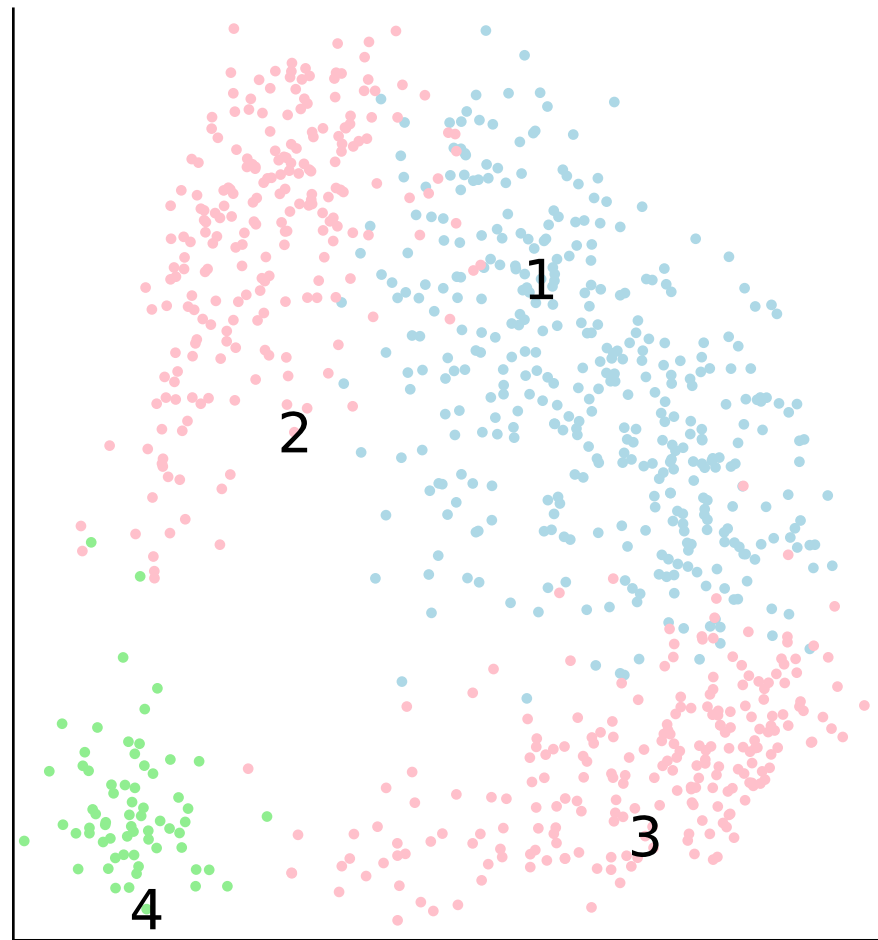


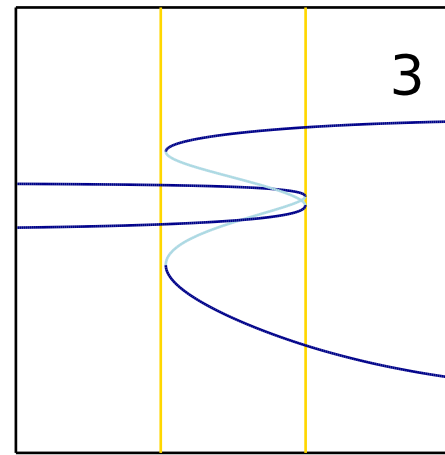
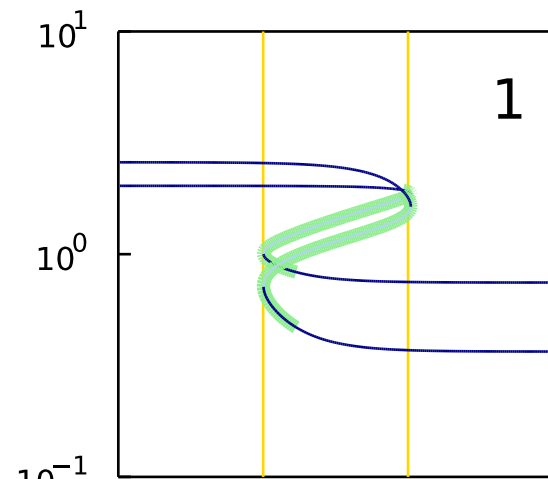
Parameter Estimates θ^*

Embedding Coordinate y

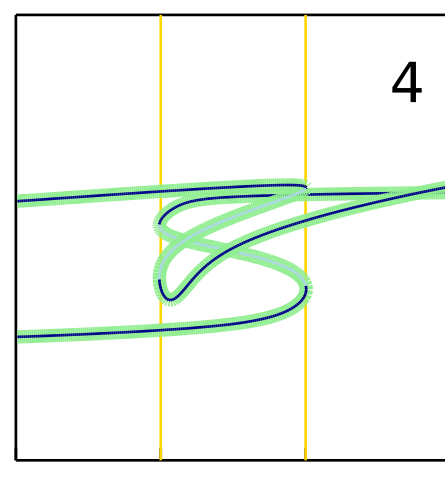
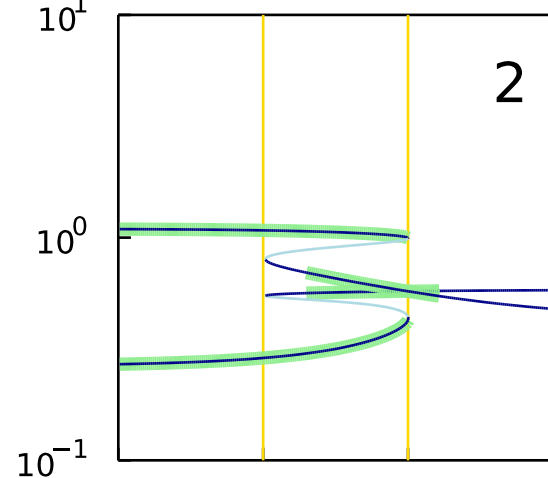


Embedding Coordinate x

steady states, L, T



steady states, L, T



control condition, p

control condition, p