Deep Neural Network for Image Classification: Application

By the time you complete this notebook, you will have finished the last programming assignment of Week 4, and also the last programming assignment of Course 1! Go you!

To build your cat/not-a-cat classifier, you'll use the functions from the previous assignment to build a deep network. Hopefully, you'll see an improvement in accuracy over your previous logistic regression implementation.

After this assignment you will be able to:

Build and train a deep L-layer neural network, and apply it to supervised learning

Let's get started!

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1 - Packages

Begin by importing all the packages you'll need during this assignment.

- <u>numpy (https://www.numpy.org/)</u> is the fundamental package for scientific computing with Python.
- matplotlib (http://matplotlib.org) is a library to plot graphs in Python.
- <u>h5py (http://www.h5py.org)</u> is a common package to interact with a dataset that is stored on an H5 file.
- PIL (http://www.pythonware.com/products/pil/) and scipy (https://www.scipy.org/) are used here to test your model with your own picture at the end.
- dnn app utils provides the functions implemented in the "Building your Deep Neural Network: Step by Step" assignment to this notebook.
- np.random.seed(1) is used to keep all the random function calls consistent. It helps grade your work so please don't change it!

```
In [1]: import time
        import numpy as np
        import h5py
        import matplotlib.pyplot as plt
        import scipy
        from PIL import Image
        from scipy import ndimage
        from dnn app utils v3 import *
        from public tests import *
        %matplotlib inline
        plt.rcParams['figure.figsize'] = (5.0, 4.0) # set default size of plots
        plt.rcParams['image.interpolation'] = 'nearest'
        plt.rcParams['image.cmap'] = 'gray'
        %load ext autoreload
        %autoreload 2
        np.random.seed(1)
```

2 - Load and Process the Dataset

You'll be using the same "Cat vs non-Cat" dataset as in "Logistic Regression as a Neural Network" (Assignment 2). The model you built back then had 70% test accuracy on classifying cat vs non-cat images. Hopefully, your new model will perform even better!

Problem Statement: You are given a dataset ("data.h5") containing:

- a training set of `m_train` images labelled as cat (1) or non-cat (0)
- a test set of `m test` images labelled as cat and non-cat
- each image is of shape (num_px, num_px, 3) where 3 is for the 3 channels (RGB).

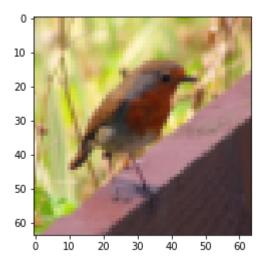
Let's get more familiar with the dataset. Load the data by running the cell below.

```
In [2]: train_x_orig, train_y, test_x_orig, test_y, classes = load_data()
```

The following code will show you an image in the dataset. Feel free to change the index and re-run the cell multiple times to check out other images.

```
In [3]: # Example of a picture
        index = 10
        plt.imshow(train_x_orig[index])
        print ("y = " + str(train_y[0,index]) + ". It's a " + classes[train_y[0,index]].decode("utf-8") +
        " picture.")
```

y = 0. It's a non-cat picture.



```
In [4]: # Explore your dataset
        m train = train x orig.shape[0]
        num px = train x orig.shape[1]
        m test = test x orig.shape[0]
        print ("Number of training examples: " + str(m_train))
        print ("Number of testing examples: " + str(m_test))
        print ("Each image is of size: (" + str(num_px) + ", " + str(num_px) + ", 3)")
        print ("train x orig shape: " + str(train x orig.shape))
        print ("train y shape: " + str(train y.shape))
        print ("test x orig shape: " + str(test x orig.shape))
        print ("test y shape: " + str(test y.shape))
```

Number of training examples: 209 Number of testing examples: 50 Each image is of size: (64, 64, 3) train x orig shape: (209, 64, 64, 3) train y shape: (1, 209) test x orig shape: (50, 64, 64, 3) test y shape: (1, 50)

As usual, you reshape and standardize the images before feeding them to the network. The code is given in the cell below.

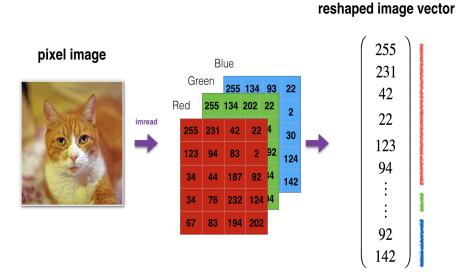


Figure 1: Image to vector conversion.

```
In [5]: # Reshape the training and test examples
        train_x_flatten = train_x_orig.reshape(train_x_orig.shape[0], -1).T # The "-1" makes reshape fla
        tten the remaining dimensions
        test_x_flatten = test_x_orig.reshape(test_x_orig.shape[0], -1).T
        # Standardize data to have feature values between 0 and 1.
        train_x = train_x_flatten/255.
        test x = test x flatten/255.
        print ("train_x's shape: " + str(train_x.shape))
        print ("test_x's shape: " + str(test_x.shape))
        train x's shape: (12288, 209)
        test x's shape: (12288, 50)
```

Note: 12, 288 equals $64 \times 64 \times 3$, which is the size of one reshaped image vector.

3 - Model Architecture

3.1 - 2-layer Neural Network

Now that you're familiar with the dataset, it's time to build a deep neural network to distinguish cat images from non-cat images!

You're going to build two different models:

- A 2-layer neural network
- An L-layer deep neural network

Then, you'll compare the performance of these models, and try out some different values for L.

Let's look at the two architectures:

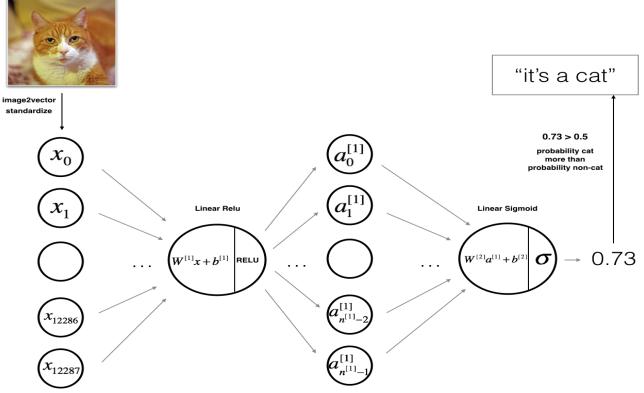


Figure 2: 2-layer neural network.

The model can be summarized as: INPUT -> LINEAR -> RELU -> LINEAR -> SIGMOID -> OUTPUT.

Detailed Architecture of Figure 2:

- The input is a (64,64,3) image which is flattened to a vector of size (12288, 1).
- The corresponding vector: $[x_0, x_1, \dots, x_{12287}]^T$ is then multiplied by the weight matrix $W^{[1]}$ of size $(n^{[1]}, 12288)$.
- Then, add a bias term and take its relu to get the following vector: $[a_0^{[1]}, a_1^{[1]}, \dots, a_{n^{[1]}-1}^{[1]}]^T$.
- · Repeat the same process.
- Multiply the resulting vector by $W^{[2]}$ and add the intercept (bias).
- Finally, take the sigmoid of the result. If it's greater than 0.5, classify it as a cat.

3.2 - L-layer Deep Neural Network

It's pretty difficult to represent an L-layer deep neural network using the above representation. However, here is a simplified network representation:

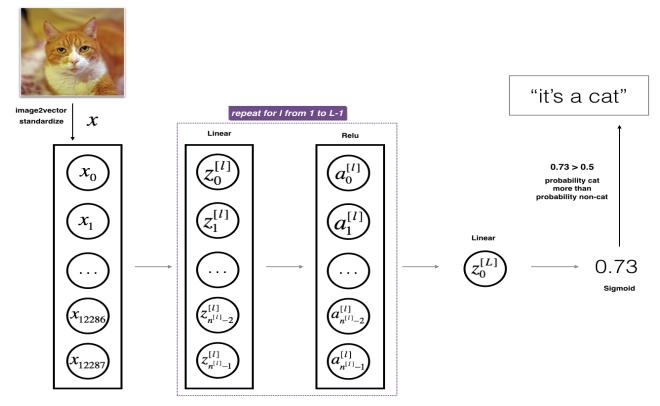


Figure 3: L-layer neural network.

The model can be summarized as: [LINEAR -> RELU] × (L-1) -> LINEAR -> SIGMOID

Detailed Architecture of Figure 3:

- The input is a (64,64,3) image which is flattened to a vector of size (12288,1).
- The corresponding vector: $[x_0, x_1, \dots, x_{12287}]^T$ is then multiplied by the weight matrix $W^{[1]}$ and then you add the intercept $b^{[1]}$. The result is called the linear unit.
- Next, take the relu of the linear unit. This process could be repeated several times for each $(W^{[l]}, b^{[l]})$ depending on the model architecture.
- Finally, take the sigmoid of the final linear unit. If it is greater than 0.5, classify it as a cat.

3.3 - General Methodology

As usual, you'll follow the Deep Learning methodology to build the model:

- 1. Initialize parameters / Define hyperparameters
- 2. Loop for num iterations: a. Forward propagation b. Compute cost function c. Backward propagation d. Update parameters (using parameters, and grads from backprop)
- 3. Use trained parameters to predict labels

Now go ahead and implement those two models!

4 - Two-layer Neural Network

Exercise 1 - two_layer_model

Use the helper functions you have implemented in the previous assignment to build a 2-layer neural network with the following structure: LINEAR -> *RELU -> LINEAR -> SIGMOID.* The functions and their inputs are:

```
def initialize_parameters(n_x, n_h, n_y):
    return parameters
def linear_activation_forward(A_prev, W, b, activation):
    return A, cache
def compute_cost(AL, Y):
    . . .
    return cost
def linear_activation_backward(dA, cache, activation):
    return dA_prev, dW, db
def update parameters(parameters, grads, learning rate):
    return parameters
 In [6]: ### CONSTANTS DEFINING THE MODEL ####
          n x = 12288  # num px * num px * 3
          n h = 7
          n y = 1
          layers_dims = (n_x, n_h, n_y)
          learning rate = 0.0075
```

```
In [9]: # GRADED FUNCTION: two layer model
        def two layer model(X, Y, layers dims, learning rate = 0.0075, num iterations = 3000, print cost=F
        alse):
             Implements a two-layer neural network: LINEAR->RELU->LINEAR->SIGMOID.
            Arguments:
            X -- input data, of shape (n x, number of examples)
             Y -- true "label" vector (containing 1 if cat, 0 if non-cat), of shape (1, number of examples)
             layers dims -- dimensions of the layers (n x, n h, n y)
             num iterations -- number of iterations of the optimization loop
             learning rate -- learning rate of the gradient descent update rule
             print cost -- If set to True, this will print the cost every 100 iterations
             Returns:
             parameters -- a dictionary containing W1, W2, b1, and b2
             np.random.seed(1)
             qrads = \{\}
             costs = []
                                                      # to keep track of the cost
                                                       # number of examples
             m = X.shape[1]
             (n \times n + n \times n) = layers dims
             # Initialize parameters dictionary, by calling one of the functions you'd previously implement
        ed
             \#(\approx 1 \text{ line of code})
             # parameters = ...
             # YOUR CODE STARTS HERE
             parameters = initialize parameters(n x,n h,n y)
             # YOUR CODE ENDS HERE
             # Get W1, b1, W2 and b2 from the dictionary parameters.
            W1 = parameters["W1"]
             b1 = parameters["b1"]
             W2 = parameters["W2"]
             b2 = parameters["b2"]
             # Loop (gradient descent)
```

```
for i in range(0, num iterations):
        # Forward propagation: LINEAR -> RELU -> LINEAR -> SIGMOID. Inputs: "X, W1, b1, W2, b2". 0
utput: "A1, cache1, A2, cache2".
        \#(\approx 2 \text{ lines of code})
        \# A1, cache1 = ...
        \# A2, cache2 = ...
        # YOUR CODE STARTS HERE
        A1, cache1 = linear_activation_forward(X, W1, b1, 'relu')
        A2, cache2 = linear activation forward(A1, W2, b2, 'sigmoid')
        # YOUR CODE ENDS HERE
        # Compute cost
        \#(\approx 1 \text{ line of code})
        \# cost = \dots
        # YOUR CODE STARTS HERE
        cost = compute cost(A2, Y)
        # YOUR CODE ENDS HERE
        # Initializing backward propagation
        dA2 = - (np.divide(Y, A2) - np.divide(1 - Y, 1 - A2))
        # Backward propagation. Inputs: "dA2, cache2, cache1". Outputs: "dA1, dW2, db2; also dA0
 (not used), dW1, db1".
        \#(\approx 2 \text{ lines of code})
        \# dA1, dW2, db2 = ...
        \# dA0, dW1, db1 = ...
        # YOUR CODE STARTS HERE
        dA1, dW2, db2 = linear activation backward(dA2, cache2, "sigmoid")
        dAO, dW1, db1 = linear activation backward(dA1, cache1, "relu")
        # YOUR CODE ENDS HERE
        # Set grads['dWl'] to dW1, grads['db1'] to db1, grads['dW2'] to dW2, grads['db2'] to db2
        qrads['dW1'] = dW1
        grads['db1'] = db1
        grads['dW2'] = dW2
        grads['db2'] = db2
        # Update parameters.
```

```
#(approx. 1 line of code)
        # parameters = ...
        # YOUR CODE STARTS HERE
        parameters = update parameters(parameters, grads, learning rate)
        # YOUR CODE ENDS HERE
       # Retrieve W1, b1, W2, b2 from parameters
       W1 = parameters["W1"]
       b1 = parameters["b1"]
       W2 = parameters["W2"]
       b2 = parameters["b2"]
       # Print the cost every 100 iterations
       if print cost and i % 100 == 0 or i == num iterations - 1:
            print("Cost after iteration {}: {}".format(i, np.squeeze(cost)))
       if i % 100 == 0 or i == num iterations:
            costs.append(cost)
    return parameters, costs
def plot costs(costs, learning rate=0.0075):
    plt.plot(np.squeeze(costs))
    plt.ylabel('cost')
    plt.xlabel('iterations (per hundreds)')
    plt.title("Learning rate =" + str(learning rate))
    plt.show()
```

```
In [10]: parameters, costs = two_layer_model(train_x, train_y, layers_dims = (n_x, n_h, n_y), num_iteration
         s = 2, print cost=False)
         print("Cost after first iteration: " + str(costs[0]))
         two_layer_model_test(two_layer_model)
         Cost after iteration 1: 0.6926114346158595
         Cost after first iteration: 0.693049735659989
         Cost after iteration 1: 0.6915746967050506
         Cost after iteration 1: 0.6915746967050506
         Cost after iteration 1: 0.6915746967050506
         Cost after iteration 2: 0.6524135179683452
          All tests passed.
```

Expected output:

cost after iteration 1 must be around 0.69

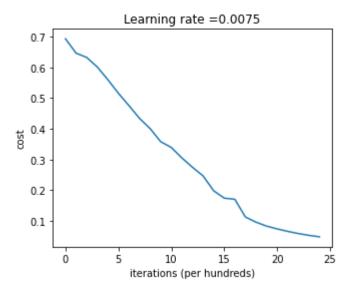
4.1 - Train the model

If your code passed the previous cell, run the cell below to train your parameters.

- The cost should decrease on every iteration.
- It may take up to 5 minutes to run 2500 iterations.

```
In [11]: parameters, costs = two_layer_model(train_x, train_y, layers_dims = (n_x, n_h, n_y), num_iteration
         s = 2500, print_cost=True)
         plot_costs(costs, learning_rate)
```

```
Cost after iteration 0: 0.693049735659989
Cost after iteration 100: 0.6464320953428849
Cost after iteration 200: 0.6325140647912677
Cost after iteration 300: 0.6015024920354665
Cost after iteration 400: 0.5601966311605747
Cost after iteration 500: 0.5158304772764729
Cost after iteration 600: 0.4754901313943325
Cost after iteration 700: 0.43391631512257495
Cost after iteration 800: 0.4007977536203886
Cost after iteration 900: 0.3580705011323798
Cost after iteration 1000: 0.3394281538366413
Cost after iteration 1100: 0.30527536361962654
Cost after iteration 1200: 0.2749137728213015
Cost after iteration 1300: 0.2468176821061484
Cost after iteration 1400: 0.19850735037466102
Cost after iteration 1500: 0.17448318112556638
Cost after iteration 1600: 0.1708076297809692
Cost after iteration 1700: 0.11306524562164715
Cost after iteration 1800: 0.09629426845937156
Cost after iteration 1900: 0.0834261795972687
Cost after iteration 2000: 0.07439078704319085
Cost after iteration 2100: 0.06630748132267933
Cost after iteration 2200: 0.05919329501038172
Cost after iteration 2300: 0.053361403485605606
Cost after iteration 2400: 0.04855478562877019
Cost after iteration 2499: 0.04421498215868956
```



Expected Output:

Cost after iteration 0 0.6930497356599888

Cost after iteration 100 0.6464320953428849

Cost after iteration 2499 0.04421498215868956

Nice! You successfully trained the model. Good thing you built a vectorized implementation! Otherwise it might have taken 10 times longer to train this. Now, you can use the trained parameters to classify images from the dataset. To see your predictions on the training and test sets, run the cell below.

Accuracy: 0.99999999999998

Expected Output:

Accuracy 0.99999999999998

```
In [13]: predictions_test = predict(test_x, test_y, parameters)
         Accuracy: 0.72
```

Expected Output:

Accuracy 0.72

Congratulations! It seems that your 2-layer neural network has better performance (72%) than the logistic regression implementation (70%, assignment week 2). Let's see if you can do even better with an L-layer model.

Note: You may notice that running the model on fewer iterations (say 1500) gives better accuracy on the test set. This is called "early stopping" and you'll hear more about it in the next course. Early stopping is a way to prevent overfitting.

5 - L-layer Neural Network

Exercise 2 - L_layer_model

Use the helper functions you implemented previously to build an L-layer neural network with the following structure: [LINEAR -> RELU] \times (L-1) -> LINEAR -> SIGMOID. The functions and their inputs are:

```
def initialize_parameters_deep(layers_dims):
    return parameters
def L_model_forward(X, parameters):
    return AL, caches
def compute_cost(AL, Y):
    return cost
def L_model_backward(AL, Y, caches):
    return grads
def update_parameters(parameters, grads, learning_rate):
    return parameters
```

```
In [ ]: ### CONSTANTS ###
        layers_dims = [12288, 20, 7, 5, 1] # 4-layer model
```

```
In [14]: # GRADED FUNCTION: L layer model
         def L layer model(X, Y, layers dims, learning rate = 0.0075, num iterations = 3000, print cost=Fal
         se):
              Implements a L-layer neural network: [LINEAR->RELU]*(L-1)->LINEAR->SIGMOID.
             Arguments:
             X -- data, numpy array of shape (num px * num px * 3, number of examples)
             Y -- true "label" vector (containing 0 if cat, 1 if non-cat), of shape (1, number of examples)
             layers dims -- list containing the input size and each layer size, of length (number of layers
         + 1).
             learning rate -- learning rate of the gradient descent update rule
             num iterations -- number of iterations of the optimization loop
             print cost -- if True, it prints the cost every 100 steps
              Returns:
              parameters -- parameters learnt by the model. They can then be used to predict.
              np.random.seed(1)
                                                  # keep track of cost
              costs = []
              # Parameters initialization.
              \#(\approx 1 \text{ line of code})
              # parameters = ...
              # YOUR CODE STARTS HERE
             parameters = initialize parameters deep(layers dims)
              # YOUR CODE ENDS HERE
             # Loop (gradient descent)
             for i in range(0, num iterations):
                  # Forward propagation: [LINEAR -> RELU]*(L-1) -> LINEAR -> SIGMOID.
                  \#(\approx 1 \text{ line of code})
                 # AL, caches = ...
                  # YOUR CODE STARTS HERE
                 AL, caches = L model forward(X, parameters)
                  # YOUR CODE ENDS HERE
```

```
# Compute cost.
   #(≈ 1 line of code)
   # cost = ...
   # YOUR CODE STARTS HERE
   cost = compute_cost(AL, Y)
   # YOUR CODE ENDS HERE
   # Backward propagation.
   #(≈ 1 line of code)
   \# grads = ...
   # YOUR CODE STARTS HERE
   grads = L model backward(AL,Y,caches)
   # YOUR CODE ENDS HERE
   # Update parameters.
   #(≈ 1 line of code)
   # parameters = ...
   # YOUR CODE STARTS HERE
   parameters = update parameters(parameters, grads, learning rate)
   # YOUR CODE ENDS HERE
   # Print the cost every 100 iterations
   if print cost and i % 100 == 0 or i == num iterations - 1:
       print("Cost after iteration {}: {}".format(i, np.squeeze(cost)))
   if i % 100 == 0 or i == num iterations:
       costs.append(cost)
return parameters, costs
```

```
In [15]: parameters, costs = L_layer_model(train_x, train_y, layers_dims, num_iterations = 1, print_cost =
         False)
         print("Cost after first iteration: " + str(costs[0]))
         L_layer_model_test(L_layer_model)
         Cost after iteration 0: 0.6950464961800915
         Cost after first iteration: 0.6950464961800915
         Cost after iteration 1: 0.7070709008912569
         Cost after iteration 1: 0.7070709008912569
         Cost after iteration 1: 0.7070709008912569
         Cost after iteration 2: 0.7063462654190897
          All tests passed.
```

5.1 - Train the model

If your code passed the previous cell, run the cell below to train your model as a 4-layer neural network.

- The cost should decrease on every iteration.
- It may take up to 5 minutes to run 2500 iterations.

```
parameters, costs = L layer model(train x, train y, layers dims, num iterations = 2500, print cost
In [16]:
         = True)
         Cost after iteration 0: 0.6950464961800915
         Cost after iteration 100: 0.5892596054583805
         Cost after iteration 200: 0.5232609173622991
         Cost after iteration 300: 0.4497686396221906
         Cost after iteration 400: 0.4209002161883899
         Cost after iteration 500: 0.37246403061745953
         Cost after iteration 600: 0.3474205187020191
         Cost after iteration 700: 0.31719191987370265
         Cost after iteration 800: 0.2664377434774658
         Cost after iteration 900: 0.21991432807842573
         Cost after iteration 1000: 0.1435789889362377
         Cost after iteration 1100: 0.4530921262322132
         Cost after iteration 1200: 0.09499357670093511
         Cost after iteration 1300: 0.08014128076781366
         Cost after iteration 1400: 0.0694023400553646
         Cost after iteration 1500: 0.060216640231745895
         Cost after iteration 1600: 0.05327415758001879
         Cost after iteration 1700: 0.04762903262098432
         Cost after iteration 1800: 0.04297588879436867
         Cost after iteration 1900: 0.03903607436513823
         Cost after iteration 2000: 0.03568313638049028
         Cost after iteration 2100: 0.032915263730546776
         Cost after iteration 2200: 0.030472193059120623
         Cost after iteration 2300: 0.028387859212946117
         Cost after iteration 2400: 0.026615212372776077
         Cost after iteration 2499: 0.024821292218353375
```

Expected Output:

Cost after iteration 0 0.771749 Cost after iteration 100 0.672053

Cost after iteration 2499 0.088439

```
In [17]: pred_train = predict(train_x, train_y, parameters)
         Accuracy: 0.99999999999998
```

Expected Output:

Train Accuracy 0.985645933014

```
In [18]: | pred_test = predict(test_x, test_y, parameters)
         Accuracy: 0.74
```

Expected Output:

Test Accuracy 0.8

Congrats! It seems that your 4-layer neural network has better performance (80%) than your 2-layer neural network (72%) on the same test set.

This is pretty good performance for this task. Nice job!

In the next course on "Improving deep neural networks," you'll be able to obtain even higher accuracy by systematically searching for better hyperparameters: learning rate, layers dims, or num iterations, for example.

6 - Results Analysis

First, take a look at some images the L-layer model labeled incorrectly. This will show a few mislabeled images.

print_mislabeled_images(classes, test_x, test_y, pred_test) In [19]:

A few types of images the model tends to do poorly on include:

- · Cat body in an unusual position
- Cat appears against a background of a similar color
- Unusual cat color and species
- Camera Angle
- · Brightness of the picture
- Scale variation (cat is very large or small in image)

Congratulations on finishing this assignment!

You just built and trained a deep L-layer neural network, and applied it in order to distinguish cats from non-cats, a very serious and important task in deep learning.;)

By now, you've also completed all the assignments for Course 1 in the Deep Learning Specialization. Amazing work! If you'd like to test out how closely you resemble a cat yourself, there's an optional ungraded exercise below, where you can test your own image.

Great work and hope to see you in the next course!

7 - Test with your own image (optional/ungraded exercise)

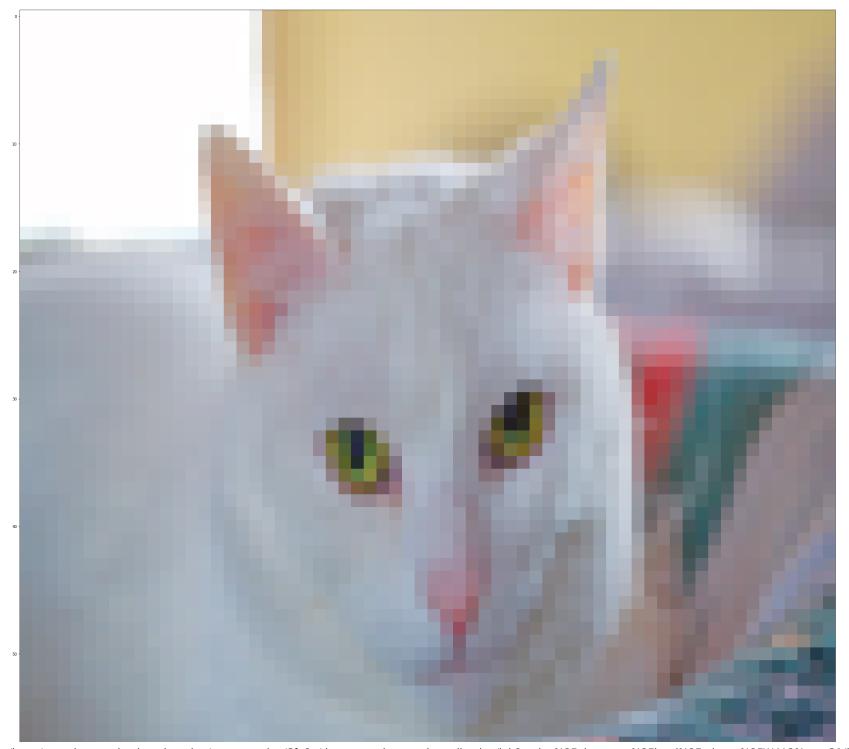
From this point, if you so choose, you can use your own image to test the output of your model. To do that follow these steps:

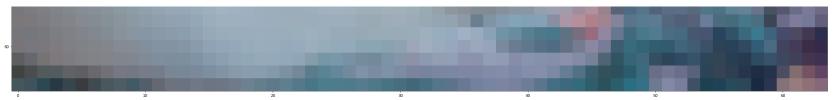
- 1. Click on "File" in the upper bar of this notebook, then click "Open" to go on your Coursera Hub.
- 2. Add your image to this Jupyter Notebook's directory, in the "images" folder
- 3. Change your image's name in the following code
- 4. Run the code and check if the algorithm is right (1 = cat, 0 = non-cat)!

```
In [20]: ## START CODE HERE ##
         my_image = "my_image.jpg" # change this to the name of your image file
         my_{abel_y} = [1] # the true class of your image (1 -> cat, 0 -> non-cat)
         ## END CODE HERE ##
         fname = "images/" + my image
         image = np.array(Image.open(fname).resize((num px, num px)))
         plt.imshow(image)
         image = image / 255.
         image = image.reshape((1, num px * num_px * 3)).T
         my_predicted_image = predict(image, my_label_y, parameters)
         print ("y = " + str(np.squeeze(my_predicted_image)) + ", your L-layer model predicts a \"" + class
         es[int(np.squeeze(my_predicted image)),].decode("utf-8") + "\" picture.")
```

Accuracy: 1.0

y = 1.0, your L-layer model predicts a "cat" picture.





References:

• for auto-reloading external module: http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython (http://stackoverflow.com/questions/1907993/autoreload-of-modules-in-ipython)