

Synchronization-III Semaphores

Didem Unat Lecture 11

COMP304 - Operating Systems (OS)

Mutex Locks

```
do {
    acquire lock
        critical section
    release lock
        remainder section
} while (true);
```

```
acquire() {
    while (!available)
    ; /* busy wait */
    available = false;;
}

release() {
    available = true;
}
```

- Software interface for locks
- Calls to acquire() and release()
 must be atomic
 - implemented via hardware atomic instructions
- But this solution requires busy waiting
 - And also called a spinlock

Semaphores

- We want to be able to write more complex constructs
 - need a language to do so. We define semaphores which we assume are atomic operations.
- Semaphores are more general synchronization tools
 - Operating System Primitive
 - Two standard atomic operations modify semaphore variable S: wait()
 and signal()

```
WAIT (S):

while (S <= 0);
S = S - 1;
```

```
SIGNAL (S):
S = S + 1;
```

• As given here, these are not atomic as written in "macro code". We define these operations, however, to be atomic (Protected by a hardware lock.)

Critical Section for n Processes

• Shared semaphore:

```
semaphore mutex = 1; //initial value
```

• Process Pi:

```
do {
    wait(mutex)
        critical section
    signal(mutex)
        remainder section
} while (true);
```

Shared Account Balance Example

semaphore mutex = 1;

```
proc_0() {
    . . .
    /* Enter the CS */
    wait(mutex);
    balance += amount;
    signal(mutex);
    . . .
}
```

```
proc_1() {
    . . .
    /* Enter the CS */
    wait(mutex);
    balance -= amount;
    signal(mutex);
    . . .
}
```

//CS stands for critical section

Semaphore as a general synchronization tool

Provides mutual exclusion

```
Semaphore S = 1; // initialized to 1 or initialized to # of resources
wait (S);
   Critical Section
signal (S);
```

- Counting semaphore integer value can range over an unrestricted domain
 - For example: resources in the hardware: semaphore is initialized to number of printers
- Binary semaphore integer value can range only between 0 and 1; can be simpler to implement
 - This is the same as mutex locks

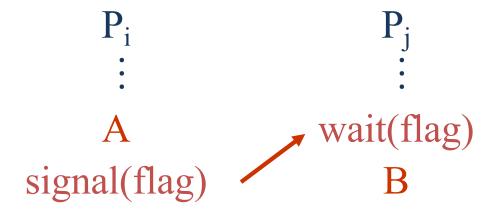
Semaphore as a general synchronization tool

 Semaphores can be used to force synchronization (precedence) if the preceder does a signal at the end, and the follower does wait at beginning.

For example, here we want P1 to execute before P2.

- Execute B in P_i only after A is executed in P_i
- Use semaphore flag initialized to 0

Code:



Classical Problems of Synchronization

Bounded-Buffer Problem

Readers and Writers Problem

Dining Philosophers Problem

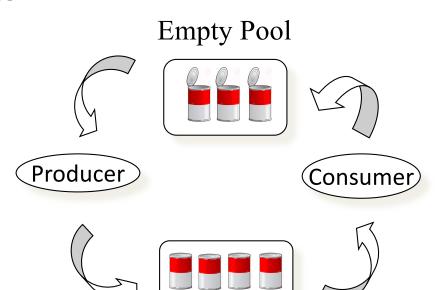
These classical problems are used for testing newly proposed synchronization methods.

- Buffer size: buffer can hold n items
- Binary semaphores
 semaphore mutex;
- Counting semaphores

```
semaphore full, empty;
```

Initially:

```
full = 0, empty = n, mutex = 1
```



Full Pool

This is the same producer / consumer problem as before. But now we'll do it with signals and waits. Remember: a **wait decreases** its argument and a **signal increases** its argument.

Empty and Full are counting semaphores

```
producer:
do {
      /* produce an item in nextp */
      wait (empty); /* Do action
       /* add nextp to buffer */
      signal (empty);
                                          Signals are wrong!
  } while(TRUE);
                                         Producer (consumer)
                                        needs to wake up the
consumer:
                                        consumer (producer)!
do {
     wait (full);
       /* remove an item from buffer to nextc */
      signal (full);
      /* consume an item in nextc */
   } while(TRUE);
```

• Mutex is binary semaphore, Empty and Full are counting semaphores

```
producer:
do {
      /* produce an item in nextp */
      wait (empty); /* Do action
                                                  * /
                                         Does this work for multiple producers
       /* add nextp to buffer */
                                         and consumers?
      signal (full);
                                         Only works for one producer and
                                         consumer. Need the mutex to prevent
  } while(TRUE);
                                         multiple producers writing into the
consumer:
                                         same buffer.
do {
      wait (full);
       /* remove an item from buffer to nextc */
      signal (empty);
      /* consume an item in nextc */
   } while(TRUE);
```

Mutex is binary semaphore, Empty and Full are counting semaphores

```
producer:
do {
      /* produce an item in nextp */
      wait (empty); /* Do action */
      wait (mutex); /* Buffer guard*/
      /* add nextp to buffer */
      signal (mutex);
      signal (full);
                                     We need a mutex in addition
  } while(TRUE);
                                     to empty and full semaphores because
                                     multiple producers (hence consumers)
consumer:
do {
                                     are operating on the same buffer
     wait (full);
      wait (mutex);
       /* remove an item from buffer to nextc */
      signal (mutex);
      signal (empty);
      /* consume an item in nextc */
   } while(TRUE);
```

Semaphores

- Spinlocks (mutexes) are useful in a system since no context switch is required
- A disadvantage of mutex solutions so far:
 - —they all require busy waiting.
- To overcome busy waiting → blocking a process

No busy waiting (blocking) Semaphores

- With each semaphore there is an associated waiting queue:
 - Keeps list of processes waiting on the semaphore
- Two operations:
 - Block place the process invoking the operation on the appropriate waiting queue if semaphore == false
 - Wakeup Wakes up one of the blocked processes upon getting a signal and places the process to ready queue

Blocking Semaphores

```
typedef struct {
   int value;
   struct process *list; /* list of processes waiting on S */
} SEMAPHORE;
```

```
SEMAPHORE s;
wait(s) {
    s.value = s.value - 1;
    if ( s.value < 0 ) {
       add this process to s.list;
       block ();
    }
}</pre>
```

Block – place the process invoking the operation on the appropriate waiting queue if semaphore is not available

```
SEMAPHORE s;
signal(s) {
    s.value = s.value + 1;
    if ( s.value <= 0 ) {
       remove a process P from s.list;
       wakeup(P);
    }
}</pre>
```

Wakeup – Wakes up one of the blocked processes upon getting a signal and places the process to ready queue

Deadlock and Starvation

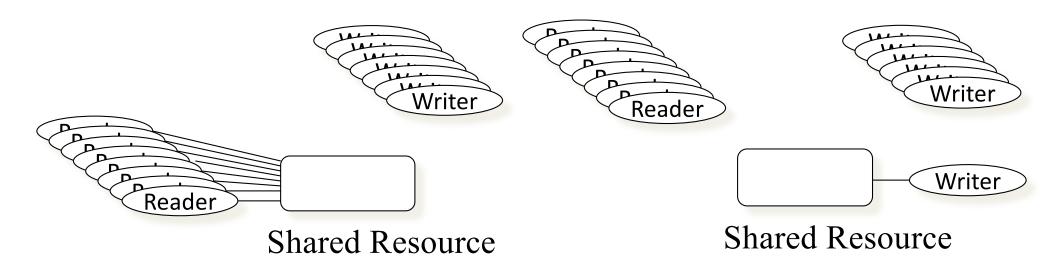
- **Deadlock** two or more processes are waiting indefinitely for an event that can be caused by only one of the waiting processes.
- Let S and Q be two semaphores initialized to 1

```
P_0 P_1 wait(S); wait(Q); wait(Q); i. i. i. signal(S); signal(Q) signal(S);
```

- **Starvation** indefinite blocking. A process may never be removed from the semaphore queue in which it is suspended.
- May occur if we add and remove processes from the list in LIFO order or based on priority.

Readers and Writers Problem

- A data set is shared among a number of concurrent processes
 - Readers only read the data set; they do not perform any updates
 - Writers can both read and write.
- Problem
 - Allow multiple readers to read at the same time.
 - Only one single writer can access the shared data at a time.



Readers/Writers Problem

Locks:

• are shared (for the readers) and exclusive (for the writer).

Two possible (contradictory) guidelines can be used:

- No reader is kept waiting unless a writer holds the lock (the readers have precedence).
 - First readers problem
- If a writer is waiting for access, no new reader gains access (writer has precedence).
 - Second readers problem

Can starvation occur on either of these rules?

First-Readers Problem

Favoring readers over writers

```
semaphore rdwrt = 1;
semaphore cntmutex = 1;
int readcount = 0;
```

```
Writer:
do {
    wait( rdwrt );
    /* writing is performed */
    signal( rdwrt );
} while(TRUE);
```

```
Reader:
do {
      wait( cntmutex );
                                   /* Allow 1 reader in entry*/
      readcount = readcount + 1;
      if readcount == 1 then
                                  /* 1st reader locks rdwrt */
         wait(rdwrt );
      signal( cntmutex );
         /* reading is performed */
      wait( cntmutex );
      readcount = readcount - 1;
      signal( cntmutex );
      if readcount == 0 then
         signal(rdwrt); /*last reader frees writer */
} while(TRUE);
```

First-Readers Problem

Favoring readers over writers

```
semaphore rdwrt = 1;
semaphore cntmutex = 1;
int readcount = 0;
```

```
Writer:
do {
    wait( rdwrt );
    /* writing is performed */
    signal( rdwrt );
} while(TRUE);
```

```
Reader:
do {
                                      /* Allow 1 reader in entry*/
       wait( cntmutex );
       readcount = readcount + 1;
       if readcount == 1 then
                                    /* 1st reader locks rdwrt */
          wait(rdwrt );
       signal( cntmutex );
                                            A reader might be
              reading is performed
                                          reading while a writer is
                                            writing at the same
       wait( cntmutex );
       readcount = readcount - 1;
                                          time or two writers can
       signal( cntmutex );
                                           perform their writes!
       if readcount == 0 then
                          /*last reader frees writer */
          signal(rdwrt);
                                           How can that happen?
} while(TRUE);
```

First-Readers Problem

Correct Implementation, Favoring readers over writers

```
semaphore rdwrt = 1;
semaphore cntmutex = 1;
int readcount = 0;
```

```
Writer:
do {
    wait( rdwrt );
    /* writing is performed */
    signal( rdwrt );
} while(TRUE);
```

```
Reader:
do {
    wait( cntmutex );
    readcount = readcount + 1;
    if readcount == 1 then
        wait(rdwrt );
    signal( cntmutex );

    /* reading is performed

    wait( cntmutex );
    readcount = readcount - 1;
    if readcount == 0 then
        signal(rdwrt );
    signal( cntmutex );
} while(TRUE);
```

```
/* Allow 1 reader in entry*/
```

Assume there are two readers left (r1 and r2). r1 may be interrupted before it checks readcount == 0. The second reading is performe reader(r2) decrements the readcount from 1 to 0 and both will check readcount == 0 and get true, then both send a signal(wrt) allowing two writers or one reader and one writer in the system.

Question

 Many events on campus take place in SGKM. Assume that the show room can only allow N many people.
 As soon as N audience are in the room, the staff will not accept another incoming audience until an existing audience leaves the event.

- Explain how semaphores can be used by the staff to limit the number of people in the SGKM event room.
- Show your pseudo-code.

Solution

• Semaphore is initialized to the number of allowable people in SGKM. When a reservation is accepted, the acquire() method is called; when someone leaves the event, the release() method is called. If the system reaches the number of allowable people, subsequent calls to acquire() will block until an existing person leaves the event and the release method is invoked.

Reading

- Read Chapter 6
- Acknowledgments
 - -These slides are adapted from
 - Öznur Özkasap (Koç University)
 - Operating System and Concepts (9th edition) Wiley
 - Jerry Breecher