Summary of emulation comparisons (variance = v_k

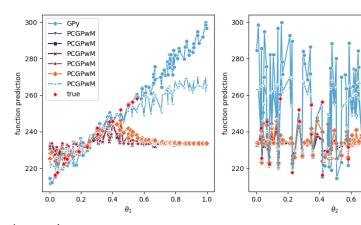
- » Functions: borehole, OTL circuit, Wing weight, and piston
- » Number of locations: 25
- » Number of training parameters: 100
- » x are sampled uniformly in $[0,1]^{d_x}$
- » θ are sampled from latin hypercube sampling in $[0,1]^{d_{\theta}}$
- » Test parameters are sampled uniformly in $[0,1]^{d_{\theta}}$

Comparing between choices of variance constants β_k 's Main observation:

- » If a linear trend is present in one of the parameters, emulator prediction is better with very large β_k 's.
- » Often MLE does not work in such cases.

Example: Wing weight function

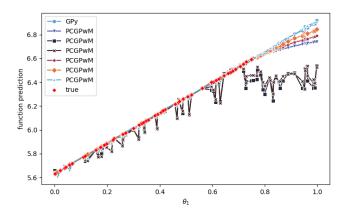
Failure mechanism: if min(x) < 0.05 and $max(\theta) > 0.8$



*legend (top to bottom): GPy, PCGPwM (optimized, $\log(\beta_k) = -6$, -4, 0, 4, 20)

Example: OTL circuit function

Failure mechanism: if max(x) > 0.75 and $max(\theta) > 0.6$



*legend (top to bottom): GPy, PCGPwM (optimized,log(β_k)= -6, -4, 0, 4, 20)

6.8

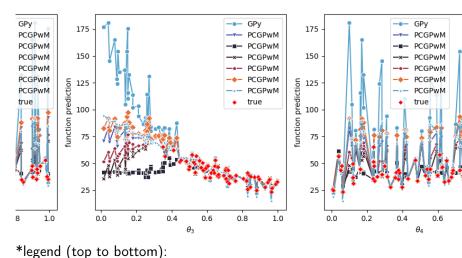
function prediction

5.8

5.6

Example: borehole function

Failure mechanism: if $f(x, \theta) > f(x, [0.5]^{d_{\theta}})$



GPy, PCGPwM (optimized, $log(\beta_k) = -6$, -4, 0, 4, 20)

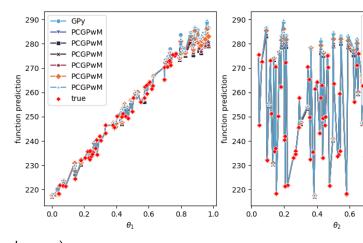
Summary of emulation comparisons (variance $=v_k/(1-v_k)$

- » Functions: borehole, OTL circuit, Wing weight, and piston
- » Number of locations: 25
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- » x are sampled uniformly in $[0,1]^{d_x}$
- » heta are sampled from latin hypercube sampling in $[0,1]^{d_{ heta}}$
- » Test parameters are sampled uniformly in $[0,1]^{d_{\theta}}$

Comparing between choices of variance constants β_k 's

Example: Wing weight function

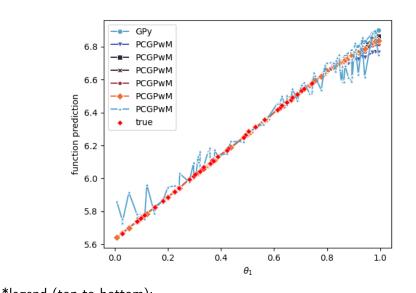
Failure mechanism: if min(x) < 0.05 and $max(\theta) > 0.8$



*legend (top to bottom): GPy, PCGPwM (optimized, $\log(\beta_k) = -6$, -4, 0, 4, 20)

Example: OTL circuit function

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5.8

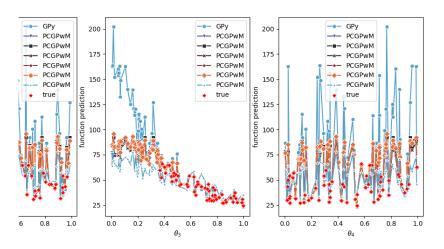
5.6

6.8

6.6

Example: borehole function

Failure mechanism: if $f(x, \theta) > f(x, [0.5]^{d_{\theta}})$



*legend (top to bottom): GPy, PCGPwM (optimized, $log(\beta_k) = -6$, -4, 0, 4, 20)