

Brandon Joel Gonzalez – Curriculum Vitae

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Career Objectives

Interested in the development and innovation of electronics engineering and related fields. Planning to begin a doctorate in electrical engineering, starting in Fall 2021 (school choice pending). Love of learning, teaching, and helping guide others to their fullest potential.

Education

University of Pennsylvania – School of Engineering and Applied Science (SEAS)

- ❖ M.S.E. in *Robotics* – Spring 2021 – GPA: 3.39/4.00
 - Master's Thesis: "Exploring Development of Novel Sensor Systems for Occupancy Detection", which aims to design a hybrid single-chip solution by combining optimal sensor technologies
 - Primary advisor: Dr. Camillo Jose Taylor of [GRASP](#)
 - Secondary advisor: Dr. Madhu Annapragada of [Automation Research Group](#)
 - Work done in collaboration with [InstaHub](#)
 - Began in June 2020 and expected to complete in May 2021
- ❖ B.S.E. in *Computer Science*, minor in *Mathematics* – Fall 2019 – GPA: 3.54/4.00 – *Cum Laude*
 - Senior Project: [TeaBot](#), a mechatronic robot arm that uses computer vision to harvest tea leaves
 - Advisor: Dr. Camillo Jose Taylor
 - Began in August 2018 and completed in May 2019

Teaching Experience

UPenn SEAS – CIS/ESE Teaching Assistant

- ❖ TA for the Department of Computer and Information Science (CIS) & Department of Electrical and Systems Engineering (ESE)
- ❖ Responsibilities include: lecturing, recitations, lab and review sessions, lab and office hours, explanation videos, forum monitoring, staff meetings, grading, project advising, development of course labs, projects, and curricula
- ❖ Semesters as head TA denoted with * and semesters online denoted with ^
- ❖ TA history:
 - CIS240/CIT593: *Introduction to Computer Systems* – Fall 2018, Spring 2019, Summer 2019^
 - Introductory systems course covering topics from CMOS logic gates to architecture design to operating systems programming
 - CIS380/548/CIT595: *Operating Systems* – Fall 2019, Spring 2020*, Summer 2020*^
 - Advanced course exploring design and implementation of operating systems, primarily Unix-based, in C
 - CIS371/501: *Computer Architecture* – Fall 2019, Spring 2020^
 - Advanced course exploring design and optimization techniques in modern computer architecture
 - ESE190/M&TSI: *Introduction to Hardware/Software Lab* – Spring 2019, Summer 2020^, Summer 2021^

- Introductory laboratory course exploring the Arduino platform, primarily to students without engineering background
- ESE350/519: *Embedded Systems Lab* – Fall 2020[^], Spring 2021^{*^}
 - Advanced laboratory course covering the foundations and design of embedded systems platforms, across hardware and software levels
- ESE450/451: *ESE Senior Design* – Fall 2019, Spring 2020[^], Fall 2020^{*^}, Spring 2021^{*^}
 - Two-part senior capstone project series for students in the Electrical and Systems Engineering department and related majors

Research Experience

Pennovation – Electronics Design Researcher – Occupancy Detection Device

- ❖ Goals:
 - Designing a hybrid sensor device for occupancy detection
 - Collecting in-lab occupancy test data to identify which combinations of sensors most accurately count occupants while conserving power consumption
 - Aiming to enhance automatic lighting control as a possible application
- ❖ Based in Pennovation, working with Automation Research Group and Instahub
- ❖ Using MATLAB for data acquisition + algorithm development, and PIR + thermopile array + mm-wave sensors compared against camera-based vision as a baseline
- ❖ Began in June 2020

UPenn – Robotics Research Assistant – SMORES-EP Robot

- ❖ Goals:
 - Built and enhanced robotics simulations for SMORES-EP
 - Sought to more easily test configurations and commands for the robot
- ❖ Based in the ModLab under the guidance of Dr. Mark Yim, Department of Mechanical Engineering and Applied Mechanics, and MEAM doctoral candidate Chao Liu
- ❖ Used Unity, C#, ROS, Unix shell
- ❖ Funded by the Littlejohn Scholars Summer Research Grant
- ❖ Began in May 2019 and ended in August 2019

UPenn – Computer Graphics Research Assistant – Virtual Reality Hand-Tracking

- ❖ Goals:
 - Designed interface using uSens Fingo device to integrate hand-tracking into VR
 - Sought to provide recording and playback of hand models inside VR environments
- ❖ Based in the SIG Center under the guidance of Dr. Stephen Lane, Department of Computer and Information Science
- ❖ Used Unity, C#
- ❖ Began in May 2018 and ended in August 2018

UPenn – Physics Research Assistant – Neutrino Interaction Studies

- ❖ Goals:
 - Programmed and ran simulation tools to collect data on neutrino interactions
 - Sought to understand trends of particle interactions based on detector geometries, particle energy levels, and particle locations inside of the detector
- ❖ Based in the SNO Laboratory under the guidance of Dr. Joshua Klein, Department of Physics and Astronomy
- ❖ Used C++, Unix shell
- ❖ Funded by the Penn Undergraduate Research Mentoring (PURM) Grant
- ❖ Began in May 2017 and ended in August 2017

Skills and Coursework

Languages: Native in English, fluent/heritage in Spanish, elementary in French

Key Courses Taken: Operating Systems, Computer Architecture, Computer Graphics, Signal Processing, Control Systems, Digital Circuits, Laboratory Electronics, Embedded Systems, Mechatronic Systems, Autonomous Robotics

Technologies Learned/Utilized:

- ❖ Software
 - Programming languages such as C, C++, Python, MATLAB
 - Hardware description languages such as Verilog
 - Programming environment tools such as ROS, Simulink
 - Operating systems tools such as Unix shells
- ❖ Hardware
 - Microcontrollers such as ATmega328P, ESP32
 - Circuit simulation tools such as SPICE, Ngspice
 - PCB design tools such as Altium, EAGLE
 - Various electrical components such as resistors, capacitors, inductors, diodes, MOSFETs, BJTs, op-amps, transducers, sensors, servomotors, DC motors, batteries, power supplies, voltage regulators, etc.

Projects

Battle Bot

- ❖ Custom 4-wheel robot for tower defense game constructed from laser-cut CAD models, using differential drive with continuous servos, powered by AA/9V/LiPo batteries with C++ code on ESP32 boards

Balance Bot

- ❖ 2-wheel self-balancing robot, using PID controls to correct tilting and displacement

Memory Design

- ❖ SRAM FIFO queue built at the MOSFET transistor level with SPICE circuit simulator

LC4 Processor

- ❖ 16-bit RISC processor written in Verilog, implementing a pipelined superscalar datapath

PennOS

- ❖ Unix-like operating system written in C, with priority scheduler, flat filesystem, user shell

Activities and Interests

- ❖ SEAS Orientation Peer Adviser for Class of 2022 (CIS) and Class of 2023 (CMPE)
- ❖ SEAS Mentor for First-Year Robotics Graduate Students in Spring 2021
- ❖ Head of Hardware team for [PennApps](#) hackathon from Spring 2019 to Spring 2021, organized with [Major League Hacking](#) (MLH)

Awards and Recognitions

- ❖ Recipient of the 2017 [Penn Undergraduate Research Mentoring \(PURM\) Grant](#)
- ❖ Recipient of the 2018 [Penn Engineering Exceptional Service Award](#)
- ❖ Recipient of the 2019 [Littlejohn Scholars Summer Research Grant](#)
- ❖ Recipient of the 2019-2020 [J.P. Eckert Fellowship](#)
- ❖ 2020 inductee of the [CIS TA Hall of Fame](#)
- ❖ Recipient of the 2021 [Diversity, Equity, and Inclusion Fellowship in ESE](#)

References available upon request.