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## **CERTIFICATE**

It is certified that the work contained in this thesis, titled “ ” by NAME, has been carried out under my supervision and is not submitted elsewhere for a degree.

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Date

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To SOMEONE

## **Acknowledgments**

Acknowledgements goes here ...

## **Abstract**

Abstract goes here ...

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## *Chapter 1*

### **Introduction**

The popular opinion thanks to a confluence of distributional semantics and machine learning is that systems such as `word2vec` learn "vector representations". This seemed to me to be confusing the encoding the object (as a tuple of real numbers) with the algebraic structure (that of a vector space). Hence, the modest goal of the thesis is an attempt to disambiguate the term "vector representations".

Towards this end, we begin by surveying the algebraic structure of a vector space, and what it would really mean if words were vectors. We then provide a short explanation of the training mechanism of `word2vec`, and discuss why the embeddings that are learnt by systems it and its ilk do not deserve to be called vectors.

Thereafter, we take a step back and start from scratch; what ought the axioms be? Starting from a purely linguistic approach, we are led to conjecture, following the seminal work of Montague, that a set-based representation ought to be the best representation possible.

Following an empirical approach, we attempt to generalize the success of `word2vec` and the newly developed theory of contrastive losses, where we conjecture that a Lie group representation ought to be the best representation possible.

We report on experiments performed on both of these representations, always explained through the dual lenses of linguistics and abstract algebra. We hope that this blend of perspectives provides fresh insight into representation learning for NLP.

## *Chapter 2*

### **Are words vectors?**

#### **2.1 word2vec**

The core training loop of `word2vec` (trained using negative sampling, in skip-gram mode) involves attempting to learn *two* representations for a given word, called as the positive representation and the negative representation.

#### **2.2 Testing regime**

#### **2.3 Interpretations**

The output of the training regime are popularly interpreted as vectors. However, we augment this discussion by bringing in nuance. In particular, we note that:

- Scalar multiples of the same vector represent the same concept as per the testing regime.
- Vector addition has no clear meaning in the representation.
- The identity element (the zero vector) holds no semantic meaning in the representation.
- The reality of the training regime as-implemented makes it unclear as to what mathematical object is being learnt.

The classic explanation of ‘word2vec’, in skip-gram, with negative sampling, in the paper and countless blog posts on the internet is as follows:

## 2.4 Popular misconceptions

The original `word2vec` C implementation does not do what's explained above, and is drastically different. Most serious users of word embeddings, who use embeddings generated from `word2vec` do one of the following things:

- They invoke the original C implementation directly.
- They invoke the `gensim` implementation, which is *transliterated* from the C source to the extent that the variables names are the same.

## 2.5 The C implementation

The C implementation in fact maintains *two vectors for each word*, one where it appears as a focus word, and one where it appears as a context word. (Is this sounding familiar? Indeed, it appears that GloVe actually took this idea from 'word2vec', which has never mentioned this fact!)

The setup is incredibly well done in the C code:

- An array called `'syn0'` holds the vector embedding of a word when it occurs as a *focus word*. This is random initialized.

Another array called `syn1neg` holds the vector of a word when it occurs as a *context word*. This is zero initialized.

- During training (skip-gram, negative sampling, though other cases are also similar), we first pick a focus word. This is held constant throughout the positive and negative sample training. The gradients of the focus vector are accumulated in a buffer, and are applied to the focus word *after* it has been affected by both positive and negative samples.

## 2.6 Why random and zero initialization?

Once again, since none of this actually explained in the original papers *or on the web*, I can only hypothesize.

My hypothesis is that since the negative samples come from all over the text and are not really weighed by frequency, you can wind up picking *any word*, and more often than not, *a word whose vector has not been trained much at all*. If this vector actually had a value, then it could move the actually important focus word randomly.

The solution is to set all negative samples to zero, so that *only vectors that have occurred somewhat frequently* will affect the representation of another vector.

It's quite ingenious, really, and until this, I'd never really thought of how important initialization strategies really are.

This also explains GloVe's radical choice of having a separate vector for the negative context — they were just doing what `word2vec` does, but they told people about it

## Chapter 3

### Fuzzy set representations

In this paper, we provide an alternate perspective on word representations, by reinterpreting the dimensions of the vector space of a word embedding as a collection of features. In this reinterpretation, every component of the word vector is normalized against all the word vectors in the vocabulary. This idea now allows us to view each vector as an  $n$ -tuple (akin to a fuzzy set), where  $n$  is the dimensionality of the word representation and each element represents the probability of the word possessing a feature. Indeed, this representation enables the use of fuzzy set theoretic operations, such as union, intersection and difference. Unlike previous attempts, we show that this representation of words provides a notion of similarity which is inherently asymmetric and hence closer to human similarity judgements. We compare the performance of this representation with various benchmarks, and explore some of the unique properties including function word detection, detection of polysemous words, and some insight into the interpretability provided by set theoretic operations.

### 3.1 Introduction

Word embedding is one of the most crucial facets of Natural Language Processing (NLP) research. Most non-contextualized word representations aim to provide a distributional view of lexical semantics, known popularly by the adage "*a word is known by the company it keeps*" `cite: firth1957synopsis`. Popular implementations of word embeddings such as word2vec `cite: mikolov2013efficient` and GloVe `cite: pennington2014glove` aim to represent words as embeddings in a vector space. These embeddings are trained to be oriented such that vectors with higher similarities have higher dot products when normalized. Some of the most common methods of intrinsic evaluation of word embeddings include similarity, analogy and compositionality. While similarity is computed using the notion of dot product, analogy and compositionality use vector addition.

However, distributional representations of words over vector spaces have an inherent lack of interpretability `cite: goldberg2014word2vec`. Furthermore, due to the symmetric nature of the vector space operations for similarity and analogy, which are far from human similarity judgements `cite: tversky1977features`. Other word representations tried to provide asymmetric notions

of similarity in a non-contextualized setting, including Gaussian embeddings `cite: vilnis2014word` and word similarity by dependency `cite: gawron2014improving`. However, these models could not account for the inherent compositionality of word embeddings `cite: mikolov2013distributed`.

Moreover, while work has been done on providing entailment for vector space models by entirely reinterpreting word2vec as an entailment based semantic model `cite: henderson2016vector`, it requires an external notion of compositionality. Finally, word2vec and GloVe, as such, are meaning conflation deficient, meaning that a single word with all its possible meanings is represented by a single vector `cite: camacho2018word`. Sense representation models in non-contextualized representations such as multi-sense skip gram, by performing joint clustering for local word neighbourhood. However, these sense representations are conditioned on non-disambiguated senses in the context and require additional conditioning on the intended senses `cite: li2015multi`.

In this paper, we aim to answer the question: *Can a single word representation mechanism account for lexical similarity and analogy, compositionality, lexical entailment **and** be used to detect and resolve polysemy?* We find that by performing column-wise normalization of word vectors trained using the word2vec skip-gram negative sampling regime, we can indeed represent all the above characteristics in a single representation. We interpret a column wise normalized word representation. We now treat these representations as fuzzy sets and can therefore use fuzzy set theoretic operations such as union, intersection, difference, etc. while also being able to succinctly use asymmetric notions of similarity such as K-L divergence and cross entropy. Finally, we show that this representation can highlight syntactic features such as function words, use their properties to detect polysemy, and resolve it qualitatively using the inherent compositionality of this representation.

In order to make these experiments and their results observable in general, we have provided the code which can be used to run these operations. The code can be found at [https://github.com/AlokDebnath/fuzzy\\_embeddings](https://github.com/AlokDebnath/fuzzy_embeddings). The code also has a working command line interface where users can perform qualitative assessments on the set theoretic operations, similarity, analogy and compositionality which are discussed in the paper.

## 3.2 Related Work

The representation of words using logical paradigms such as fuzzy logic, tensorial representations and other probabilistic approaches have been attempted before. In this section, we uncover some of these representations in detail.

`cite: lee1999measures` introduced measures of distributional similarity to improve the probability estimation for unseen occurrences. The measure of similarity of distributional word clusters was based on multiple measures including Euclidian distance, cosine distance, Jaccard's Coefficient, and asymmetric measures like  $\alpha$ -skew divergence.

`cite: bergmair2011monte` used a fuzzy set theoretic view of features associated with word representations. While these features were not adopted from the vector space directly, it presents a



unique perspective of entailment chains for reasoning tasks. Their analysis of inference using fuzzy representations provides interpretability in reasoning tasks.

`cite: grefenstette2013towards` presents a tensorial calculus for word embeddings, which is based on compositional operators *which uses* vector representation of words to create a compositional distributional model of meaning. By providing a category-theoretic framework, the model creates an inherently compositional structure based on distributional word representations. However, they showed that in this framework, quantifiers could not be expressed.

`cite: herbelot2015building` refers to a notion of general formal semantics inferred from a distributional representation by creating relevant ontology based on the existing distribution. This mapping is therefore from a standard distributional model to a set-theoretic model, where dimensions are predicates and weights are generalised quantifiers.

`cite: emerson2016functional, emerson2017semantic` developed functional distributional semantics, which is a probabilistic framework based on model theory. The framework relies on differentiating and learning entities and predicates and their relations, on which Bayesian inference is performed. This representation is inherently compositional, context dependent representation.

### 3.3 Background: Fuzzy Sets and Fuzzy Logic

In this section, we provide a basic background of fuzzy sets including some fuzzy set operations, reinterpreting sets as tuples in a universe of finite elements and showing some set operations. We also cover the computation of fuzzy entropy as a Bernoulli random variable.

A fuzzy set is defined as a set with probabilistic set membership. Therefore, a fuzzy set is denoted as  $A = \{(x, \mu_A(x)), x \in \Omega\}$ , where  $x$  is an element of set  $A$  with a probability  $\mu_A(x)$  such that  $0 \leq \mu_A \leq 1$ , and  $\Omega$  is the universal set.

If our universe  $\Omega$  is finite and of cardinality  $n$ , our notion of probabilistic set membership is constrained to a maximum  $n$  values. Therefore, each fuzzy set  $A$  can be represented as an  $n$ -tuple, with each member of the tuple  $A[i]$  being the probability of the  $i$ th member of  $\Omega$ . We can rewrite a fuzzy set as an  $n$ -tuple  $A' = (\mu_{A'}(x), \forall x \in \Omega)$ , such that  $|A'| = |\Omega|$ . In this representation,  $A[i]$  is the probability of the  $i$ th member of the tuple  $A$ . We define some common set operations in terms of this representation as follows.

$$\begin{aligned}
(A \cap B)[i] &\equiv A[i] \times B[i] \quad (\text{set intersection}) \\
(A \cup B)[i] &\equiv A[i] + B[i] - A[i] \times B[i] \quad (\text{set union}) \\
(A \sqcup B)[i] &\equiv \max(1, \min(0, A[i] + B[i])) \quad (\text{disjoint union}) \\
(\neg A)[i] &\equiv 1 - A[i] \quad (\text{complement}) \\
(A \setminus B)[i] &\equiv A[i] - \min(A[i], B[i]) \quad (\text{set difference}) \\
(A \subseteq B) &\equiv \forall x \in \Omega : \mu_A(x) \leq \mu_B(x) \quad (\text{set inclusion}) \\
|A| &\equiv \sum_{i \in \Omega} \mu_A(i) \quad (\text{cardinality})
\end{aligned}$$

The notion of entropy in fuzzy sets is an extrapolation of Shannon entropy from a single variable on the entire set. Formally, the fuzzy entropy of a set  $S$  is a measure of the uncertainty of the elements belonging to the set. The possibility of a member  $x$  belonging to the set  $S$  is a random variable  $X_i^S$  which is *true* with probability ( $p_i^S$ ) and *false* with probability ( $1 - p_i^S$ ). Therefore,  $X_i^S$  is a Bernoulli random variable. In order to compute the entropy of a fuzzy set, we sum the entropy values of each  $X_i^S$ :

$$\begin{aligned}
H(A) &\equiv \sum_i H(X_i^A) \\
&\equiv \sum_i -p_i^A \ln p_i^A - (1 - p_i^A) \ln(1 - p_i^A) \\
&\equiv \sum_i -A[i] \ln A[i] - (1 - A[i]) \ln(1 - A[i])
\end{aligned}$$

This formulation will be useful in section 3.4.4 where we discuss two asymmetric measures of similarity, cross-entropy and K-L divergence, which can be seen as a natural extension of this formulation of fuzzy entropy.

### 3.4 Representation and Operations

In this section, we use the mathematical formulation above to reinterpret word embeddings. We first show how these word representations are created, then detail the interpretation of each of the set operations with some examples. We also look into some measures of similarity and their formulation in this framework. All examples in this section have been taken using the Google News Negative 300 vectors<sup>1</sup>. We used these gold standard vectors

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<sup>1</sup><https://code.google.com/archive/p/word2vec/>

### 3.4.1 Constructing the Tuple of Feature Probabilities

We start by converting the skip-gram negative sample word vectors into a tuple of feature probabilities. In order to construct a tuple of features representation in  $\mathbb{R}^n$ , we consider that the projection of a vector  $\vec{v}$  onto a dimension  $i$  is a function of its probability of possessing the feature associated with that dimension. We compute the conversion from a word vector to a tuple of features by first exponentiating the projection of each vector along each direction, then averaging it over that feature for the entire vocabulary size, i.e. column-wise.

$$v_{exp}[i] \equiv \exp \vec{v}[i]$$

$$\hat{v}[i] \equiv \frac{v_{exp}[i]}{\sum_{w \in \text{VOCAB}} \exp w_{exp}[i]}$$

This normalization then produces a tuple of probabilities associated with each feature (corresponding to the dimensions of  $\mathbb{R}^n$ ).

In line with our discussion from 3.3, this tuple of probabilities is akin to our representation of a fuzzy set. Let us consider the word  $v$ , and its corresponding  $n$ -dimensional word vector  $\vec{v}$ . The projection of  $\vec{v}$  on a dimension  $i$  normalized (as shown above) to be interpreted as *if this dimension  $i$  were a property, what is probability that  $v$  would possess that property?*

In word2vec, words are distributed in a vector space of a particular dimensionality. Our representation attempts to provide some insight into how the arrangement of vectors provides insight into the properties they share. We do so by considering a function of the projection of a word vector onto a dimension and interpreting as a probability. This allows us an avenue to explore the relation between words in relation to the properties they share. It also allows us access to the entire arsenal of set operations, which are described below in section 3.4.2.

### 3.4.2 Operations on Feature Probabilities

Now that word vectors can be represented as tuples of feature probabilities, we can apply fuzzy set theoretic operations in order to ascertain the veracity of the implementation. We show qualitative examples of the set operations in this subsection, and the information they capture. Throughout this subsection, we follow the following notation: For any two words  $w_1, w_2 \in \text{VOCAB}$ ,  $\hat{w}_1$  and  $\hat{w}_2$  represents those words using our representation, while  $\vec{w}_1$  and  $\vec{w}_2$  are the word2vec vectors of those words.

**3.4.2.0.1 Feature Union, Intersection and Difference** In section 3.3, we showed the formulation of fuzzy set operations, assuming a finite universe of elements. As we saw in section 3.4.1, considering each dimension as a feature allows us to reinterpret word vectors as tuples of feature probabilities. Therefore, we can use the fuzzy set theoretic operations on this reinterpretation of fuzzy sets. For convenience, these operations have been called feature union, intersection and difference.

$\hat{R}$	$\vec{R}$	$\hat{V}$	$\vec{V}$	$\hat{R} \cup \hat{V}$
risen	cashew	wavelengths	yellowish	flower
capita	risen	ultraviolet	whitish	red
peaked	soared	purple	aquamarine	stripes
declined	acuff	infrared	roans	flowers
increased	rafters	yellowish	bluish	green
rises	equalled	pigment	greenish	garlands

**Table 3.1** An example of feature union. `Rose` is represented by  $R$  and `Violet` by  $V$ . We see here that while the word `rose` and `violet` have different meanings and senses, the union  $R \cup V$  captures the sense of the flower as well as of colours, which are the senses common to these two words. We list words closest to the given word in the table. Closeness measured by cosine similarity for word2vec and cross-entropy-similarity for our vectors.

$\hat{C}$	$\hat{P}$	$\hat{C} \cap \hat{P}$
hardware	vested	cpu
graphics	purchasing	hardware
multitasking	capita	powerpc
console	exercise	machine
firewire	parity	multitasking
mainframe	veto	microcode
$\vec{C}$	$\vec{P}$	$\vec{C} + \vec{P}$
bioses	centralize	expandability
scummvm	veto	writable
hardware	decembrist	cpcs
imovie	exercised	reconfigure
writable	redistribution	backplane
console	devolving	oem

**Table 3.2** An example of feature intersection with the possible word2vec analogue (vector addition). The word `computer` is represented by  $C$  and `power` by  $P$ . Note that `power` is also a decent example of polysemy, and we see that in the context of computers, the connotations of `hardware` and the `CPU` are the most accessible. We list words closest to the given word in the table. Closeness measured by cosine similarity for word2vec and cross-entropy-similarity for our vectors.

Intuitively, the feature intersection of words  $\hat{w}_1$  and  $\hat{w}_2$  should give us that word  $\hat{w}_{1 \cap 2}$  which has the features common between the two words; an example of which is given in table 3.1. Similarly, the feature union  $\hat{w}_{1 \cup 2} \simeq \hat{w}_1 \cup \hat{w}_2$  which has the properties of both the words, normalized for those properties which are common between the two, and feature difference  $\hat{w}_{1 \setminus 2} \simeq \hat{w}_1 \setminus \hat{w}_2$  is that word which is similar to  $w_1$  without the features of  $w_2$ . Examples of feature intersection and feature difference are shown in table ?? and ?? respectively.

While feature union does not seem to have a word2vec analogue, we consider that feature intersection is analogous to vector addition, and feature difference as analogous to vector difference.

**3.4.2.0.2 Feature Inclusion** Feature inclusion is based on the subset relation of fuzzy sets. We aim to capture feature inclusion by determining if there exist two words  $w_1$  and  $w_2$  such that *all* the feature

$\hat{F}$	$\hat{B}$	$\hat{F} \setminus \hat{B}$
french	isles	communaut
english	colonial	aise
france	subcontinent	langue
german	cinema	monet
spanish	boer	dictionnaire
british	canadians	gascon
$\vec{F}$	$\vec{B}$	$\vec{F} - \vec{B}$
french	scottish	ranjit
english	american	privatised
france	thatcherism	tardis
german	netherlands	molloy
spanish	hillier	isaacs
british	cukcs	raj

**Table 3.3** An example of feature difference, along with a possible word2vec analogue (vector difference). French is represented by  $F$  and British by  $B$ . We see here that set difference capture french words from the dataset, while there does not seem to be any such correlation in the vector difference. We list words closest to the given word in the table. Closeness measured by cosine similarity for word2vec and cross-entropy-similarity for our vectors.

probabilities of  $\hat{w}_1$  are less than that of  $\hat{w}_2$ , then  $\hat{w}_2 \subseteq \hat{w}_1$ . We find that feature inclusion is closely linked to hyponymy, which we will show in 3.5.3.

### 3.4.3 Interpreting Entropy

For a word represented using a tuple of feature probabilities, the notion of entropy is strongly tied to the notion of certainty `cite: xuecheng1992entropy`, i.e. with what certainty does this word possess or not possess this set of features? Formally, the fuzzy entropy of a set  $S$  is a measure of the uncertainty of elements belonging to the set. The possibility a member  $x_i$  belonging to  $S$  is a random variable  $X_i^S$ , which is `true` with probability  $p_i^S$ , `false` with probability  $(1 - p_i^S)$ . Thus,  $X_i^S$  is a Bernoulli random variable. So, to measure the fuzzy entropy of a set, we add up the entropy values of each of the  $X_i^S$  `cite: mackay2003information`.

Intuitively, words with the highest entropy are those which have features which are equally likely to belong to them and to their complement, i.e.  $\forall i \in \Omega, A[i] \simeq 1 - A[i]$ . So words with high fuzzy entropy can occur only in two scenarios: (1) The words occur with very low frequency so their random initialization remained, or (2) The words occur around so many different word groups that their corresponding fuzzy sets have some probability of possessing most of the features.

Therefore, our representation of words as tuples of features can be used to isolate function words better than the more commonly considered notion of simply using frequency, as it identifies the information theoretic distribution of features based on the context the function word occurs in. Table ?? provides the top 15 function words by entropy, and the correspondingly ranked words by frequency. We see that frequency is clearly not a good enough measure to identify function words.

### 3.4.4 Similarity Measures

One of the most important notions in presenting a distributional word representation is its ability to capture similarity `cite: van2006finding`. Since we use and modify vector based word representations, we aim to preserve the "distribution" of the vector embeddings, while providing a more robust interpretation of similarity measures. With respect to similarity, we make two strong claims:

1. Representing words as a tuple of feature probabilities lends us an inherent notion of similarity. Feature difference provides this notion, as it estimates the difference between two words along each feature probability.
2. Our representation allows for an easy adoption of known similarity measures such as K-L divergence and cross-entropy.

Note that feature difference (based on fuzzy set difference), K-L divergence and cross-entropy are all asymmetric measures of similarity. As `cite: nematzadeh2017evaluating` points out, human similarity judgements are inherently asymmetric in nature. We would like to point out that while most methods of introducing asymmetric similarity measures in word2vec account for both the focus and context vector `cite: asr2018querying` and provide the asymmetry by querying on this combination of focus and context representations of each word. Our representation, on the other hand, uses only the focus representations (which are a part of the word representations used for downstream task as well as any other intrinsic evaluation), and still provides an innately asymmetric notion of similarity.

**3.4.4.0.1 K-L Divergence** From a fuzzy set perspective, we measure similarity as an overlap of features. For this purpose, we exploit the notion of fuzzy information theory by comparing how close the probability distributions of the similar words are using a standard measure, Kullback-Leibler (K-L) divergence. K-L divergence is an asymmetric measure of similarity.

The K-L divergence of a distribution  $P$  from another distribution  $Q$  is defined in terms of loss of compression. Given data  $d$  which follows distribution  $P$ , the extra bits need to store it under the false assumption that the data  $d$  follows distribution  $Q$  is the K-L divergence between the distributions  $P$  and  $Q$ . In the fuzzy case, we can compute the KL divergence as:

We see in table ?? some qualitative examples of how K-L divergence shows the relation between two words (or phrases when composed using feature intersection as in the case of `north korea`). We exemplify `cite: nematzadeh2017evaluating`'s human annotator judgement of the distance between China and North Korea, where human annotators considered "North Korea" to be very similar to "China," while the reverse relationship was rated as significantly less strong ("China" is not very similar to "North Korea").

**3.4.4.0.2 Cross Entropy** We also calculate the cross entropy between two words, as it can be used to determine the entropy associated with the similarity between two words. Ideally, by determining the

”spread” of the similarity of features between two words, we can determine the features that allow two words to be similar, allowing a more interpretable notion of feature-wise relation.

The cross-entropy of two distributions  $P$  and  $Q$  is a sum of the entropy of  $P$  and the K-L divergence between  $P$  and  $Q$ . In this sense, it captures both the *uncertainty in  $P$* , as well as the distance from  $P$  to  $Q$ , to give us a general sense of the information theoretic difference between the concepts of  $P$  and  $Q$ . We use a generalized version of cross-entropy to fuzzy sets [cite: li2015fuzzy](#), which is:

$$H(S, T) \equiv \sum_i H(X_i^S) + D(X_i^S || X_i^T)$$

Feature representations which on comparison provide high cross entropy imply a more distributed feature space. Therefore, provided the right words to compute cross entropy, it could be possible to extract various features common (or associated) with a large group of words, lending some insight into how a single surface form (and its representation) can capture the distribution associated with different senses. Here, we use cross-entropy as a measure of polysemy, and isolate polysemous words based on context. We provide an example of capturing polysemy using composition by feature intersection in [table ??](#).

We can see that the words which are most similar to `noble` are a combination of words from many senses, which provides some perspective into its distribution, . Indeed, it has an entropy value of 6.2765<sup>2</sup>.

### 3.4.5 Constructing Analogy

Finally, we construct the notion of analogy in our representation of a word as a tuple of features. Word analogy is usually represented as a problem where given a pairing ( $a : b$ ), and a prior  $x$ , we are asked to compute an unknown word  $y?$  such that  $a : b :: x : y?$ . In the vector space model, analogy is computed based on vector distances. We find that this training mechanism does not have a consistent interpretation beyond evaluation. This is because normalization of vectors *performed only during inference, not during training*. Thus, computing analogy in terms of vector distances provides little insight into the distribution of vectors or to the notion of the length of the word vectors, which seems to be essential to analogy computation using vector operations

In using a fuzzy set theoretic representation, vector projections are inherently normalized, making them feature dense. This allows us to compute analogies much better in lower dimension spaces. We consider analogy to be an operation involving union and set difference. Word analogy is computed as follows:

$$\begin{aligned} a : b :: x : y? \\ y? &= b - a + x \implies y? = (b + x) - a \\ y &= (b \sqcup x) \setminus a \quad (\text{Set-theoretic interpretation}) \end{aligned}$$

---

<sup>2</sup>For reference, the word `the` has an entropy of 6.2934.

Notice that this form of word analogy can be "derived" from the vector formula by re-arrangement. We use non-disjoint set union so that the common features are not eliminated, but the values are clipped at  $(0, 1]$  so that the fuzzy representation is consistent. Analogical reasoning is based on the common features between the word representations, and conflates multiple types of relations such as synonymy, hypernymy and causal relations `cite: chen2017evaluating`. Using fuzzy set theoretic representations, we can also provide a context for the analogy, effectively reconstructing analogous reasoning to account for the type of relation from a lexical semantic perspective.

Some examples of word analogy based are presented in table ??.

## 3.5 Experiments and Results

In this section, we present our experiments and their results in various domains including similarity, analogy, function word detection, polysemy detection, lexical entailment and compositionality. All the experiments have been conducted on established datasets.

### 3.5.1 Similarity and Analogy

Similarity and analogy are the most popular intrinsic evaluation mechanisms for word representations `cite: mikolov2013efficient`. Therefore, to evaluate our representations, the first tasks we show are similarity and analogy. For similarity computations, we use the SimLex corpus `cite: hill2015simlex` for training and testing at different dimensions For word analogy, we use the MSR Word Relatedness Test `cite: mikolov2013linguistic`. We compare it to the vector representation of words for different dimensions.

#### 3.5.1.1 Similarity

Our scores are compared to the word2vec scores of similarity using the Spearman rank correlation coefficient `cite: spearman1987proof`, which is a ratio of the covariances and standard deviations of the inputs being compared.

As shown in table ??, using our representation, similarity is *slightly* better represented according to the SimLex corpus. We show similarity on both the asymmetric measures of similarity for our representation, K-L divergence as well as cross-entropy. We see that cross-entropy performs better than K-L Divergence. While the similarity scores are generally higher, we see a reduction in the degree of similarity beyond 100 dimension vectors (features).

#### 3.5.1.2 Analogy

For analogy, we see that our model outperforms word2vec at both 50 and 100 dimensions. We see that at lower dimension sizes, our normalized feature representation captures significantly more



syntactic and semantic information than its vector counterpart. We conjecture that this can primarily be attributed to the fact that constructing feature probabilities provides more information about the common (and distinct) "concepts" which are shared between two words.

Since feature representations are inherently fuzzy sets, lower dimension sizes provide a more reliable probability distribution, which becomes more and more sparse as the dimensionality of the vectors increases (i.e. number of features rise). Therefore, we notice that the increase in feature probabilities is a lot more for 50 dimensions than it is for 100.

### 3.5.2 Function Word Detection

As mentioned in section 3.4.3, we use entropy as a measure of detecting function words for the standard GoogleNews-300 negative sampling dataset<sup>3</sup>. In order to quantitatively evaluate the detection of function words, we choose the top  $n$  words in our representation ordered by entropy with a frequency  $\geq 100$ , and compare it to the top  $n$  words ordered by frequency from word2vec;  $n$  being 15, 30 and 50. We compare the number of function words in both in table ?? . The list of function words is derived from cite: nation2016making.

### 3.5.3 Compositionality

Finally, we evaluate the compositionality of word embeddings. cite: mikolov2013distributed claims that word embeddings in vector spaces possess additive compositionality, i.e. by vector addition, semantic phrases such as compounds can be well represented. We claim that our representation in fact captures the semantics of phrases by performing a literal combination of the features of the head and modifier word, therefore providing a more robust representation of phrases.

We use the English nominal compound phrases from cite: ramisch-etal-2016-naked. An initial set of experiments on nominal compounds using word2vec have been done before cite: cordeiro-etal-2016-predicting, where it was shown to be a fairly difficult task for modern non-contextual word embeddings. In order to analyse nominal compounds, we adjust our similarity metric to account for asymmetry in the similarity between the head-word and the modifier, and vice versa. We report performance on two metrics, the Spearman correlation cite: spearman1987proof and Pearson correlation cite: pearson1920notes. The results are shown in table ?? . The difference in scores for the Pearson and Spearman rank correlation show that word2vec at higher dimensions better represents the rank of words (by frequency), but at lower dimensions, the feature probability representation has a better analysis of both rank by frequency, and its correlation with similarity of words with a nominal compound. Despite this, we show a higher Spearman correlation coefficient at 200 dimensions as well, as we capture non-linear relations.

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<sup>3</sup><https://code.google.com/archive/p/word2vec/>

### 3.5.4 Dimensionality Analysis and Feature Representations

In this subsection, we provide some interpretation of the results above, and examine the effect of scaling dimensions to the feature representation. As seen here, the evaluation has been done on smaller dimension sizes of 50 and 100, and we see that our representation can be used for a slightly larger range of tasks from the perspective of intrinsic evaluations. However, the results of quantitative analogy for higher dimensions have been observed to be lower for fuzzy representations rather than the word2vec negative-sampling word vectors.

We see that the representation we propose does not scale well as dimensions increase. This is because our representation relies on the distribution of probability mass per feature (dimension) across all the words. Therefore, increasing the dimensionality of the word vectors used makes the representation that much more sparse.

## 3.6 Conclusion

In this paper, we presented a reinterpretation of distributional semantics. We performed a column-wise normalization on word vectors, such that each value in this normalized representation represented the probability of the word possessing a feature that corresponded to each dimension. This provides us a representation of each word as a tuple of feature probabilities. We find that this representation can be seen as a fuzzy set, with each probability being the function of the projection of the original word vector on a dimension.

Considering word vectors as fuzzy sets allows us access to set operations such as union, intersection and difference. In our modification, these operations provide the product, disjoint sum and difference of the word representations, feature wise. Using qualitative examples, we show that our representation naturally captures an asymmetric notion of similarity using feature difference, from which known asymmetric measures can be easily constructed, such as Cross Entropy and K-L Divergence.

We qualitatively show how our model accounts for polysemy, while showing quantitative proofs of our representation’s performance at lower dimensions in similarity, analogy, compositionality and function word detection. We hypothesize that lower dimensions are more suited for our representation as sparsity increases with higher dimensions, so the significance of feature probabilities reduces. This sparsity causes a diffusion of the probabilities across multiple features.

Through this work, we aim to provide some insights into interpreting word representations by showing one possible perspective and explanation of the lengths and projections of word embeddings in the vector space. These feature representations can be adapted for basic neural models, allowing the use of feature based representations at lower dimensions for downstream tasks.

## Chapter 4

### Optimisation on manifolds

We now consider manifold optimisation techniques on embedded riemannian manifolds  $M$ , equipped with the metric  $g : (p : M) \rightarrow T_p M \times T_p M \rightarrow \mathbb{R}$ . The metric at a point  $g(p)$  provides an inner product structure on the point  $T_p M$  for a  $p \in M$ .

where we are optimising a cost function  $c : M \rightarrow \mathbb{R}$ . We presume that we have a diffeomorphism  $E : M \rightarrow \mathbb{R}^n$  (Embedding) which preserves the metric structure. We will elucidate this notion of preserving the metric structure once we formally define the mapping between tangent spaces. This allows us to treat  $M$  as a subspace of  $\mathbb{R}^n$ .

For any object  $X$  defined with respect to the manifold, we define a new object  $\overline{X}$ , which is the embedded version of  $X$  in  $\mathbb{R}^n$ .

We define  $\overline{M} \subset \mathbb{R}^n$ ;  $\overline{M} \equiv \text{image}(E)$ . We define  $\bar{c} : \overline{M} \subseteq \mathbb{R}^n \rightarrow \mathbb{R}$ ;  $\bar{c} \equiv c \circ E^{-1}$

We then needh two operators, that allows us to project onto the tangent space and the normal space. The tangent space at a point  $x_0 \in M$ ,  $\overline{T_{x_0} M} \equiv \text{span}(\partial_i E|_{E(x_0)})$ . We get an induced mapping of tangent spaces  $dE : T_{x_0} M$  and  $T_{x_0} \overline{M}$ .

we consider the gradient  $\overline{\nabla} c : (p : \overline{M}) \rightarrow \overline{T_p M}$ ;  $\overline{\nabla} c \equiv dE \bar{c}$

The normal space,  $\overline{N_{x_0} M}$  is the orthogonal complement of the tangent space, defined as  $\overline{N_{x_0} M} \equiv \{v \in \mathbb{R}^n \mid \langle v | \overline{T_{x_0} M} \rangle = 0\}$ . It is often very easy to derive the projection onto the normal space, from whose orthogonal complement we derive the projection of the tangent space.

The final piece that we require is a retraction  $R : \mathbb{R}^n \rightarrow \overline{M} \subseteq \mathbb{R}^n$ . This allows us to project elements of the ambient space that are not on the manifold. The retraction must obey the property  $R(p \in \overline{M}) = p$ . (TODO: is this correct? Do we need  $R(\overline{M}) = \overline{M}$  or is this pointwise?) (what are the other conditions on the retraction? smoothness?)

Given all of this machinery, the algorithm is indeed quite simple.

- $x \in \overline{M} \subseteq \mathbb{R}^n$  is the current point on the manifold as an element of  $\mathbb{R}^n$
- Compute  $g = \overline{\nabla} c(x) \in T_x \mathbb{R}^n$  is the gradient with respect to  $\mathbb{R}^n$ .
- $\bar{g} = P_{T_x} g \in T_x M$  is the projection of the gradient with respect to  $\mathbb{R}^n$  onto the tangent space of the manifold.

- $x_{mid} \in \mathbb{R}^n \equiv x + \eta \bar{g}$ , a motion along the tangent vector, giving a point in  $\mathbb{R}^n$ .
- $\bar{x}_{next} : \bar{M} \equiv R(x_{mid})$ , the retraction of the motion along the tangent vector, giving a point on the manifold  $\bar{M}$ .

## Chapter 5

### Distinction with a difference: Grassmanian representations

Embedding words in vector spaces has become the norm for distributional lexical semantic representations. While esoteric literature has attempted to change the underlying embedding space, the resultant word embeddings are specific to a given task or linguistic property. In this paper, we hypothesize that word representations need not change the embedding space, rather the object they are embedded as. We address the notion of a context vector introduced in the skip-gram, CBOW and GloVe models, and test our hypothesis by analyzing word embeddings in the symplectic manifold, where each word is represented by a 2-dimensional pair of (position, momentum), as proposed by Hamiltonian mechanics. We further generalize our representation to embedding words in a Grassmanian space  $\mathbf{Gr}(p, V)$ , where each word is a  $p$ -dimensional subspace of a larger  $n$  dimensional vector space  $V$ , and similarity and analogy are computed exploiting the Lie theoretic structure of the Grassmanian; its exponential map, retraction, and parallel transport of geodesics. Finally, we provide rigorous empirical evidence and theoretical insight into our embeddings' ability to capture sense information and latent syntactic characteristics, improving the expressivity of the overall representation.

Word representation is a central challenge in natural language processing. The terms *word vectors* and *word embeddings* synonymous to one another, due to the success of vector based models such as word2vec, GloVe and FastText. Even with the introduction of contextualized word representations, the underlying structure of word representations has remained the same, mapping a word to a single vector in a continuous vector space. Some of the known challenges with this assumption of word to vector have been based around resolving polysemy and the treatment of function words, to which the classical answer has been extracting and using contextual information.

#### 5.0.1 The blessing and curse of $\mathbb{R}^n$

Let us consider the fundamental operations performed with `word2vec` :

- Similarity: Given two words, find how similar they are in meaning. This is expressed as a dot product between the two word vectors.

- Analogy: Given three words representing a sense of analogy ( $\text{king} : \text{man} :: \text{woman}$ ), find the unknown word  $x$  which represents the analogy  $\text{king} : \text{man} :: \text{woman} : x$ . This is computed as  $x \equiv \text{man} - \text{king} + \text{woman}$ .

Let us see how we use the vector space structure for these operations. For similarity, we use the dot product for a notion of similarity. For analogy, we use the vectorial addition and subtraction operations.

However, linguistically speaking, there is a difference between *words* such as *man*, *woman*, and *analogies*, such as  $\text{king} : \text{man}, \text{woman} : \text{queen}$ . How ought we interpret this with respect to the mathematics?

Towards capturing this difference between words and anaalogies mathematically, we rewrite the analogy as  $(\text{man} - \text{king}) + \text{woman}$ . This is suggestive: it suggests that an analogy is a subtraction of vectors of the form  $(\text{man} - \text{king})$ , while a word is just a vector such as *woman*. In  $\mathbb{R}^n$ , the subtraction of vectors continues to be a vector.

Hence, the distinction between points such as  $c$  and directions such as  $(b - a)$  is a distinction without a (pun intended) difference, since both of these continue to be vectors. This no longer holds in curved spaces. Directions or paths are curved, and words are points of the space.

This distinction *does* make a difference for more complicated spaces. In particular, we choose to examine the example of a sphere versus the plane  $\mathbb{R}^2$ :

## 5.0.2 Generalizing `word2vec` : Distinction with differences

Let us reformulate the fundamental operations performed with `word2vec` , in light of our discussion above.

- Similarity: Given two words, find how similar they are in meaning. This is expressed as a dot product between the two vectors.
- Analogy: Given two words, representing a sense of analogy ( $\text{king} : \text{man}$ ), then a third word, representing the base of another analogous pair ( $\text{woman} : ?$ ), find the unknown word ?

In our description of analogy, we deliberately describe the analogy operation in two steps: first to provide an analogy ( $\text{king} : \text{man}$ ), and second to provide the base of a new analogy ( $\text{woman} : ?$  ). As we shall see, the mathematical generalization to Lie groups naturally contains this distinction; Words such as *man*, *king*, *woman* become *points* on the manifold, while analogies such as ( $\text{king} : \text{man}$ ) become *paths* on the manifold. This is not so strange, as this is exactly what happens in `word2vec` . We have words such as *king*, *man*, *woman* which are vectors (elements of  $\mathbb{R}^n$ ). On performing analogy ( $a : b :: c : ?$ ), we perform the vector space operation  $b - a + c$ , which can be rearranged as  $c + (b - a)$ , which is the base point  $c$  to which we add the direction  $(b - a)$ .

### 5.0.3 Lexical Semantics on a Symplectic Manifold

We first explain a modest generalisation of `word2vec`, the symplectic manifold, after which we move on to the full generalisation. In the symplectic manifold, we train pairs of vectors as our embedding representation, and use the angle between their subspaces as the similarity measure.

### 5.0.4 The Grassmanian: Generalizing `word2vec` to $n$ -Dimensions

The grassmanian Represents all  $k$ -dimensional subspaces of an  $n$ -dimensional vector space. More importantly, the grassmanian is a *lie group*; This means that we can build analogues of the `word2vec` operations for the Grassmanian. Here, we lay out a general theory of similarity and analogy, and use the theory to develop our implementation of the Grassmanian.

## 5.1 Training Mechanism

## 5.2 Results and Evaluation

## 5.3 Analysis

## 5.4 Contrastive Losses

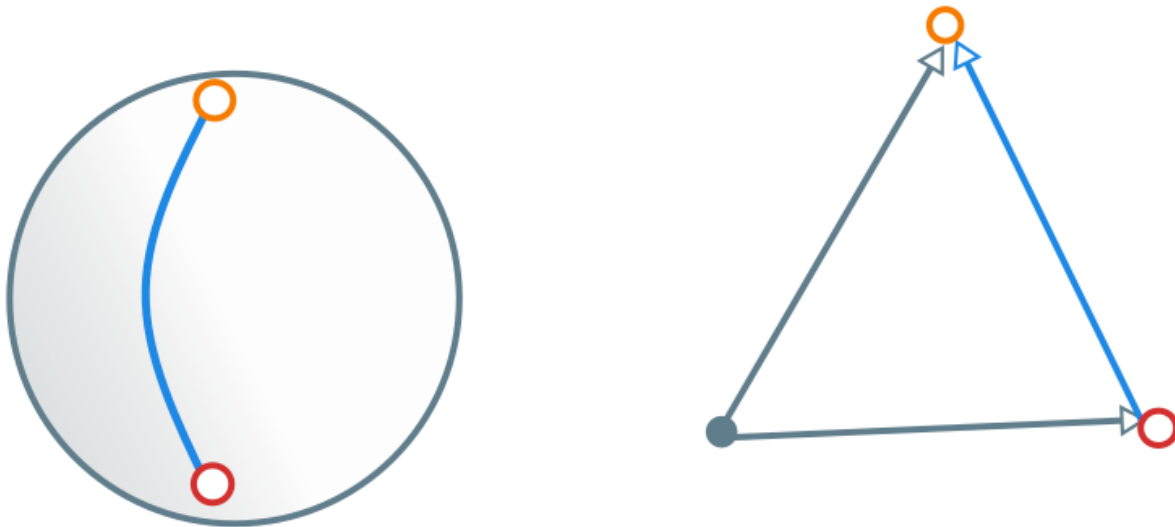
### 5.4.1 The setting: Lie groups, Similarly, and Analogy

A Lie group is a mathematical object that abstracts the ideas of "analogy" and "similarity". These ideas are called as:

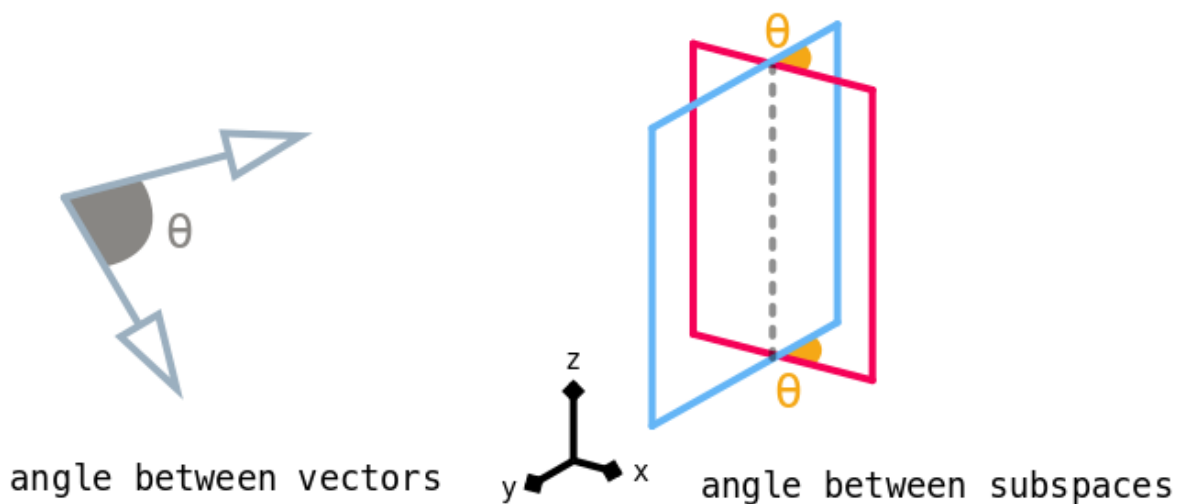
- *Parallel transport*: given a base word and an analogy, find a word with the analogy we are interested in
- *Geodesic computation*: given two words, represent the analogy between the words.

## 5.5 Related Work

## 5.6 Conclusion



**Figure 5.1**  $(b - a)$  on a sphere versus the plane ( $\mathbb{R}^2$ ). Red and orange are the words  $b$ ,  $a$ . The path in blue for the sphere and the line in blue for the plane corresponds to the difference  $(b - a)$ . See how in the case of the plane, both the points as well as the difference can be represented by vectors. However, in the case of a sphere, this is not possible since there is no clean correspondence between a "path" and a point on the sphere.



**Figure 5.2** Angle between subspaces. Here, we see that when we consider angle between words, it is only possible to consider a single sense direction. When we consider angles between subspaces, the subspace can capture multiple senses since it can extend into multiple directions. The angle between the subspaces provides us our notion of similarity.



## Chapter 6

### Research direction II: Geometric algebras

While not strictly in the realm of differential geometry, geometric algebras are an interesting beast. Essentially, they answer the question:

What if we could study vectors on equal footing with arbitrary subspaces?

#### 6.1 Exterior Algebras

We first define the *exterior algebra of degree 2* of a vector space  $V$ . Intuitively, these represent *oriented areas* of a space. Later, we generalize these to volumes and hypervolumes.

Given a vector space  $V$  of dimension  $n$ , we define a space  $(\Omega^2(V))$ , called as the exterior algebra of  $V$  of degree 2. We can construct elements of  $(\Omega^2(V))$  by using an operator  $(\wedge)$ , defined by the following axioms:

$$\wedge : V \times V \rightarrow \Omega^2(V)$$

$$\vec{v} \wedge \vec{w} = -\vec{w} \wedge \vec{v} \quad (\text{skew-symmetry})$$

$$\forall \alpha, \beta, \gamma, \delta \in \mathbb{R} \quad \vec{u}, \vec{v}, \vec{w}, \vec{x} \in V,$$

$$(\alpha \vec{u} + \beta \vec{v}) \wedge (\gamma \vec{w} + \delta \vec{x}) = \alpha \gamma (\vec{u} \wedge \vec{w}) + \alpha \delta (\vec{u} \wedge \vec{x}) + \beta \gamma (\vec{v} \wedge \vec{w}) + \beta \delta (\vec{v} \wedge \vec{x}) \quad (\text{bilinearity})$$

#### 6.2 Intuition of the definition of wedge products on $\mathbb{R}^2$

From the above axioms, we can derive an intuition for the wedge product in  $\mathbb{R}^2$ . let us consider  $\vec{x}, \vec{y}$  as unit basis vectors of  $\mathbb{R}^2$ .

We first show:  $[\vec{x} \wedge \vec{x} = -(\vec{x} \wedge \vec{x}) \implies 2(\vec{x} \wedge \vec{x} = 0) \implies (\vec{x} \wedge \vec{x} = 0)]$ . Similarly,  $(\vec{y} \wedge \vec{y} = 0)$ . We also note that  $\vec{x} \wedge \vec{y} = -\vec{y} \wedge \vec{x}$ , by using the skew-symmetry rule.

Now, we observe the value of  $(v \wedge w)$  for a general  $(v, w \in \mathbb{R}^2)$  and we provide a geometric interpretation. We first write  $\vec{v}, \vec{w}$  in terms of the basis vectors  $\vec{x}, \vec{y}$  as:  $(\vec{v} = \alpha\vec{x} + \beta\vec{y}), (\vec{w} = \gamma\vec{x} + \delta\vec{y})$ . Next, we expand  $(\vec{v} \wedge \vec{w})$  as:

$$\begin{aligned}\vec{v} \wedge \vec{w} &= (\alpha\vec{x} + \beta\vec{y}) \wedge (\gamma\vec{x} + \delta\vec{y}) \\ &= \alpha\gamma(\vec{x} \wedge \vec{x}) + \alpha\delta(\vec{x} \wedge \vec{y}) + \beta\gamma(\vec{y} \wedge \vec{x}) + \beta\delta(\vec{y} \wedge \vec{y}) \\ &= \alpha\gamma(0) + \alpha\delta(\vec{x} \wedge \vec{y}) + \beta\gamma(-\vec{x} \wedge \vec{y}) + \beta\delta(0) \\ &= (\alpha\delta - \beta\gamma)(\vec{x} \wedge \vec{y})\end{aligned}$$

We know from 2D geometry that  $(\alpha\delta - \beta\gamma)$  is the area of the parallelogram spanned by vectors  $(\vec{v}, \vec{w})$ . Now,  $\vec{x} \wedge \vec{x} = 0$  can be interpreted as "the parallelogram made up of two sides which are collinear has 0 area". The fact  $(\vec{x} \wedge \vec{y} = -\vec{y} \wedge \vec{x})$  can be interpreted as *orientation*. We view  $(\vec{x} \wedge \vec{y})$  as an "anti-clockwise" orientation going from the positive  $x$ -axis (3 o'clock) to the positive  $y$ -axis (12 o'clock).  $(\vec{y} \wedge \vec{x})$  is a clockwise orientation, going from the positive  $y$ -axis to the positive  $x$ -axis.

### 6.3 Generalizing exterior algebras to arbitrary dimensions

Given a vector space  $V$  of dimension  $k$ , we define the  $k$ -dimensional exterior algebra space inductively as follows:

$$\begin{aligned}\Omega^k(n) &\equiv \{\vec{x}_1 \wedge \vec{x}_2 \wedge \dots \wedge \vec{x}_k \mid \vec{x}_1, \vec{x}_2, \dots, \vec{x}_k \in V\} \\ (\vec{x}_1 \wedge \dots \wedge \vec{x}_k) &= \text{sign}(P)(\vec{x}_{P(1)} \wedge \vec{x}_{P(2)} \wedge \dots \wedge \vec{x}_{P(k)}) \quad (\text{skew-symmetry})\end{aligned}$$

where  $(P : \{1, 2, \dots, k\} \rightarrow \{1, 2, \dots, k\})$  is a permutation (bijection).  $\text{sign}(P)$  is  $+1$  if the permutation is an even permutation (contains an even number of swaps), and  $-1$  if it is an odd permutation (contains an odd number of swaps)

$$\begin{aligned}(\vec{x}_1 \wedge \dots \wedge (\alpha\vec{y}_1 + \beta\vec{y}_2) \wedge \vec{x}_k) &= \\ \alpha(\vec{x}_1 \wedge \dots \wedge \vec{y}_1 \wedge \dots \wedge \vec{x}_k) &+ \beta(\vec{x}_1 \wedge \dots \wedge \vec{y}_2 \wedge \dots \wedge \vec{x}_k) \quad (\text{multi-linearity})\end{aligned}$$

Note that this clearly extends the situation as described in 2D to  $nD$ .

### 6.4 Geometric algebra

The geometric algebra of a vector space  $V$  over the reals  $\mathbb{R}$  of dimension  $n$  is called as  $\mathbb{G}(V)$ .  $\mathbb{G}(V)$  contains all *formal linear combinations* of elements from  $(\mathbb{R}, V, \Omega^2(V), \Omega^3(V), \dots, \Omega^n(V))$ . For example, if we consider the space  $\mathbb{G}(\mathbb{R}^2)$ , an element of this space is  $(2 - 3\vec{x} + 4\vec{y} + 5\vec{x} \wedge \vec{y})$ .

This is a unique space, because it allows us to combine objects such as scalars, vectors, areas, volumes, etc. This is the power that we shall exploit to model a wide variety of situations.

In general, if the vector space  $V$  is of dimension  $n$ , then the geometric algebra  $\mathbb{G}(V)$  will have dimension  $2^n$ , since it will contain as a basis all possible collections of subspaces.

## 6.5 The philosophy of geometric algebra

In general, within vector spaces, vectors are privileged. Subspaces on the other hand are defined with equations: for example, in  $3D$ , the subspace spanned by the  $\vec{x}, \vec{y}$  axes would be  $span(\vec{x}, \vec{y}) = \{\lambda_x \vec{x} + \lambda_y \vec{y} \mid \lambda_x, \lambda_y \in \mathbb{R}\}$ . This is a *set of vectors*, and not an *element of the vector space*.

In a geometric algebra, we would represent the subspace (roughly) as  $(\vec{x} \wedge \vec{y})$ . This allows us to treat vectors, scalar, volumes, and hypervolumes on equal footing, and develop a theory that includes all of these objects.

It also provides a *geometric product*, that allows us to easily relate the regular *inner product* to the *exterior product*, thereby creating a unifying theory of vectors and all differential forms.

### 6.5.1 The geometric product

We first define the geometric product for vectors:

$$ab \equiv (a \cdot b) + (a \wedge b)$$

### 6.5.2 Construction: A non-commutative, bilinear structure for geometric algebra

We define a non-commutative, bilinear structure  $(\langle \cdot | \cdot \rangle : \mathbb{G}(V) \times \mathbb{G}(V) \rightarrow \mathbb{R})$ . We define the effect on the basis elements, and then extend it to the full space. Let the basis of  $V$  be  $\{b_1, b_2, \dots, b_k\}$ .

$$\langle b_{i_1} \wedge b_{i_2} \wedge \dots \wedge b_{i_n} | c_{j_1} \wedge c_{j_2} \wedge \dots \wedge c_{j_m} \rangle \equiv \begin{cases} 1 & span(b_{i_1}, b_{i_2}, \dots, b_{i_n}) \subseteq span(c_{j_1}, c_{j_2}, \dots, c_{j_m}) \\ 0 & \text{otherwise} \end{cases}$$

Then we extend this multi-linearly to the full space, since we have defined its action on the basis.

#### Example 1.

$$\begin{aligned} & \langle 2 + 3\vec{x} + 4\vec{x} \wedge \vec{y} | 4\vec{y} \rangle \\ &= \langle 2 | 4\vec{y} \rangle + \langle 3\vec{x} | 4\vec{y} \rangle + \langle 4\vec{x} \wedge \vec{y} | 2\vec{x} \wedge \vec{y} \rangle \\ &= (2 \cdot 4) \langle 1 | \vec{y} \rangle + (3 \cdot 4) \langle \vec{x} | \vec{y} \rangle + (4 \cdot 4) \langle \vec{x} \wedge \vec{y} | \vec{y} \rangle \\ &= 8(1) + 12(0) + 16(0) = 8 \end{aligned}$$

Note that  $(\langle \vec{x} | \vec{y} \rangle = 0)$ , since the space spanned by  $\vec{x}$  is not contained in the space spanned by  $\vec{y}$ . Similarly,  $(\langle \vec{x} \wedge \vec{y} | \vec{y} \rangle = 0)$ , since the subspace spanned by  $(\vec{x}, \vec{y})$  is strictly bigger than the subspace spanned by  $(\vec{y})$ .

This dot product structure captures the asymmetric notion of "containment":  $\langle b | c \rangle \neq 0$  iff the span of  $b$  is contained in the span of  $c$ . This allows us to model situations where we wish to have a notion of containment *across subspaces* of a given space.

## **Related Publications**