# Nearest Neighbor Classification

Machine Learning Fall 2017



### This lecture

- K-nearest neighbor classification
  - The basic algorithm
  - Different distance measures
  - Some practical aspects
- Voronoi Diagrams and Decision Boundaries
  - What is the hypothesis space?

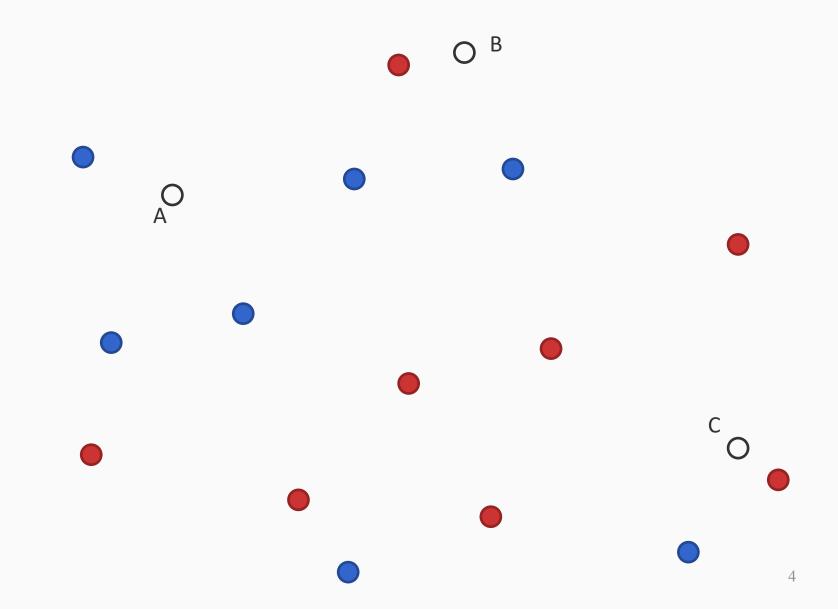
The Curse of Dimensionality

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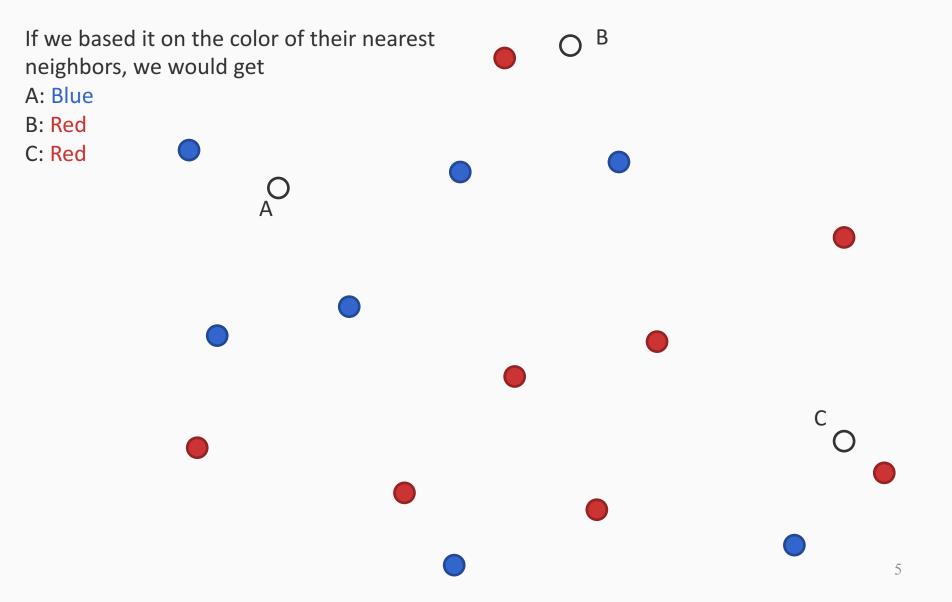
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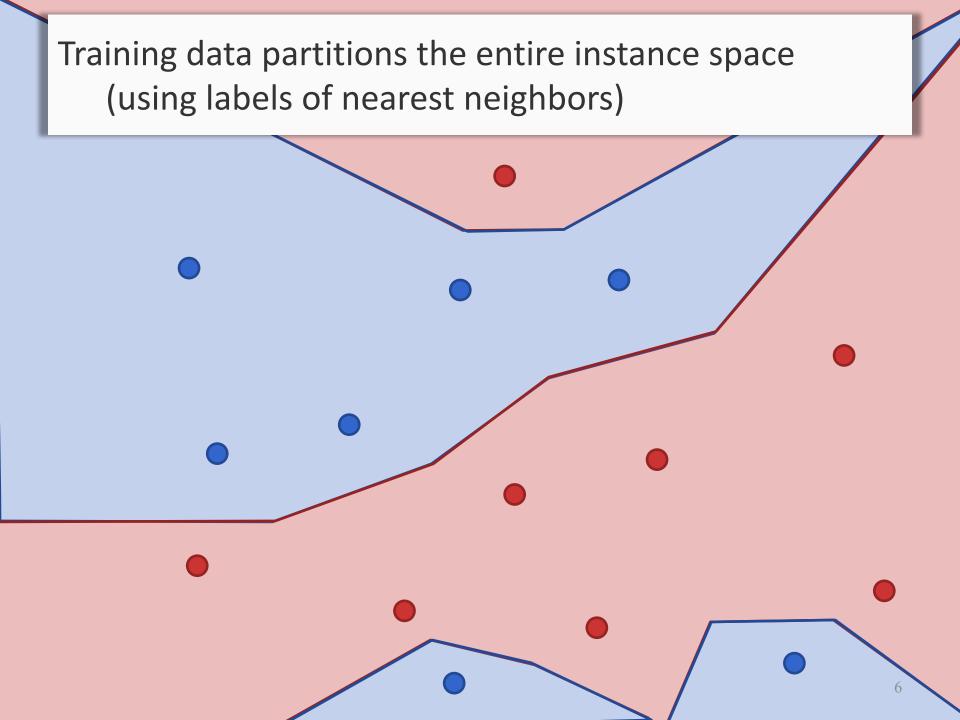
The Curse of Dimensionality

# How would you color the blank circles?



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## Nearest Neighbors: The basic version

- Training examples are vectors x<sub>i</sub> associated with a label y<sub>i</sub>
  - E.g.  $\mathbf{x}_i$  = a feature vector for an email,  $\mathbf{y}_i$  = SPAM
- Learning: Just store all the training examples
- Prediction for a new example x
  - Find the training example x<sub>i</sub> that is closest to x
  - Predict the label of  $\mathbf{x}$  to the label  $\mathbf{y}_i$  associated with  $\mathbf{x}_i$

## K-Nearest Neighbors

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  - For regression: Predict the mean value

## Instance based learning

- A class of learning methods
  - Learning: Storing examples with labels
  - Prediction: When presented a new example, classify the labels using similar stored examples
- K-nearest neighbors algorithm is an example of this class of methods
- Also called *lazy* learning, because most of the computation (in the simplest case, all computation) is performed only at prediction time

 In general, a good place to inject knowledge about the domain

Behavior of this approach can depend on this

How do we measure distances between instances?

Numeric features, represented as n dimensional vectors

#### Numeric features, represented as n dimensional vectors

Euclidean distance

$$||\mathbf{x}_1 - \mathbf{x}_2||_2 = \sqrt{\sum_{i=1}^n \left(\mathbf{x}_{1,i} - \mathbf{x}_{2,i}
ight)^2}$$

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- L<sub>p</sub>-norm
  - Euclidean =  $L_2$
  - Manhattan =  $L_1$
  - Exercise: What is  $L_{\infty}$ ?

$$||\mathbf{x}_1 - \mathbf{x}_2||_p = \left(\sum_{i=1}^n |\mathbf{x}_{1,i} - \mathbf{x}_{2,i}|^p
ight)^{rac{1}{p}}$$

What about symbolic/categorical features?

#### Symbolic/categorical features

#### Most common distance is the *Hamming distance*

- Number of bits that are different
- Or: Number of features that have a different value
- Also called the overlap
- Example:

```
X<sub>1</sub>: {Shape=Triangle, Color=Red, Location=Left, Orientation=Up}
```

X<sub>2</sub>: {Shape=Triangle, Color=Blue, Location=Left, Orientation=Down}

Hamming distance = 2

## Advantages

- Training is very fast
  - Just adding labeled instances to a list
  - More complex indexing methods can be used, which slow down learning slightly to make prediction faster
- Can learn very complex functions

- We always have the training data
  - For other learning algorithms, after training, we don't store the data anymore. What if we want to do something with it later...

## Disadvantages

- Needs a lot of storage
  - Is this really a problem now?
- Prediction can be slow!
  - Naïvely: O(dN) for N training examples in d dimensions
  - More data will make it slower
  - Compare to other classifiers, where prediction is very fast
- Nearest neighbors are fooled by irrelevant attributes
  - Important and subtle

- Probably the first "machine learning" algorithm
  - Guarantee: If there are enough training examples, the error of the nearest neighbor classifier will converge to the error of the optimal (i.e. best possible) predictor
- In practice, use an odd K. Why?

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- Feature normalization could be important
  - Often, good idea to center the features to make them zero mean and unit standard deviation. Why?

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- Feature normalization could be important
  - Often, good idea to center the features to make them zero mean and unit standard deviation. Why?
  - Because different features could have different scales (weight, height, etc); but the
    distance weights them equally
- Variants exist
  - Neighbors' labels could be weighted by their distance

### Where are we?

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The Curse of Dimensionality

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# The decision boundary for KNN

Is the K nearest neighbors algorithm explicitly building a function?

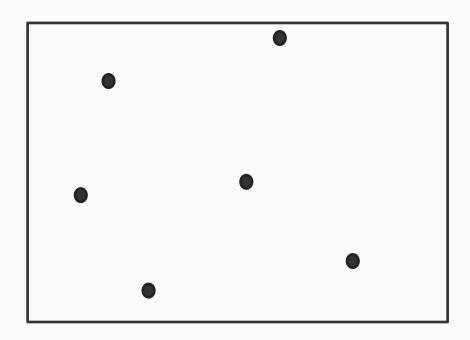
# The decision boundary for KNN

Is the K nearest neighbors algorithm explicitly building a function?

No, it never forms an explicit hypothesis

But we can still ask: Given a training set what is the implicit function that is being computed

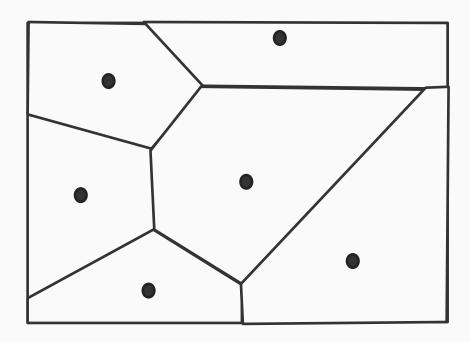
# The Voronoi Diagram



For any point **x** in a training set S, the Voronoi Cell of **x** is a polyhedron consisting of all points closer to **x** than any other points in S

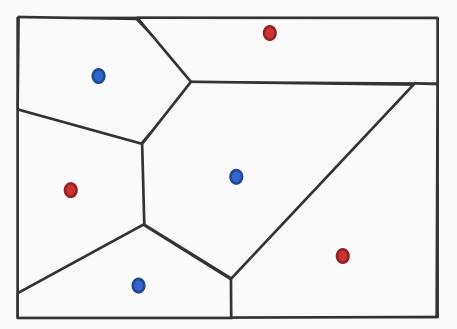
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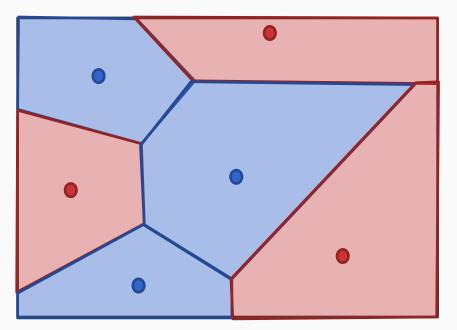
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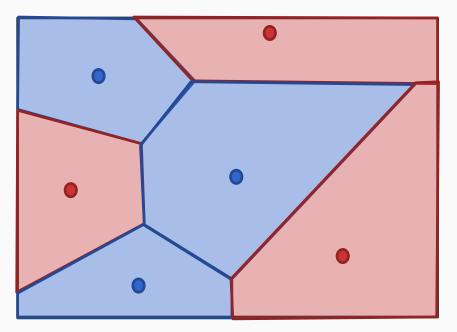
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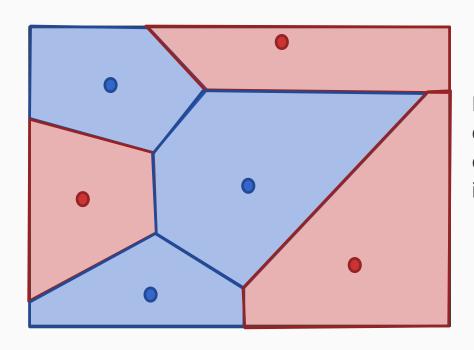
Points in the Voronoi cell of a training example are closer to it than any others

Picture uses Euclidean distance with 1-nearest neighbors.

What about K-nearest neighbors?

Also partitions the space, but much more complex decision boundary

What about points on the boundary? What label will they get?



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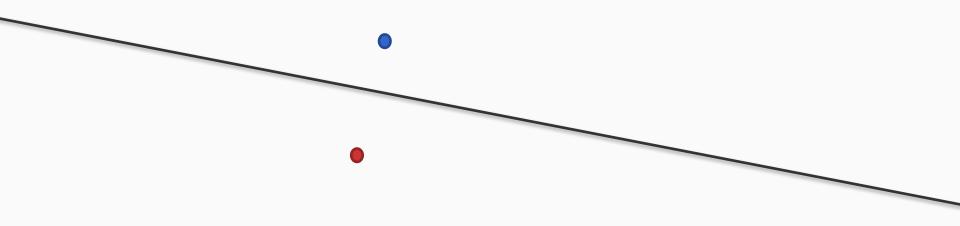
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### Exercise

If you have only two training points, what will the decision boundary for 1-nearest neighbor be?

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A line bisecting the two points

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The Curse of Dimensionality

# Why your classifier might go wrong

Two important considerations with learning algorithms

- Overfitting: We have already seen this
- The curse of dimensionality
  - Methods that work with low dimensional spaces may fail in high dimensions
  - What might be intuitive for 2 or 3 dimensions do not always apply to high dimensional spaces

Check out the 1884 book Flatland: A Romance of Many Dimensions for a fun introduction to the fourth dimension

#### Of course, irrelevant attributes will hurt

#### Suppose we have 1000 dimensional feature vectors

- But only 10 features are relevant
- Distances will be dominated by the large number of irrelevant features

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#### Suppose we have 1000 dimensional feature vectors

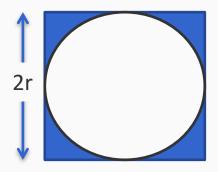
- But only 10 features are relevant
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But even with only relevant attributes, high dimensional spaces behave in odd ways

Intuitions that are based on 2 or 3 dimensional spaces do not always carry over to high dimensional spaces

**Example 1**: What fraction of the points in a cube lie outside the sphere inscribed in it?

In two dimensions

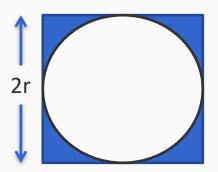


What fraction of the square (i.e the cube) is outside the inscribed circle (i.e the sphere) in two dimensions?

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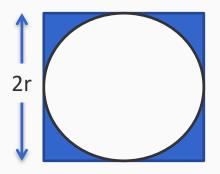
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$$1 - \frac{\pi r^2}{4r^2} = 1 - \frac{\pi}{4}$$

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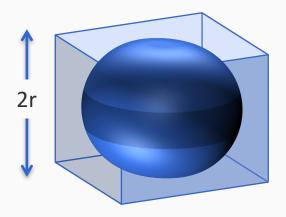
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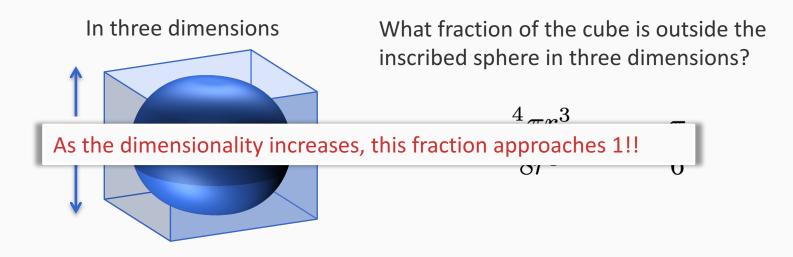
What fraction of the cube is outside the inscribed sphere in three dimensions?

$$1 - \frac{\frac{4}{3}\pi r^3}{8r^3} = 1 - \frac{\pi}{6}$$

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Example 1: What fraction of the points in a cube lie outside the sphere inscribed in it?



In high dimensions, most of the volume of the cube is far away from the center!

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Example 2: What fraction of the volume of a unit sphere lies between radius  $1 - \epsilon$  and radius 1?

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$$\frac{\pi \cdot 1^2 - \pi (1 - \epsilon)^2}{\pi \cdot 1^2} = 1 - (1 - \epsilon)^2$$

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Example 2: What fraction of the volume of a unit sphere lies between radius  $1 - \epsilon$  and radius 1?

But, distances do not behave the same way in high dimensions

In d dimensions, the fraction is  $\ 1-(1-\epsilon)^d$ 

As d increases, this fraction goes to 1!

In high dimensions, most of the volume of the sphere is far away from the center!

- Most of the points in high dimensional spaces are far away from the origin!
  - In 2 or 3 dimensions, most points are near the center
  - Need more data to "fill up the space"
- Bad news for nearest neighbor classification in high dimensional spaces

Even if most/all features are relevant, in high dimensional spaces, most points are equally far from each other!

"Neighborhood" becomes very large

Presents computational problems too

#### Dealing with the curse of dimensionality

- Most "real-world" data is not uniformly distributed in the high dimensional space
  - Different ways of capturing the underlying dimensionality of the space
  - We will see dimensionality reduction later in the semester
- Feature selection, an art
  - Different methods exist
  - Select features, maybe by information gain
  - Try out different feature sets of different sizes and pick a good set based on a validation set
- Prior knowledge or preferences about the hypotheses can also help Questions?

#### Summary: Nearest neighbors classification

- Probably the oldest and simplest learning algorithm
  - Prediction is expensive.
    - Efficient data structures help. k-D trees: the most popular, works well in low dimensions
    - Approximate nearest neighbors may be good enough some times.
       Hashing based algorithms exist
- Requires a distance measure between instances
  - Metric learning: Learn the "right" distance for your problem
- Partitions the space into a Voronoi Diagram
- Beware the curse of dimensionality

**Questions?** 

#### **Exercises**

- 1. What will happen when you choose K to the number of training examples?
- 2. Suppose you want to build a nearest neighbors classifier to predict whether a beverage is a coffee or a tea using two features: the volume of the liquid (in milliliters) and the caffeine content (in grams). You collect the following data:

Volume (ml)	Caffeine (g)	Label
238	0.026	Tea
100	0.011	Tea
120	0.040	Coffee
237	0.095	Coffee

What is the label for a test point with Volume = 120, Caffeine = 0.013?

Why might this be incorrect?

How would you fix the problem?

#### **Exercises**

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Coffee

Why might this be incorrect?

Because Volume will dominate the distance How would you fix the problem?

Rescale the features. Maybe to zero mean, unit variance