

Update overview

Date: August 23, 2021

- » New covariance adjustments
- » External comparisons (GPpy, PCGP with matrix completion)

Old covariance adjustments

Previously we proposed an adjusted covariance matrix to handle the presence of missing data, i.e.

$$\mathbf{R}_k + \text{diag}(\mathbf{w}_k),$$

where

$$\begin{aligned} w_{ik} &:= \text{Var}(\mathbf{g}_{ik}(\theta) - \tilde{\mathbf{g}}_{ik}(\theta)) \\ &= 1 - \Phi_{\cdot k}^T C_{J(i), \cdot}^T C_{J(i), J(i)}^{-1} C_{J(i), \cdot} \Phi_{\cdot k}, \end{aligned}$$

Updated covariance adjustments

We are proposing new covariance adjustments, being

$$\mathbf{R}_k + \beta_k \text{diag}(\mathbf{v}_k),$$

where

$$v_{ik} = \frac{w_{ik}}{(1 - w_{ik})^\alpha}, \quad \alpha \in [0, 1].$$

Intuition:

- » If complete data is observed for i th row, $v_{ik} = 0$.
No adjustment is introduced.
- » If no data is observed, $w_{ik} = 1$. And if $\alpha > 0$, $v_{ik} = \infty$.
The row is disregarded.

The choices of α, β_k

Hyperparameter $\alpha \in [0, 1]$

- » controls the rate of increase of variance v_{ik} as w_{ik} increases.

Hyperparameter $\log \beta_k \in (-12, 12)$

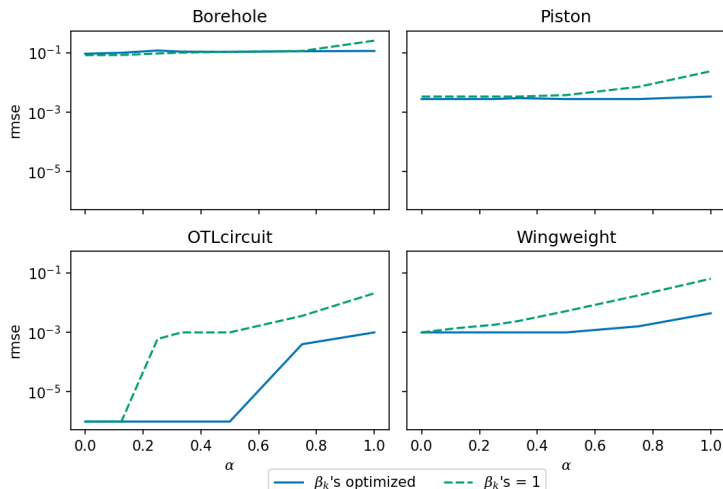
- » controls the inflation (or deflation) of additional variances for the k th surrogate component.
- » When β_k is large, any rows with missing data will be disregarded.
- » β_k 's can be included in hyperparameter estimation (through minimizing the negative loglikelihood)

Numerical experiments to determine α, β_k

- » Functions: borehole, OTL circuit, Wing weight, and piston
- » Number of locations: 25
- » Number of training parameters: 50
- » x are sampled uniformly in $[0, 1]^{d_x}$
- » θ are sampled from latin hypercube sampling in $[0, 1]^{d_\theta}$
- » Test parameters are sampled uniformly in $[0, 1]^{d_\theta}$
- » Failures are **random**

Notice the optimized β value in the legend.

Numerical results for α, β_k choices



Summary for α, β_k choices

- » Suggest $\alpha = 0.3$.
- » Suggest β_k 's to be included in optimization.

External comparisons for emulation strategies

- » GPy, PCGPwM, and PCGPwMatComp are compared
- » Functions: borehole, OTL circuit, Wing weight, and piston
- » Number of locations: 10
- » Number of training parameters: 10, 25, 50, 100, 250, 500, 1000, 1500
- » Failures are **random**
- » Comparison metrics:
 - » RMSE, MAE, median absolute error, mean error (bias)
 - » 90% coverage, 90% prediction interval width
 - » interval score, CRPS