

GLMs; definition and derivation

Ben Bolker

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Introduction

Definition:

- exponential family conditional distribution (all we will really use in fitting is the *variance function* $V(\mu)$: makes *quasi-likelihood models* possible)
- linear model η (*linear predictor*) = $\mathbf{X}\beta$
- smooth, monotonic link function $\eta = g(\mu)$

Before we used

$$f(y; \theta, \phi) = \exp[(a(y)b(\theta) + c(\theta)) / f(\phi) + d(y, \phi)]$$

but let's say without loss of generality (putting the distribution into **canonical form**):

$$\{a(y) \mapsto y, b(\theta) \mapsto \theta, c(\theta) \mapsto -b(\theta), f(\phi) \mapsto \phi, d(y, \phi) \mapsto c(y, \phi)\}^1:$$

$$\ell = (y\theta - b(\theta)) / \phi + c(y, \phi)$$

¹ McCullagh, P. and J. A. Nelder (1989). *Generalized Linear Models*. London: Chapman and Hall; and

where y =data, θ =location parameter, ϕ = dispersion parameter (scale parameter).

Example: Poisson distribution

$$\ell(y, \theta, \phi) = y(\log \theta) - \exp(\log \theta) - \log(y!) \quad (1)$$

so $b = \exp(\theta)$; a =identity; $\phi = 1$; $c = -\log(Y!)$

Useful facts

- The score function $\frac{\partial \ell}{\partial \theta}$ has expected value zero.

Therefore for exponential family:

$$\begin{aligned} E((y - b'(\theta)) / a(\phi)) &= 0 \\ \mu - b'(\theta) / a(\phi) &= 0 \\ \mu &= b'(\theta) \end{aligned} \quad (2)$$

(Check against Poisson.)

- Mean depends *only* on $b'(\theta)$.

$$E\left(\frac{\partial^2 \ell}{\partial \theta^2}\right) = -E\left(\frac{\partial \ell}{\partial \theta}\right)^2 \quad (3)$$

Therefore for exponential family:

$$\begin{aligned} E\left(\frac{b''(\theta)}{a(\phi)}\right) &= -E\left(\frac{Y - b'(\theta)}{a(\phi)}\right)^2 \\ \frac{b''(\theta)}{a(\phi)} &= -\frac{\text{var}(Y)}{a^2(\phi)} \\ \text{var}(Y) &= b''(\theta)a(\phi) = \frac{\partial \mu}{\partial \theta}a(\phi) \equiv V(\mu)a(\phi) \end{aligned} \quad (4)$$

- Check against Poisson.
- Variance depends *only* on $b''(\theta)$ and $a(\phi)$.

Usually have $a(\phi) = \phi/w$ where w are weights.

Canonical link uses $g^{-1} = b$.

Iteratively reweighted least squares

Procedure

Likelihood equations

- compute **adjusted dependent variate**:

$$Z_0 = \hat{\eta}_0 + (Y - \hat{\mu}_0) \left(\frac{d\eta}{d\mu}\right)_0$$

(note: $\frac{d\eta}{d\mu} = \frac{d\eta}{dg(\eta)} = 1/g'(\eta)$: translate from raw to linear predictor scale)

- compute **weights**

$$W_0^{-1} = \left(\frac{d\eta}{d\mu}\right)_0^2 V(\hat{\mu}_0)$$

(translate variance from raw to linear predictor scale). This is the inverse variance of Z_0 .

- regress z_0 on the covariates with weights W_0 to get new β estimates (\rightarrow new $\eta, \mu, V(\mu) \dots$)

Tricky bits: starting values, non-convergence, etc.. (We will worry about these later!)

Justification

Reminders:

- Maximum likelihood estimation (consistency; asymptotic Normality; asymptotic efficiency; “when it can do the job, it’s rarely the best tool for the job but it’s rarely much worse than the best” (S. Ellner); flexibility)
- multidimensional Newton-Raphson estimation: iterate solution of $A\Delta\mathbf{b} = \mathbf{u}$ where A is the negative of the *Hessian* (second-derivative matrix of ℓ wrt $\boldsymbol{\beta}$), \mathbf{u} is the *gradient* or *score* vector (derivatives of ℓ wrt $\boldsymbol{\beta}$)

Maximum likelihood equations Remember $\ell = \sum_i w_i ((y_i\theta_i - b(\theta_i))/\phi + c(y, \phi))$. Ignore the last term because it’s independent of θ .

Partial Decompose $\frac{\partial \ell}{\partial \beta_j}$ into

$$\frac{\partial \ell}{\partial \beta_j} = \frac{\partial \ell}{\partial \theta} \cdot \frac{\partial \theta}{\partial \mu} \cdot \frac{\partial \mu}{\partial \eta} \cdot \frac{\partial \eta}{\partial \beta_j} \quad (5)$$

- $\frac{\partial \ell}{\partial \theta}$: effect of θ on log-likelihood, $(Y - \mu)/a(\phi)$.
- $\frac{\partial \theta}{\partial \mu}$: effect of mean on θ . $d\mu/d\theta = d(b')/d\theta = b'' = V(\mu)$, so this term is $1/V$.
- $\frac{\partial \mu}{\partial \eta}$: dependence of mean on η (this is just the inverse-link function)
- $\frac{\partial \eta}{\partial \beta_j}$: the linear predictor $\boldsymbol{\eta} = \mathbf{X}\boldsymbol{\beta}$, so this is just x_j .

So we get

$$\begin{aligned} \frac{\partial \ell}{\partial \beta_j} &= \frac{(Y - \mu)}{a(\phi)} \cdot \frac{1}{V} \cdot \frac{d\mu}{d\eta} \cdot x_j \\ &= \frac{1}{a(\phi)} W(Y - \mu) \frac{d\eta}{d\mu} x_j \end{aligned} \quad (6)$$

Ignoring weights, this gives us a likelihood (score) equation

$$\sum u = \sum W(y - \mu) \frac{d\eta}{d\mu} x_j = 0 \quad (7)$$

Scoring method Going back to finding solutions of the score equation: what is A ?

$$\begin{aligned} A_{rs} &= -\frac{\partial u_r}{\partial \beta_s} \\ &= \sum \left[(Y - \mu) \frac{\partial}{\partial \beta_s} \left(W \frac{d\eta}{d\mu} x_r \right) \right. \\ &\quad \left. + W \frac{d\eta}{d\mu} x_r \frac{\partial}{\partial \beta_s} (Y - \mu) \right] \end{aligned} \quad (8)$$

The first term disappears if we take the *expectation* of the Hessian (Fisher scoring) or if we use a canonical link. (Explanation of the latter: $W d\eta/d\mu$ is constant in this case. For a canonical link $\eta = \theta$, so $d\mu/d\eta = db'(\theta)/d\theta = b''(\theta)$. Thus $W d\eta/d\mu = 1/V(d\mu/d\eta)^2 d\eta/d\mu = 1/V d\mu/d\eta = 1/b''(\theta) \cdot b''(\theta) = 1$.) (Most GLM software just uses Fisher scoring regardless of whether the link is canonical or non-canonical.)

The second term is

$$\sum W \frac{d\eta}{d\mu} x_r \frac{\partial \mu}{\partial \beta_s} = \sum W x_r x_s$$

(the sum is over observations) or $\mathbf{X}^T \mathbf{W} \mathbf{X}$ (where $\mathbf{W} = \text{diag}(W)$)

Then we have (ignoring ϕ)

$$\begin{aligned} \mathbf{A} \mathbf{b}^* &= \mathbf{A} \mathbf{b} + \mathbf{u} \\ \mathbf{X}^T \mathbf{W} \mathbf{X} \mathbf{b}^* &= \mathbf{X}^T \mathbf{W} \mathbf{X} \mathbf{b} + \mathbf{u} \\ &= \mathbf{X}^T \mathbf{W} (\mathbf{X} \mathbf{b}) + \mathbf{X}^T \mathbf{W} (y - \mu) \frac{d\eta}{d\mu} \\ &= \mathbf{X}^T \mathbf{W} \boldsymbol{\eta} + \mathbf{X}^T \mathbf{W} (y - \mu) \frac{d\eta}{d\mu} \\ &= \mathbf{X}^T \mathbf{W} \mathbf{z} \end{aligned} \tag{9}$$

This is the same form as a weighted regression . . . so we can use whatever linear algebra tools we already know for doing linear regression (QR/Cholesky decomposition, etc.)

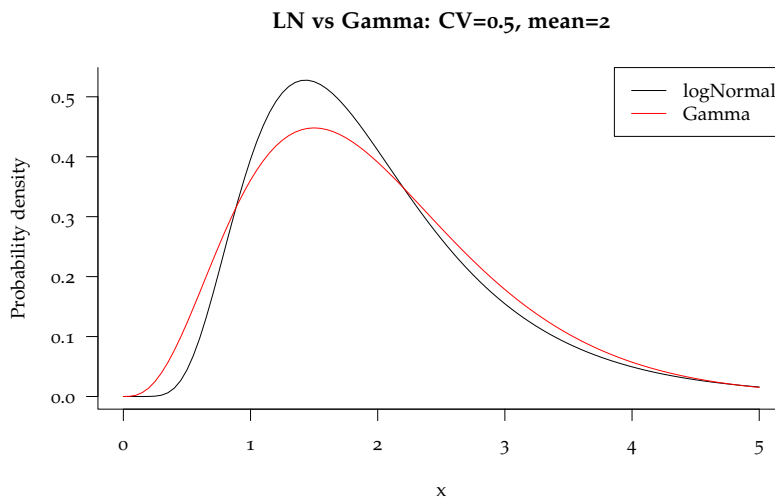
Other sources

- (McCullagh and Nelder, 1989) is really the derivation of IRLS I like best, although I supplemented it at the end with (Dobson and Barnett, 2008).
- (Myers et al., 2010) has information about Newton-Raphson with non-canonical links.
- more details on fitting: (Marschner, 2011), interesting blog posts by Andrew Gelman, John Mount

Choice of distribution As previously discussed, choice of distribution should *usually* be dictated by data (e.g. binary data=binomial, counts of a maximum possible value=binomial, counts=Poisson . . .) however, there is sometimes some wiggle room (Poisson with offset vs. binomial for rare counts; Gamma vs log-Normal for positive data). Then:

- Analytical convenience

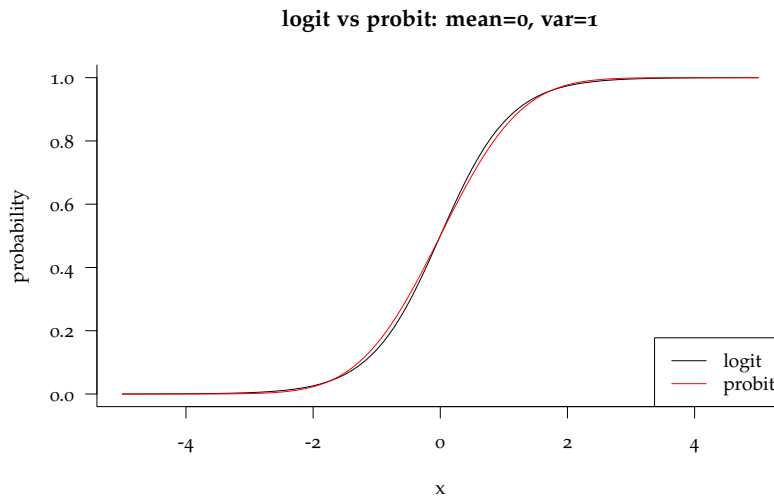
- Computational convenience (e.g. log-Normal > Gamma; Poisson > binomial?)
- Interpretability (e.g. Gamma for multi-hit model)
- Culture (follow the herd)
- Goodness of fit (if it really makes a difference)



(Note: I cheated a little bit. The differences are larger for lower CV values ...)

Choice of link function More or less the same reasons, e.g.:

- analytical: canonical link best (logistic > probit: $g = \Phi^{-1}$)
- computational convenience: logistic > probit
- interpretability:
 - probit > logistic (latent variable model)
 - complementary log-log works well with variable exposure models
 - log link: proportional effects (e.g. multiplicative risk models in predator-prey settings)
 - logit link: proportional effects on odds
- culture: depends (probit in toxicology, logit in epidemiology ...)
- restriction of parameter space (log > inverse for Gamma models, because then range of g^{-1} is $(0, \infty)$)
- Goodness of fit: probit *very* close to logit



References

- Dobson, A. J. and A. Barnett (2008, May). *An Introduction to Generalized Linear Models, Third Edition* (3 ed.). Chapman and Hall/CRC.
- Marschner, I. C. (2011, December). glm2: Fitting generalized linear models with convergence problems. *The R Journal* 3(2), 12–15.
- McCullagh, P. and J. A. Nelder (1989). *Generalized Linear Models*. London: Chapman and Hall.
- Myers, R. H., D. C. Montgomery, G. G. Vining, and T. J. Robinson (2010). Appendix A.6: Computational details for GLMs for a non-canonical link. In *Generalized Linear Models*, pp. 481–483. John Wiley & Sons, Inc.