

FIR Filter Types:

Type	$A(\omega)$	$\theta(\omega)$
I	$h(M) + 2 \sum_{n=0}^{M-1} h(n) \cos((M-n)\omega)$	$-M\omega$
II	$2 \sum_{n=0}^{M-1} h(n) \cos((M-n)\omega)$	$-M\omega$
III	$2 \sum_{n=0}^{M-1} h(n) \sin((M-n)\omega)$	$-M\omega + \frac{\pi}{2}$
IV	$2 \sum_{n=0}^{\frac{N}{2}-1} h(n) \sin((M-n)\omega)$	$-M\omega + \frac{\pi}{2}$
	$M = \frac{N-1}{2}$	

Ideal Impulse Response Truncation:

$$d[n] = \text{IDTFT}\{D^f(\omega)\} = \frac{1}{2\pi} \int_{-\pi}^{\pi} D^f(\omega) e^{j\omega n} d\omega$$

$$A^f(\omega) = \frac{1}{2\pi} (D^f(\omega) \odot W^f(\omega)); W(\omega) \equiv \text{Window Function}$$

$$W^f(\omega) = \text{DTFT}\{w[n]\}$$

$$H^f(\omega) = \frac{1}{2\pi} (D^f(\omega) \odot W^f(\omega)) e^{-jM\omega}$$

$$\therefore h[n] = d[n-M]w[n]$$

*For a fixed length window, there is a tradeoff between main lobe width and relative side lobe height. They may not be made arbitrarily good at the same time.

*To reduce spectral leakage, a window with low side lobes is required

*To reduce frequency smearing, a window with narrow main-lobe is required

Non-adjustable windows:

$$\text{For: } w[n] = a - b \cos\left(\frac{2\pi(n+1)}{N+1}\right) + c \cos\left(\frac{4\pi(n+1)}{N+1}\right)$$

Window	a	b	c
Rectangular	1	0	0
Hann	0.5	0.5	0
Hamming	0.54	0.46	0
Blackman-Harris	0.52	0.5	0.8

Zero Location of a REAL VALUED FIR Filter:

- Zeros location of a real valued impulse response exists in sets of 4: $\{z_0, z_0^*, \frac{1}{z_0}, \frac{1}{z_0^*}\}$
- Zeros on the unit circle ($z_0 = e^{j\omega_0}$) exists in sets of two (not $z_0 = \pm 1$): $\{z_0 = e^{\pm j\omega_0}\}$
- Zeros on the real axis ($z_0 = a$) exists in sets of two: $\{z_0, \frac{1}{z_0}\}$
- Zeros at ± 1 does not imply the existence of zeros at other location.

STFT:

Parameters: R: Block length, $w[n]$: Specific window function, L: Number of samples between adjacent blocks, N: FFT length after zero padding.

$$X[\omega, m] = \text{STFT}\{x[n]\} = \text{DTFT}\{x[n-m]w[n]\} = \sum_{n=-\infty}^{\infty} x[n-m]w[n] \exp(-j\omega n)$$

$$X[\omega, m] = \sum_{n=0}^{R-1} x[n-m]w[n] \exp(-j\omega n)$$

$$\Rightarrow X^d[k, m] = \text{DFT}_N \left[\left[x[n-m]w[n] \right]_{n=0}^{R-1}, \bar{\delta}_{N-R} \right]$$

Least Square Filter Design:

General Error Formula (L_p Error): $E_p = \int_0^\pi W(\omega) |A(\omega) - D(\omega)|^p d\omega$

$\epsilon_2 = \int_0^\pi W(\omega) (A(\omega) - D(\omega))^2 d\omega$; W: non-negative weighting function, A: Amplitude response, D: Desired amplitude response.

In order to minimize square error:

$$\sum_{n=0}^M Q[k, n]a[n] = b[k]; \quad 0 \leq k \leq M$$

$$Q[k, n] = \frac{1}{\pi} \int_0^\pi W(\omega) \cos(n\omega) \cos(k\omega) d\omega \quad b[k] = \frac{1}{\pi} \int_0^\pi W(\omega) D(\omega) \cos(k\omega) d\omega$$

$$\begin{bmatrix} Q[0,0] & Q[0, M] \\ Q[1,0] & \cdots & Q[1, M] \\ \vdots & \ddots & \vdots \\ Q[M,0] & \cdots & Q[M, M] \end{bmatrix} \begin{bmatrix} a[0] \\ a[1] \\ \vdots \\ a[M] \end{bmatrix} = \begin{bmatrix} b[0] \\ b[1] \\ \vdots \\ b[M] \end{bmatrix} \Rightarrow \vec{a} = \mathbf{Q}^{-1} \vec{b}$$

$$Q[k, n] = \frac{1}{2} Q_1[k, n] + \frac{1}{2} Q_2[k, n] \quad Q_1[k, n] = \frac{1}{\pi} \int_0^\pi W(\omega) \cos((k-n)\omega) d\omega = q[k-n]$$

$$Q_2[k, n] = \frac{1}{\pi} \int_0^\pi W(\omega) \cos((k+n)\omega) d\omega = q[k+n] \quad q[n] = \frac{1}{\pi} \int_0^\pi W(\omega) \cos(n\omega) d\omega$$

$$q[n] = \text{DTFT}^{-1}\{W(\omega)\} \quad b[n] = \text{DTFT}^{-1}\{W(\omega)D(\omega)\}$$

Special Case $W(\omega) = 1$:

$$a[0] = \frac{1}{\pi} \int_0^\pi D(\omega) d\omega \quad a[n] = \frac{2}{\pi} \int_0^\pi D(\omega) \cos(n\omega) d\omega; \quad 1 \leq n \leq M$$

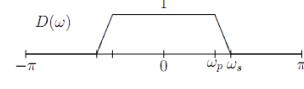
$$h[n] = \frac{1}{\pi} \int_0^\pi D(\omega) \cos((n-M)\omega) d\omega; \quad 0 \leq n \leq N$$

$$\therefore h[n] = d[n-M]; \quad 0 \leq n \leq N, \text{ Where } d[n] = \text{DTFT}^{-1}\{D(\omega)\}$$

Ideal Low Pass Filter (LPF):

$$h[n] = \frac{\omega_0}{\pi} \text{sinc}\left[\frac{\omega_0}{\pi}(n-M)\right]; \quad 0 \leq n \leq N; \quad \text{sinc}(\theta) = \frac{\sin(\pi\theta)}{\pi\theta}$$

Low Pass Filter with Transition Band:



$$D(\omega) = D_1(\omega) * D_2(\omega)$$

$$d[n] = 2\pi d_1[n] d_2[n]$$

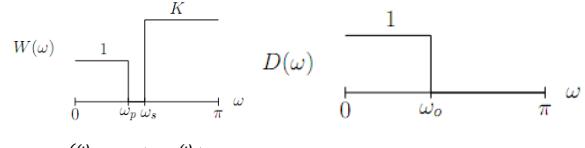
$$d[n] = \frac{\omega_0}{\pi} \text{sinc}\left[\frac{\omega_0}{\pi}n\right] \text{sinc}\left[\frac{\Delta}{\pi}n\right]$$

p^{th} Order LPF:

$$d[n] = \frac{\omega_0}{\pi} \text{sinc}\left[\frac{\omega_0}{\pi}n\right] \left[\text{sinc}\left[\frac{\Delta}{\pi}n\right] \right]^p$$

$$\Delta = \frac{(\omega_p - \omega_s)}{p}$$

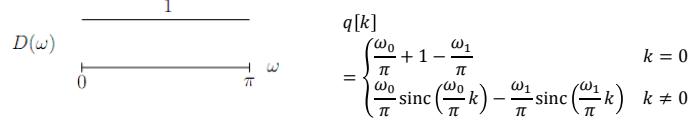
LPF Weighted Square Error:



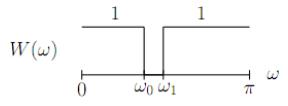
$$q[k] = \begin{cases} \frac{\omega_p}{\pi} + K\left(1 - \frac{\omega_s}{\pi}\right) & k = 0 \\ \frac{\omega_p}{\pi} \text{sinc}\left(\frac{\omega_p}{\pi}k\right) - K \frac{\omega_s}{\pi} \text{sinc}\left(\frac{\omega_s}{\pi}k\right) & k \neq 0 \end{cases}$$

$$b[k] = \frac{\omega_p}{\pi} \text{sinc}\left(\frac{\omega_p}{\pi}k\right)$$

Notch Filter:



$$q[k] = \begin{cases} \frac{\omega_0}{\pi} + 1 - \frac{\omega_1}{\pi} & k = 0 \\ \frac{\omega_0}{\pi} \text{sinc}\left(\frac{\omega_0}{\pi}k\right) - \frac{\omega_1}{\pi} \text{sinc}\left(\frac{\omega_1}{\pi}k\right) & k \neq 0 \end{cases}$$



$$b[k] = q[k]$$

Discrete Square Error:

$$W_k = W\left(\frac{2\pi}{L}k\right); \quad D_k = D\left(\frac{2\pi}{L}k\right); \quad 0 \leq k \leq L-1$$

$$q[n] \approx \frac{1}{L} \sum_{k=0}^{L-1} W_k \exp\left(jn\frac{2\pi}{L}k\right) \quad \therefore q[n] \approx \text{DFT}_L^{-1}\{W_k\} \quad \text{and} \quad b[n] \approx \text{DFT}_L^{-1}\{D_k W_k\}$$

Kaiser Minimum Filter Length Formula:

$$N \approx \frac{-20 \log_{10}(\sqrt{\delta_s \delta_p}) - 13}{14.6 \Delta F} + 1$$