

Solving Binary Consensus Problem with Synchronous Paxos Algorithm

CS403/534 - Distributed Systems

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PA3 Solution Report

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- 1) At first have imported the needed libraries and defined the default IP address and first PORT. Also have defined the context of zmq as global so all of the processes will have it by default. Inside the main part, first I check if the number of arguments passed are correct or not. If less or more arguments given display an error and guide for correct usage. If the arguments passed are correct numbered and typed, it will create “numProc” many processes with “PaxosNode” function as target. And lastly, program will wait for all of the processes to finish.

```
1  import sys
2  from multiprocessing import Process
3  import random
4  import zmq
5
6  IP = "127.0.0.1"
7  PORT = 5577
8  context = zmq.Context()
9
10 > def PaxosNode(ID, prob, N, val, numRounds): ...
124
125 if __name__ == "__main__":
126     if len(sys.argv) != 4:
127         print("Usage: python paxos.py [NUM_NODES] [CRASH_PROB] [NUM_ROUNDS]")
128         sys.exit(1)
129
130     numProc = int(sys.argv[1])
131     prob = float(sys.argv[2])
132     numRounds = int(sys.argv[3])
133     print(f"NUM NODES: {numProc}, CRASH PROB: {prob}, NUM ROUNDS: {numRounds}")
134
135     nodes = []
136     for i in range(numProc):
137         initVal = random.choice([0, 1])
138         newNode = Process(target=PaxosNode, args=(i, prob, numProc, initVal, numRounds,))
139         newNode.start()
140         nodes.append(newNode)
141
142     for i in range(numProc):
143         nodes[i].join()
144
```

- 2) “PaxosNode” function has 3 parts, first is the part that common functions that will do network operations. “send”, “sendFailure”, and “broadcastFailure”. Other than these functions, in this part the needed PULL and PUSH sockets are created using zmq. Lastly, the variables that will store the history of decisions are defined with default values. The important function among those 3, is the “send” because eventually other 2 functions use this function. The difference of this with others is that in others depending on the probability, randomly instead of message, a crash message may be sent.

```

10 def PaxosNode(ID, prob, N, val, numRounds):
11     def send(msg, sender, destination):
12         pushes[destination].send_json({'msg': msg, 'id': sender})
13
14     def sendFailure(msg, proposer, i, prob):
15         crash_status = random.choices([True, False], weights=(prob, 1-prob), k=1)[0]
16
17         if crash_status:
18             send(f"CRASH {proposer}", proposer, i)
19         else:
20             send(msg, proposer, i)
21
22     def broadcastFailure(msg, proposer, N, prob):
23         for i in range(N):
24             sendFailure(msg, proposer, i, prob)
25
26     pull = context.socket(zmq.PULL)
27     pull.bind(f"tcp://{IP}:{PORT+ID}")
28
29     pushes = []
30     for i in range(N):
31         push = context.socket(zmq.PUSH)
32         push.connect(f"tcp://{IP}:{PORT+i}")
33         pushes.append(push)
34
35     maxVotedRound = -1
36     maxVotedVal = None
37     proposeVal = None
38     decision = None
39
40 > for currRound in range(numRounds): ...

```

- 3) The part 2 is the part when the node is Leader of that round will run. Basically, at first it will “broadcastFailure(START)” and will wait for N responses. If number of responses is not more than “N/2” it will broadcast “ROUNDCHANGE” to every other node. If number of responses are more than “N/2” then it will propose the voted value of latest voted round unless this is the first round. If this is first round then it will propose its own value. And again, will wait for N responses. If number of successful votes are more than “N/2” then it will announce that he has decided has his proposal as decision. And the round ends whether it has changed round or decided on a value or not.

```

40     for currRound in range(numRounds):
41         if currRound % N == ID:
42             print(f"ROUND {currRound} STARTED WITH INITIAL VALUE {val}")
43             broadcastFailure("START", ID, N, prob)
44             tmp_maxVotedRound = -1
45             tmp_maxVotedVal = -1
46
47             join_count = 0
48             seenJoin = set()
49             while len(seenJoin) != N:
50                 tmp = pull.recv_json()
51                 if not tmp["id"] in seenJoin:
52                     seenJoin.add(tmp["id"])
53                     newMsg = tmp["msg"]
54                     print(f"LEADER OF {currRound} RECEIVED IN JOIN PHASE: {newMsg}")
55                     if not "CRASH" in newMsg:
56                         join_count += 1
57                         if "JOIN" in newMsg:
58                             parsedMsg = newMsg.split()
59                             acc_maxVotedRound = int(parsedMsg[1])
60                             if acc_maxVotedRound > -1:
61                                 acc_maxVotedVal = int(parsedMsg[2])
62                                 if tmp_maxVotedRound < acc_maxVotedRound:
63                                     tmp_maxVotedRound = acc_maxVotedRound
64                                     tmp_maxVotedVal = acc_maxVotedVal
65                             else:
66                                 if tmp_maxVotedRound < maxVotedRound:
67                                     tmp_maxVotedRound = maxVotedRound
68                                     tmp_maxVotedVal = maxVotedVal
69
70             if join_count <= N / 2:
71                 print(f"LEADER OF ROUND {currRound} CHANGED ROUND")
72                 for i in range(N):
73                     if i != ID:
74                         send("ROUNDCHANGE", ID, i)
75             else:
76                 maxVotedRound = tmp_maxVotedRound
77                 maxVotedVal = tmp_maxVotedVal
78                 if maxVotedRound == -1:
79                     maxVotedVal = val
80                 proposeVal = maxVotedVal
81                 print(f"LEADER OF ROUND {currRound} PROPOSES {proposeVal}")
82                 broadcastFailure(f"PROPOSE {proposeVal}", ID, N, prob)
83
84                 vote_count = 0
85                 seenVotes = set()
86                 while len(seenVotes) != N:
87                     tmp = pull.recv_json()
88                     if not tmp["id"] in seenVotes:
89                         seenVotes.add(tmp["id"])
90                         newMsg = tmp["msg"]
91                         print(f"LEADER OF {currRound} RECEIVED IN JOIN VOTE: {newMsg}")
92                         if "PROPOSE" in newMsg or "VOTE" in newMsg:
93                             vote_count += 1
94
95                 if vote_count > N / 2:
96                     decision = proposeVal
97                     maxVotedRound = currRound
98                     maxVotedVal = proposeVal
99                     print(f"LEADER OF {currRound} DECIDED ON VALUE {decision}")
100             else:

```

- 4) Last part is the code for node when it is an Acceptor. Basically, acceptor is inside an infinite loop until it receives a message. After receiving "START" it will send its own join message with "sendFailure" but if it receives a crash message it will send crash message back. Then it

waits for propose phase message, which can be either PROPOSE or CRASH or ROUNDCHANGE. If it is ROUNDCHANGE, nothing will happen and it will move to next round. If it is crash, it will send it back to Leader. If it is PROPOSE, then it will update its local history variables and “sendFailure(VOTE)”. In any of 3 cases now the round has ended.

```
100     else:
101         while True:
102             startMsg = pull.recv_json()['msg']
103             if len(startMsg) > 0:
104                 print(f"ACCEPTOR {ID} RECEIVED IN VOTE JOIN: {startMsg}")
105
106                 if "CRASH" in startMsg:
107                     send(f"CRASH {currRound % N}", ID, currRound % N)
108                 else:
109                     sendFailure(f"JOIN {maxVotedRound} {maxVotedVal}", ID, currRound % N, prob)
110
111             while True:
112                 proposeMsg = pull.recv_json()["msg"]
113                 if len(proposeMsg) > 0:
114                     print(f"ACCEPTOR {ID} RECEIVED IN VOTE PHASE: {proposeMsg}")
115
116                     if "PROPOSE" in proposeMsg:
117                         maxVotedRound = currRound
118                         maxVotedVal = int(proposeMsg.split()[1])
119                         sendFailure("VOTE", ID, currRound % N, prob)
120                     elif "CRASH" in proposeMsg:
121                         send(f"CRASH {currRound % N}", ID, currRound % N)
122                     break
123             break
```