

Correctness, Safety and Freedom

*or, How I Learned to Stop Worrying and Trust Myself
(and the Compiler)*

The bad ol' days...

```
if (__lc_codepage == 0)
{ /* code page was not specified */
    if ( __getlocaleinfo( LC_INT_TYPE,
        MAKELCID(__lc_id[LC_CTYPE].wLanguage, SORT_DEFAULT),
        LOCALE_IDEFAULTANSICODEPAGE, (char **)&__lc_codepage ) )
        goto error_cleanup;
}

/* ... */

/* cleanup and return success */
_free_crt (cbuffer);
return 0;

error_cleanup:
_free_crt (newctype1);
_free_crt (cbuffer);
return 1;
}
```

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Is it correct?

- Have all resources been freed?
 - ... on all possible code paths?
 - ... in the presence of exceptions?
- Have our invariants been preserved?
 - ... in all possible failure scenarios?

Well, yes. The programmer was careful.

- But will it still be correct after maintenance?

Outline

- Contract Programming—*preconditions, postconditions, and invariants*
- Exception Safety—contractually speaking, techniques, and best practices
- Resource Management—Smart Pointers and RAI

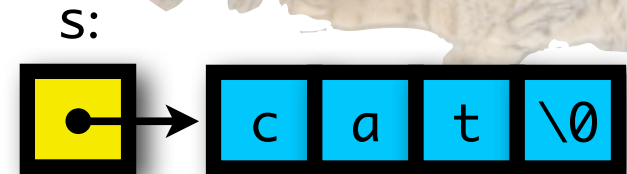
String Toy



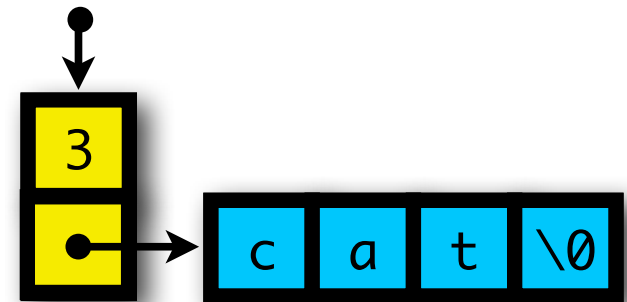
```
struct string
{
    string( char const* s )
    {
        len = std::strlen( s );
        buf = std::malloc( len+1 );
        std::strcpy( buf, s );
    }

    ~string() { std::free( buf ); }

    string( string const& rhs );
    string& operator=(
        string const& rhs );
private:
    std::size_t len;
    char* buf;
};
```



this:



Contractually Speaking

Correct code is impossible without these concepts

- **Precondition:** requirement on caller by callee
 - **Postcondition:** guarantee to caller by callee
 - **Invariant:** condition that must always* hold
 - For a class, data structure, or program
 - At each iteration of a loop
- * except during mutation

Contractually Speaking

```
string::string( char const* s ) { ... }
```

- **Precondition:** requirement on caller by callee

s is null-terminated

- **Postcondition:** guarantee to caller by callee

!std::strcmp(s, &str[0])

- **Invariant:** condition that must always* hold

- For a class, data structure, or program
- At each iteration of a loop

* except during mutation buf[len] == '\0'

Precondition: S is Null-Terminated

- This cannot be checked efficiently and safely in code
- But the caller *can* and *must* ensure null-termination
- Document the full precondition regardless of checkability!
- Q: Assuming we want to check something, what *can* we check for?

A: that S is non-NULL

When a Precondition Check Fails

- Q:What does it mean?

A:Your program is buggy.

- Q:What information do you have about the location of the bug?

A: Zip. Zilch. None. Nada.

- Q:What is an appropriate response to a failed precondition check?

When a Precondition Check Fails

- Code somewhere is broken—we don't know where
- The assumptions upon which our program was written have been violated.
- Continuing to run is hazardous. *Do as little as possible.*
- Take emergency measures:
 - Capture stack trace / program state for debugging
 - Capture unsaved work for user
 - Shutdown (and optional restart)

Checking Out the Precondition

```
struct string
{
    string( char const* s )
    {
        len = std::strlen( s );
        buf = std::malloc( len+1 );
        std::strcpy( buf, s );
    }

    ~string() { std::free( buf ); }

    string( string const& rhs );
    string& operator=(
        string const& rhs );
private:
    std::size_t len;
    char* buf;
};
```



Checking Out the Precondition

```
struct string
{
    string( char const* s )
    {
        assert( s != 0 );
        len = std::strlen( s );
        buf = std::malloc( len+1 );
        std::strcpy( buf, s );
    }

    ~string() { std::free( buf ); }

    string( string const& rhs );
    string& operator=(
        string const& rhs );
private:
    std::size_t len;
    char* buf;
};
```



Note: the code is not broken without this check!

Uh-oh. We'll come back to that.

First, Some Improvements

```
struct string
{
    string( char const* s )
        : len( std::strlen( s ) )
        , buf( std::malloc( len+1 ) )
    {
        std::strcpy( buf, s );
    }

    ~string() { std::free( buf ); }

    string( string const& rhs );
    string& operator=(
        string const& rhs );
private:
    std::size_t len;
    char* buf;
};
```

Guideline:
Isolate Mutating
Code

First, Some Improvements

```
struct string
{
    string( char const*const s )
        : len( std::strlen( s ) )
        , buf( std::malloc( len+1 , ) )
    {
        std::strcpy( buf, s );
    }

    ~string() { std::free( buf ); }

    string( string const& rhs );
    string& operator=(
        string const& rhs );
private:
    std::size_t len;
    char* buf;
};
```

Guideline: Use
const wherever
possible

What About Memory Exhaustion?

- If we can't get memory, can we satisfy our postcondition?
- Can we make “have sufficient memory” a precondition?
 - Ask yourself: *“is the caller in a position to check for or ensure that there is sufficient memory?”*
- How can we avoid a postcondition failure?

Two Ways to Avoid Postcondition Failures

1. Change the postcondition
 - In this case, allow an empty result
 - Makes error checking the client's problem
2. Throw an exception—the function never returns, thus postcondition never applies.
 - Better!

Throw an Exception

```
struct string
{
    string( char const*const s )
        : len( std::strlen( s ) )
        , buf( std::malloc( len+1 ) )
    {
        std::strcpy( buf, s );
    }

    ~string() { std::free( buf ); }

    string( string const& rhs );
    string& operator=( string const& rhs );
private:
    std::size_t len;
    char* buf;
};
```

Throw an Exception

```
struct string
{
    string( char const*const s )
        : len( std::strlen( s ) )
        , buf( std::malloc( len+1 ) )
    {
        if ( buf == 0 ) throw std::bad_alloc();
        std::strcpy( buf, s );
    }

    ~string() { std::free( buf ); }

    string( string const& rhs );
    string& operator=( string const& rhs );
private:
    std::size_t len;
    char* buf;
};
```

Throw an Exception

```
struct string
{
    string( char const*const s )
        : len( std::strlen( s ) )
        , buf( std::malloc( len+1 ) )
    {
        std::strcpy( buf, s );
    }

    ~string() { std::free( buf ); }

    string( string const& rhs );
    string& operator=( string const& rhs );
private:
    std::size_t len;
    char* buf;
};
```

Throw an Exception

```
struct string
{
    string( char const*const s )
        : len( std::strlen( s ) )
        , buf( new char[ len+1 ] )
    {
        std::strcpy( buf, s );
    }

    ~string() { std::free( buf ); }

    string( string const& rhs );
    string& operator=( string const& rhs );
private:
    std::size_t len;
    char* buf;
};
```

**Guideline: Encapsulate
throw-expressions**

Throw an Exception

```
struct string
{
    string( char const*const s )
        : len( std::strlen( s ) )
        , buf( new char[len+1] )
    {
        std::strcpy( buf, s );
    }

    ~string() { delete [] buf; }

    string( string const& rhs );
    string& operator=( string const& rhs );
private:
    std::size_t len;
    char* buf;
};
```

Copy Constructor

```
struct string
{
    string( char const*const s )
        : len( std::strlen( s ) )
        , buf( new char[len+1] )
    {
        std::strcpy( buf, s );
    }

    ~string() { delete [] buf; }

    string( string const& rhs )
        : len( rhs.len ),
        , buf( new char[len+1] )
    {
        std::strcpy( buf, rhs.buf );
    }
}
```

Copy Assignment

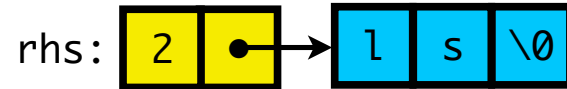
```
string( string const& rhs )  
    : len( rhs.len ),  
      buf( new char[len+1] )  
{  
    std::strcpy( buf, rhs.buf );  
}
```

```
string& operator=( string const& rhs )  
{  
    if ( this == &rhs ) return *this;  
    delete [] buf;  
    len = rhs.len;  
    buf = new char[len + 1];  
    std::strcpy( buf, rhs.buf );  
    return *this;  
}
```

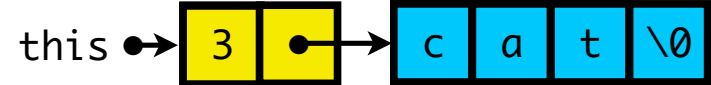
private:

Copy Assignment

```
string( string const& rhs )  
: len( rhs.len ),  
  buf( new char[len+1] )  
{  
    std::strcpy( buf, rhs.buf );  
}
```



```
string& operator=( string const& rhs )  
{  
    if ( this == &rhs ) return *this;  
    delete [] buf;  
    len = rhs.len;  
    buf = new char[len + 1];  
    std::strcpy( buf, rhs.buf );  
    return *this;  
}
```



Invariant broken

Uh-oh!

Invariant restored

private:

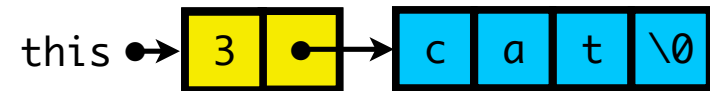
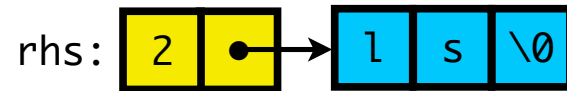
Exception Safety

- Safe code gives this **basic guarantee**:
 - All invariants are preserved
 - No resources leaked
 - Within that, arbitrary state changes allowed
- Not really specific to code that uses exceptions
- Handling errors correctly can be hard
- Exceptions can make it easier

Restoring Safety, Take I

```
string( string const& rhs )  
: len( rhs.len ),  
  buf( new char[len+1] )
```

```
{  
    std::strcpy( buf, rhs.buf );  
}
```



```
string& operator=( string const& rhs )  
{
```

```
    if ( this == &rhs ) return *this;
```

```
    delete [] buf;
```

```
    buf = 0; len = 0;
```

```
    buf = new char[rhs.len + 1];
```

```
    len = rhs.len;
```

```
    std::strcpy( buf, rhs.buf );
```

```
    return *this;
```

```
}
```

“Good state” restored

Uh-oh!

A Weakened Invariant

```
string( string const& rhs )
: len( rhs.len ),
  buf( new char[len+1] )
{
    if (rhs.buf) std::strcpy( buf, rhs.buf );
}

string& operator=( string const& rhs )
{
    if ( this == &rhs ) return *this;
    delete [] buf;
    buf = 0; len = 0;
    buf = new char[len + 1];
    len = rhs.len;
    if (rhs.buf) std::strcpy( buf, rhs.buf );
    return *this;
}
```

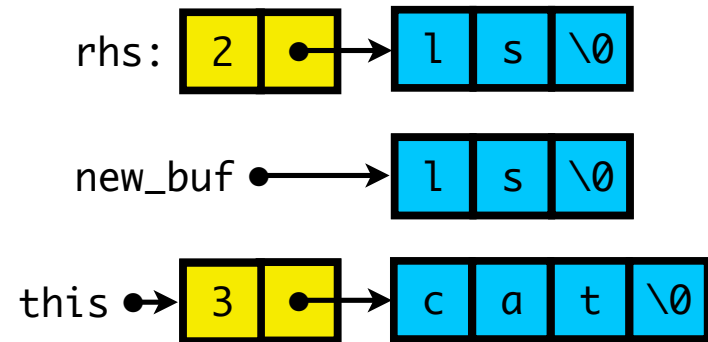
Prefer Strong Invariants

- Weaker invariants are:
 - Usually complicated to document
 - Much harder to reason about
 - Cause complexity to ripple through code

Keep the Invariant Strong

```
string( string const& rhs )  
    : len( rhs.len ),  
      buf( new char[len+1] )  
{  
    std::strcpy( buf, rhs.buf );  
}
```

```
string& operator=( string const& rhs )  
{  
    if ( this == &rhs ) return *this;  
    char* const new_buf = new char[rhs.len + 1];  
    std::strcpy( new_buf, rhs.buf );  
    delete [] buf;  
    buf = new_buf;  
    len = rhs.len;  
    return *this;  
}
```



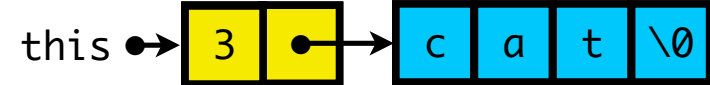
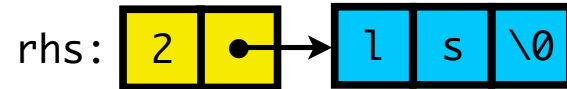
First, the step(s)
that can throw

No: all data now
“safe” from loss

Only later, the
irreversible changes

Atomicity!

```
string( string const& rhs )  
: len( rhs.len ),  
  buf( new char[len+1] )  
{  
    std::strcpy( buf, rhs.buf );  
}
```



```
string& operator=( string const& rhs )  
{  
    char* const new_buf = new char[rhs.len + 1];  
    std::strcpy( new_buf, rhs.buf );  
    delete [] buf;  
    buf = new_buf;  
    len = rhs.len;  
    return *this;  
}
```

Q: If an exception is thrown, what will have been changed?

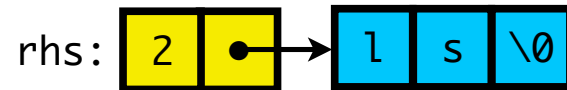
A: Nothing. Zip. Zilch. Nada... this is the “**strong guarantee**.”

Note: Guarantee was not sought; it “fell out” of a fix.

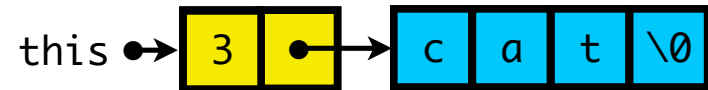
private:

Atomicity!

```
string( string const& rhs )  
: len( rhs.len ),  
  buf( new char[len+1] )  
{  
    std::strcpy( buf, rhs.buf );  
}
```



```
string& operator=( string const& rhs )  
{  
    char* const new_buf = new char[rhs.len + 1];  
    std::strcpy( new_buf, rhs.buf );  
    delete [] buf;  
    buf = new_buf;  
    len = rhs.len;  
    return *this;  
}
```



char* const new_buf = new char[rhs.len + 1];
std::strcpy(new_buf, rhs.buf);

Q: If an exception is thrown, what will have been changed?

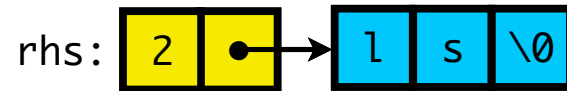
A: Nothing. Zip. Zilch. Nada... this is the “**strong guarantee**.”

Note: Guarantee was not sought; it “fell out” of a fix.

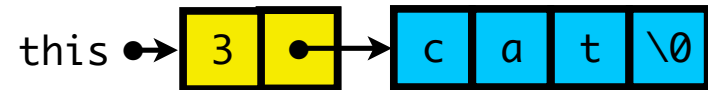
private:

Copy/Swap Idiom

```
string( string const& rhs )  
  : len( rhs.len ),  
    buf( new char[len+1] )  
{  
    std::strcpy( buf, rhs.buf );  
}
```



rep:



```
string& operator=( string const& rhs )  
{  
    string rep( rhs );  
    swap( *this, rep );  
    return *this;  
}
```

Strong guarantee iff
swap is non-throwing
(but always correct).

```
friend void swap( string&, string& );  
private:  
    std::size_t len;  
    char* buf;
```


Copy/Swap Idiom

```
string( string const& rhs )  
    : len( rhs.len ),  
      buf( new char[len+1] )  
{  
    std::strcpy( buf, rhs.buf );  
}
```

```
string& operator=( string const& rhs )  
{  
    string rep( rhs );  
    swap( *this, rep );  
    return *this;  
}
```

```
friend void swap( string&, string& );  
private:  
    std::size_t len;  
    char* buf;
```

Strong guarantee iff
swap is non-throwing
(but always correct).

Copy/Swap Idiom

```
string( string const& rhs )  
: len( rhs.len ),  
  buf( new char[len+1] )  
{  
    std::strcpy( buf, rhs.buf );  
}
```

```
string& operator=( string rep )
```

```
{  
    swap( *this, rep );  
    return *this;  
}
```

Copy will be elided for
rvalue arguments

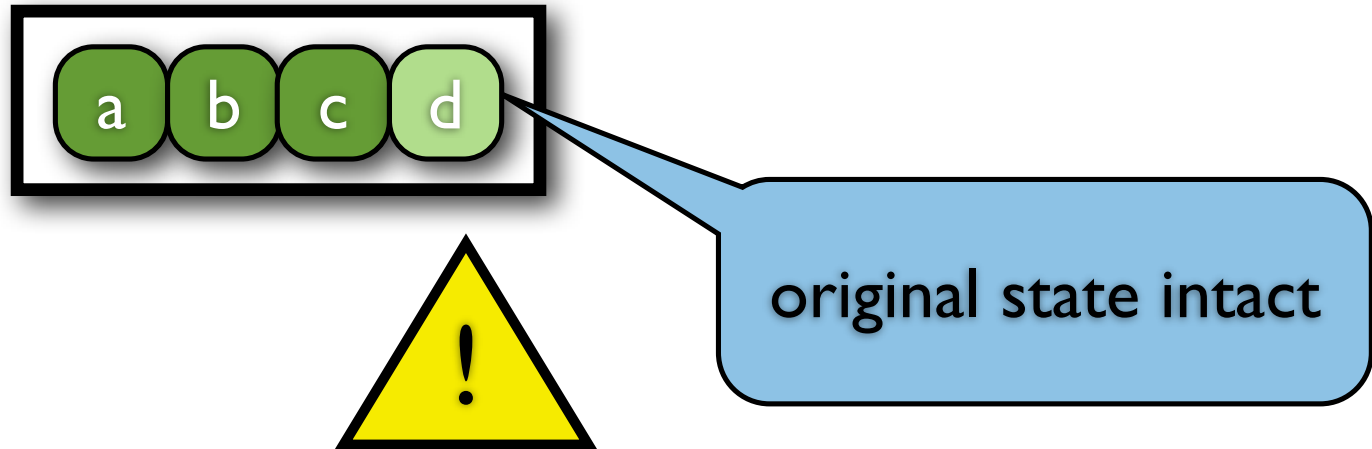
Strong guarantee iff
swap is non-throwing
(but always correct).

```
friend void swap( string&, string& );  
private:  
    std::size_t len;  
    char* buf;  
};
```

A Little Perspective

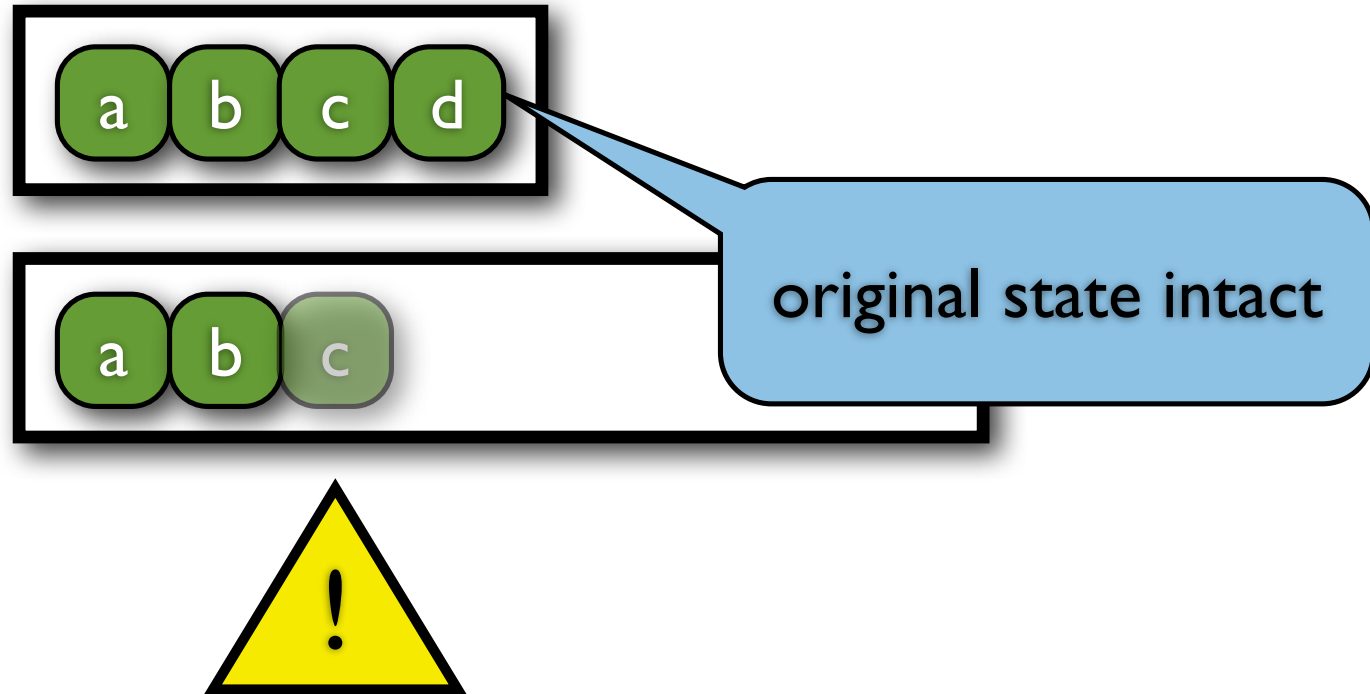
- The “strong guarantee” is not synonymous with safety
 - Basic guarantee often suffices, especially for stack objects
 - non-throwing operations are still needed for error handling
- Some operations can be “naturally strong,” e.g. vector `push_back`
- Others only give the basic guarantee when implemented efficiently, e.g. vector assignment.
- Don't copy/swap prematurely, and code that only needs the basic guarantee won't be penalized.
- The one exception to that rule is in defining copy assignment. Why?
- Q: Is our copy/swap implementation of string assignment optimal?

Appending to a vector



code

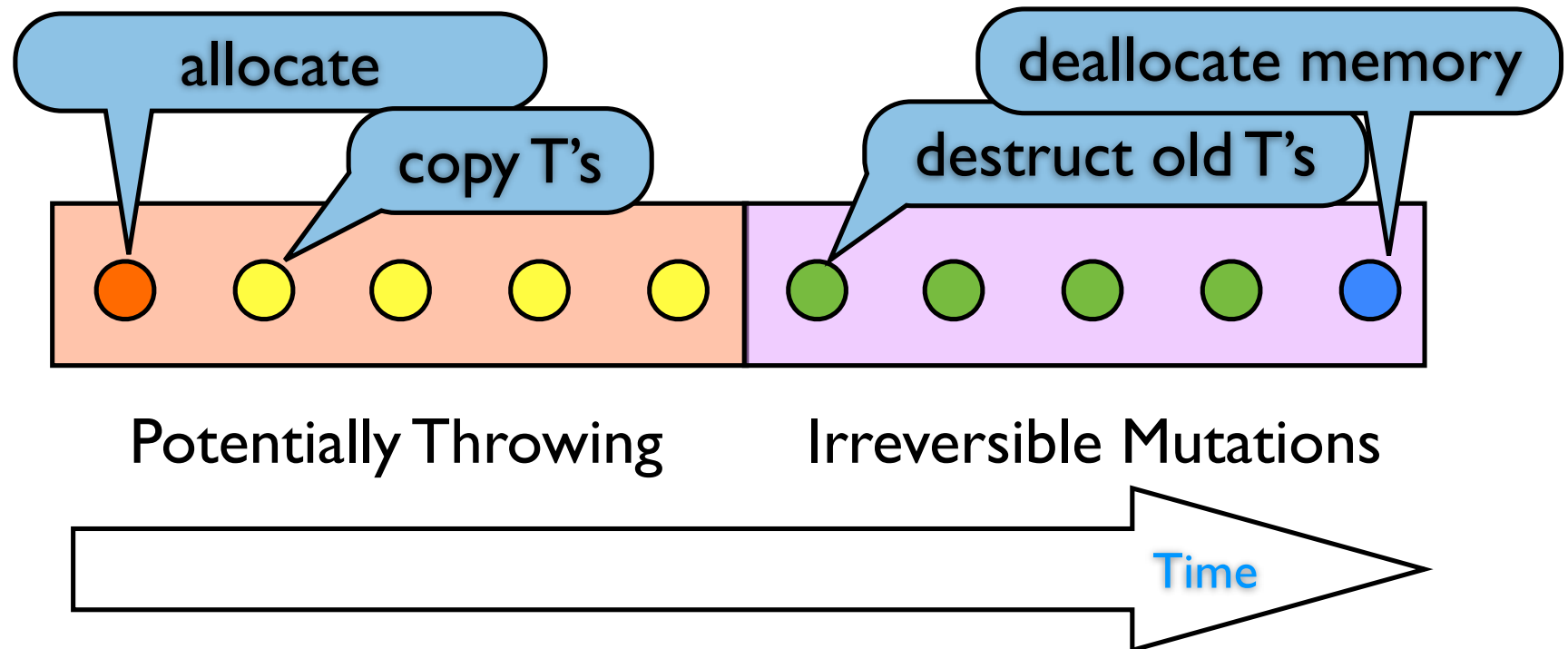
Appending to a vector



code

Observation

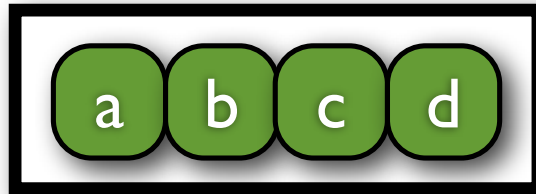
The *strong guarantee* depends on a partitioning in the sequence of sub-operations



`vector<T>::push_back` is
“naturally strong.” There’s
(basically) no other way to
implement it

Assigning std::vector

RHS



LHS



original state lost!
(basic guarantee)

code

Why not copy / swap
assignment for `std::vector`?

Constructors that Throw?

```
struct string
{
    string( char const*const s )
        : len( std::strlen( s ) )
        , buf( new char[len+1] )
    {
        std::strcpy( buf, s );
    }

    ~string() { delete [] buf; }

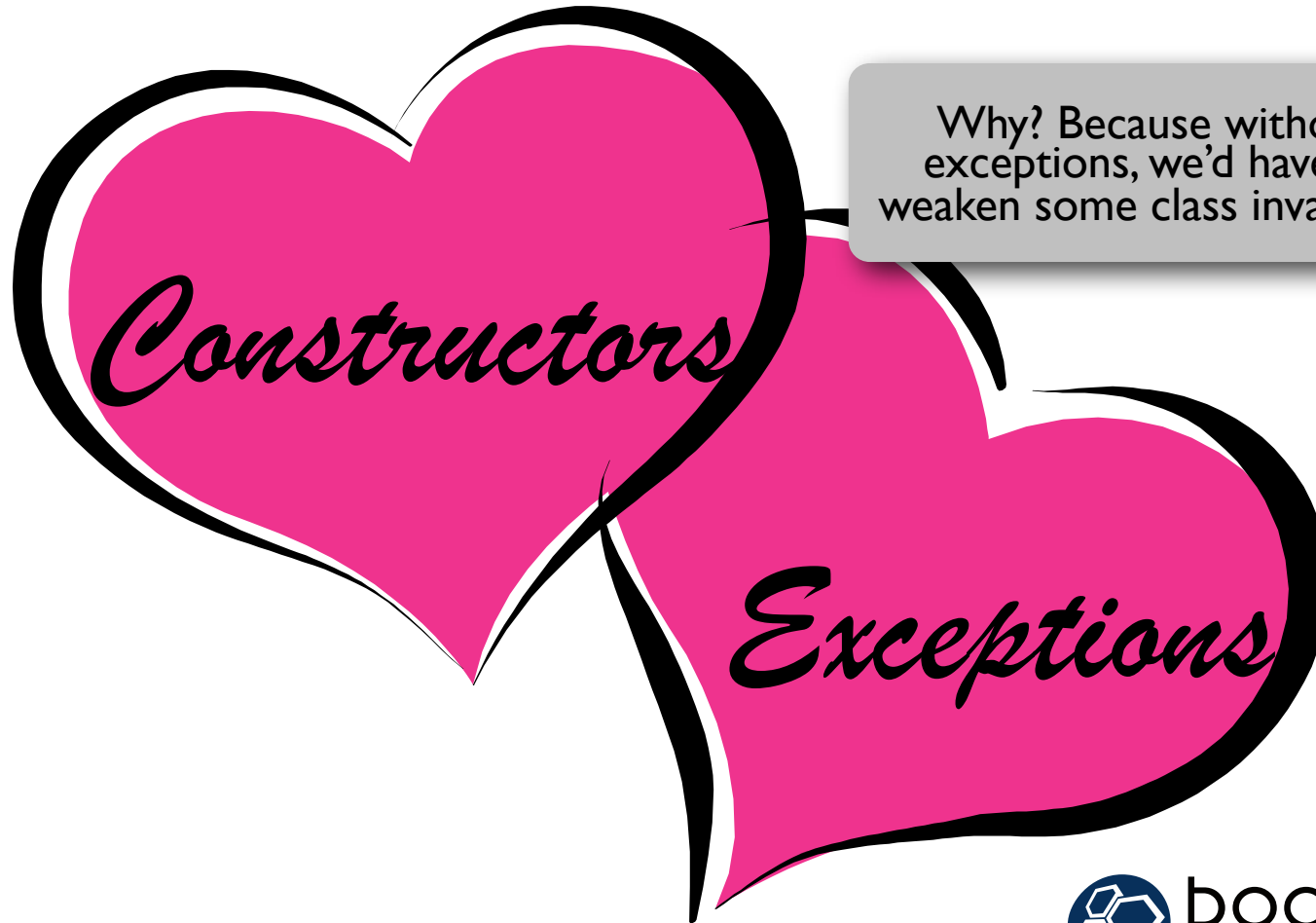
    string( string const& rhs )
        : len( rhs.len ),
        buf( new char[len+1] )
    {
        std::strcpy( buf, rhs.buf );
    }
}
```

Q: What if we avoid throwing from constructors?

A: Invariants are weakened
(need an empty state)

Q: But how can this report failure?

A Match Made in Heaven



Why? Because without exceptions, we'd have to weaken some class invariants

Destructors that Throw?

```
struct X
{
    ~X() { something_that_might_throw(); }
};
```

```
void g( std::string message );
```

```
void f()
{
```

```
    X a;
```

```
    g( "this is the end" );
```

```
    a.~X();
```

```
}
```

Might throw

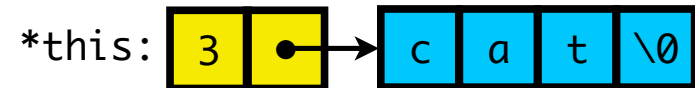
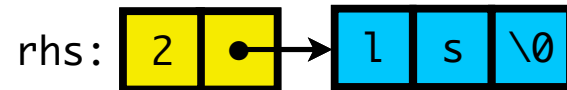
If this throws too? Doom.

A Missed Opportunity

```
string( string const& rhs )
: len( rhs.len ),
  buf( new char[len+1] )
{
    std::strcpy( buf, rhs.buf );
}

string& operator=( string rep )
{
    swap( *this, rep );
    return *this;
}

friend void swap( string&, string& );
private:
    std::size_t len;
    char* buf;
};
```



“Composite Ownership”

```
// reactor.hpp
class Controller;
class TSensor;

class Reactor
{
public:
    Reactor();
    ~Reactor();
    run();
private:
    // copy ctor, copy assignment
    // go here
    TSensor* s;
    Controller* c;
};
```

```
// reactor.cpp
class Controller { ... };
class TSensor { ... };

Reactor::~~Reactor()
{
    delete c;
    delete s;
}

Reactor::Reactor()
: s( new TSensor ),
  c( new Controller(s) )
{ }
```

“Composite Ownership”

```
// reactor.hpp
class Controller;
class TSensor;

class Reactor
    : boost::noncopyable
{
public:
    Reactor();
    ~Reactor();
    run();
private:
    TSensor* s;
    Controller* c;
};
```

```
// reactor.cpp
class Controller { ... };
class TSensor { ... };

Reactor::~Reactor()
{
    delete c;
    delete s;
}

Reactor::Reactor()
    : s( new TSensor ),
      c( new Controller(s) )
{ }
```

Fixing the Leak

```
// reactor.hpp
class Controller;
class TSensor;

class Reactor
    : boost::noncopyable
{
public:
    Reactor();
    ~Reactor();
    run();
private:
    TSensor* s;
    Controller* c;
};
```

```
// reactor.cpp
class Controller { ... };
class TSensor { ... };

Reactor::~Reactor()
{ delete c; delete s; }

Reactor::Reactor()
    : s ( new TSensor ), c( 0 )
{
    try {
        c = new Controller( s );
    }
    catch(...) { delete s; throw; }
}
```


Exercise: Compressed Sparse Row Matrix

	0	1	2	3	4		
0	0	d	0	0	0		0
1	b	0	0	c	0		1
2	0	0	a	0	0		3
3	0	h	0	e	0		4
4	0	f	0	0	g		6
							8

col_indices							
1	0	3	2	1	3	1	4
0	1	2	3	4	5	6	7
0	1	2	3	4	5	6	7
d	b	c	a	h	e	f	g

data							
d	b	c	a	h	e	f	g

row_starts							
0	1	3	4	6	8		

Exercise: Implement Sparse Matrix



- <http://www.filetolink.com/c8adce0a>
- `Wed/sparse_eh.cpp`
- allocate memory with `new T[n]`
- release memory with `delete[] p`
- Make it exception-safe
- What guarantee does your operator= offer?

Raw Pointers

+1

- Easy to come by
- Efficient

-1

- Uninitialized
- Dangling
- Leaks
- Double delete
- Ownership semantics
- Array semantics
- Delete slicing
- Deletion of incomplete type
- Deletion in wrong heap

Overcoming fear of failure

- Principle: Ownership
 - Every resource is owned by an object whose sole responsibility is to free the resource
- Resource acquisition is initialization (RAII)
 - Constructor acquires resource
 - Destructor frees resource

Deleting an Incomplete Type

```
#include <set>

class Z;    // forward declaration
std::set<Z*> known_zs;

destroy(Z* a)
{
    std::set<Z*>::iterator p = known_zs.find(a);
    known_zs.erase(p);
    delete a;
}
```

Boost solution: `checked_delete(z);`

Deletion in Wrong Heap

```
#include "x.hpp"
X* producer()
{
    return new X;
}
```

Statically-linked
C++ runtime

```
#include "x.hpp"
void consumer(X* x)
{
    delete x;
}
```

Statically-linked
C++ runtime

```
int main()
{
    consumer( producer() );
}
```

“What we’ve got here is...



...failure to communicate.”

Smart Pointers

- Class types—usually instances of class templates
- “Like built-in pointer types” but with attached semantics, especially *destruction semantics*
- Usually a subset of the built-in pointer interface
- Make dynamic memory safe(r) to handle
- Communicate intent to readers/maintainers

Basics of `std::auto_ptr<T>`

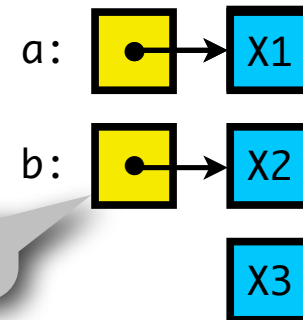
- One data member: `T* px;`
- Dereference semantics (“pointer-ness”):
`T& operator*() const { return *px; }`
`T* operator->() const { return px; }`
- Destructor semantics: `delete px;` (“smartness”)
- ***Transfer-of-ownership*** on copy and assignment
- ***Not an array pointer*** (no indexing, arithmetic, or order comparison)

auto_ptr Examples

```
#include "X.hpp"
#include <memory>
std::auto_ptr<X> factory()
{
    return std::auto_ptr<X>( new X ); // ok
}
```

```
void dump( std::auto_ptr<X> );
```

```
int main()
{
    std::auto_ptr<X> a = factory();
    std::auto_ptr<X> b;
    b = a;
    dump( b );
    a.reset( new X );
    delete a.release();
    b = factory();
    b.reset( new X );
}
```



Initialized to 0

auto_ptr Caveats

- Can't place in std containers
- Can't use with std algorithms
- That goes for classes with auto_ptr members and default copy/assignment too

```
template <class T>  
struct auto_ptr  
{
```

```
    auto_ptr( auto_ptr& rhs );  
    auto_ptr& operator=( auto_ptr& rhs );  
    ~auto_ptr() { delete px; }  
    bool operator==( auto_ptr const& rhs);  
    ...
```

*Transfer-of-ownership
mutates rhs*

**T could be
incomplete here!**

boost::scoped_ptr<T>

```
template <class T> struct scoped_ptr : noncopyable
{
    typedef T element_type;
    explicit scoped_ptr(T* p = 0)      : px(p) {}
    ~scoped_ptr()                      { boost::checked_delete(px); }
    void reset(T * p = 0)              { scoped_ptr(p).swap(*this); }
    T & operator*() const              { return *px; }
    T * operator->() const             { return px; }
    T * get() const                   { return px; }
    void swap(scoped_ptr & b)         { std::swap(this->px, b.px); }

    friend void swap( scoped_ptr& a, scoped_ptr& b)      { a.swap(b); }
private:
    T* px;
};
```

boost::scoped_array<T>

```
template <class T> struct scoped_array : noncopyable
{
    typedef T element_type;
    explicit scoped_array(T * p = 0) : px(p) {}
    ~scoped_array()                { boost::checked_array_delete(px); }
    void reset(T * p = 0)          { scoped_array(p).swap(*this); }
    T & operator*() const           { return *px; }
    T * operator->() const          { return px; }
    T * get() const                { return px; }
    void swap(scoped_array& b) { std::swap(this->px, b.px); }
    T& operator[](std::ptrdiff_t i) const { return px[i]; }

    friend void swap( scoped_array& a, scoped_array& b) { a.swap(b); }
private:
    T* px;
};
```

Fixing the Leak

```
// reactor.hpp
class Controller;
class TSensor;

class Reactor
    : boost::noncopyable
{
public:
    Reactor();
    ~Reactor();
    run();
private:
    TSensor* s;
    Controller* c;
};
```

```
// reactor.cpp
class Controller { ... };
class TSensor { ... };

Reactor::~Reactor()
{ delete c; delete s; }

Reactor::Reactor()
    : s ( new TSensor ), c( 0 )
{
    try {
        c = new Controller( s );
    }
    catch(...) { delete s; throw; }
}
```

A Cleaner Fix

```
// reactor.hpp
class Controller;
class TSensor;

class Reactor
{
public:
    Reactor();
    ~Reactor();
    run();
private:
    boost::scoped_ptr<TSensor> s;
    boost::scoped_ptr<Controller> c;
};
```

```
// reactor.cpp
class Controller { ... };
class TSensor { ... };

Reactor::~Reactor()
{}

Reactor::Reactor()
    : s ( new TSensor )
    , c( new Controller(s.get()) )
{}

```

Can we get rid of the dtor? It's empty

A: no, but the compiler will catch us if we do.

A2: we could move the class definitions into the header.

Resource Management Gotcha

```
void g();
```

```
int f( std::auto_ptr<X> a, int b );
```

```
int a = f( std::auto_ptr<X>(new X), g() );
```


The Dimov Directive

```
void g();  
  
int f( std::auto_ptr<X> a, int b );  
  
std::auto_ptr<X> new_x(new X);  
  
int a = f( new_x, g() );
```

Assign ownership of every resource, immediately upon allocation, to a **named** manager object that manages no other resources

Exercise: Reimplement Sparse Matrix

- allocate memory with `new T[n]`
- release memory with `delete[] p`
- Make it exception-safe
- What guarantee does `operator=` offer?
- Reimplement it using `boost::scoped_array`
- Did that simplify your code?

Exercise: Reimplement Sparse Matrix

- allocate memory with `new T[n]`
- release memory with `delete[] p`
- Make it exception-safe
- What guarantee does your `operator=` offer?
- Reimplement it using `boost::scoped_array`
- Reimplement it using `std::vector`
- Did that simplify your code?

boost::scoped_ptr Solution Checklist

- ✓ Leaks
 - ➡ Delete Slicing
- ✓ Double Delete
 - ➡ Use in std::containers
- ✓ Uninitialized
 - ➡ Deletion in wrong heap
- ✓ Array Semantics
 - ➡ Dangling
- ✓ Ownership Semantics
- ✓ Deletion of Incomplete Type

boost::scoped_ptr

Delete Slicing

```
struct Base  
{  
    ~Base(); // non-virtual  
};
```

```
struct Derived : Base  
{  
    ~Derived();  
};
```

```
scoped_ptr<Derived> x( new Derived );
```

```
scoped_ptr<Base> y( x );
```

```
scoped_ptr<Base> x( new Derived );
```

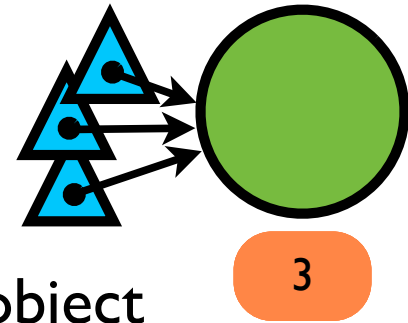


Compile-time error:
no such conversion



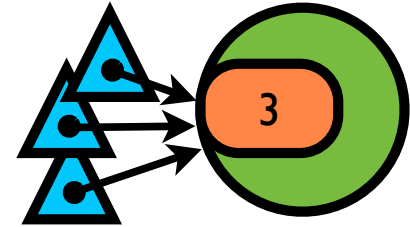
Destruction \Rightarrow
undefined behavior

Reference Counted Smart Pointer



- Basic strategy:
 - Count ptrs that refer to each object
 - Delete object when count goes to zero
- Implements shared ownership model
- Has proper *value semantics*: can be copied, put in containers, used with algorithms, etc.

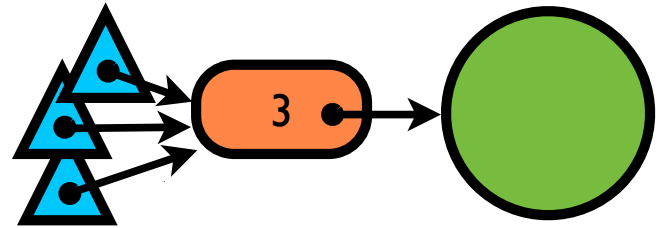
Intrusive Ref-Counting



- + Extremely lightweight
- + Raw \Rightarrow smart pointer conversion *always* safe
- + Boost's `intrusive_ptr` is très cool
- Reference count “intrudes” on design of pointee
- Doesn't address delete slicing, deletion in wrong heap, or dangling

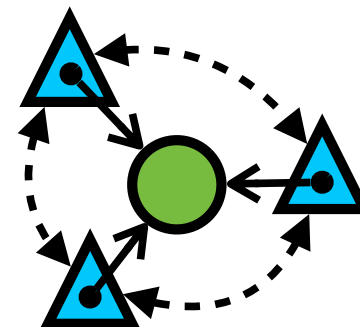
Indirect Ref-Counting

- + Non-intrusive
- Costs an allocation
- Can only convert raw \Rightarrow smart pointer once
- Can't support derived-to-base conversions
- Doesn't address deletion in wrong heap, dangling



Cyclic Ref-Counting

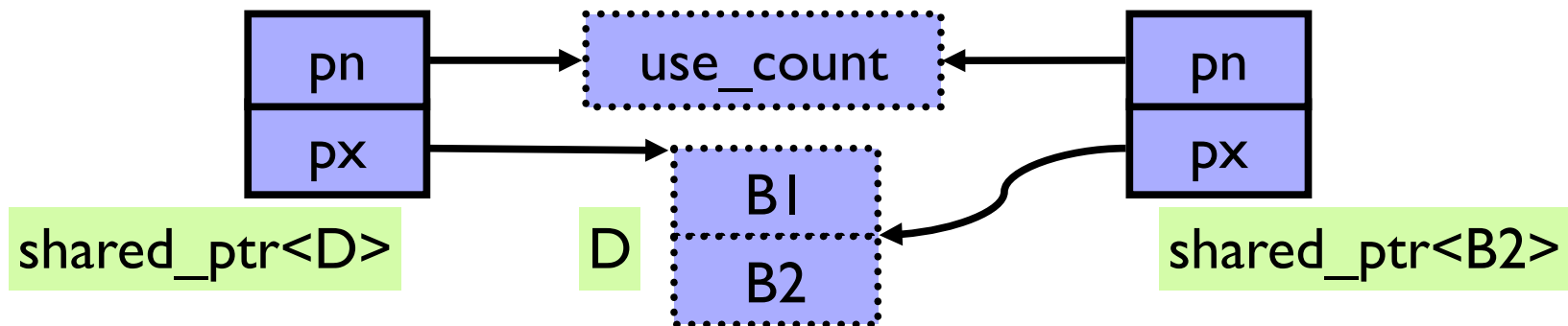
- + Non-intrusive
- + No count allocation needed
- Can only convert raw \Rightarrow smart pointer once
- Can't support derived-to-base conversions
- Doesn't address deletion in wrong heap, dangling
- Very hard / expensive to make thread-safe



boost::shared_ptr

Basic Strategy

- Store pointers to count and pointee separately
- Allows derived-to-base conversion



Gotcha, Revisited

```
void g();  
  
int f( boost::shared_ptr<D> a, int b );  
  
int a = f( boost::shared_ptr<D>( new D("foo", 3) ), g() );
```

Gotcha, Revisited

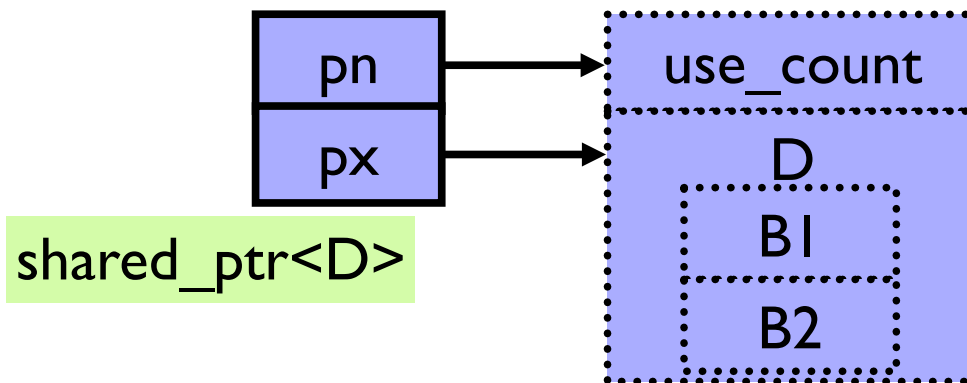
```
#include <boost/make_shared.hpp>

void g();

int f( boost::shared_ptr<D> a, int b );

int a = f( boost::make_shared<D>("foo", 3), g() );
```

No unmanaged
resources exposed!

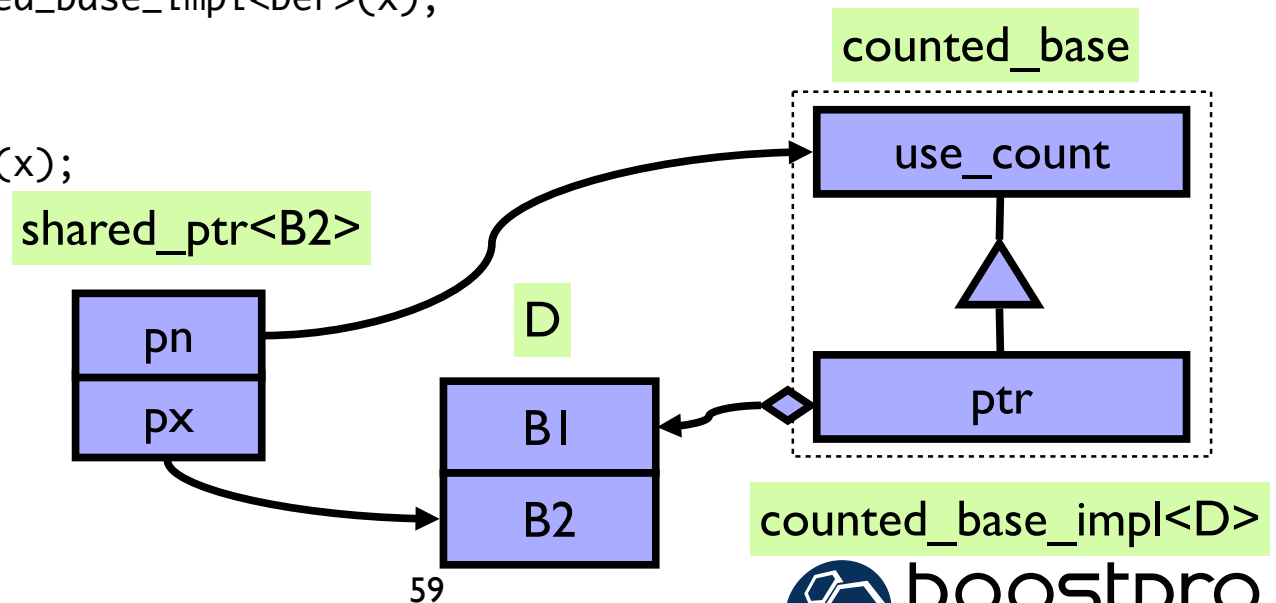


No separate
use_count allocation!

Solving the delete slicing problem

```
template <class Base>
template <class Der>
shared_ptr<Base>::shared_ptr(Der* x)
: px(x)
{
    try
    {
        pn = new counted_base_impl<Der>(x);
    }
    catch(...)
    {
        checked_delete(x);
        throw;
    }
}
```

```
shared_ptr<B2>
factory()
{
    return shared_ptr<B2>(new D);
}
```



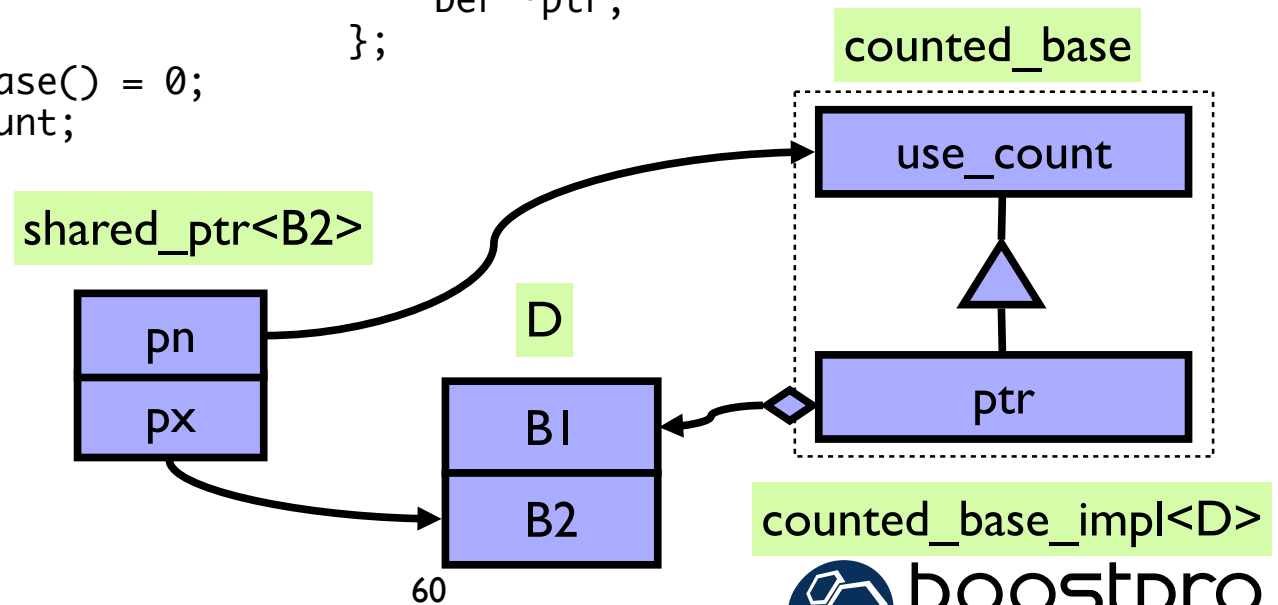
Solving the delete slicing problem

```
template <class Base>
shared_ptr<Base>::~~shared_ptr()
{
    if (--pn->use_count == 0)
        delete pn;
}
```

```
struct counted_base
{
    virtual ~counted_base() = 0;
    std::size_t use_count;
};
```

```
template <class Der>
struct counted_base_impl
    : counted_base
{
    ~counted_base_impl()
    { delete ptr; }

    Der *ptr;
};
```

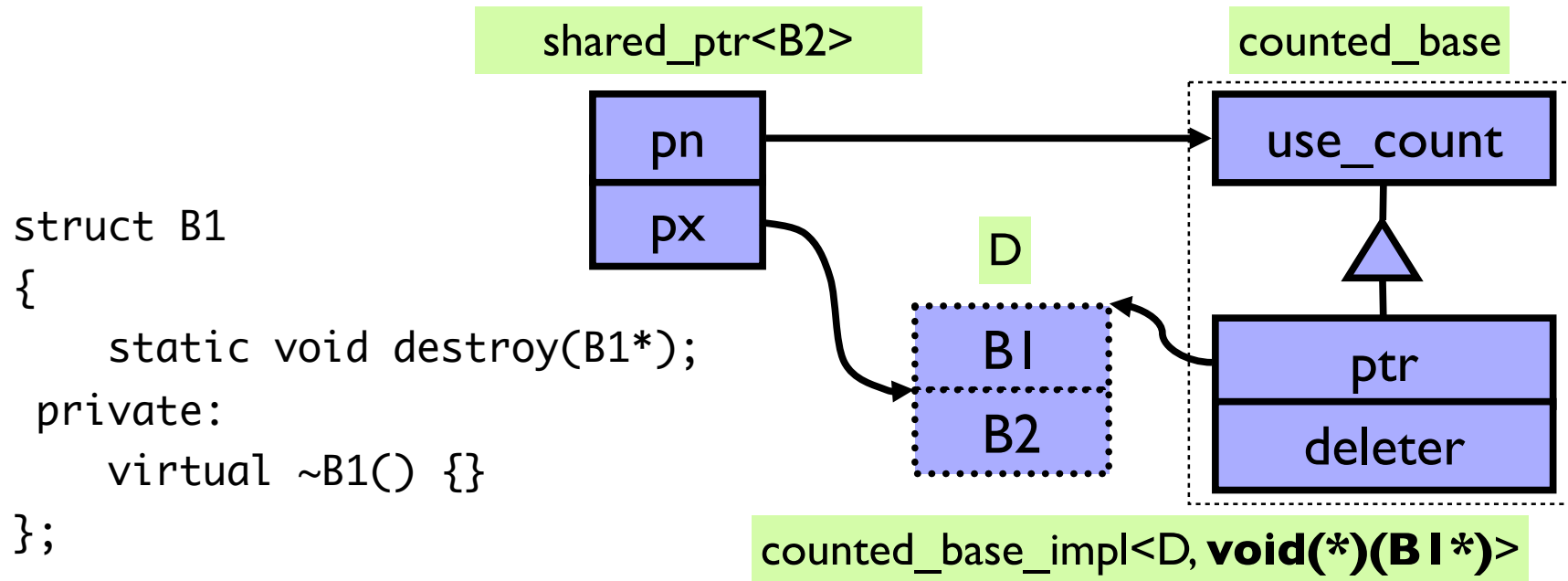


shared_ptr doesn't delete px!

What have we gained?

- Derived \Rightarrow base conversion loses no destruction info (no more delete slicing)!
- Type to delete *and* deletion heap determined at moment of initialization (no more deletion in wrong heap)!
- Template parameter may be an incomplete type at `shared_ptr` destruction!
- Manage life of everything with `shared_ptr<void>`

Low-hanging fruit: Custom Deleters



```
B1 b1; // error, private destructor!
D d; // ditto
shared_ptr<B2> p(new D, B1::destroy); // OK
```


boost::shared_ptr

Solution Checklist

- ✓ Leaks
- ✓ Double Delete
- ✓ Uninitialized
- ✓ Array Semantics
- ✓ Ownership Semantics
- ✓ Deletion of incomplete type ✓
- ✓ Delete Slicing ✓
- ✓ Use in std:: containers
- ✓ Deletion in wrong heap
- ❌ Dangling

Solving the Dangling Problem

- Problem: battlefield simulation
- In each timeslice, GameObjects may:
 - Acquire a target, or
 - Fire on the target acquired last slice (if still alive)
- Target acquisition must not keep the target alive (shared_ptr<> won't work)
- Some other GameObject might kill the target before us (raw pointer won't work)

boost::weak_ptr<T>

overview

- Implicit conversion/assignment from `shared_ptr<T>`
- Can be converted to `shared_ptr<T>`
 - explicit construction: throws if target deleted
 - `w.lock()`: NULL if target deleted
- No dereference operations! (Not a ptr?)
- Good for child-to-parent pointers

Solving the Dangling Problem

```
std::set< shared_ptr<GameObject> > all_targets;

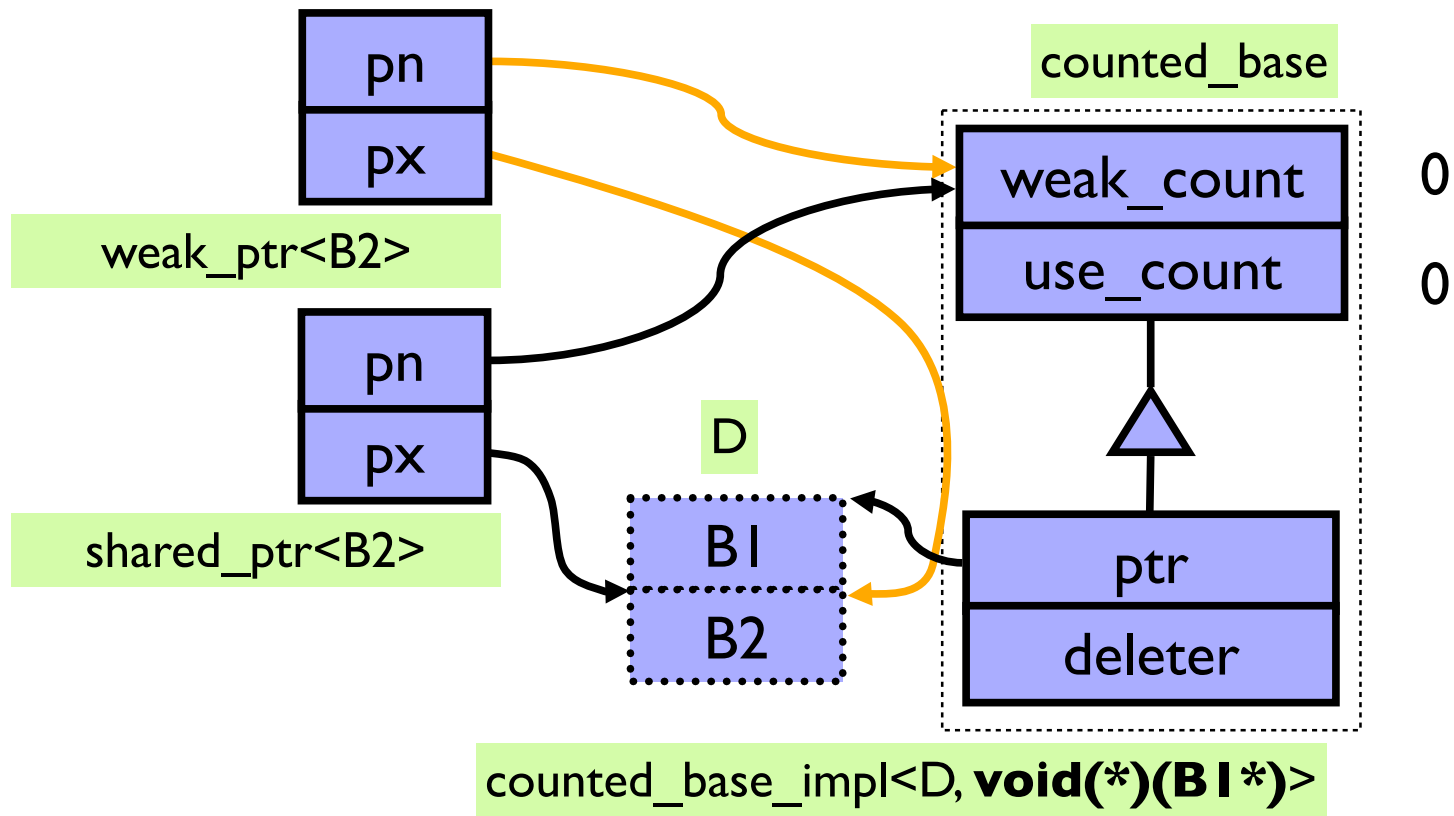
struct Tank : GameObject
{
    virtual void time_slice()
    {
        shared_ptr<GameObject> p = this->target.lock();

        if (p)
            p->damage(500);
        else
            this->target = this->select_target();
    }

    shared_ptr<GameObject> select_target();

private:
    weak_ptr<GameObject> target;
};
```

weak_ptr implementation



boost::shared_ptr

Solution Checklist

- ✓ Leaks
- ✓ Double Delete
- ✓ Uninitialized
- ✓ Array Semantics
- ✓ Ownership Semantics
- ✓ Deletion of incomplete type ✓
- ✓ Delete Slicing ✓
- ✓ Use in std:: containers
- ✓ Deletion in wrong heap
- ✓ Dangling

Reference Cycles

- Usually there's a natural ownership relationship

```
struct tree_node
{
    void add_child(shared_ptr<tree_node> c)
    {
        this->children.push_back( c );
        c->parent = this;
    }

private:
    weak_ptr<tree_node> parent;           // OK
    std::list<shared_ptr<tree_node> > children;
};
```

Reference Cycles

```
struct tree_node
{
    void add_child(shared_ptr<tree_node> c)
    {
        this->children.push_back( c );
        c->parent = ???;
    }

private:
    weak_ptr<tree_node> parent;
    std::list<shared_ptr<tree_node> > children;
};
```


Reference Cycles

```
struct tree_node
{
    static void parent_child(
        shared_ptr<tree_node> p, shared_ptr<tree_node> c)
    {
        parent->children.push_back( c );
        c->parent = p;
    }

private:
    weak_ptr<tree_node> parent;
    std::list<shared_ptr<tree_node> > children;
};
```

Raw \Rightarrow Shared

```
struct tree_node
{
    void add_child(shared_ptr<tree_node> c)
    {
        this->children.push_back( c );
        c->parent = ???;
    }

private:
    weak_ptr<tree_node> parent;
    std::list<shared_ptr<tree_node> > children;
};
```

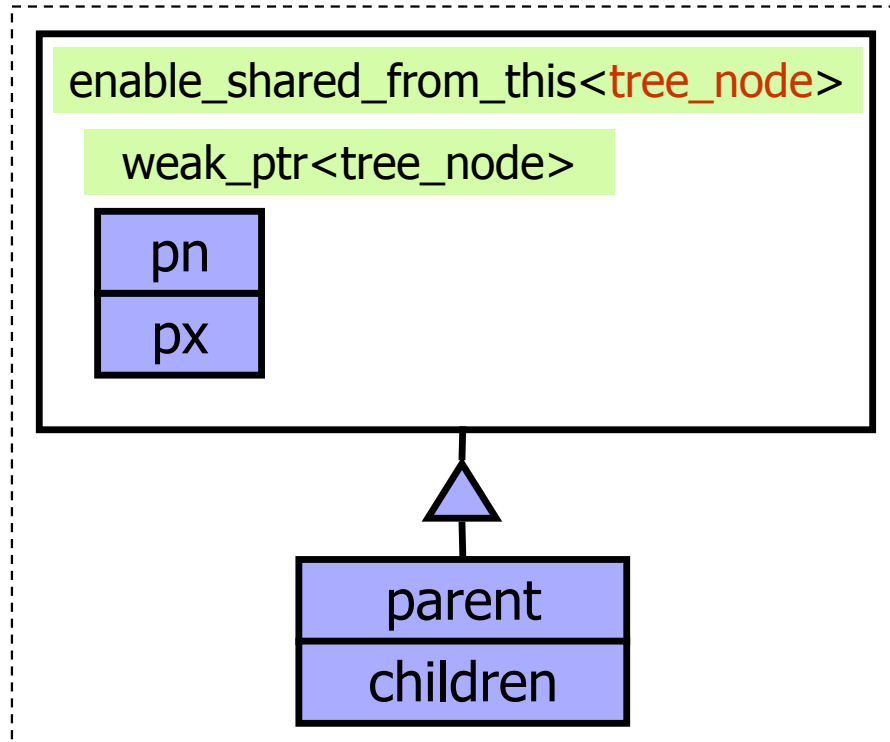
Raw \Rightarrow Shared

```
struct tree_node
: boost::enable_shared_from_this<tree_node>
{
    void add_child(shared_ptr<tree_node> c)
    {
        this->children.push_back( c );
        c->parent = shared_from_this();
    }

private:
    weak_ptr<tree_node> parent;
    std::list<shared_ptr<tree_node> > children;
};
```

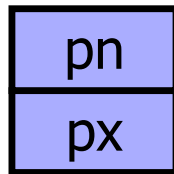
Raw \Rightarrow Shared

tree_node

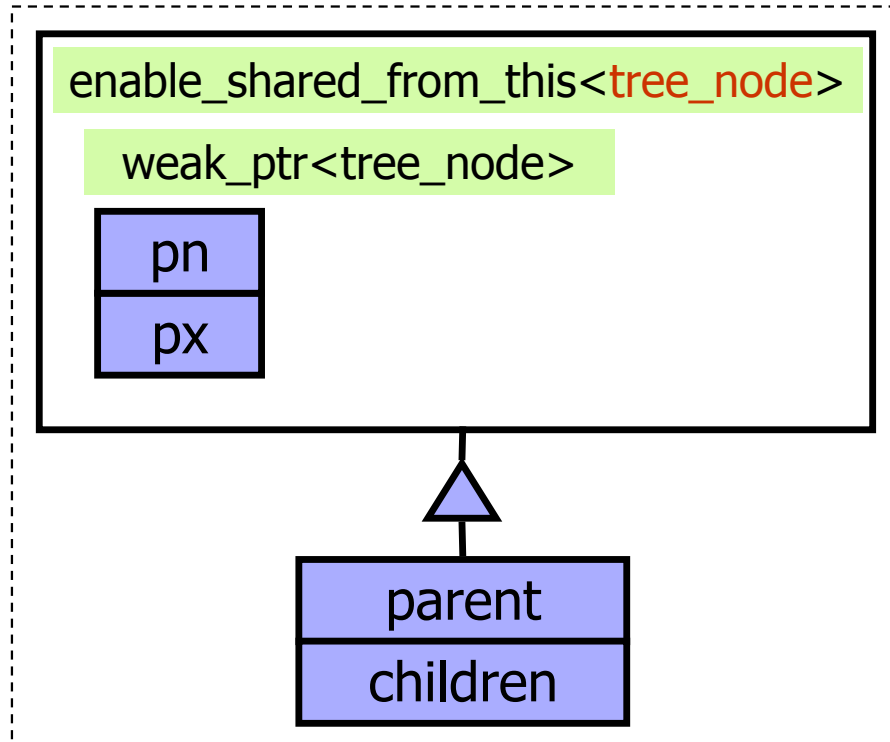


Raw \Rightarrow Shared

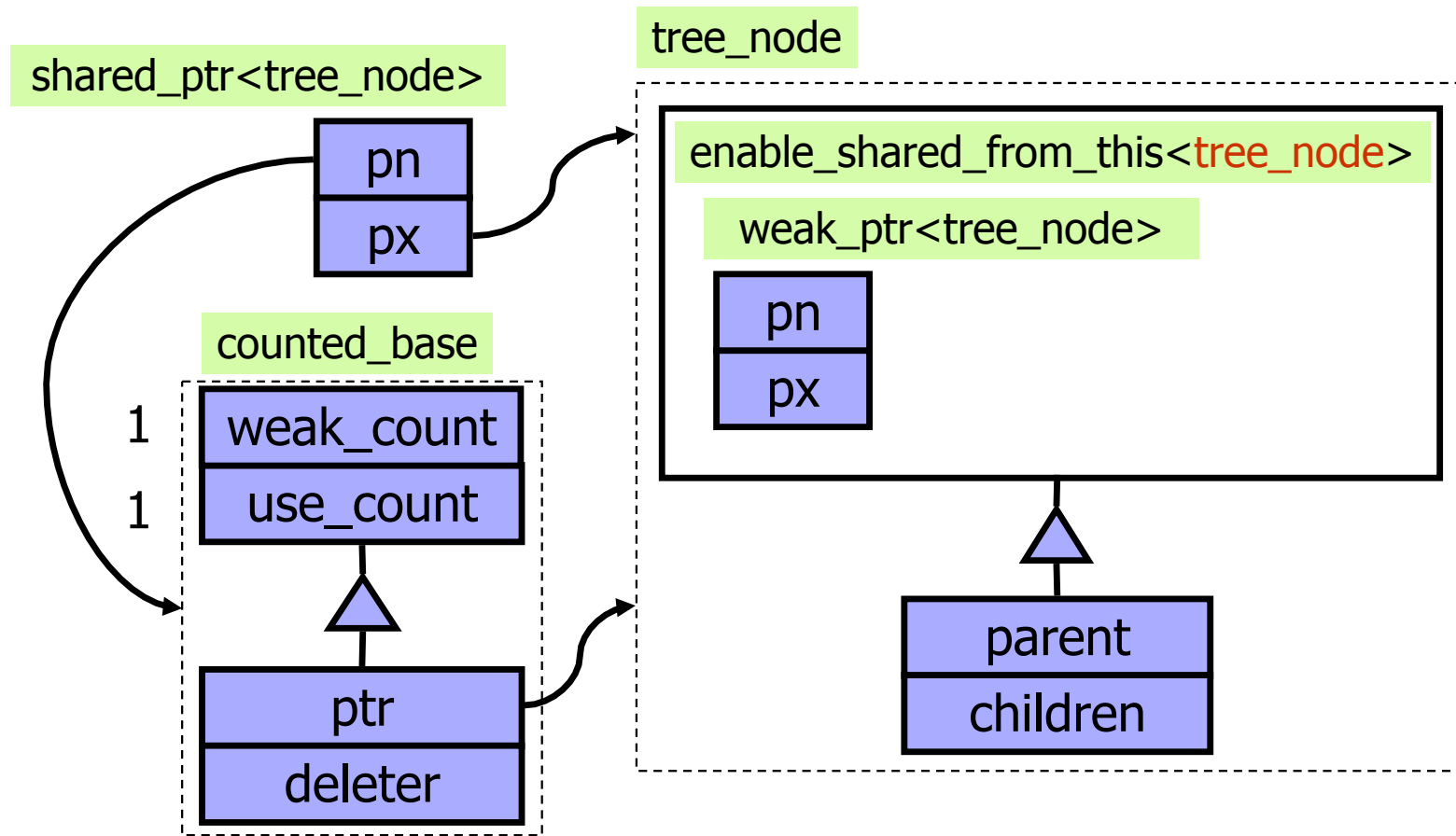
shared_ptr<tree_node>



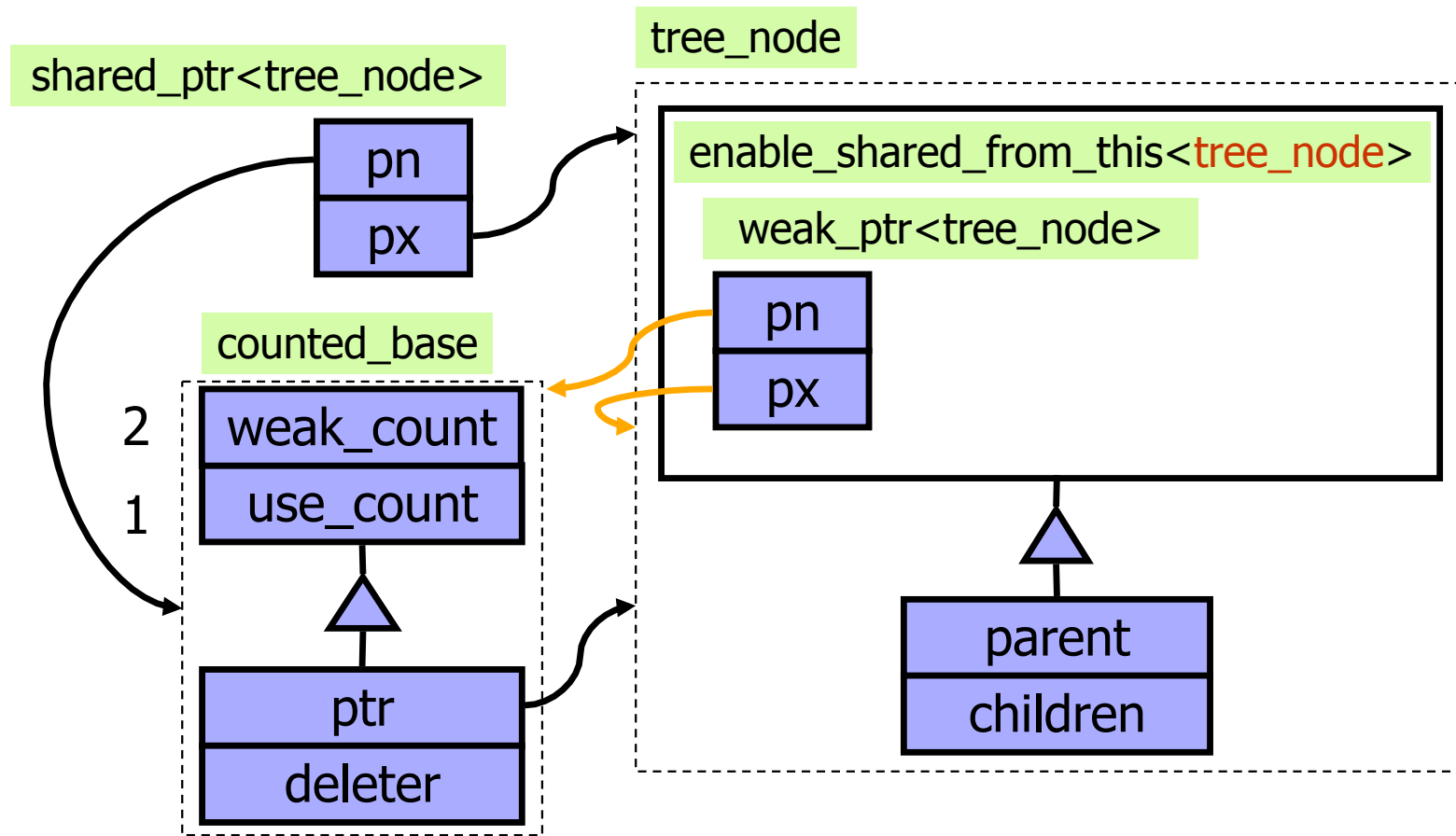
tree_node



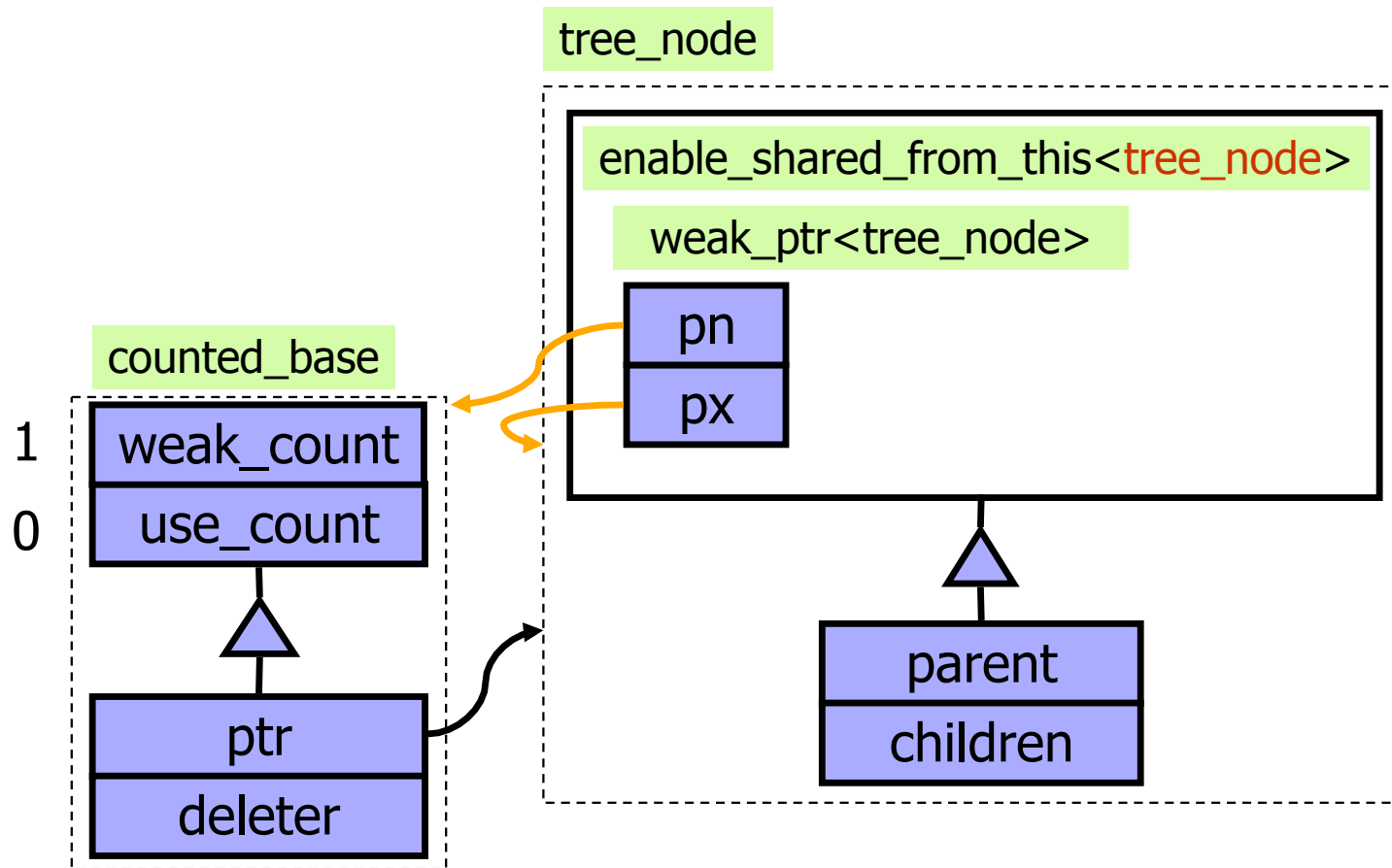
Raw \Rightarrow Shared



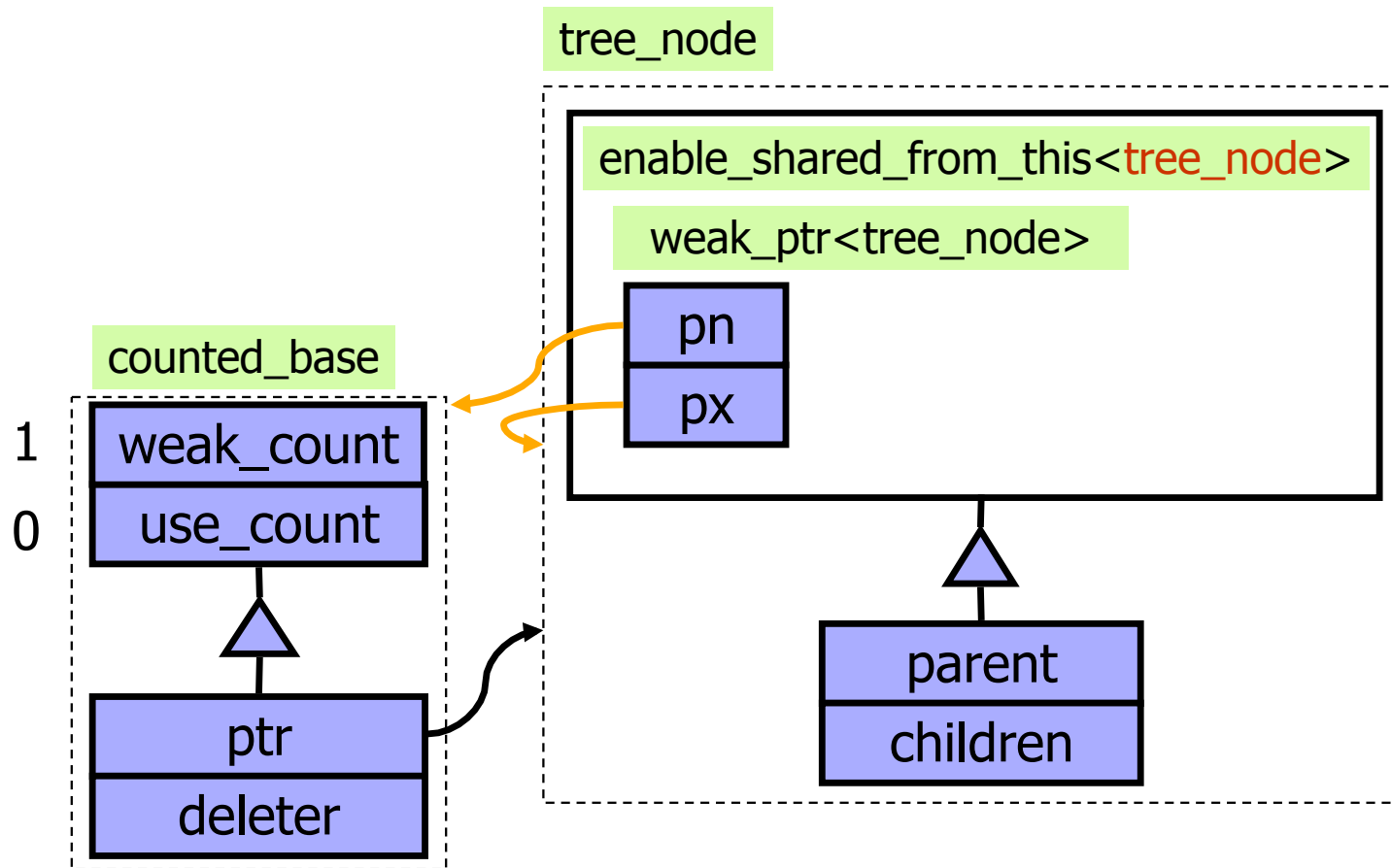
Raw \Rightarrow Shared



Raw \Rightarrow Shared



Raw \Rightarrow Shared



Exercise 5: GameObject Simulation

- In each timeslice, GameObjects:
 - Acquire a target, or
 - Fire on acquired target
- Firing on acquired target may destroy it
- Multiple GameObjects may acquire the same target
- Extra credit: Using a deleter, make it impossible for anyone to destroy a Tank except through a `shared_ptr`