Data-Driven Design & Analysis of Structures & Materials (3dasm)

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Homework 3

Deliver a short PDF report of this assignment containing the answers to the questions listed here. UPLOAD to CANVAS in the Assignments section (Homework 3) by the due date.

Due date: September 27, 2023 (until 11:59pm)

Exercise 1

1. Show that the product of two Gaussian probability density functions (pdf's) for the same random variable (rv) z is:

$$\mathcal{N}(z|\mu_1, \sigma_1^2) \cdot \mathcal{N}(z|\mu_2, \sigma_2^2) = C \cdot \mathcal{N}(z|\mu, \sigma^2)$$

where

$$\sigma^{2} = \frac{1}{\frac{1}{\sigma_{1}^{2}} + \frac{1}{\sigma_{2}^{2}}},$$

$$\mu = \sigma^{2} \left(\frac{\mu_{1}}{\sigma_{1}^{2}} + \frac{\mu_{2}}{\sigma_{2}^{2}} \right),$$

$$C = \frac{1}{\sqrt{2\pi(\sigma_{1}^{2} + \sigma_{2}^{2})}} \exp \left[-\frac{1}{2(\sigma_{1}^{2} + \sigma_{2}^{2})} (\mu_{1} - \mu_{2})^{2} \right].$$

Exercise 2

- 2. Returning to our favorite problem of the car stopping distance for a constant velocity of x = 75 m/s, and considering the following model choices:
 - Observation distribution:

$$p(y|z) = \mathcal{N}\left(y|\mu_{y|z} = wz + b, \sigma_{y|z}^2\right) = \frac{1}{C_{y|z}} \exp\left[-\frac{1}{2\sigma_{y|z}^2}(y - \mu_{y|z})^2\right]$$

where $C_{y|z} = \sqrt{2\pi\sigma_{y|z}^2}$ is the **normalization constant** of the Gaussian pdf, and where $\mu_{y|z} = wz + b$, with w, b and $\sigma_{y|z}^2$ being constants.

• and prior distribution: $p(z) = \frac{1}{C_z}$ where $C_z = z_{max} - z_{min}$ is the normalization constant of the Uniform pdf, i.e. the value that guarantees that p(z) integrates to one. Consider the domain for z to be $-\infty$ to ∞ .

In Lecture 6 we determined that the Posterior Predictive Distribution (PPD) for this case is:

$$p(y|\mathcal{D}_y) = \frac{1}{|w|} \frac{1}{\sqrt{2\pi \left(\sigma^2 + \frac{\sigma_{y|z}^2}{w^2}\right)}} \exp\left[-\frac{\left(\mu - \frac{y-b}{w}\right)^2}{2\left(\sigma^2 + \frac{\sigma_{y|z}^2}{w^2}\right)}\right]$$

Rewrite the PPD to show that it becomes:

$$p(y|\mathcal{D}_y) = \mathcal{N}\left(y|b + \mu w, w^2 \sigma^2 + \sigma_{y|z}^2\right)$$

a normalized univariate Gaussian!

Exercise 3

- 3. Consider again the same car stopping distance problem, but now defining a model with a different prior distribution:
 - Observation distribution:

$$p(y|z) = \mathcal{N}\left(y|\mu_{y|z} = wz + b, \sigma_{y|z}^2\right) = \frac{1}{C_{y|z}} \exp\left[-\frac{1}{2\sigma_{y|z}^2}(y - \mu_{y|z})^2\right]$$

where $C_{y|z} = \sqrt{2\pi\sigma_{y|z}^2}$ is the normalization constant of the Gaussian pdf, and where $\mu_{y|z} = wz + b$, with w, b and $\sigma_{y|z}^2$ being constants.

• and prior distribution: $p(z) = \mathcal{N}\left(z|\tilde{\mu}_z = 3, \tilde{\sigma}_z^2 = 2^2\right)$

Follow the Bayesian approach and determine the PPD using this model.

Exercise 4¹

- 4. Plot² the PPD obtained in Exercise 2 and in Exercise 3 together on the same figure with different line thicknesses and colors such that you can visualize the two PPDs at the same time. Create two plots considering a different number of samples, i.e. for y_i with i = 1, ..., N where:
 - 4.1. N = 5 samples.
 - 4.2. N = 300 samples.

Exercise 5

- 5. Calculate point estimates for different problems:
 - 5.1. Using the MLE point estimate, predict the PPD for the car stopping distance problem with the Gaussian observation distribution and the Uniform prior considered in Exercise 2.
 - 5.2. Using the MAP estimate, predict the PPD for the car stopping distance problem with the Gaussian observation distribution and the Gaussian prior considered in Exercise 3.
 - 5.3. Create a plot³ of the two PPD's and compare them with the PPD's obtained in Exercise 2 and Exercise 3 (in other words, the PPD's you plotted in Exercise 4).

Note: create these plots of the PPD's such that the abscissa (horizontal) axis is the y rv and the ordinate (vertical axis) is the probability density.

As in Exercise 4, make these plots considering a different number of samples y_i :

- 5.3.1. N = 5 samples.
- 5.3.2. N = 300 samples.

¹Coding exercise

²Code is available in Lecture 6

³Coding exercise