Tortoise Occupancy

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Desert Tortoise Occupancy

Analyze survey data for desert tortoises from Saguaro National Park

Set-Up

I have installed the unmarked package for you already in Posit Cloud. This is a new package we will be using to do our occupancy calculations.

The code for using unmarked is not intuitive AT ALL. We will walk through an example together first, and then you can apply the code we write today to your assignment.

We will need to first load unmarked packages.

```
library(unmarked)
```

Now we need to read in our data set, called tortoise_occupancy.csv

```
tort_occ <- read.csv("../data_raw/tortoise_occupancy.csv")</pre>
```

Explore the data

First, let's take a look at tort_occ, our tortoise occupancy data. What does each column represent? How about each row?

head(tort_occ)

```
j_1 j_2 j_3 j_4 j_5
       0
           0
               1
                        0
       0
           0
               0
                        0
           0
               1
                        0
## 5
           0
                        0
## 6
           1
                        0
```

Naive Occupancy

Before we run any occupancy models that take detection probability into account, let's calculate the naive occupancy.

Naive occupancy is calculated by the number of sites where a species was detected (at least once) divided by the total number of sites surveyed.

```
# count up the number of times each site was marked as occupied
# returns a vector that we can now use
num_detections <- rowSums(tort_occ)
num_detections</pre>
```

[1] 5 1 0 2 0 2 4 0 0 3 1 4 0 2 0 0 0 3 2 3

```
# total number of sites that were surveyed
sites_surveyed <- nrow(tort_occ)
sites_surveyed</pre>
```

[1] 20

```
# number of sites with detection of greater than zero
sites_detection <- length(num_detections[num_detections > 0])
sites_detection
```

[1] 12

```
# divide the number of sites with detection
naive_occupancy <- sites_detection / sites_surveyed
naive_occupancy</pre>
```

[1] 0.6

Is this estimate of occupancy going to be higher or lower than when we take detection probability into account?

Occupancy Models

Now we are going to run a few models that take detection probability into account in our estimate. To do this, we will use the unmarked package, which has functions specifically for running these types of models.

To run correctly, the unmarked package requires we put our data in a very specific format.

Prepare Our Data

Create a time data frame First, we need to create a list of data frames (why, I don't know...) that includes our survey occasions.

Create unmarked data frame Now that we have both our occupancy data frame (the encounter histories) and a list that contains our survey data frame, we can create the specific type of data frame that the unmarked package requires. To do this, we use the unmarkedFrameOccu() function.

Running this line of code will produce a warning, but you can ignore it.

```
tortUMF <- unmarkedFrameOccu(tort_occ, obsCovs = surveys)</pre>
```

Warning: obsCovs contains characters. Converting them to factors.

Let's take a look at this new data frame that we just created.

```
head(tortUMF)
```

```
## Data frame representation of unmarkedFrame object.
      y.1 y.2 y.3 y.4 y.5 time.1 time.2 time.3 time.4 time.5
##
## 1
            1
                     1
                                               3
                                                       4
        1
                1
                         1
                                1
                                        2
                                                              5
                                        2
## 2
        0
            0
                 1
                     0
                         0
                                1
                                               3
                                                       4
                                                              5
## 3
            0
                     0
                         0
                                        2
                                               3
                                                              5
        0
                0
                                1
                                                       4
## 4
        1
            0
                     0
                         0
                                1
                                               3
                                                              5
## 5
            0
               0
                     0
                         0
                                               3
                                                              5
        0
                                1
                                        2
## 6
            1
                0
                    0
                         0
                                        2
                                               3
                                                              5
        1
                                1
                                                              5
## 7
            1 0
                    1
                                        2
                                               3
        1
                         1
                                1
## 8
        0
            0
                    0
                         0
                                1
                                        2
                                               3
                                                              5
                    0
                                        2
                                                              5
## 9
        0
            0
                0
                         Ω
                                1
                                               3
## 10
                     1
                         0
                                                              5
```

Fit Models for Occupancy

Occupancy models take the data from our encounter histories and first estimates detection probability. It then uses that detection probability estimate to produce an estimate of occupancy (our parameter of interest).

The function to run the occupancy model in unmarked is occu(). The function always take the argument for detection probability first and then the argument for occupancy.

Let's demonstrate. Our first model will have detection probability consistent across time (surveys) and occupancy consistent across sites. Remember, an assumption we have about occupancy is that it stays consistent through our surveys.

```
# Model \ p(.)psi(.) -- psi \ constant \ across \ sites, \ det \ prob \ constant \ over \ time \ pdot_psidot <- occu(~1 ~1, \ data = tortUMF)
```

Our second model will have occupancy consistent across sites but detection variability can vary with time (survey occasion).

Model Selection

We can run both models and then use AIC (an index of model quality) to determine which model fits our data the best. We want to choose the model with the lowest AIC because it represents the most parsimonious model.

We first make an object with a list of our models. Then we have the function modSel run the models and present us with the AIC values.

```
## pdot_psidot 2 113.25 0.00 0.75 cumltvWt
## ptime psidot 6 115.49 2.23 0.25 1.00
```

Based on the AIC values, which is our top model?

Estimates & 95% CIs

Now that we have chosen our top model, we want to discover what the actual values detection probability (p) and occupancy (psi) are and our uncertainty around them (95% confidence intervals).

Thankfully, there are functions that produce these values for us.

First, let's look at the parameter estimates (p and psi)

```
# This pulls out the coefficients (estimates) for the model

# For model: p(.)psi(.)
plogis(coef(pdot_psidot)) # estimates of psi and p

## psi(Int) p(Int)
## 0.6157371 0.5197018

# For model: p(t)psi(.)
plogis(coef(ptime_psidot))

## psi(Int) p(time1) p(time2) p(time3) p(time4) p(time5)
## 0.6112910 0.7361347 0.3271639 0.6543438 0.4089494 0.4907800
```

Note that there are 5 estimates for detection probability in the model that we allowed to vary through time. This is because the model produced a detection probability estimate for each survey occasion rather than just one overall detection probability estimate.

We can also calculate the 95% confidence intervals for each estimate. This time we use the **confint** function. We need to indicate the estimate type:

```
• occupancy: type = "state", as in the "true state" of occupancy
# model p(.)psi(.)
plogis(confint(pdot_psidot, type = "det", level = 0.95)) # 95% CI for p
##
              0.025
                        0.975
## p(Int) 0.3867842 0.6498879
plogis(confint(pdot_psidot, type = "state", level = 0.95)) # 95% CI for psi
                0.025
                          0.975
## psi(Int) 0.3858832 0.8033929
# model p(t)psi(.)
plogis(confint(ptime_psidot, type = "det",
                                              level = 0.95)
                0.025
                          0.975
## p(time1) 0.4295640 0.9117811
## p(time2) 0.1276352 0.6177361
## p(time3) 0.3625520 0.8630293
## p(time4) 0.1799118 0.6857501
## p(time5) 0.2368970 0.7495098
plogis(confint(ptime_psidot, type = "state", level = 0.95))
                0.025
##
                          0.975
## psi(Int) 0.3843875 0.7984203
```

• detection probability: type = "det"

Stop for a moment and think about what the 0.025 and 0.975 values represent. These are *not* estimates. Instead, they are signalling the upper and lower bounds of the confidence intervals.

Remember how confidence intervals are calculated in part based on a t-value from the Student's t-distribution? Each tail of the distribution represents 2.5% of the remaining probability, meaning the 95% confidence intervals include the values between 2.5% and 97.5% of the distribution.

Similar to the parameter estimates, we have 5 sets of confidence intervals for the model that allows the estimates of detection probability to vary with time; these are the confidence intervals for each estimate.