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Brandon Joel Gonzalez – Curriculum Vitae

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Career Objectives

Interested in the development and innovation of electronics engineering and related fields. Long-term goals of pursuing a doctorate in electrical engineering and working in higher education. Love of learning, teaching, and helping guide others to their fullest potential.

Education

University of Pennsylvania - School of Engineering and Applied Science (SEAS)

- ♦ M.S.E. in *Robotics* Spring 2021 GPA: 3.39/4.00
 - Master's Thesis: "Exploring Development of Novel Sensor Systems for Occupancy Detection", which aims to design a hybrid single-chip solution by combining optimal sensor technologies
 - Primary advisor: Dr. Camillo Jose Taylor of <u>GRASP</u>
 - Secondary advisor: Dr. Madhu Annapragada of <u>Automation Research Group</u>
 - Work done in collaboration with <u>InstaHub</u>
 - Began in June 2020 and expected to complete in May 2021
- ♦ B.S.E. in *Computer Science*, minor in *Mathematics* − Fall 2019 − GPA: 3.54/4.00 − *Cum Laude*
 - > Senior Project: <u>TeaBot</u>, a mechatronic robot arm that uses computer vision to harvest tea leaves
 - Advisor: Dr. Camillo Jose Taylor
 - Began in August 2018 and completed in May 2019

Teaching Experience

UPenn SEAS - CIS/ESE Teaching Assistant

- ❖ TA for the Department of Computer and Information Science (CIS) & Department of Electrical and Systems Engineering (ESE)
- Responsibilities include: lecturing, recitations, lab and review sessions, lab and office hours, explanation videos, forum monitoring, staff meetings, grading, project advising, development of course labs, projects, and curricula
- ❖ Semesters as head TA denoted with * and semesters online denoted with ^
- **♦** TA history:
 - ➤ CIS240/CIT593: *Introduction to Computer Systems* Fall 2018, Spring 2019, Summer 2019[^]
 - Introductory systems course covering topics from CMOS logic gates to architecture design to operating systems programming
 - ➤ CIS380/548/CIT595: *Operating Systems* Fall 2019, Spring 2020*^, Summer 2020*^
 - Advanced course exploring design and implementation of operating systems, primarily Unix-based, in C
 - ➤ CIS371/501: Computer Architecture Fall 2019, Spring 2020^
 - Advanced course exploring design and optimization techniques in modern computer architecture
 - ➤ ESE190/M&TSI: *Introduction to Hardware/Software Lab* Spring 2019, Summer 2020^, Summer 2021^

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- Introductory laboratory course exploring the Arduino platform, primarily to students without engineering background
- ➤ ESE350/519: Embedded Systems Lab Fall 2020^, Spring 2021*^
 - Advanced laboratory course covering the foundations and design of embedded systems platforms, across hardware and software levels
- ➤ ESE450/451: ESE Senior Design Fall 2019, Spring 2020^, Fall 2020*^, Spring 2021*^
 - Two-part senior capstone project series for students in the Electrical and Systems Engineering department and related majors

Research Experience

Pennovation - Electronics Design Researcher - Occupancy Detection Device

- ❖ Goals:
 - > Designing a hybrid sensor device for occupancy detection
 - > Collecting in-lab occupancy test data to identify which combinations of sensors most accurately count occupants while conserving power consumption
 - > Aiming to enhance automatic lighting control as a possible application
- Based in Pennovation, working with Automation Research Group and Instahub
- Using MATLAB for data acquisition + algorithm development, and PIR + thermopile array + mm-wave sensors compared against camera-based vision as a baseline
- ❖ Began in June 2020

UPenn - Robotics Research Assistant - SMORES-EP Robot

- ❖ Goals:
 - > Built and enhanced robotics simulations for <u>SMORES-EP</u>
 - > Sought to more easily test configurations and commands for the robot
- ♦ Based in the <u>ModLab</u> under the guidance of Dr. Mark Yim, Department of Mechanical Engineering and Applied Mechanics, and MEAM doctoral candidate Chao Liu
- ❖ Used Unity, C#, ROS, Unix shell
- Funded by the Littlejohn Scholars Summer Research Grant
- ❖ Began in May 2019 and ended in August 2019

UPenn - Computer Graphics Research Assistant - Virtual Reality Hand-Tracking

- ❖ Goals:
 - > Designed interface using <u>uSens Fingo</u> device to integrate hand-tracking into VR
 - > Sought to provide recording and playback of hand models inside VR environments
- ❖ Based in the <u>SIG Center</u> under the guidance of Dr. Stephen Lane, Department of Computer and Information Science
- Used Unity, C#
- ❖ Began in May 2018 and ended in August 2018

UPenn - Physics Research Assistant - Neutrino Interaction Studies

- Goals:
 - > Programmed and ran simulation tools to collect data on neutrino interactions
 - > Sought to understand trends of particle interactions based on detector geometries, particle energy levels, and particle locations inside of the detector
- ❖ Based in the <u>SNO Laboratory</u> under the guidance of Dr. Joshua Klein, Department of Physics and Astronomy
- ❖ Used C++. Unix shell
- ❖ Funded by the <u>Penn Undergraduate Research Mentoring (PURM) Grant</u>
- ❖ Began in May 2017 and ended in August 2017

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Skills and Coursework

Languages: Native in English, fluent/heritage in Spanish, elementary in French **Key Courses Taken:** Operating Systems, Computer Architecture, Computer Graphics, Signal Processing, Control Systems, Digital Circuits, Laboratory Electronics, Embedded Systems, Mechatronic Systems, Autonomous Robotics

Technologies Learned/Utilized:

- Software
 - > Programming languages such as C, C++, Python, MATLAB
 - > Hardware description languages such as Verilog
 - > Programming environment tools such as ROS, Simulink
 - > Operating systems tools such as Unix shells
- Hardware
 - ➤ Microcontrollers such as ATmega328P, ESP32
 - > Circuit simulation tools such as SPICE, Ngspice
 - > PCB design tools such as Altium, EAGLE
 - ➤ Various electrical components such as resistors, capacitors, inductors, diodes, MOSFETs, BJTs, op-amps, transducers, sensors, servomotors, DC motors, batteries, power supplies, voltage regulators, etc.

Projects

Battle Bot

Custom 4-wheel robot for tower defense game constructed from laser-cut CAD models, using differential drive with continuous servos, powered by AA/9V/LiPo batteries with C++ code on ESP32 boards

Balance Bot

- 2-wheel self-balancing robot, using PID controls to correct tilting and displacement
 Memory Design
- SRAM FIFO queue built at the MOSFET transistor level with SPICE circuit simulator
 LC4 Processor
- ❖ 16-bit RISC processor written in Verilog, implementing a pipelined superscalar datapath PennOS
- ❖ Unix-like operating system written in C, with priority scheduler, flat filesystem, user shell

Activities and Interests

- SEAS Orientation Peer Adviser for Class of 2022 (CIS) and Class of 2023 (CMPE)
- ❖ SEAS Mentor for First-Year Robotics Graduate Students in Spring 2021
- Head of Hardware team for <u>PennApps</u> hackathon from Spring 2019 to Spring 2021, organized with <u>Major League Hacking</u> (MLH)

Awards and Recognitions

- Recipient of the 2017 Penn Undergraduate Research Mentoring (PURM) Grant
- * Recipient of the 2018 <u>Penn Engineering Exceptional Service Award</u>
- Recipient of the 2019 Littlejohn Scholars Summer Research Grant
- Recipient of the 2019-2020 J.P. Eckert Fellowship
- ❖ 2020 inductee of the CIS TA Hall of Fame
- Recipient of the 2021 Diversity, Equity, and Inclusion Fellowship in ESE

References available upon request.