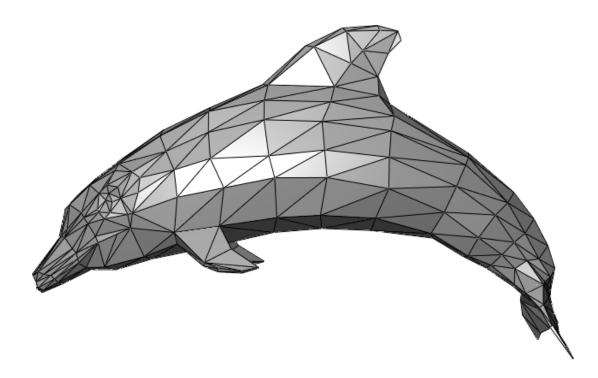
# Detailed and adaptive surface reconstruction of implicit models

Bernhard Manfred Gruber 2014-12-10

## What are implicit models?

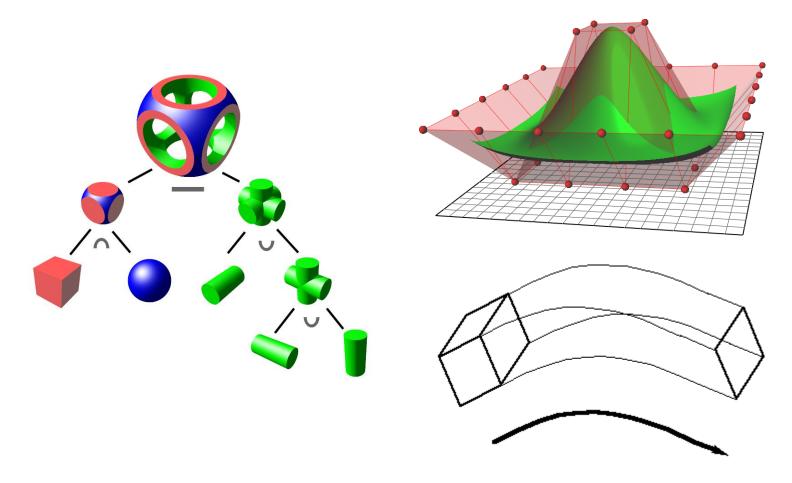
#### **Explict surface models**

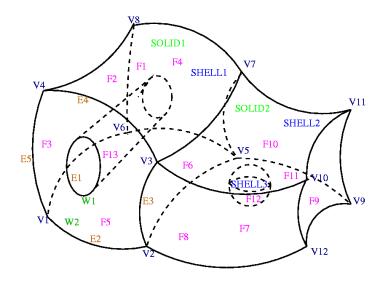


#### Implict surface models

- Parametric
- Functional (iso surface)
- Boundary Representation
- Constructive Solid Geomtry
- Sweeps
- •

## What are implicit models?





$$f(x,y,z) = x^{2} + y^{2} + z^{2} - 5^{2}$$

$$f(x,y,z) < 0 \quad inside$$

$$f(x,y,z) > 0 \quad outside$$

$$f(x,y,z) = 0 \quad surface$$

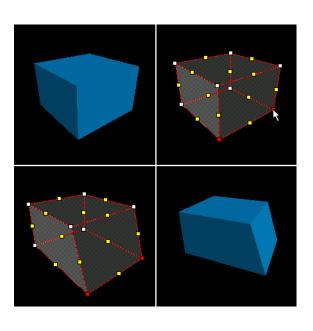
$$S = \{(x, y, z) \mid x^2 + y^2 + z^2 = 5^2\}$$

#### Motivation

#### **Explicit surfaces**

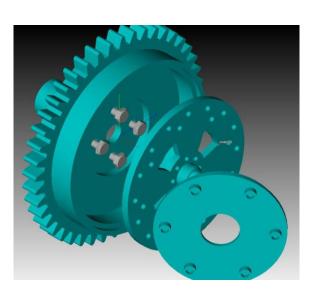
- Wide support
- Render
- Process
- Store
- Edit
- Distribute
- Sell
- ...





#### **Implicit surfaces**

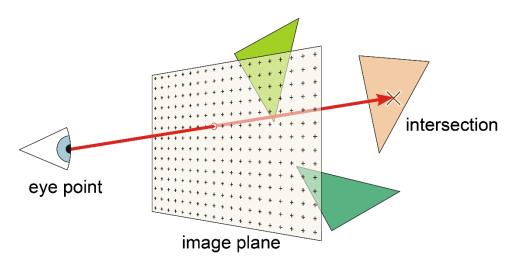
- Exact
- Expressive
- Small memory
- Ray tracing
- ...

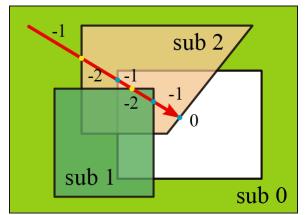


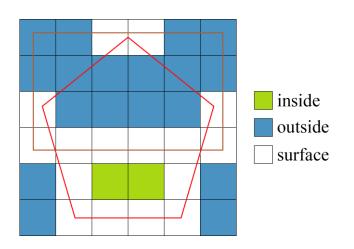
## Previous work - Enlight

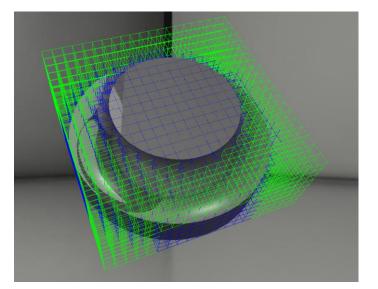


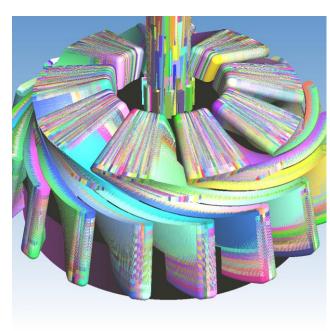


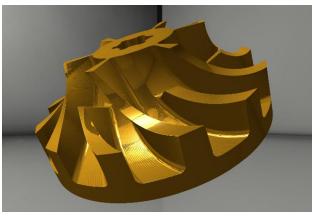










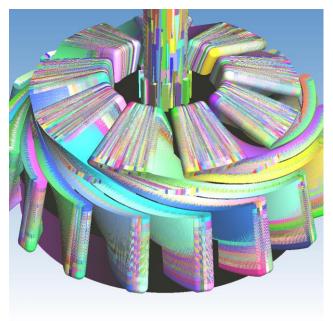


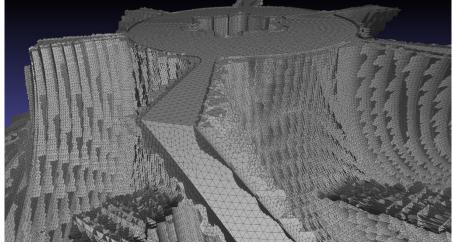
# Enlight

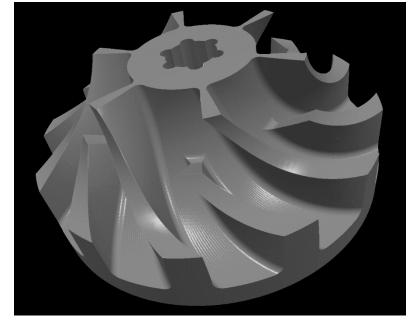
**Swept volumes** 

**Data model** 

**Raycast** 







#### Problem statement

Surface mesh extraction from Enlight's data model

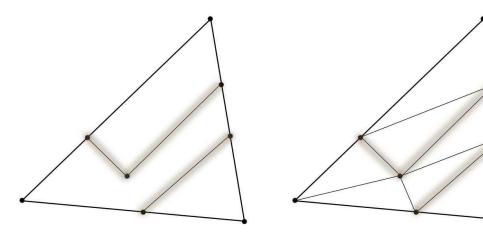
- 1. Determine state of the art
- 2. Prototypic implementation and comparison runtime, memory, complexity, visual quality, errors, divergence, numeric, mesh quality, feature conservation, adaptivity
- 3. Intensive testing on selected models. Is there a "best" algorithm? Under which circumstances? How to select best suited algorithm?

# Approaches

- Direct intersection
- Point cloud based
- Voxel based
- Dexel based

#### Direct intersection

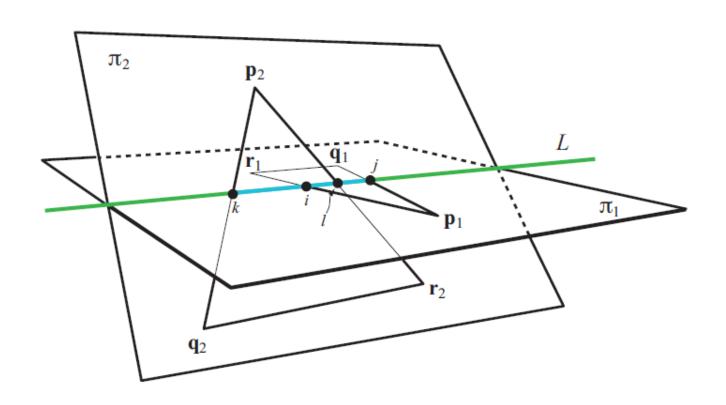
- Most naïve, probably most accurate
- David Rosen,
   Seamless Intersection Between
   Triangle Meshes,
   2008



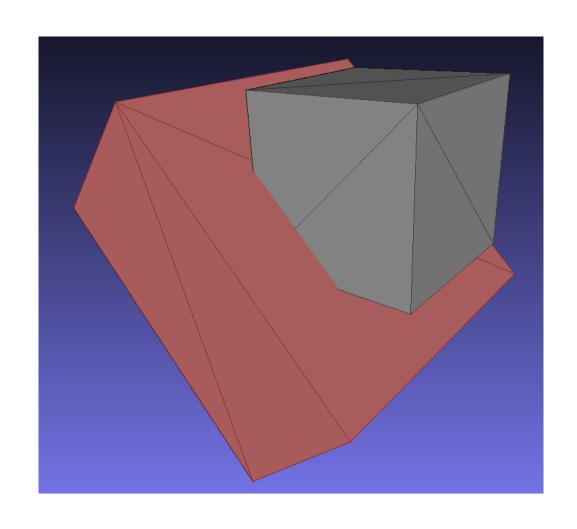


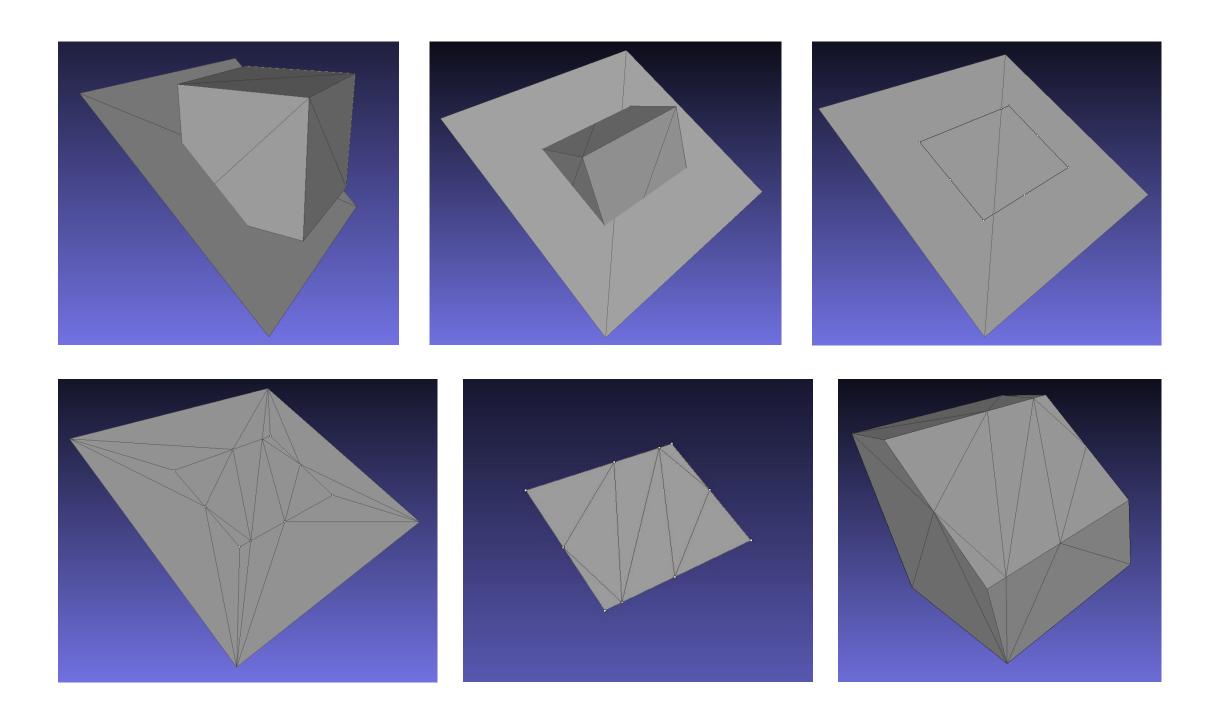
## Triangle triangle intersection

Tomas Möller,
 A fast triangle-triangle intersection test,
 1997

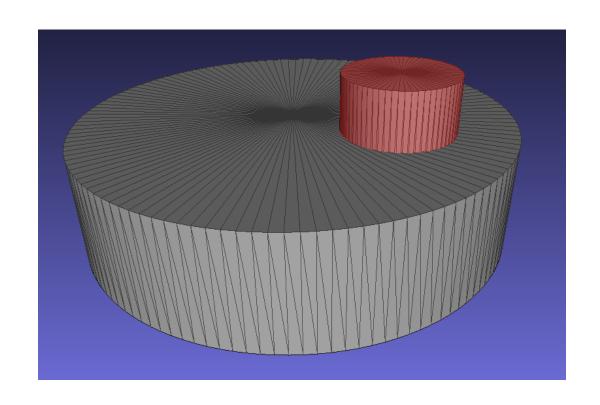


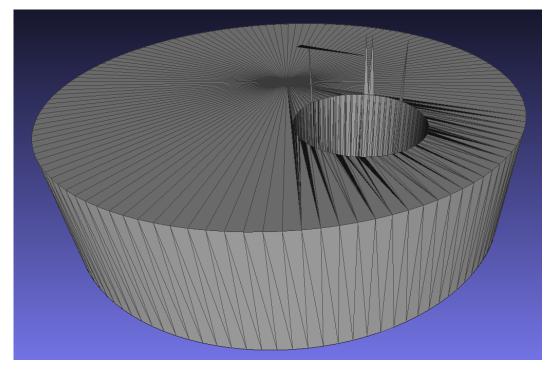
## Cube vs. cube



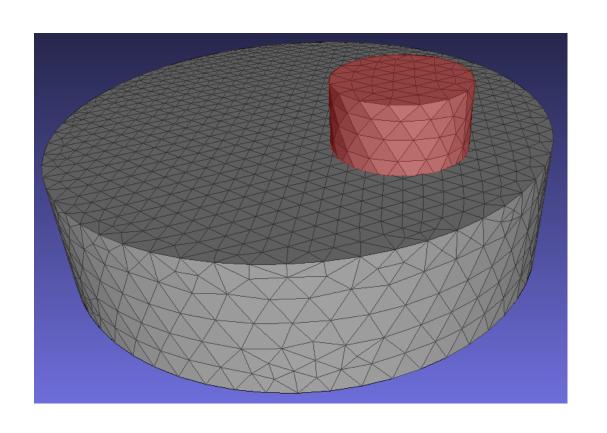


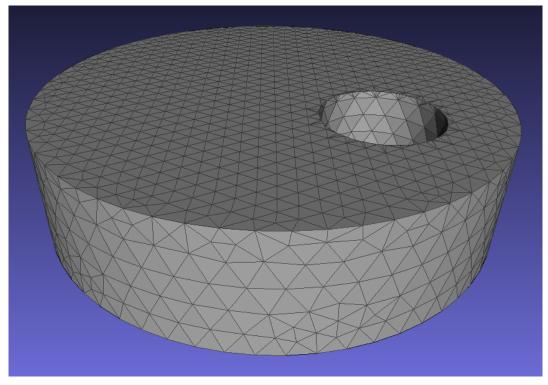
# Cylinder vs. cylinder



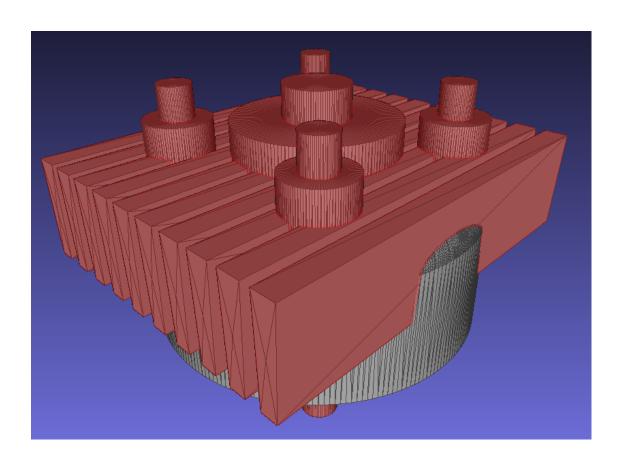


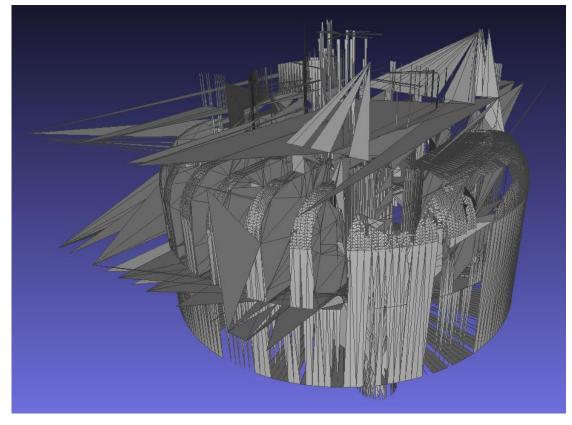
# Cylinder vs. cylinder - Delaunay





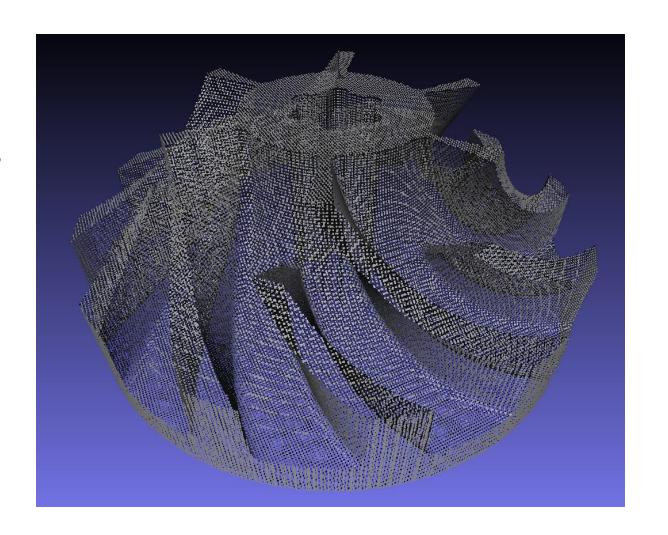
# Cylinder head





#### Point cloud based

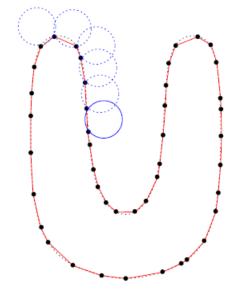
Sample surface,
 e.g. 3 orthongal raycasts,
 reconstruct surface from points

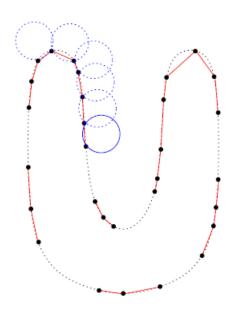


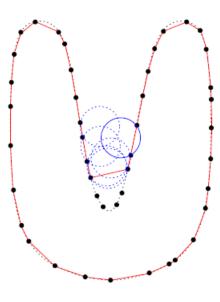
## Surface reconstruction from point cloud

 Fausto Bernardini et al.,
 The ball-pivoting algorithm for surface reconstruction,
 1999

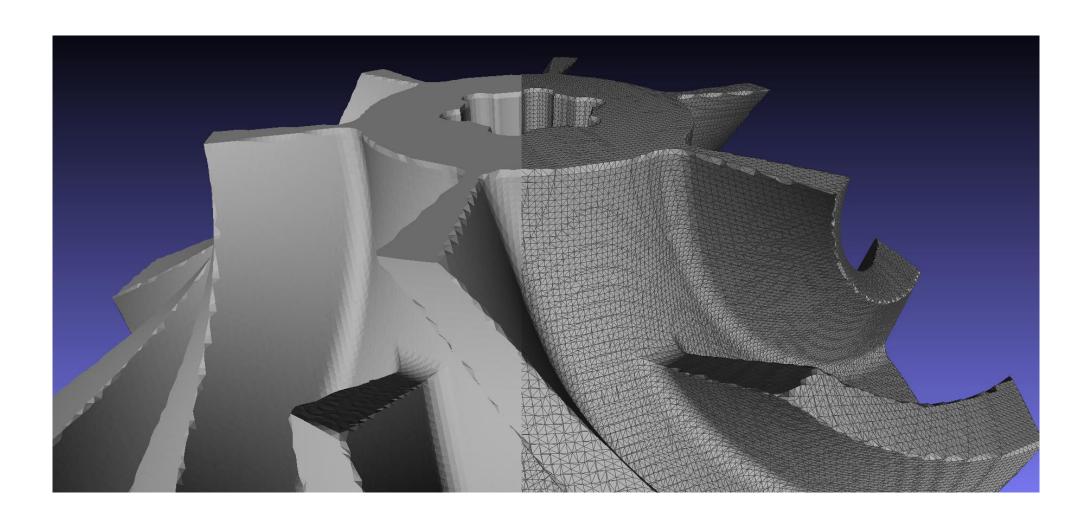
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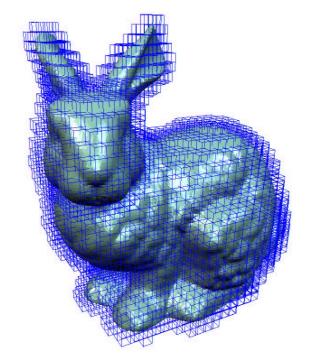


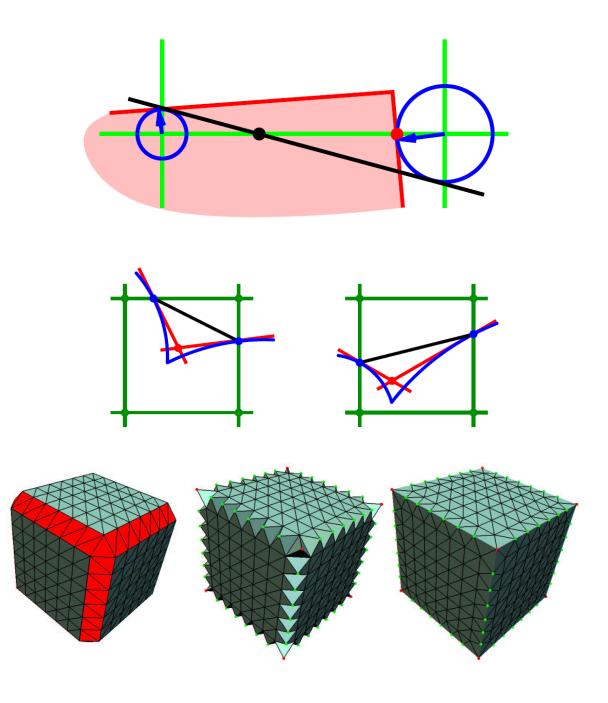
# Ball pivoting algorithm



#### Voxel based

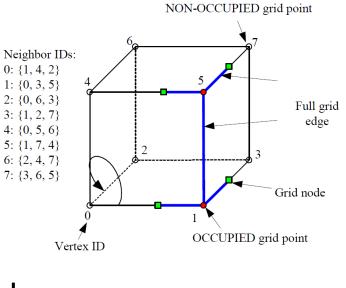
 Leif Kobbelt et al.,
 Feature sensitive surface extraction from volume data,
 2001



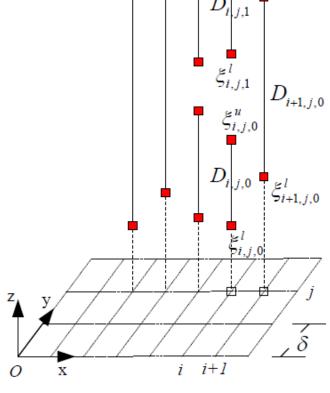


#### Dexel based

Yongfu Ren et al.,
 Feature conservation and conversion of Tri-dexel volumetric models to polyhedral surface models for product prototyping,
 2008



D



#### Goal

- Implement presented approaches
- Create appropriate test suite (models)
- Evaluate algorithms
- Try to find "best" algorithm or hybrid
- Development on "best" algorithm will be continued at RISC ...

## Schedule

Time	Milestone
October	DPR3: Technical lecture, infrastructure code, some test models
November	Exposè, direct triangle-triangle intersection
December	DPR3: Thesis introduction, point cloud based approaches
January	Voxel based approaches
February	Dexel based approaches
March	Comparing implementations, introductory and fundamental chapters
April/May	Implementation chapters, adjusting implementations, more test models
June	Finishing touches and submission

# Thank you!

Questions?