

# Compilers, assignment 6 theory

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25.03.2014

## Problem 1, Optimization

Original flow graph:

```
-----  
B1: i = 1  
-----  
B2: if i > b GOTO B4  
-----  
B3: t = a * c  
    i = i + t  
    j = i  
    d = 0  
    d = j + 2  
    e = i + t  
    f = f * e  
    GOTO B2  
-----  
B4:  
-----
```

### 1.a) Common subexpression elimination

If the same expression is computed multiple times, reuse it. Saves computation.

```
-----  
B1: i = 1  
-----  
B2: if i > b GOTO B4  
-----  
B3: t = a * c  
    i = i + t  
    j = i  
    d = 0  
    d = j + 2  
    e = i + t          ; Can't eliminate because i was reassigned  
    f = f * e  
    GOTO B2  
-----  
B4:  
-----
```

## 1.b) Copy Propagation

After assignment  $x = y$ , replace uses of  $x$  with  $y$ . Replace until  $x$  is assigned again. Helps with register allocation.

```
-----  
B1: i = 1  
-----  
B2: if i > b GOTO B4  
-----  
B3: t = a * c  
    i = i + t  
    j = i  
    d = 0  
    d = i + 2    ; Copy Propagation  
    e = i + t  
    f = f * e  
    GOTO B2  
-----  
B4:  
-----
```

## 1.c) Code Motion

Hoist static computations outside of loops (must have no externally visible side-effects). Saves computation.

```
-----  
B1: i = 1  
-----  
B2: t = a * c    ; Code Motion  
    d = 0        ; Code Motion  
    if i > b GOTO B4  
-----  
B3: i = i + t  
    j = i  
    d = j + 2  
    e = i + t  
    f = f * e  
    GOTO B2  
-----  
B4:  
-----
```

### 1.d) Dead Code elimination

If effect of a statement is never observed, eliminate the statement. Saves computation, space.

```
-----  
B1: i = 1  
-----  
B2: if i > b GOTO B4  
-----  
B3: t = a * c  
    i = i + t  
    j = i  
    d = j + 2    ; Removed d = 0.  
    e = i + t  
    f = f * e  
    GOTO B2  
-----  
B4:  
-----
```

*(This task is interpreted as a local optimization pass. If this was the complete code, a lot more code could have been removed.)*

## Problem 2, Optimization

Consider the following c code:

```
for(int i = 0; i < n; i++){
    sum = 4 * i;
    for(int j = 0; j < m; j = j + i){
        a = a + b * 2;
    }
}
```

### 2.a) What is an induction variable, and what is reduction in strength?

**Induction variable:** A loop variable whose value depends linearly on the iteration number

**Strength reduction** Replace expensive operations (multiplication, division) by cheap ones (addition, subtraction, shifts)

### 2.b) Convert the code to a three-address flow graph

**Notice:** *Provided code contains infinite loop :(*

```
B1: int i = -1
-----
B2: i = i+1
    if i >= n GOTO B6
-----
B3: sum = 4 * i
    int j = -i
-----
B4: j = j + i
    if j >= m GOTO B2
-----
B5: int _bb = b * 2
    a = a + _bb
    GOTO B4
-----
B6:
-----
```

## 2.c) Optimize the flow graph using strength reduction and induction variable elimination

### 2.c.i) Strength Reduction

```
B1: int i = -1
    int sum = 0
-----
B2: i = i+1
    if i >= n GOTO B6
-----
B3: sum = sum + 4
    int j = -i
-----
B4: j = j + i
    if j >= m GOTO B2
-----
B5: _bb = b + b
    a = a + _bb
    GOTO B4
-----
B6:
-----
```

### 2.c.ii) Induction Variable Elimination

*Plan of attack, in c:*

```
int _a = a; // Initial value for a
for(; a < (_a + (b*2*m)/i); a = a + b * 2){
}
```

*IR Code:*

```
B1: int i = -1
    int sum = 0
    int _bb = b + b // code motion :D
-----
B2: i = i+1
    if i >= n GOTO B6
-----
B3: sum = sum + 4
    int _condition = _bb * m
    _condition = _condition / i
    _condition = _condition + a
-----
B4: if a >= _condition GOTO B2
-----
B5: a = a + _bb
    GOTO B4
-----
B6:
-----
```

### Problem 3

#### 3.a) What does it mean for a definition to reach a pint in the code?

The definition is observable at that point in the code.

#### 3.b) Perform reaching definition analysis

| B  | IN                          | kill       | gen          | OUT                            |
|----|-----------------------------|------------|--------------|--------------------------------|
| B1 | {}                          |            | {d1, d2, d3} | {d1, d2, d3}                   |
| B2 | {d1, d2, d3}                | {d1}       | {d4, d5}     | {d2, d4, d5}                   |
| B3 | {d2, d3, d4, d5}            | {d2}       | {d6, d7}     | {d4, d5, d6, d7}               |
| B4 | {d2, d4, d4, d5}            | {d2}       | {d8, d9}     | {d4, d5, d8, d9}               |
| B5 | {d3 d4, d5, d6, d7, d8, d9} | {d3, {d5}} | {d10, d12}   | {d4, d6, d7, d8, d9, d10, d12} |

Table 1: Reaching definition analysis - Iteration 1

| B  | IN   | kill     | gen          | OUT  |
|----|--|----------|--------------|--|
| B1 | {d4, d6, d7, d8, d9}, d10, d12}            |          | {d1, d2, d3} | {d1, d2, d3, d4, d6, d7, d8, d9, d10, d12} |
| B2 | {d1, d2, d3, d4, d6, d7, d8, d9, d10, d12} | {d1}     | {d4, d5}     | {d2, d3, d4, d5, d6, d7, d8, d9, d10, d12} |
| B3 | {d2, d3, d4, d5, d6, d7, d8, d9, d10, d12} | {d2}     | {d6, d7}     | {d3, d4, d5, d6, d7, d8, d9, d10, d12}     |
| B4 | {d3, d4, d5, d6, d7, d8, d9, d10, d12}     | {d2}     | {d8, d9}     | {d3, d4, d5, d6, d7, d8, d9, d10, d12}     |
| B5 | {d3, d4, d5, d6, d7, d8, d9, d10, d12}     | {d3, d5} | {d10, d12}   | {d4, d6, d7, d8, d9, d10, d12}             |

Table 2: Reaching definition analysis - Iteration 2

#### 3.c) Explain how a compiler can use the results to determine that the variable **b** must be a constant at the start of the exit node

We know that  $IN[exit\_node] = OUT[B5]$ . All **b**-entries in  $OUT[B5]$  comes from B3 or B4. In these blocks, both assignments to **b** are constants.

## Problem 4, Register Allocation

```
a = b + c
d = a + b
e = 2 * a
a = e + c
b = d + a
c = e - 2
```

4. a) What does it mean for a variable to be *live* at a point in the code?

A variable being live at a point in code means that it will be used at a later point in code. Liveness analysis is a *backwards* flow of information.

4.b) Perform live variable analysis on the code above

(start from bottom)

| PP        | OUT       | def | use    | IN        |
|-----------|-----------|-----|--------|-----------|
| a = b + c | {c, a, b} | {a} | {b, c} | {c, b}    |
| d = a + b | {d, c, a} | {d} | {a, b} | {c, a, b} |
| e = 2 * a | {e, d, c} | {e} | {a}    | {d, c, a} |
| a = e + c | {e, d, a} | {a} | {e, c} | {e, d, c} |
| b = d + a | {e}       | {b} | {d, a} | {e, d, a} |
| c = e - 2 | {}        | {c} | {e}    | {e}       |

Table 3: Live variable analysis

4.c) Draw the register interference graph for the following code

```
a = b + c      // {c, b}
d = a + b      // {c, a, b}
e = 2 * a      // {d, c, a}
a = e + c      // {e, d, c}
b = d + a      // {e, d, a}
c = e - 2      // {e}
               // {}
```

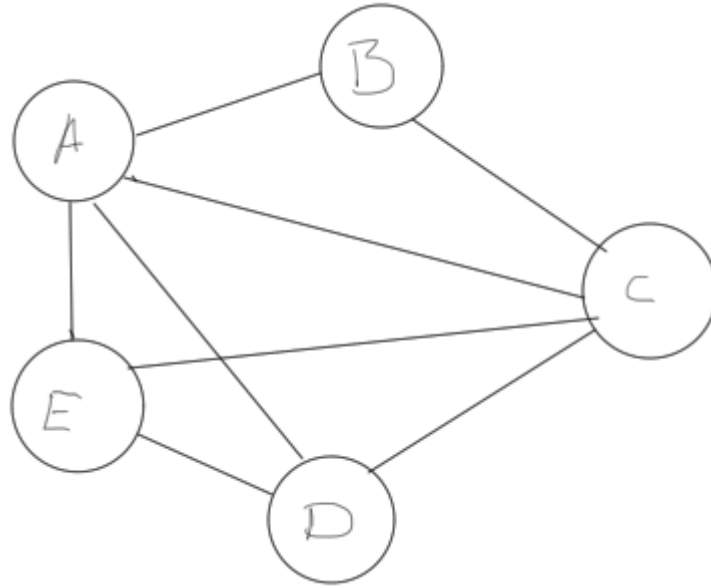


Figure 1: register inference graph

d) How many registers are needed to avoid register spills for the above code (assuming a hardware architecture capable of three-address code (e.g. ARM))?

1. Build stack by pushing the least connected node not yet pushed

bdeac // stack grows right

2. Pop nodes and assign nonconflicting colors, then add back to graph.

**Four** registers are needed.



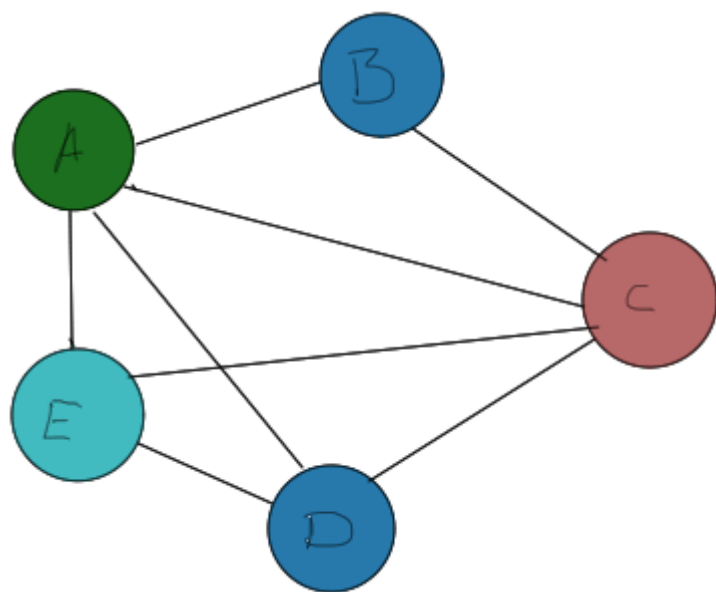


Figure 2: graph coloring