

Data-Driven Design & Analyses of Structures & Materials (3dasm)

Lecture 10

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Outline for today

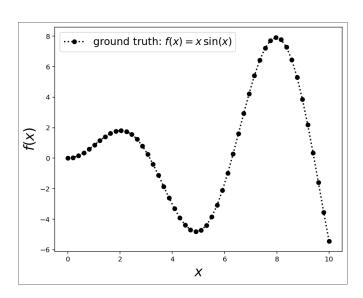
- Linear models for regression (continuation of practical session):
 - One-dimensional examples (continued)
 - Influence of noise, i.e. uncertainty
 - Multi-dimensional example

Reading material: This notebook + Chapter 11

Example 2: linear model for a noiseless problem

Consider now a problem **not governed** by a polynomial law and without uncertainty. Let's consider the function $x\sin(x)$ in the domain $x\in[0,10]$. We did this in Lecture 2!

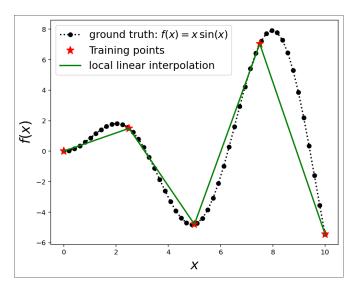
```
In [3]: # 1. Define the function f(x) = x \sin(x)
       def f(x):
    return x * np.sin(x)
# 2. Create a vector of 50 points that are uniformly spaced between 0 and 10
n data = 50 # number of points for plotting the function
x data = np.linspace(0, 10, n data) # uniformly spaced points
# 3. Compute the output vector:
y data = f(x data)
# 4. Plot the function and the data
fig1, ax1 = plt.subplots() # This opens a new figure
# Plot points and interpolate them:
ax1.plot(x data, y data, 'ko:', markersize=6, linewidth=2, label=u'ground truth: <math>f(x) = x \cdot sin(x)
ax1.set xlabel('$x$', fontsize=20) # label of the x axis
ax1.set ylabel('\$f(x)\$', fontsize=20) # label of the y axis
ax1.legend(loc='upper left', fontsize=15) # plot legend in the upper left corner
figl.set size inches(7.5, 6) # scale figure to be taller
```



With lots of data, even linear interpolation between the points can approximate the function well.

However, what if we use just a few points from our dataset x_data?

Out[4]:



This is called local interpolation because each line only depends on the two points it is connecting (not on the other points).

• This is not an ML model! It's different from the linear model we created for the car stopping distance problem.

So, let's train a linear ML model using a polynomial of degree 4 as basis function for this example.

```
In [5]: degree = 4 # degree of polynomial
poly_model = make_pipeline(PolynomialFeatures(degree), LinearRegression()) # model

X_train = np.reshape(x_train, (-1, 1)) # convert input vector into 2d array

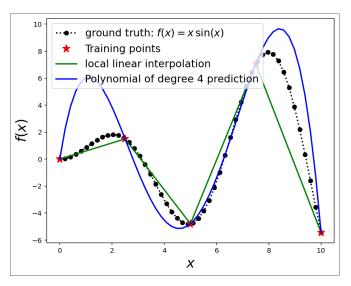
poly_model.fit(X_train,y_train) # fit the polynomial to our 5 training points
#y_pred = poly_model.predict(X_train) # prediction of our polynomial

X_data = np.reshape(x_data, (-1, 1)) # Don't forget to convert to a 2d array
y_pred = poly_model.predict(X_data) # prediction our model for all 50 data points

# Plot x_data and prediction as a blue line:
axl.plot(x_data, y_pred, 'b-', linewidth=2, label="Polynomial of degree %d prediction" % degree)

# Replot figure and legend:
axl.legend(loc='upper left', fontsize=15)
figl
```

Out[5]:



Our polynomial (blue) is clearly different to the function that we want to "learn", i.e. $x \sin(x)$. How do we evaluate the quality of our approximation?

• By evaluating the error of our polynomial model in the points that we didn't use in the fit. Two common metrics are R^2 and MSE (you will have to search for them and explain them!)

```
In [6]: # Import error metrics:
    from sklearn.metrics import mean_squared_error, r2_score

# Compute MSE and R2 for the polynomial model we fitted
mse_value = mean_squared_error(y_data, y_pred)
r2_value = r2_score(y_data, y_pred)

print('MSE for polynomial = ', mse_value)
print('R2 score for polynomial = ', r2_value)
```

MSE for polynomial = 5.826961574277652 R2 score for polynomial = 0.5786918607519673

As expected, these predictions are not great because:

- We want MSE to be as low as possible
- The closer R² is to 1.0 the better

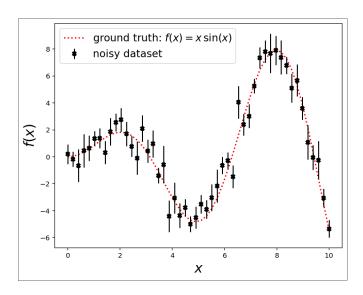
You will dive deeper into this in **Homework 4**.

Example 3: linear model for noisy datasets

Let's consider one last case where we perturb the function of Example 2 $f(x) = x \sin(x)$ with noise.

- This is similar to what happens in the car stopping distance problem.
- Here, the difference is that at every point the noise is random (not as predictable as before) Let's "fabricate" such dataset.

For comparison, we plot the noisy data with the noiseless function that we would like to discover $x \sin(x)$:



Note a couple of things:

- The black "x" marks the actual measured value.
- The black bars indicate the noise in each data point (each data point has a different noise value). Formally, we call this aleatoric uncertainty.
 - In the plot, I centered the error bars around the measured value. Note that the bars do not have the same length (different standard deviation).

Important note on data preprocessing

Usually, when we are given a dataset we need to find a way to **train** and **test** our model using that data.

However, to test our model we have to use data that we have not used in training, otherwise we would be cheating!

This is done by splitting the dataset (in this case x_{data}) into two sets:

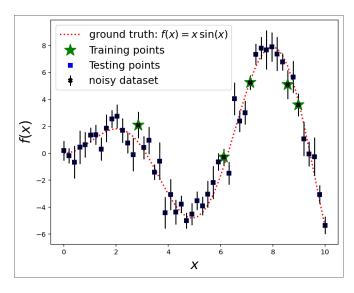
- 1. **Training** set (for example: 75% of the dataset)
- 1. **Test** set with the remaining points of the dataset

Scikit-learn has a very easy way of doing this:

Note that the train_test_split module of scikit-learn picks points pseudo-randomly according to the random state seed value.

Let's visualize the training and testing sets:

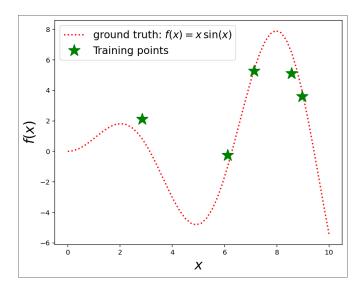
Out[10]:



Let's create a new figure with less clutter by just plotting the ground truth function and the training points.

```
In [11]: fig3, ax3 = plt.subplots() # This opens a new figure

# Plot the noiseless function ("the ground thruth")
ax3.plot(x_data, y_data, 'r:', linewidth=2, label=u'ground truth: $f(x) = x\,\sin(x)$')
ax3.plot(x_train, y_train, 'g*', markersize=18, label="Training points") # Markers locating training points
ax3.set_xlabel('$x$', fontsize=20) # label of the x axis
ax3.set_ylabel('$f(x)$', fontsize=20) # label of the y axis
ax3.legend(loc='upper left', fontsize=15) # plot legend in the upper left corner
fig3.set_size_inches(7.5, 6) # scale figure to be taller
```



In-class Exercise

Fit a polynomial of degree 4 to this training data and calculate the \mathbb{R}^2 and \mathbb{MSE} metrics for the testing data.

In [12]: # Write your code for In-class Exercise:

until here.

Well done...

Yet, this does not seem like a great result, does it?

The R^2 value is so bad that it is even negative!

- What explains this result?
- Can we do something to fix this while still using polynomials?
- If we used more points would that help?
- What if we increased the degree of the polynomial?

In Homework 4 you will explore more...

Multi-dimensional example of Linear Regression

We are now going to try to learn a three-dimensional function named "Schwefel".



Note that the X1_plot (and X2_plot) are 2D arrays with the following size: (50, 50)

The output of the function is a vector with size: (2500, 1)
So, we reshape the output vector into a 2D array needed to plot surfaces: (50, 50)

Let's plot the function in a few different ways:

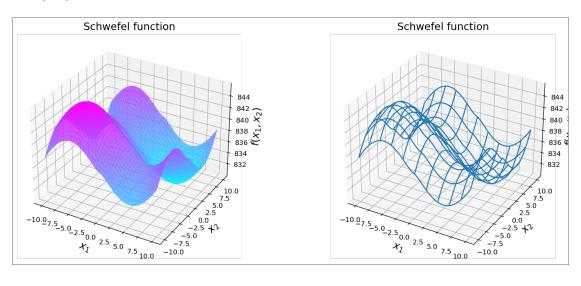
- Left subplot: 3D surface of the function
- Right subplot: a wireframe of the surface (no colors)

Now evaluate the function of interest (Schwefel function) at these input points to plot the "ground-truth" that we want to learn afterwards.

```
In [16]: fig3 = plt.figure(figsize=plt.figaspect(0.5)); ax3 = [];
        # Subplot 1 (left) of Figure 1
ax3.append(fig3.add subplot(1, 2, 1, projection='3d')) # just a way to use the same variable for all axes of fig1
# Surface plot:
surf = ax3[0].plot surface(X1 plot, X2 plot, Y plot true, cmap=set cm, alpha=0.8, linewidth=0, antialiased=False)
ax3[0].set xlabel('$x 1$', fontsize=15)
ax3[0].set_ylabel('$x 2$', fontsize=15)
ax3[0].set zlabel('$f(x 1,x 2)$', fontsize=15)
ax3[0].set title("%s function" % function name, fontsize=15)
# Subplot 2 (right) of Figure 1
ax3.append(fig3.add subplot(1, 2, 2, projection='3d'))
# Plot a 3D wireframe (no colors)
ax3[1].plot wireframe(X1 plot, X2 plot, Y plot true, rstride=5, cstride=5)
ax3[1].set xlabel('$x 1$', fontsize=15)
ax3[1].set_ylabel('$x 2$', fontsize=15)
ax3[1].set zlabel('$f(x 1,x 2)$', fontsize=15)
ax3[1].set title("%s function" % function name, fontsize=15)
#plt.tight layout() # if we want to enlarge the figures, but sometimes this leads to label occlusion.
fig3.set size inches(15, 6)
plt.close(fig3)
```

In [17]: fig3

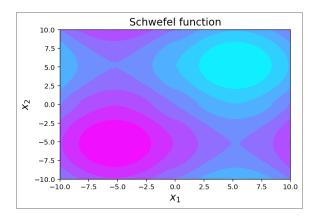
Out[17]:



In the next figure, we show a contour plot of the same function.

Out[18]:

<matplotlib.colorbar.Colorbar at 0x7f73290f8910>



LOADING SCHWEFEL FUNCTION DATA FROM "../DATA" FOLDER

• The "docs" folder contains a file called "data_noiseless_schwefel_2D_regression.pkl" with a Pandas DataFrame with data obtained from the Schwefel function in the domain $x \in [-10, 10]$ without considering noise.

So, let's load this DataFrame and use it for training a 2D Linear Regression model

```
Show the DataFrame in the docs folder:
             x1
                   x2
     -10.000000 -10.0 837.552129
1
     -9.591837 -10.0 838.185887
     -9.183673 -10.0 838.777493
     -8.775510 -10.0 839.323512
      -8.367347 -10.0 839.820614
2495
      8.367347 10.0 836.110986
      8.775510 10.0 836.608088
2496
2497
      9.183673 10.0 837.154107
2498
      9.591837 10.0 837.745713
2499
     10.000000 10.0 838.379471
[2500 rows x 3 columns]
```

Although we introduced pandas in Lecture 2, you should keep exploring how it works... For example, there are a few different ways to access the data of a DataFrame. The notes below (not shown in the presentation), show you 3 different ways:

- 1. Direct way to select columns & rows by how they were labeled originaly
- 1. DataFrame.loc to select columns & rows by Name
- 1. DataFrame.iloc to select columns & rows by Index Positions (integer numbers)

```
In [20]: # Let's access every row of feature 'x1' and of target 'y1':
        way1 = df[['x1','y1']] # direct way
way2 = df.loc[:,['x1','y1']] # using the labels of rows and columns
way3 = df.iloc[:,[0,2]] # using indices (integers) of rows and columns
print('way 1 = \n', way 1, '\n') # the '\n' is to make a new line for visualization purposes only.
print('way 2 =\n', way2, '\n\n')
print('way 3 =\n', way3, '\n\n')
way 1 =
              х1
     -10.000000 837.552129
0
1
      -9.591837 838.185887
2
      -9.183673 838.777493
      -8.775510 839.323512
       -8.367347 839.820614
4
 . . .
       8.367347
                 836.110986
2495
```

[2500 rows x 2 columns]

8.775510 836.608088

9.183673 837.154107

9.591837 837.745713

10.000000 838.379471

2496

2497

2498

2499

```
way 2 =
             x1
0
     -10.000000 837.552129
1
     -9.591837 838.185887
2
      -9.183673 838.777493
3
      -8.775510 839.323512
      -8.367347 839.820614
            . . .
. . .
      8.367347
                836.110986
2495
2496
      8.775510 836.608088
2497
      9.183673 837.154107
      9.591837 837.745713
2498
2499 10.000000 838.379471
```

[2500 rows x 2 columns]

```
way 3 =
             x1
                        у1
   -10.000000 837.552129
    -9.591837 838.185887
   -9.183673 838.777493
     -8.775510 839.323512
     -8.367347 839.820614
           . . .
      8.367347 836.110986
2495
2496
      8.775510 836.608088
2497
      9.183673 837.154107
2498
      9.591837 837.745713
2499
     10.000000
               838.379471
```

[2500 rows x 2 columns]

```
Specific rows, way 2 = x2 y1
2 -10.0 838.777493
3 -10.0 839.323512
4 -10.0 839.820614
5 -10.0 840.265605

Specific rows, way 3 = x2 y1
2 -10.0 838.777493
3 -10.0 839.323512
4 -10.0 839.820614
5 -10.0 840.265605
```

[9.18367347 10. [9.59183673 10.

838.37947063]

10.

Target loaded from the saved DataFrame:

11

[837.55212937 838.18588668 838.77749275 ... 837.15410725 837.74571332

[10.

Now that we loaded the dataset, we should split it into training and testing sets (as we did in the beginning of this lecture).

• For now, we split the data with the following ratio: 75% for training set, and 25% for testing set

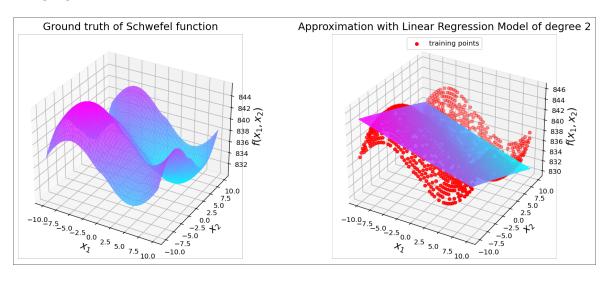
Now we can train the Linear Regression model on the training data and test it on the testing data! Let's use a polynomial of degree 2

MSE for polynomial = 6.630555027981865 R2 score for polynomial = 0.5931096654841044 And now we can plot the result (we will also plot the "ground truth" of the Schwefel function)

```
In [25]: fiq5 = plt.figure(figsize=plt.figaspect(0.5)); ax5 = []
        # Subplot 1 (left): ground truth
ax5.append(fig5.add subplot(1, 2, 1, projection='3d'))
surf = ax5[0].plot surface(X1 plot, X2 plot, Y plot true,
                                 cmap=set cm, alpha=0.8, linewidth=0, antialiased=False)
ax5[0].set xlabel('$x 1$', fontsize=15)
ax5[0].set ylabel('$x 2$', fontsize=15)
ax5[0].set zlabel('$f(x 1,x 2)$', fontsize=15)
ax5[0].set title("Ground truth of %s function" % function name, fontsize=15)
# Subplot 2 (right): Linear Regression approximation
ax5.append(fig5.add subplot(1, 2, 2, projection='3d'))
y plot pred = poly model 2D.predict(X plot) # prediction of our polynomial for the points used for plotting
Y plot pred = np.reshape(y plot pred, np.shape(X1 plot)) # convert targets into grid format for plotting
surf = ax5[1].plot surface(X1 plot, X2 plot, Y plot pred,
                           cmap=set cm, alpha=0.8, linewidth=0, antialiased=False)
ax5[1].set xlabel('$x 1$', fontsize=15)
ax5[1].set ylabel('$x 2$', fontsize=15)
ax5[1].set zlabel('$f(x 1,x 2)$', fontsize=15)
ax5[1].set title("Approximation with Linear Regression Model of degree %s" % degree, fontsize=15)
ax5[1].scatter(X train[:,0], X train[:,1], y train, marker='o', color='red', label="training points")
ax5[1].legend(loc='upper center')
#plt.tight layout()
fig5.set size inches(15, 6)
plt.close(fia5) # close figure to open it in next cell.
```

In [26]: fig5 # show figure

Out[26]:



In-class Exercise

- 1. Go back and train a polynomial of degree 3. You will get a much better approximation and a nicely looking plot!
- 1. Go back and train a polynomial of degree 20. You will get a pretty bad prediction... In Homework 4 you will explore more this and other aspects of Linear Regression.

See you next class

Have fun!