CS351 Introduction to Computer Graphics

Test A: Shape

	0 pts max. in 31, 2016
(netID is 6 letters + 6digits, e.g. jet861) INSTRUCTIONS: Edit this file in Microsoft Word or in Google Docs to enter your HIGHL answers. Upload your own file on Canvas before the end of the day Sunday, Jan 31, 2016. 1) Suppose that: Our HTML5 on-screen display canvas is square (height=width) and displays Web and we wrote a Javascript 'drawAxes()' function that causes WebGL to:draw an arrow from the origin to (+1,0,0) to depict the x axis, anddraw an arrow from the origin to (0,+1,0) to depict the y axis, and In JavaScript we send the 4x4 'modelMatrix' as a uniform to the graphics hardware In GLSL, our Vertex shader applies that uniform matrix to all vertex positions before the on-screen result of this sequence of statements is:	GL output,
modelMatrix.setIdentity(); // set to identity matrix. drawAxes(); // draw it!	
(HINT: All arrows stay entirely within the square canvas for all answers) 1a) (5pts) Sketch the on-screen result if you used these statements instead:	
modelMatrix.setIdentity(); modelMatrix.scale(0.5, 0.5, 0.5); // shrink to 50% drawAxes(); // draw it! ANS: >>>>	1->
1b) (5pts) Sketch the on-screen result if you used these statements instead:	
modelMatrix.setIdentity(); modelMatrix.scale(0.5, 0.5, 0.5); // shrink to 50% modelMatrix.translate(1.0, 0.0, 0.0); // move +x by 1 drawAxes(); // draw it! ANS: >>>>	1,
1c) (5pts) Sketch the on-screen result if you used these statements instead:	
modelMatrix.setIdentity(); modelMatrix.translate(0.5, 0.0, 0.0); // move +x by .5 modelMatrix.scale(0.5, 0.5, 0.5); // shrink to 50% modelMatrix.rotate(-45.0,0.0,0.0,1.0);// z-axis rotate drawAxes(); // draw it! ANS: >>>>	3
1d) (5pts) Sketch the on-screen result if you used these statements instead:	
<pre>modelMatrix.setIdentity(); modelMatrix.translate(0.5, 0.0, 0.0); // move +x by .5 modelMatrix.scale(0.5, 0.5, 0.5); // shrink to 50% modelMatrix.rotate(-45.0,0.0,0.0,1.0);// z-axis rotate modelMatrix.translate(-1.0, 0.0, 0.0);// move +x by 1 drawAxes(); // draw it! ANS: >>>></pre>	Z,

2) (16pts) TRUE/FALSE: (copy-and-paste your choice of these highlighted answers "True" or "False")

- a) True Drawing commands for WebGL and drawing commands for HTML5 'canvas' elements use different on-screen drawing axes; one has its origin at the upper left corner.
- True WebGL requires users to specify all vertex positions using real values (float/double). This requirement ensures that limited precision never introduces rendering flaws on-screen.
- WebGL provides its own built-in functions that can create a 4x4 matrix for translation, for rotation, or for scale, each from a single function call, as well as a push-down stack for them.
- d) All the many parameters kept as state variables by WebGL, such as background color, buffer bindings, depth testing, etc., are 'write-only': you can't read any of their current values.
- e) True Every WebGL/HTML5/JavaScript program that can draw WebGL drawing primitives on-screen (e.g. TRIANGLES) must include both a 'Vertex Shader' and a 'Fragment Shader'.
- With proper selection of 'stride' and 'offset', WebGL can render the contents of a vertex buffer object (VBO) that holds 100 vertex positions, followed 100 vertex colors, followed by 100 vertex surface normals. In this VBO, the attributes are NOT interleaved!
- WebGL permits you to use the same 'uniform' variable to send values to both the Vertex Shader and Fragment Shader. If JavaScript sets its value, then both shaders can use it.
- h) WebGL itself provides built-in functions for mouse, keyboard, and window-system interactions. We use HTML and JavaScript functions instead because they're more convenient.

HIGHLIGHT your one choice to mark your answer.

- 3) (4pt) What are the dimensions of the 'Canonical View Volume' (CVV) in openGL?
 - a) adjustable—specified indirectly HTML commands for 'canvas' object where WebGL renders.
 - **b)** adjustable—call the gl.setCVV() command. Default is unit cube: (+/-1, +/-1, +/-1))
 - c))Fixed—a unit cube centered at the origin: (+/-1, +/-1, +/-1)
 - d) Fixed—a unit cube, with x,y,z origin shown at the lower-left corner of the display window.
 - e) Fixed—a unit cube, with x,y,z origin shown at the upper-left corner of the display window.
- **4)(3pt)** Calculate the area of a triangle whose sequence of vertices lie at these three (x,y,z) positions: (1,2,3), (-3,3,-4), (3,-4,5). Briefly, show your work in the space below.

(HOW? see assigned readings: Chap 2,3 Lengyel "Math for 3D..." posted on Canvas)

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$$A = \int S(s-a)(s-b)(s-c), \quad S = \begin{cases} a+b+c \\ 2 \end{cases}$$

$$Area = (23.07)$$

$$bz 6.63 \quad c = 12.88 \quad s = 13.97$$

5)(3pt) Calculate the surface normal vector for that same triangle: be sure to 'normalize' the vector to ensure its length is 1.0. (Again, see Lengyel "Math for 3D..." reading posted on Canvas).

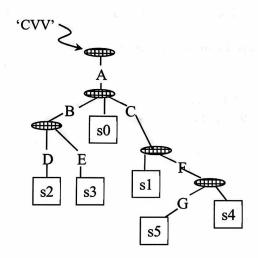
normal vector $(nx,ny,nz) == (-\sqrt{37,-13},.49)$ (write 3 numbers, not expressions!)

Normal = A & B A = (1+3) + (2-3) - + (3+4) = 4 - - + 7 k
=-407-65+226 B= (1-3) + (2+4) - + (3-5) = -27+6 = -27 k
-> normal ze
$$|\nabla I|$$

Scene Graph:

This 'scene graph' describes a jointed 3D object:

- -- Each letter is a transformation node (e.g. holds a 4x4 matrix that combines rotation, translation, scale, etc.)
- -- Each gridded ellipse is a 'group' node, where we have uniquely defined 'drawing axes' (a coordinate system)
- --Each square holds vertices (fixed, in a VBO) & shape-drawing fcns (e.g. 'drawAxes()', 'drawCube()', etc.)



The root of the tree shown begins in the 'CVV' coordinate system, and each leaf of the tree ends in its own separate coordinate system where we draw a shape (s0,s1,s2, etc.), defined by fixed sets of vertices.

RECALL THAT:

All our matrix transformation commands presume:

- a) Vertices are 4-element column vectors;
- b) When the current transform matrix [M] multiplies a given vertex v to make v', we get v' = [M]v, and
- c) Any transform command (e.g. rotate(), translate(), scale()) multiplies the current matrix M with a new matrix that 'precedes' it's effect on vertices. Thus a call to rotate() will replace current matrix [M] with the result of this matrix multiply: [M][R], which we write as [MR]. If applied to the coordinate values for a vertex, the result is the same as multiplying by [R], and then by [M]. *BUT* we could also interpret these same calculations as: "Starting from the CVV, we first transform the drawing axes by [M], then transform these new drawing axes by [R]."

6) (8pts) Suppose we write software that traverses the tree and draws the entire scene, using pushMatrix() and popMatrix() as necessary. When we issue the drawing commands contained in scene-graph node s5,

what are the contents of our current matrix? (HIGHLIGHT YOUR ONE ANSWER)

a) [A]
b) [G]
c) [ACFG]
d) [GFCA]

- d) [GFCA] e) [AGCF]
- f) [GAFC]
- g) Something else:_

7) (6pts) List all transform nodes that can modify the on-screen result for each shape. For example, shape s2 might change on-screen if we modified transform D, but G can't change s2. Write your answers as comma-separated lists of letters, such as (A,B,C,D,E).

s0:<u>A</u> s3

s1: AC s4: ACF

s2: ABD s5: ACFG

VERTEX / VECTOR MATH:

Use these x,y,z coordinates for the 3D points P0, P1, the origin, and the 3D vectors V0,V1:

, , , , , , , , , , , , , , , , , , , ,				, - , - , - , - , - , - , - , - , - , -	r				0		
NAME:	x,	У,	z,	W			NAME:	x,	У,	z,	W
PO:	1,	2,	3	?			V0:	3,	2,	1	?
P1:-							V1:	0,	4,	3	?
Orig:	0.	0.	0	?							

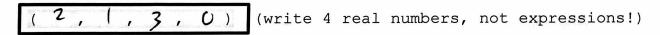
- 8)(4pts) What are the correct 'w' values for P0 and P1?

 What are the correct 'w' values for V0 and V1?

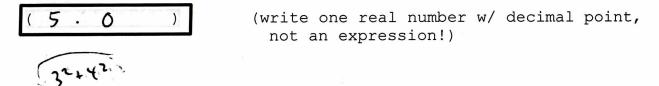
 What is the correct 'w' value for (P0-P1)?

 What is the correct 'w' value for (P0-V0)?

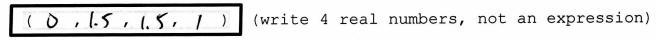
 What is the correct 'w' value for (P0-V0)?
- 9) Find your answer using 3-D homogeneous coordinates (e.g. a 4-tuple; a column of 4 numbers):
 a) (3pts) Find a new vector that points from P1 to P0: (P1→P0)



b) (3pts) Find the length of vector V1 given above:



c) (3pts) Find the point halfway between points P0 and P1:



d) (3pts) Find the dot product of vectors v0 and v1:

e) (4pts) Find vector perpendicular to both v0 and v1, with z <0

$$(2,-9,(2,6))$$
 (write 4 numbers, not expressions!)

