Show all your work.

1. (10 pts.) Let 
$$A = \begin{pmatrix} 0 & 1 & 1 \\ 1 & 1 & -2 \\ 1 & 3 & 0 \end{pmatrix}$$
 and  $b = \begin{pmatrix} 2 \\ -1 \\ 3 \end{pmatrix}$ .

(a) Find all solutions to Ax = b.

$$\begin{pmatrix}
0 & 1 & 1 & 2 \\
1 & 1 & -2 & -1 \\
1 & 3 & 0 & 3
\end{pmatrix} \rightarrow \begin{pmatrix}
11 & -2 & -1 \\
0 & 1 & 2 \\
1 & 3 & 0 & 3
\end{pmatrix} \rightarrow \begin{pmatrix}
11 & -2 & -1 \\
0 & 1 & 2 \\
6 & 2 & 2 & 4
\end{pmatrix} \rightarrow \begin{pmatrix}
11 & -2 & -1 \\
0 & 1 & 2 \\
0 & 0 & 0 & 0
\end{pmatrix}$$

$$\times + y - 2z = -1$$

$$y + z = 2$$

$$z = free$$

$$y = 2 - z$$

$$x = -y + 2z - 1$$

$$z = -(2-z) + 2z - 1 = -3 + 3z$$

Use your answer to (a) to answer the following, without additional calculation:

- (b) Give a basis for the nullspace of A.  $\binom{3}{1}$  (from the solutions in (a))
- (c) Give a basis for the columnspace of A.  $\binom{9}{1}$ ,  $\binom{1}{3}$  (the pivot columns of A)
- 2. (6 pts.)
  - (a) (2 pts.) Give a symmetric matrix A so that  $\mathbf{x}^T A \mathbf{x} = 2x^2 2xy + y^2$

$$A = \begin{pmatrix} 2 - 1 \\ -1 & 1 \end{pmatrix}$$

(b) (4 pts.) Determine whether A is positive definite. (This can be done several different ways; any correct method is acceptable as long as your work is shown.)

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$$|z|=2$$
 and  $\left|\frac{2^{-1}}{-1}\right|=2-1=1$ . Both are positive, so A is positive definite

3. (8 pts.) The vectors  $\mathbf{v_1} = (1,0,0,0), \mathbf{v_2} = (-2,1,0,2), \mathbf{v_3} = (-1,3,0,1)$  are a basis for a subspace of  $\mathbb{R}^4$ . Find an orthonormal basis for that subspace.

$$W_{1} = V_{1} = (\ell_{1}0, 0, 0)$$

$$W_{2} = V_{2} - proj_{W_{1}}V_{2} = (-2, 1, 0, 2) - \frac{W_{1}V_{2}}{W_{1}W_{1}}W_{1} = (-2, 1, 0, 2) - \frac{-2}{1}(l_{1}0, 0, 0) = (0, 1, 0, 2)$$

$$W_{3} = V_{3} - proj_{W_{1}}V_{3} - proj_{W_{2}}V_{3} = (-1, 3, 0, 1) - \frac{-1}{1}(l_{1}0, 0, 0) - \frac{5}{5}(0, 1, 0, 2) = (0, 2, 0, -1)$$

$$Q_{1} = \frac{W_{1}}{|l_{1}W_{2}|l_{1}} = (0, \frac{1}{V_{5}}, 0, \frac{2}{V_{5}})$$

$$Q_{3} = \frac{W_{2}}{|l_{1}W_{2}|l_{1}} = (0, \frac{2}{V_{5}}, 0, -\frac{1}{V_{5}})$$

4. (10 pts.) Find inverses of the following matrices, if they exist. If no inverse exists, explain how you know that.

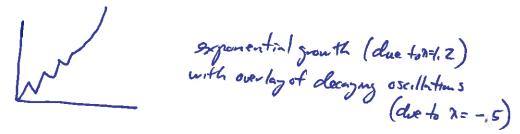
- 5. (10 pts.) The annual changes in the population of an organism is modeled by  $\mathbf{p}_{t+1} = A\mathbf{p}_t$ , where  $A = \begin{pmatrix} 0 & 3 \\ 0.2 & 0.7 \end{pmatrix}$ . The first entry of  $\mathbf{p}_t$  refers to young, and the second to adults.
  - (a) (2 pts.) What is the biological meaning of the 0.2 in this matrix?

20% of the young become adults each year

(b) (2 pts.) The diagonalization  $A = S\Lambda S^{-1}$  has  $\Lambda = \begin{pmatrix} 1.2 & 0 \\ 0 & -.5 \end{pmatrix}$  and  $S = \begin{pmatrix} 5 & 6 \\ 2 & -1 \end{pmatrix}$ . What is the stable age distribution of this model? What does it tell you about the population?

(5) In the long term, the population will have voyaly 5 young for every 2 adults.

(c) (3 pts.) Sketch a graph of time vs. population size for the two groups in this model that indicates typical qualitative behavior you should see if the initial population,  $p_0$ , is randomly chosen.



- (d) (3 pts.) If the initial population were  $\mathbf{p}_0 = (10,4)$  (twice the first column of S), what would  $\mathbf{p}_{20}$  be?  $(1.2)^{20} \binom{10}{4}$
- 6. (8 pts. 4 pts. each) Decide whether each of these transformations  $T : \mathbb{R}^2 \to R^2$  is linear or not. If it is not linear, explain why it is not. If it is linear, give a matrix to express it (using the standard bases).

(a) 
$$T(x,y) = (x,y) + (1,-1)$$
.  
Not linear.  $7(0,0) \neq 0$ 

(b) 
$$T(x,y) = (y,0)$$
.

Linear  $A = \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix}$ 

7. (8 pts. — 4 pts. each) Let 
$$A = \begin{pmatrix} 3 & 1 & 4 \\ 0 & 1 & 5 \\ 0 & 1 & 5 \end{pmatrix}$$

(a) Find all eigenvalues of A.

$$\begin{vmatrix} 3-N & 1 & 4 \\ 0 & 1-N & 5 \\ 0 & 1 & 5-N \end{vmatrix} = (3-N) \left[ (1-N)(5-N) - 5 \right] = (3-N)(N^2 - 6N) = (3-N)N(N-6)$$
(b) Find an eigenvector for the *largest* eigenvalue of A.

$$\frac{7 = 6}{A - 6I} = \begin{pmatrix} -3 & 1 & 4 \\ 0 & -5 & 5 \\ 0 & 1 & -1 \end{pmatrix} \rightarrow \begin{pmatrix} -3 & 1 & 4 \\ 0 & -5 & 5 \\ 0 & 0 & 0 \end{pmatrix} = \frac{3 \times + 7 + 42 = 0}{-57 + 52 = 0}$$

$$\frac{7}{2} = \begin{pmatrix} \frac{5}{3} & \frac{7}{3} & \frac{$$

8. (8 pts.) Let 
$$A = \begin{pmatrix} 1 & 1 & 2 & 3 \\ 2 & -1 & 1 & 0 \\ 1 & 0 & 1 & 1 \end{pmatrix}$$
.

(a) (6 pts.) Let V be the column space of A. Find a basis for  $V^{\perp}$ 

$$V = C(A) \qquad V^{\perp} = M(A^{T})$$

$$\begin{pmatrix} 1 & 2 & 1 \\ 1 & -1 & 0 \\ 2 & 1 & 1 \\ 3 & 0 & 1 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 & 1 \\ 0 & -3 & -1 \\ 0 & -6 & -2 \end{pmatrix} \rightarrow \begin{pmatrix} 1 & 2 & 1 \\ 0 & -3 & -1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix} \qquad \begin{array}{c} x + 2y + 2 = 6 \\ -3y - 2 = 0 \\ 2 & 6 = 0 \\ 2 &$$

(b) (2 pts.) What is the rank of A? (If you did part (a) you should be able to answer this with no further computation.) rank (A) = 2

- 9. (8 pts.) Four data points in the plane are (x,y)=(-2,2), (-1,2), (0,1), (1,-1).
  - (a) (2 pts.) Give a matrix equation that you would *like to solve* (but which has no solution) to find the equation of a line y = mx + b through these points.

$$\begin{pmatrix} -2 & 1 \\ -1 & 1 \\ 0 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} \mathbf{m} \\ \mathbf{b} \end{pmatrix} = \begin{pmatrix} 2 \\ 2 \\ 1 \\ -1 \end{pmatrix}$$

(b) (6 pts.) Give a matrix equation that can be solved to find the least squares best-fit line for these points. (Do not solve it.)

$$\begin{pmatrix} -2 & -1 & 0 & 1 \\ 1 & 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} -2 & 1 \\ -1 & 1 \\ 0 & 1 \\ 1 & 1 \end{pmatrix} \begin{pmatrix} m \\ b \end{pmatrix} = \begin{pmatrix} -2 - 1 & 0 & 1 \\ 1 & 1 & 1 \end{pmatrix} \begin{pmatrix} 2 \\ 2 \\ 1 \\ -1 \end{pmatrix}$$

$$\left(\begin{pmatrix} 6 & -2 \\ -2 & 4 \end{pmatrix}\begin{pmatrix} m \\ b \end{pmatrix} = \begin{pmatrix} -7 \\ 4 \end{pmatrix}\right)$$

- 10. (24 pts. 2 pts. each) Give short answers.

  - (b) If for some specific A, b, where A is  $4 \times 5$  and  $b \in \mathbb{R}^4$ , we know  $A\mathbf{x} = \mathbf{b}$  has no solution, then the rank of A must be (list all possibilities) 0, 1, 2, 3
  - (c) If for some specific A, b, where A is  $4 \times 5$  and  $b \in \mathbb{R}^4$ , we know  $A\mathbf{x} = \mathbf{b}$  has a 2-dimensional plane of solutions, then the rank of A must be (list all possibilities)
  - (d) If for some specific A, where A is  $4 \times 5$  we know  $A\mathbf{x} = \mathbf{b}$  has a solution for every b, then the rank of A must be (list all possibilities)
  - (e) If Q is an orthogonal matrix, then its determinant can only be  $\frac{2}{2}$  (Hint: What is  $Q^TQ$ ?)
  - (f) Using the 'big formula' to find the determinant of a 7 × 7 matrix would requiring adding (or subtracting) \_\_\_\_\_\_\_ terms, each of which is the product of \_\_\_\_\_\_ numbers. For such a matrix, it would be much easier to compute the determinant by \_\_\_\_\_\_\_ terms.

- (g) Using Cramer's rule to solve  $\begin{pmatrix} a & b \\ c & d \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} = \begin{pmatrix} e \\ f \end{pmatrix}$  gives  $x = \frac{\begin{vmatrix} e & b \\ d & d \end{vmatrix}}{\begin{vmatrix} e & d \\ d & d \end{vmatrix}} = \frac{ed-bf}{ad-bc}$
- (i) If  $\mathbf{a}, \mathbf{b}, \mathbf{c}$  in  $\mathbb{R}^3$  form three edges of a parallelopiped, then its volume can be computed as  $\frac{\mathbf{a} \cdot \mathbf{b} \cdot \mathbf{c} \cdot \mathbf{c} \cdot \mathbf{c}}{(-\mathbf{v}_3 \mathbf{c})}$
- (j) A matrix that rotates vectors in  $\mathbb{R}^2$  about the origin by an angle of  $\theta$  counterclockwise is  $R_{\theta} = \begin{pmatrix} \cos \Theta & -\sin \Theta \\ \sin \Theta & \cos \Theta \end{pmatrix}$
- (k) If the SVD of a matrix A is

$$U\Sigma V^T = egin{pmatrix} 1/\sqrt{2} & -1/\sqrt{2} \\ 1/\sqrt{2} & 1/\sqrt{2} \end{pmatrix} egin{pmatrix} 10 & 0 \\ 0 & 0 \end{pmatrix} egin{pmatrix} 2/\sqrt{5} & 1/\sqrt{5} \\ 1/\sqrt{5} & -2/\sqrt{5} \end{pmatrix}$$

then the rank of A is  $\frac{1}{\sqrt{\binom{\frac{1}{0}}{0}}}$  and the pseudoinverse  $A^+$  is (you may leave your answer as a product):

(1) If A has eight vector  $\mathbf{v}$  with eigenvalue  $\lambda$ , then  $MAM^{-1}$  will have eigenvector M with eigenvalue  $\lambda$ .