# STOCHASTIC BEAMS AND WHERE TO FIND THEM

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#### INTERESTING APPLICATIONS

#### **Applications**

- Image captioning
- Neural machine translation
- Speech recognition

## MATH

#### THE CATEGORICAL DISTRIBUTION

$$I \sim \text{Categorical}(p_1, ..., p_n)$$
  
 $P(I = i) = p_i \quad \forall i \in N$   
 $\phi_i, i \in N$ ,  $\exp \phi_i \propto p_i$ 

$$I \sim \mathsf{Categorical}\left(\frac{\exp\phi_i}{\sum_{j \in \mathsf{N}} \exp\phi_j}, i \in \mathsf{N}\right).$$
 (1)

#### THE GUMBEL DISTRIBUTION

 $U \sim \text{Uniform}(0,1)$   $G = \phi - \log(-\log U)$ :  $G \sim \text{Gumbel}(\phi)$   $G' = G + \phi' \sim \text{Gumbel}(\phi + \phi')$ Properties: we can *shift* Gumbel variables.

#### THE GUMBEL MAX-TRICK

The Gumbel-Max trick allows to sample from the categorical distribution by independently *perturbing* the log-probabilities  $\phi_i$  with Gumbel noise and finding the largest element.

$$G_i \sim \operatorname{Gumbel}(\mathsf{o}), i \in \mathsf{N}, I^* = \operatorname{argmax}_i \{ \phi_i + G_i \}$$
  
 $I^* \sim \operatorname{Categorical}(p_i, i \in \mathsf{N}) \text{ with } p_i \propto \exp \phi_i.$   
 $G_{\phi_i} = G_i + \phi_i \sim \operatorname{Gumbel}(\phi_i)$   
 $\forall B \subseteq \mathsf{N}:$ 

$$\max_{i \in B} \mathbf{G}_{\phi_i} \sim \mathsf{Gumbel}\left(\log \sum_{j \in B} \exp \phi_j\right),\tag{2}$$

$$argmax_{i \in B} G_{\phi_i} \sim \mathsf{Categorical}\left(\frac{\exp \phi_i}{\sum\limits_{i \in B} \exp \phi_i}, i \in B\right).$$
 (3

Max and argmax are independent.

#### THE GUMBEL TOP-K-TRICK

Difference: ordered sample of size k without replacement.

#### Theorem

For  $k \leq n$ , let  $I_1^*,...,I_k^* = \operatorname{argtopk} G_{\phi_i}$ . Then  $I_1^*,...,I_k^*$  is an (ordered) sample without replacement from the Categorical  $\left(\frac{\exp \phi_i}{\sum_{j \in \mathbb{N}} \exp \phi_j}, i \in \mathbb{N}\right)$  distribution, e.g. for a realization  $i_1^*,...,i_h^*$  it holds that

$$P(I_1^* = i_1^*, ..., I_k^* = i_k^*) = \prod_{j=1}^k \frac{\exp \phi_{i_j^*}}{\sum_{\ell \in N_j^*} \exp \phi_{\ell}}$$
(4)

where  $N_j^* = N \setminus \{i_1^*, ..., i_{j-1}^*\}$  is the domain (without replacement) for the j-th sampled element.

#### **SEQUENCE MODELS**

Typically  $p_{\theta}(y_t|\mathbf{y}_{1:t-1})$  is defined as a softmax normalization of unnormalized log-probabilities  $\phi_{\theta}(y_t|\mathbf{y}_{1:t-1})$  with optional temperature T (default T=1):

$$p_{\theta}(y_t|\mathbf{y}_{1:l-1}) = \frac{\exp\left(\phi_{\theta}(y_t|\mathbf{y}_{1:t-1})/T\right)}{\sum_{y'}\exp\left(\phi_{\theta}(y'|\mathbf{y}_{1:t-1})/T\right)}.$$
 (5)

The normalization is w.r.t. a single token, so the model is *locally* normalized. The total probability of a (partial) sequence  $y_{1:l}$  follows from the chain rule of probability:

$$p_{\theta}(\mathbf{y}_{1:t}) = p_{\theta}(y_t|\mathbf{y}_{1:t-1}) \cdot p_{\theta}(\mathbf{y}_{1:t-1})$$
(6)

$$=\prod_{t'=1}^{t}p_{\theta}(y_{t'}|\mathbf{y}_{1:t'-1}). \tag{7}$$

#### **BEAM SEARCH**

- 1. Limited-width breadth first search.
- Often used as an approximation to finding the (single) sequence y that maximizes, or as a way to obtain a set of high-probability sequences from the model.
- 3. Expands at every step t=0,1,2,... at most k partial sequences (those with highest probability) to compute the probabilities of sequences with length t+1.
- 4. Terminates with a beam of k complete sequences.

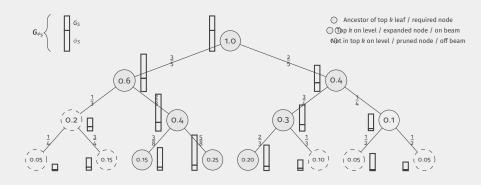
#### THE GUMBEL-TOP-K TRICK ON A TREE

We represent the sequence model as a tree. Internal nodes at level t represent partial sequences  $\mathbf{y}_{1:t}$  Leaf nodes represent completed sequences. Normalized log-probability  $\phi_i = \log p_{\theta}(\mathbf{y}^i)$ .

- Compute  $\phi_i = \log p_{\theta}(\mathbf{y}^i)$  for all sequences  $\mathbf{y}^i, i \in N$ . (Complete probability tree is instantiated)
- Sample  $G_{\phi_i}$   $\sim$  Gumbel $(\phi_i)$ , so  $G_{\phi_i}$  can be seen as the perturbed log-probability of sequence  $\mathbf{y}^i$ .
- perturbed log-probability of sequence  $\mathbf{y}^i$ .

  Let  $i_1^*,...,i_k^* = \arg \operatorname{top} k G_{\phi_i}$ , then  $\mathbf{y}^{i_1^*},...,\mathbf{y}^{i_k^*}$  is a sample of sequences without replacement.

#### **EXAMPLE ON TREE**



#### PERTURBING LOG PROBABILITY

Internal or leaf – the set S of leaves in the corresponding subtree, and  $y^S$  – the corresponding sequence.

$$\phi_{\mathsf{S}} = \log p_{\theta}(\mathbf{y}^{\mathsf{S}}) = \log \sum_{i \in \mathsf{S}} \exp \phi_{i}.$$
 (8)

 $\forall S \ G_{\phi_S}$  – maximum of the perturbed log-probabilities  $G_{\phi_i}$  in the subtree leaves S.

$$G_{\phi_{\mathsf{S}}} = \max_{i \in \mathsf{S}} G_{\phi_i} \sim \mathsf{Gumbel}(\phi_{\mathsf{S}}) \tag{9}$$

Gumbel noise  $G_S \sim \text{Gumbel}(O)$  $G_{\phi_S} = \phi_S + G_S$ .

#### BOTTOM-UP

Children(S) – set of direct children of the node S Rule:

$$G_{\phi_{S}} = \max_{S' \in \text{Children}(S)} G_{\phi_{S'}}. \tag{10}$$

If we want to sample  $G_{\phi_S}$  for all nodes, we can use the *bottom-up* sampling procedure: sample the leaves  $G_{\phi_{\{i\}}} = G_{\phi_i}, i \in N$  and recursively compute  $G_{\phi_S}$ . This is effectively sampling from the degenerate (constant) distribution resulting from conditioning on the children.

#### TOP DOWN

- 1. Initialize from the root
- 2. Rule: (from bottom up)
- 3. Sample the children conditionally on the parent variable (preserving max).
- 4. Sampling a set of Gumbels conditionally on their maximum being equal to a certain value can be done by first sampling the arg max and then sampling the individual Gumbels conditionally on both the max and arg max.
- 5. For all leaves  $(G_{\phi_{\{i\}}} =) G_{\phi_i} \sim \mathsf{Gumbel}(\phi_i)$  is independent
- 6. The benefit of using top-down sampling is that if we are interested only in obtaining the top *k* leaves, we do *not* need to instantiate the complete tree.

#### STOCHASTIC BEAM SEARCH ALGORITHM

- 1. Apply the top-down sampling procedure
- 2. At each level we only need to expand the k nodes with the highest perturbed log-probabilities  $G_{\phi_{\rm S}}$
- 3. By the Gumbel-Top-k trick the result is a sample without replacement from the sequence model

We can also think of  $G_{\phi_S}$  as the *stochastic score* of the partial sequence  $\mathbf{y}^S$ .

#### WHY BETTER?

- 1. A sampling procedure
- 2. Principled way to randomize a beam search.

#### Randomized beam search problems:

- Low-probability partial sequence need to be re-chosen, independently, again with low probability at each step. The result is a much lower probability to sample this sequence than assigned by the model. Intuitively, we should somehow commit to a sampling 'decision' made at step t.
- Stochastic Beam Search is better suited because it makes a soft commitment to a partial sequence by propagating the Gumbel perturbation of the log-probability consistently down the subtree.

### **EXPERIMENTS**

#### **COMPEARED ALGORITHMS**

#### Different algorithms

- Beam Search
- Sampling
- Stochastic Beam Search
- Diverse Beam Search with G groups

#### Metrics

- Diversity the fraction of unique *n*-grams in the *k* translations
- Quality of the sample maximum BLEU score
- Diversity mean BLEU score

#### **FORMULAS**

#### N-gram diversity

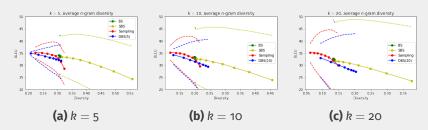
$$d_n = \frac{\text{# of unique } n\text{-grams in } k \text{ translations}}{\text{total # of } n\text{-grams in } k \text{ translations}}.$$

#### **BLEU**

Bilingual evaluation understudy

"The closer a machine translation is to a professional human translation, the better it is"

The wmt14.v2.en-fr.newstest2014 test set consisting of 3003 sentences



**Figure:** Minimum, mean and maximum BLEU score vs. diversity for different sample sizes k. Points indicate different temperatures/diversity strengths, from 0.1 (low diversity, left in graph) to 0.8 (high diversity, right in graph).

BLUE:  $f(\mathbf{y}) = \mathsf{BLEU}(\mathbf{y}, \mathbf{x})$ Entropy:  $f(\mathbf{y}) = -\log p_{\theta}(\mathbf{y}|\mathbf{x})$ 

#### **Evaluation** methods

■ Monte Carlo

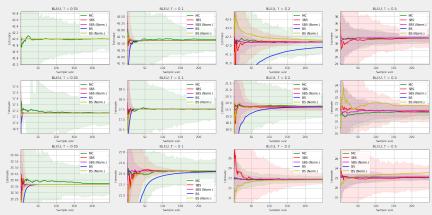
$$\mathbb{E}_{\mathbf{y} \sim p_{\theta}(\mathbf{y}|\mathbf{x})} [f(\mathbf{y})] \approx \frac{1}{k} \sum_{i \in S} f(\mathbf{y}^i).$$
 (11)

StochasticBeamSearch (Normalized)

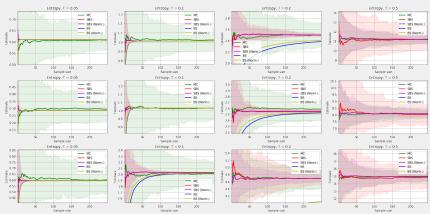
$$\mathbb{E}_{\mathbf{y} \sim p_{\theta}(\mathbf{y}|\mathbf{x})}[f(\mathbf{y})] \approx \sum_{i \in S} \frac{p_{\theta}(\mathbf{y}^{i}|\mathbf{x})}{q_{\theta,\kappa}(\mathbf{y}^{i}|\mathbf{x})} f(\mathbf{y}^{i}) \text{ if norm } (\frac{1}{W(S)})$$
 (12)

■ Beam search (Norm)

$$\sum_{i \in S} p_{\theta}(\mathbf{y}^{i}|\mathbf{x}) f(\mathbf{y}^{i}) \text{ if norm } \left(\frac{1}{\sum_{i \in S} p_{\theta}(\mathbf{y}^{i}|\mathbf{x})}\right)$$
(13)



**Figure:** BLEU score estimates for three sentences sampled/decoded by different estimators for different temperatures.



**Figure:** Entropy score estimates for three sentences sampled/decoded by different estimators for different temperatures.

#### DISCUSSION

Stochastic Beam Search shares some of the benefits of these heuristic variants, such as the ability to control diversity or produce randomized output.

#### **Benefits**

- Linear towards k and the length of the sequence
- Ability to control diversity
- Produce randomized output
- Easy to implement on top of a beam search as a way to sample sequences without replacement

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Thank you for your **attention**!

#### **Algorithm 1** StochasticBeamSearch( $p_{\theta}$ , k)

```
1: Input: one-step probability distribution p_{\theta}, beam/sample size k
2: Initialize BEAM empty
3: add (\boldsymbol{y}^N = \varnothing, \phi_N = 0, G_{\phi_N} = 0) to BEAM
4: for t = 1, ..., \text{steps do}
5:
       Initialize EXPANSIONS empty
6: for (\boldsymbol{y}^S, \phi_S, G_{\phi_S}) \in \text{BEAM do}
 \begin{array}{ll} 7 \colon & Z \leftarrow -\infty \\ 8 \colon & \text{for } S' \in \operatorname{Children}(S) \text{ do} \end{array} 
9:
            \phi_{S'} \leftarrow \phi_S + \log p_{\boldsymbol{\theta}}({\boldsymbol{y}^S}'|{\boldsymbol{y}^S})
10:
           G_{\phi_{S'}} \sim \text{Gumbel}(\phi_{S'})
11: Z \leftarrow \max(Z, G_{\phi_{S'}})
12:
       end for
13: for S' \in Children(S) do
14:
                 \tilde{G}_{\phi_S} \leftarrow -\log(\exp(-G_{\phi_S}) - \exp(-Z) + \exp(-G_{\phi_S}))
15:
                 add ({\boldsymbol{y}^S}', \phi_{S'}, \tilde{G}_{\phi_{S'}}) to EXPANSIONS
16:
             end for
17:
          end for
          BEAM \leftarrow take top k of EXPANSIONS according to \tilde{G}
19: end for
20: Return BEAM
```