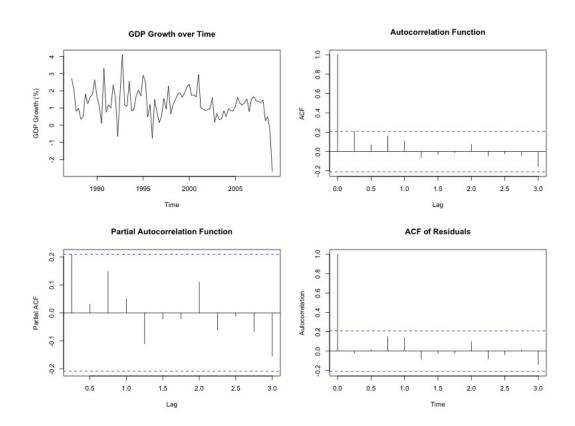
# Econometrics III Assignment Part 1 & 2 Tinbergen Insitute

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## Question 1

## Part (a)



# Part 1: Plot the Dutch GDP, ACF, and PACF
df <- readr::read\_csv("./data/data\_assign\_p1.csv")

df <- ts(df\$GDP\_QGR,</pre>

```
frequency = 4,
start = c(1987, 2))
```

In the above figure, upper left, we observe the growth rates of Dutch GDP from 1987 to 2009.

```
autoc <- acf(df,
    lag.max = 12, plot = F)

Box.test(df,
    lag = 12,
    type = "Ljung-Box")

##
## Box-Ljung test
##
## data: df
## X-squared = 12.106, df = 12, p-value = 0.4372

pautoc <- pacf(df,
    lag.max = 12, plot = F)</pre>
```

In the above figure, we also plot the ACF and PACF, which is the ACF controlled for the other lagged correlations. The ACF tells us that the correlation of GDP growth with its lags is very low - hinting at very little time-dependence in this time-series. More precisely, the estimated correlation coefficients are not higher than 0.2 (for the lag of 1 period). If the GDP is indeed generated by an AR(p) process, the estimates show that the process has low  $\phi$ 's (in absolute value), indicating a low time dependence.

#### Part (b)

The table below shows us the coefficients of the AR(p) models with 1 to 4 lags included. Using a general-to-specific approach, we eliminate insignificant lags ( $\alpha=0.05$  level) at each step. Column (1) shows that only the first lag is significant at the 0.1 level. The second lag has the lowest  $\psi$  coefficient and the highest s.e., thus, we eliminate it first. Doing this iteratively, we are left with the first lag in the model which is significant at the 0.05 level. Investigating the coefficient, we observe there is a 1-period persistence of the time series on its lagged value. The degree of persistence, however, is not large, as the magnitude of the coefficient is fairly small (0.26).

#### Part c

In the fourth plot above, we show the autocorrelation of the residuals. We observe that none of the coefficients attain significance. Hence, we think that the model is well-specified. Formally, we compute the Durbin-Watson test statistic, of which the output is shown below. The null hypothesis of no autocorrelation is not

Table 1:

	Dependent variable:  df				
	(1)	(2)	(3)	(4)	
L(df, 1)	$0.232^{*}$	$0.240^{*}$	0.257**	0.267**	
, ,	(0.124)	(0.122)	(0.119)	(0.117)	
L(df, 2)	0.055				
	(0.126)				
L(df, 3)	0.203	$0.210^{*}$	$0.210^{*}$		
	(0.126)	(0.124)	(0.120)		
L(df, 4)	0.094	0.092			
( , ,	(0.125)	(0.124)			
Constant	0.479	$0.533^{*}$	0.631***	0.896***	
	(0.299)	(0.271)	(0.238)	(0.181)	
Observations	84	84	85	87	
Observations			0.089	0.058	

rejected. In an unreported plot, we also investigate the *partial* autocorrelation of residuals, in which there is also no sign of autocorrelation.

```
durbinWatsonTest(ar1)
```

#### Part d

```
# Part 4: Forecast AR model for 2 years
df_pred <- predict(ar1_m, n.ahead = 8)$pred</pre>
```

We derived the forecast by making use of the conditional expectation as the forecast minimizing the forecast error under quadratic loss. The conditional expectation of the forecast for T+1 is:  $\mathbb{E}[X_{T+1}|X_1,\ldots,X_T]=\mathbb{E}[\phi X_T+\alpha+\epsilon_{T+1}|X_1,\ldots,X_T]=\phi X_T+\alpha$ . Similarly, the forecast for T+2 equals  $\phi\mathbb{E}[X_{T+1}+\alpha]=\phi(\alpha+\phi X_T)+\alpha$ . Generalizing this pattern, we then end up with the following recursive forecasts (for j>1):

$$\mathbb{E}[X_{T+j}] = \alpha + \alpha \cdot \left(\sum_{i=1}^{j-1} \phi^i\right) + \phi^j X_T$$

#### Part e

We construct the forecasts using a 95% symmetric confidence interval around the forecast.

```
# Part 5: Produce CI
phi <- ar1_m$coef[1]
sigma <- sqrt(ar1_m$sigma2)

df_ciu <- predict(ar1_m, n.ahead = 8)$pred + predict(ar1_m, n.ahead = 8)$se*1.96
df_cil <- predict(ar1_m, n.ahead = 8)$pred - predict(ar1_m, n.ahead = 8)$se*1.96</pre>
```

We can reproduce the forecasts manually by using a standard confidence interval around the aforementioned predicted value,  $CI(\mathbb{E}[X_{T+j}]) = \alpha + \alpha \cdot \left(\sum_{i=1}^{j-1} \phi^i\right) + \phi^j X_T \pm 1.96 \cdot \sigma$ , where  $\sigma_j^2 = \sigma_\epsilon^2 \cdot (1 + \phi^2 + \dots + \phi^{2(j-1)})$ .

#### Part f

We check for normality of the residuals using the Jarque-Bera test:

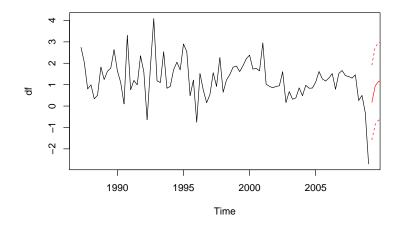
```
jb.norm.test(ar1_m$resid)

##

## Jarque-Bera test for normality
##

## data: ar1_m$resid
## JB = 31.722, p-value = 0.001
```

According to the test, we have to reject H0, indicating that normality of the innovations is violated. In the figure below, we plot the forecasts (red) next to the actual data (blue).

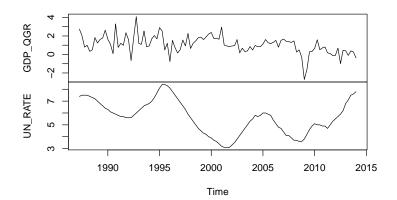


## Question 2

### Part (a)

```
# Part a: Plot the Dutch GDP/unemployment, AR and ADL plot(df2)
```

df2



```
ar4 <- dynlm(df2[,1] ~ L(df2[,1], 1) + L(df2[,1], 2) + L(df2[,1], 3) + L(df2[,1], 4))
ar3 <- dynlm(df2[,1] ~ L(df2[,1], 1) + L(df2[,1], 3) + L(df2[,1], 4))
ar2 <- dynlm(df2[,1] ~ L(df2[,1], 1) + L(df2[,1], 3))

# Create lags
library(data.table)
df_lags <- setDT(as.data.frame(df2[,1]))[, paste("x", 1:4) := shift(x, 1:4)][]
df_lags2 <- setDT(as.data.frame(df2[,2]))[, paste("x", 1:4) := shift(x, 1:4)][]
df_lags <- cbind(df_lags, df_lags2)
df_lags <- df_lags[,c(1:5, 7:10)]
colnames(df_lags) <- as.character(c(0:8))

# To check whether we can use lm and not dynlm with lags
lm_1 <- lm(df_lags$^0 ~ df_lags$^1 + df_lags$^2 + df_lags$^3 + df_lags$^4 + df_lags$^5 + df_lags$
ad18 <- dynlm(df2[,1] ~ L(df2[,1], 1) + L(df2[,1], 2) + L(df2[,1], 3) + L(df2[,1], 4) + L(df2[,2], 1) +
stargazer(ad18, lm_1, type = "text", header = FALSE)</pre>
```

## =========	===========	
## ##	Dependent	variable:
##	df2[, 1]	`0`
##	dynamic	OLS
##	linear	
## ##	(1)	(2)
## L(df2[, 1], 1)	0.305***	
## ##	(0.101)	
## L(df2[, 1], 2)	0.078	
##	(0.105)	
##		
## L(df2[, 1], 3)	0.218**	
##	(0.104)	
##		
## L(df2[, 1], 4)	0.010	
##	(0.102)	
##		
## L(df2[, 2], 1)	0.620	
##	(0.713)	
##		
## L(df2[, 2], 2)	-0.088	
##	(1.326)	
##		
## L(df2[, 2], 3)	-1.931	
##	(1.335)	
## 1 ( ) 4 )	1 500	
## L(df2[, 2], 4) ##	1.502** (0.717)	
##	(0.717)	
## `1`		0.305***
##		(0.101)
##		(0.101)
## `2`		0.078
##		(0.105)
##		
## `3`		0.218**
##		(0.104)
##		
## `4`		0.010
##		(0.102)
##		
## `5`		0.620
##		(0.713)
##		
## `6` 		-0.088
##		(1.326)
##		1 001
## `7` ##		-1.931
## ##		(1.335)
## ## `8`		1.502**
ππ Ο		1.002**

##			(0.717)
##	Constant	-0.184	-0.184
##	0011201111	(0.398)	(0.398)
##			
##			
##	Observations	104	104
##	R2	0.282	0.282
##	Adjusted R2	0.222	0.222
##	Residual Std. Error (df = 95)	0.859	0.859
##	F Statistic (df = 8; 95)	4.674***	4.674***
##		========	=========
##	Note:	*p<0.1; **p<	0.05; ***p<0.01

# yes, we can