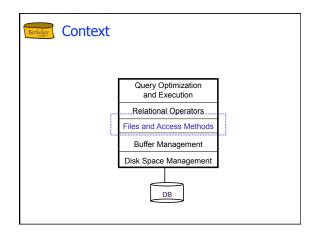
# File Organizations and Indexing R&G Chapter 8 "If you don't find it in the index, look very carefully through the entire catalogue." -- Sears, Roebuck, and Co., Berkeley Consumer's Guide, 1897



### Berkeley Goal for Today

- Big picture overheads for data access
  - We'll simplify things to get focused
  - Still, a bit of discipline:
    - Clearly identify assumptions up front
    - Then estimate cost in a principled way
- Foundation for guery optimization
  - Can't choose the fastest scheme without an estimate of speed!



# Multiple File Organizations

Many alternatives exist, each good for some situations, and not so good in others:

- Heap files: Suitable when typical access is a file scan retrieving all records.
- Sorted Files: Best for retrieval in search key order, or only a `range' of records is
- Clustered Files (with Indexes): Coming



# Cost Model for Analysis

- B: The number of data blocks
- R: Number of records per block
- D: (Average) time to read or write disk block
- Average-case analyses for uniform random workloads
- · We will ignore:
  - Sequential vs. Random I/O
  - Pre-fetching
  - Any in-memory costs
    - Good enough to show the overall trends!



# More Assumptions

- Single record insert and delete.
- Equality selection exactly one match
- For Heap Files:
  - Insert always appends to end of file.
- · For Sorted Files:
  - Files compacted after deletions.
  - Selections on search key.
- Question all these assumptions and rework
  - As an exercise to study for tests, generate ideas

| Cost of Operations |           | B: The number of data pages R: Number of records per page D: (Average) time to read or write disk page |                |
|--------------------|-----------|--|----------------|
|                    | Heap File | Sorted File  | Clustered File |
| Scan all records   |           |  |                |
| Equality<br>Search |           |  |                |
| Range<br>Search    |           |  |                |
| Insert             |           |  |                |
| Delete             |           |  |                |

|                     | erations  | B: The number of R: Number of rec<br>D: (Average) time | f data pages<br>ords per page<br>e to read or write disk |
|---------------------|-----------|--|--|
|                     | Heap File | Sorted File  | Clustered File   |
| Scan all<br>records | BD        | BD   |  |
| Equality<br>Search  |           |  |  |
| Range<br>Search     |           |  |  |
| Insert              |           |  |  |
| Delete              |           |  |  |

|                    | ost of<br>perations | B: The number of R: Number of reco | data pages<br>ords per page<br>to read or write disk |
|--------------------|---------------------|------------------------------------|--|
|                    | Heap File           | Sorted File                        | Clustered File                                       |
| Scan all records   | BD                  | BD                                 |  |
| Equality<br>Search | 0.5 BD              | (log <sub>2</sub> B) * D           |  |
| Range<br>Search    |                     |                                    |  |
| Insert             |                     |                                    |  |
| Delete             |                     |                                    |  |

| Cost of Operations |           | B: The number of data pages R: Number of records per page D: (Average) time to read or write disk p |                |  |
|--------------------|-----------|---|----------------|--|
|                    | Heap File | Sorted File   | Clustered File |  |
| Scan all records   | BD        | BD  |                |  |
| Equality<br>Search | 0.5 BD    | (log <sub>2</sub> B) * D  |                |  |
| Range<br>Search    | BD        | [(log <sub>2</sub> B) +<br>#match pg]*D   |                |  |
| Insert             |           |   |                |  |
| Delete             |           |   |                |  |

| Cost of Operations |           | B: The number of data pages R: Number of records per page D: (Average) time to read or write disk page |                |  |
|--------------------|-----------|--|----------------|--|
|                    | Heap File | Sorted File  | Clustered File |  |
| Scan all records   | BD        | BD   |                |  |
| Equality<br>Search | 0.5 BD    | (log <sub>2</sub> B) * D   |                |  |
| Range<br>Search    | BD        | [(log <sub>2</sub> B) +<br>#match pg]*D  |                |  |
| Insert             | 2D        | ((log <sub>2</sub> B)+B)D  |                |  |
| Delete             |           |  |                |  |

| Cost of Operations |           | B: The number of data pages R: Number of records per page D: (Average) time to read or write disk page |                |
|--------------------|-----------|--|----------------|
|                    | Heap File | Sorted File  | Clustered File |
| Scan all records   | BD        | BD   |                |
| Equality<br>Search | 0.5 BD    | (log <sub>2</sub> B) * D   |                |
| Range<br>Search    | BD        | [(log <sub>2</sub> B) +<br>#match pg]*D  |                |
| Insert             | 2D        | ((log <sub>2</sub> B)+B)D  |                |
| Delete             | 0.5BD + D | ((log <sub>2</sub> B)+B)D  |                |



#### Berkeley Indexes

- Allow record retrieval by value in ≥1 field, e.g.,
  - Find all students in the "CS" department
  - Find all students with a gpa > 3
- <u>Index</u>: disk-based data structure for fast lookup by
  - Search key: any subset of columns in the relation.
  - Search key need not be a key of the relation
  - · Can have multiple items matching a lookup
- Index contains a collection of data entries
  - Items associated with each search key value  ${\pmb k}$
  - Data entries come in various forms, as we'll see



#### 1st Question to Ask About Indexes

- · What kinds of selections (lookups) do they support?
  - Any selection of form field <op> constant?
  - Equality selections (op is =)?
  - Range selections (op is one of <, >, <=, >=, BETWEEN)?
  - More exotic selections?
    - 2-dimensional ranges ("east of Berkeley and west of Truckee and North of Fresno and South of Eureka")
      - Or n-dimensional
    - · 2-dimensional radii ("within 2 miles of Soda Hall") - Or n-dimensional
    - Ranking queries ("10 restaurants closest to Berkeley")
    - Regular expression matches, genome string matches, etc.
    - · One common n-dimensional index: R-tree
      - See http://gist.cs.berkelev.edu for research on this topic



#### Berkeley Index Breakdown

- What selections does the index support
- Representation of data entries in index
  - i.e., what kind of info is the index actually storina?
  - 3 alternatives here
- Clustered vs. Unclustered Indexes
- Single Key vs. Composite Indexes
- · Tree-based, hash-based, other



#### Alternatives for Data Entry k\* in Index

- Three alternatives:
  - Actual data record (with key value k)
  - <k, rid of matching data record>
  - <k, list of rids of matching data records>
- Choice is orthogonal to the indexing technique.
  - Examples of indexing techniques: B+ trees, hashbased structures, R trees, GiSTs, ...
  - Typically, index contains auxiliary information that directs searches to the desired data entries
- Can have multiple (different) indexes per file.
  - E.g. file sorted by age, with a hash index on salary and a B+tree index on name.



# Alternatives for Data Entries (Contd.)

- Alternative 1:
  - Actual data record (with key value **k**)
  - Index as a file organization for records
    - Alongside Heap files or sorted files
  - But at most one index on a given collection of data records can use Alternative 1.
  - No "pointer lookups" to get the data records
    - can be expensive to maintain with insertions and deletions.



# Alternatives for Data Entries (Contd.)

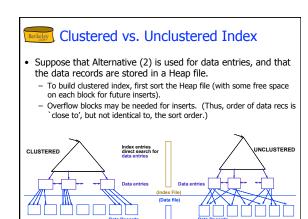
#### Alternative 2

- <k, rid of matching data record> and Alternative 3
  - <k, list of rids of matching data records>
  - Easier to maintain than Alt 1.
  - If more than one index is required on a given file, at most one index can use Alternative 1: rest must use Alternatives 2 or 3.
  - Alternative 3 more compact than Alternative 2, but leads to ble sized data entries even if search keys are of fixed
  - Even worse, for large rid lists the data entry would have to span multiple blocks!



#### Index Classification

- Clustered vs. unclustered: If order of data records is the same as, or `close to', order of index data entries, then called clustered index.
  - A file can be clustered on at most one search key.
  - Cost of retrieving data records through index varies greatly based on whether index is clustered or not!
  - Alternative 1 implies clustered, but not vice-versa.





#### Unclustered vs. Clustered Indexes

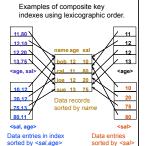
- What are the tradeoffs????
- Clustered Pros
  - Efficient for range searches
  - May be able to do some types of compression
  - Possible locality benefits (related data?)
  - ???
- Clustered Cons
  - Expensive to maintain (on the fly or sloppy with reorganization)
  - Pages tend to be only 2/3 full!

| Cost of Operations |           | B: The number of data pages R: Number of records per page D: (Average) time to read or write disk page |  |  |
|--------------------|-----------|--|--|--|
|                    | Heap File | Sorted File  | Clustered File                             |  |
| Scan all records   | BD        | BD   | 1.5 BD                                     |  |
| Equality<br>Search | 0.5 BD    | (log <sub>2</sub> B) * D   | (log <sub>F</sub> 1.5B) * D                |  |
| Range<br>Search    | BD        | [(log <sub>2</sub> B) +<br>#match pg]*D  | [(log <sub>F</sub> 1.5B) +<br>#match pg]*D |  |
| Insert             | 2D        | ((log <sub>2</sub> B)+B)D  | ((log <sub>F</sub> 1.5B)+1) *<br>D         |  |
| Delete             | 0.5BD + D | ((log <sub>2</sub> B)+B)D<br>(because R, W 0.5)  | ((log <sub>F</sub> 1.5B)+1) *              |  |



# Composite Search Keys

- Search on a combination of fields.
  - Equality query: Every field value is equal to a constant value. E.g. wrt <age,sal> index:
  - age=20 and sal =75
  - Range query: Some field value is not a constant. E.g.: • age > 20; or age=20 and sal > 10
- Data entries in index sorted by search key to support
- range queries. Lexicographic order
- Like the dictionary, but on fields,



#### Summary

- File Layer manages access to records in pages.
  - Record and page formats depend on fixed vs. variable-length.
  - Free space management an important issue.
  - Slotted page format supports variable length records and allows records to move on page.
- Many alternative file organizations exist, each appropriate in some situation.
- If selection queries are frequent, sorting the file or building an index is important.
  - Hash-based indexes only good for equality search.
  - Sorted files and tree-based indexes best for range search; also good for equality search. (Files rarely kept sorted in practice; B+ tree index is better.)
- Index is a collection of data entries plus a way to quickly find entries with given key values.

# Summary (Contd.)

- Data entries in index can be actual data records, <key, rid> pairs, or <key, rid-list> pairs.
   Choice orthogonal to indexing structure (i.e., tree, hash, etc.).
- Usually have several indexes on a given file of data records, each with a different search key.
  Indexes can be classified as *clustered* vs. *unclustered*
- Differences have important consequences for utility/performance.
- Catalog relations store information about relations, indexes and