%
enable optimisations	0.21961	+24%
remove complex numbers	0.07595	+189%
remove mod and branch	0.07611	+0%
loop unrolling	0.02933	+159%
main cardioid fastpath	0.00258	+1033%
fractal bulb fastpath	0.00188	+37%
distributed initialisation	0.00177	+6%
total	0.00177	×564.97

#### Baseline

```
for (int i = 0; i < size_y; i++) {
 for (uint64_t j = 0; j < size_x; ++j) {
    double x = view_x0 + j * step_x;
    double y = view_y1 - (i + offset_y) * step_y;
    complex double C = x + v * I. Z = C:
   int k;
   for (k = 1; cabs(Z) < 2 \&\& k < max iter; ++k) {
     Z = Z * Z + C:
    if (k == max iter) {
      memcpy(image, "\0\0", 3);
   } else {
      int index = (k + palette_shift) % number_of_colors;
      memcpy(image, colors[index], 3);
   image += 3:
```

► Some tiny changes to code style and control flow, nothing performance related

### Parallelise (+188%)

```
for (int i = 0; i < work_size; ++i) {
  work_args[i] = (Mandelbrot_call_args) {(u8*)image, size_x, size_y, ... };
  work_args[i].offset_y = size_y*i / work_size;
  work_args[i].size_y = size_y*(i+1) / work_size - work_args[i].offset_y;
  work_args[i].image += work_args[i].size_x * work_args[i].offset_y * 3;
}
pthread_t threads[num_threads];
for (int i = 0; i < num_threads; ++i) {
  pthread_create(&threads[i], NULL, &mandelbrot_thread, NULL);
}
for (int i = 0; i < num_threads; ++i) {
  pthread_join(threads[i], NULL);
}</pre>
```

- Note that work is spread over threads if uneven
- Always split into contiguous chunks!
  - ► Here, x-axis is contiguous in memory

## Dynamic distribution (+28%)

```
#define work_size 512
Mandelbrot_call_args work_args[work_size];
atomic_int work_index;

void* mandelbrot_thread(void* _) {
  while (work_index < work_size) {
    int i = work_index++;
    if (i >= work_size) break;
    Mandelbrot_call_args* p = &work_args[i];
    mandelbrot_calculate( ... );
  }
}
```

- ► Synchronisation is just a single integer
- ► Not much to see here

## Enable optimisations (+24%)

```
__attribute__((optimize(3), __target__("avx,ssse3,sse4a")))
void mandelbrot_calculate( ... ) { ... }
```

► Enable via an attribute as I cannot control the compilation process

### Remove complex numbers (+189%)

```
for (int i = 0: i < size x: ++i) {
 double Cr = view_x0 + j * step_x;
 double Ci = v, Zr = 0, Zi = 0, Zr old = 0:
 int k:
 for (k = 0; Zr*Zr + Zi*Zi < 4 \&\& k < max iter; ++k) {
   Zr old = Zr:
   Zr = Zr*Zr - Zi*Zi + Cr:
   Zi = 2.0 * Zr old * Zi + Ci;
 if (k == max iter) {
   memcpy(image, "\0\0", 3);
 } else {
    int index = (k + palette shift) % number of colors);
   memcpy(image, colors[index], 3);
 image += 3:
```

- ► Remove the square root inside cabs
- ▶ Write down the complex math by hand, simplify squaring a bit

### Remove mod and branch (+0%)

```
for (int j = 0; j < size_x; ++j) {
   double Cr = view_x0 + j * step_x;
   double Ci = y, Zr = 0, Zi = 0, Zr_old = 0;
   int k;
   for (k = 0; Zr*Zr + Zi*Zi < 4 && k < max_iter; ++k) {
        Zr_old = Zr;
        Zr = Zr*Zr - Zi*Zi + Cr;
        Zi = 2.0 * Zr_old * Zi + Ci;
   }
   memcpy(image, &colors_opt[3*k], 3);
   image += 3;
}</pre>
```

- ► Context: Similar size of max\_iter and number\_of\_colors
- ► No performance gain right now, but simplifies code
- ▶ Has to be set up by the main thread beforehand (almost no overhead)

### Loop unrolling (+159%)

```
for (int kk = 0: kk < max iter: ++kk) {
 u8 flag1 = Z1r*Z1r + Z1i*Z1i < 4:
 u8 flag2 = Z2r*Z2r + Z2i*Z2i < 4;
 u8 flag3 = Z3r*Z3r + Z3i*Z3i < 4:
 u8 flag4 = Z4r*Z4r + Z4i*Z4i < 4;
 if (!(flag1 || flag2 || flag3 || flag4)) break;
 k1 += flag1; k2 += flag2; k3 += flag3; k4 += flag4;
 Z1r old = Z1r; Z2r old = Z2r; Z3r old = Z3r; Z4r old = Z4r;
 Z1r = Z1r*Z1r - Z1i*Z1i + C1r:
 Z2r = Z2r*Z2r - Z2i*Z2i + C2r:
 Z3r = Z3r*Z3r - Z3i*Z3i + C3r:
 Z4r = Z4r*Z4r - Z4i*Z4i + C4r:
 Z1i = 2.0 * Z1r old * Z1i + v:
 Z2i = 2.0 * Z2r old * Z2i + v:
 Z3i = 2.0 * Z3r_old * Z3i + y;
 Z4i = 2.0 * Z4r_old * Z4i + y;
. . .
```

► Manually unroll the loop to process four elements at once.

# Loop unrolling (+159%)

- ► No branches for the finished elements!
  - ▶ not trivial to make work, compiler cannot do this
  - if |Z| > 2 in some iteration, it will continue to be
- ► size\_x may not be a multiple of 4
  - ► must process remaining elements afterwards

#### Manual vectorisation

```
typedef double v4d __attribute__((vector_size (sizeof(double) *4)));
typedef long int v4i attribute ((vector size (sizeof(long int)*4)));
v4d Cr;
for (int m = 0: m < 4: ++m)
 Cr[m] = view x0 + (j+m) * step x;
double Ci = v:
v4d Zr = \{0\}, Zi = \{0\}, Zr_old = \{0\};
v4i k = \{0\}:
for (int kk = 0: kk < max iter: ++kk) {
 v4i tmp = (Zr*Zr + Zi*Zi) < 4;
 k -= tmp; // Note that vector comparison set all bits
  if (!(tmp[0] || tmp[1] || tmp[2] || tmp[3])) break;
 Zr old = Zr:
 Zr = Zr*Zr - Zi*Zi + Cr:
 Zi = 2.0 * Zr_old * Zi + y;
for (int m = 0: m < 4: ++m)
  memcpv(image+3*m, &colors opt[3*k[m]], 3);
```

▶ Nice and easy to use

### Manual vectorisation

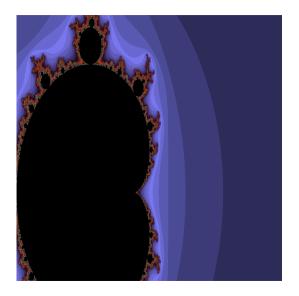
```
typedef double v4d attribute ((vector size (sizeof(double) *4)));
typedef long int v4i attribute ((vector size (sizeof(long int)*4)));
v4d Cr;
for (int m = 0; m < 4: ++m)
 Cr[m] = view_x0 + (j+m) * step_x;
double Ci = v:
v4d Zr = \{0\}, Zi = \{0\}, Zr_old = \{0\};
v4i k = \{0\}:
for (int kk = 0: kk < max iter: ++kk) {
 v4i tmp = (Zr*Zr + Zi*Zi) < 4;
 k -= tmp; // Note that vector comparison set all bits
  if (!(tmp[0] || tmp[1] || tmp[2] || tmp[3])) break;
 Zr old = Zr:
 Zr = Zr*Zr - Zi*Zi + Cr:
 Zi = 2.0 * Zr_old * Zi + y;
for (int m = 0: m < 4: ++m)
  memcpv(image+3*m, &colors opt[3*k[m]], 3);
```

- ► Nice and easy to use
- ► Makes things about 12% slower!

### Domain-specific optimisations

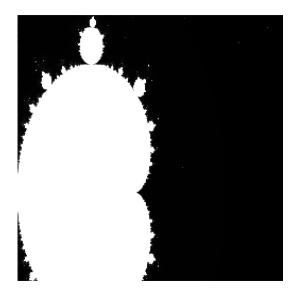
- ▶ Done with routine tricks, now the real work starts
- ▶ Bottleneck is in inner loop, CPU-bound
  - ► Use profiler / custom timing code (see below) to verify
- ► Try to figure out behaviour of the program, have to look at what the code is actually trying to accomplish

### Domain-specific optimisations



- ► Where is the time spent?
  - ► No need to guess, just measure.

### Domain-specific optimisations



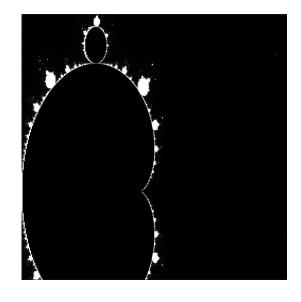
- ► White is more time
- ► The main cardioid is about a third, and quite expensive

# Main cardioid fastpath (+1033%)

```
u64 j;
for (j = 0; j+4 <= size_x; j += 4) {
  while (j < size_x) {
    double a = view_x0 + j*step_x - 0.25;
    double q = a*a + y*y;
    if (q*(q+a) >= y*y * 0.25) break;
    memcpy(image, "\0\0", 3);
    ++j;
    image += 3;
}
if (j+4 > size_x) break;
...
```

- ► Context: This optimisation is only good when the main cardioid makes up a large part of the image!
- ► Use formula to detect the inside (I simply looked it up)
- ► Check is quite cheap, can do it on every pixel
- ▶ Same thing for the bulb on the top (additional +37%)

# Main cardioid fastpath (+1033%)



► Much better.

### Distributed initialisation (+6%)

```
int thread count;
pthread_t threads[64];
int work size:
Mandelbrot call args work args[1000];
atomic int thread index. work index:
void* mandelbrot thread(void* ) {
  while (thread_index < thread_count) {</pre>
    int i = thread_index++;
    if (i >= thread count) break;
    pthread_create(&threads[i], NULL, &mandelbrot_thread, NULL);
  while (work_index < work_size) {</pre>
    int i = work index++:
    if (i >= work size) break:
    Mandelbrot_call_args* p = &work_args[i];
    mandelbrot calculate( ... ):
```

► Let the threads initialise each other

#### Final notes

- ► Don't blindly trust the compiler to do non-trivial optimisations—you know much better which transformations are safe
- ► Look at the actual data, effort spent visualising is seldom wasted
- ightharpoonup Code is now fast enough ( $\sim$ 10ms) that constant overheads (initialisation, synchronisation) become relevant again
- ► No changes to the calculation (e.g. low precision approximation or such) as Mandelbrot is sensitive to rounding errors