Precision Measurement of the Radiative Decay Mode of the Neutron

RDK II Collaboration

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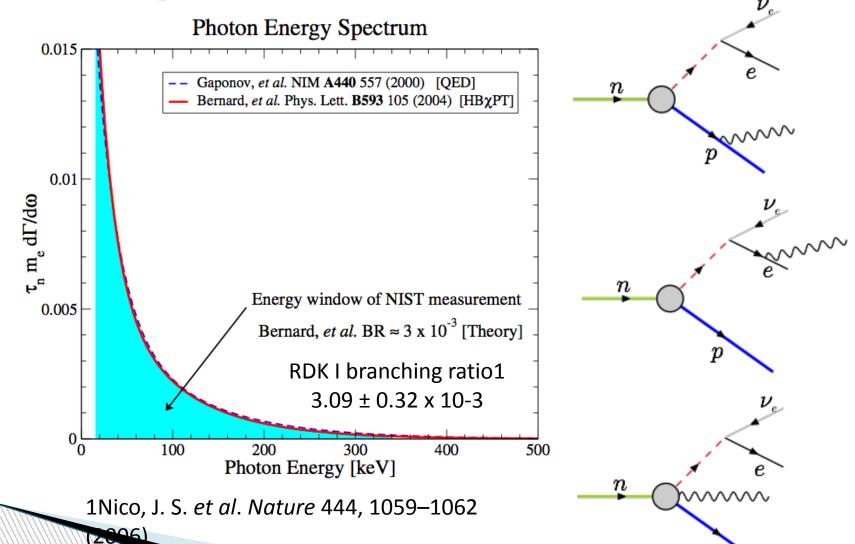
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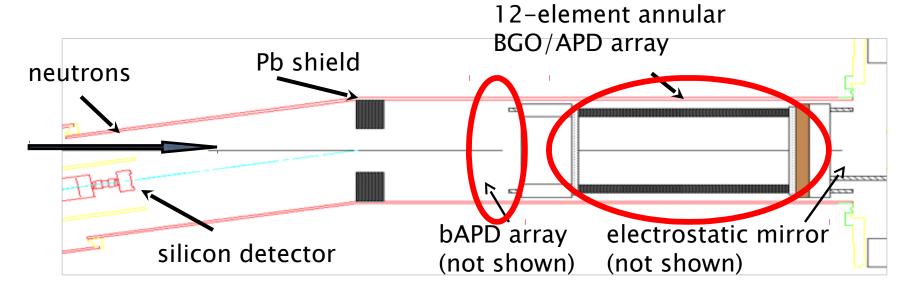
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Theory



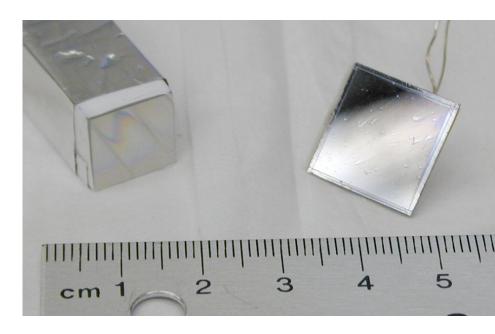
Overview

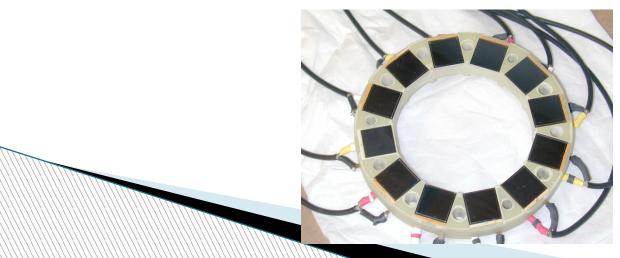


- National Institute of Standards & Technology (NIST) NG6 cold neutron beam
- On beam from July 2008 to Nov 2009
- 4.6 T magnetic field traps charged decay products to tight orbits giving large solid angle coverage
- Electrostatic mirror turns around "wrong-way" protons
- Delayed electron-proton coincidence trigger
- Waveform-based data acquisition

Primary detector

- Bismuth germanate (BGO) scintillator crystals coupled to avalanche photo-diodes (APD)
 - 12 detectors
 - 200x12x12mm3 BGOs
 - 14x14mm2 APDs
 - <10keV-endpoint</pre>

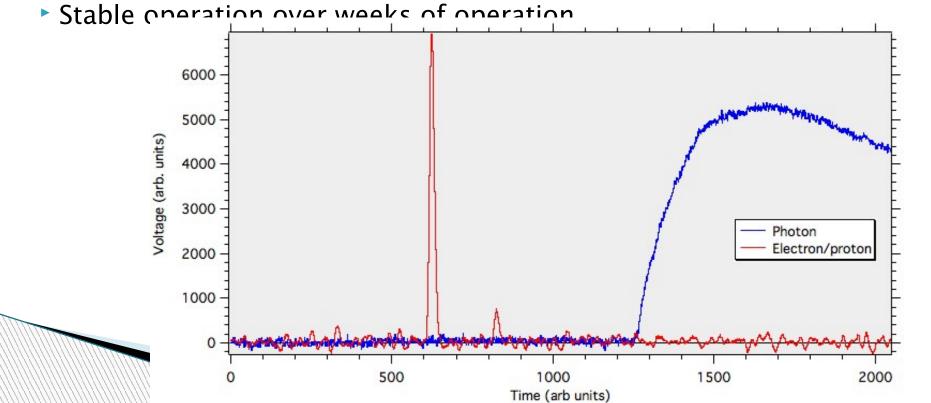






Primary detector

- APDs operate in vacuum and high magnetic field (~5 T)
- APD gain increases and noise decreases with cooling
- Light yield of BGO increases with cooling
- Large crystals available at reasonable cost



Direct detector

Large area bare avalanche photo-diode

(bAPD)

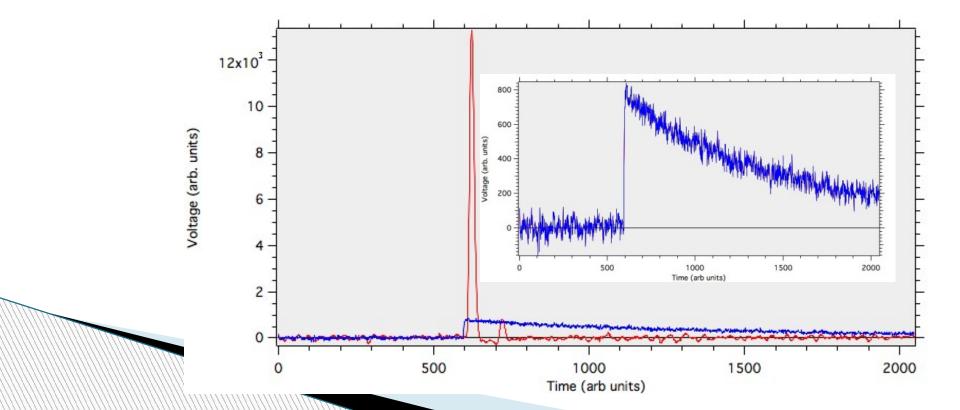
- 3 detectors

- 28x28mm2
- ~500eV-20keV



Direct detector

- Lower energy range
- Lower background
- Narrower timing peak
- Smaller cross section



Analysis

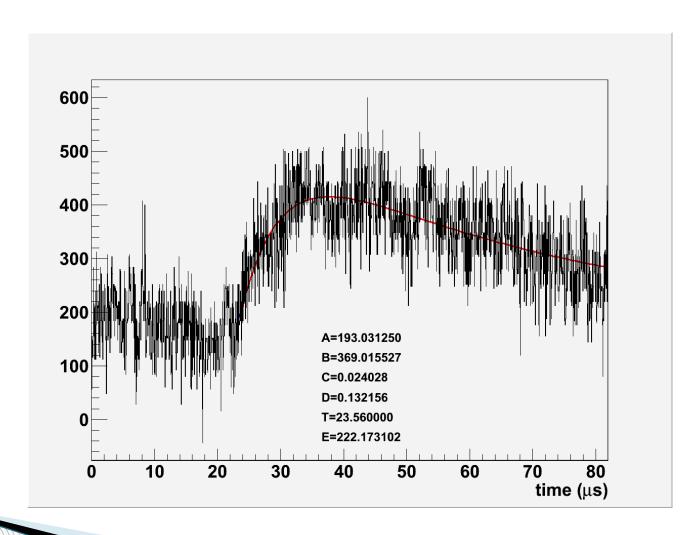
	All voltages	Full Mirror
Run time	164.4d	97.8d
Live time	147.1d	87.5d
Total triggers	9.7x107	6.8x107
Run data	6.4Tb	4.4Tb
Total data	22Tb	

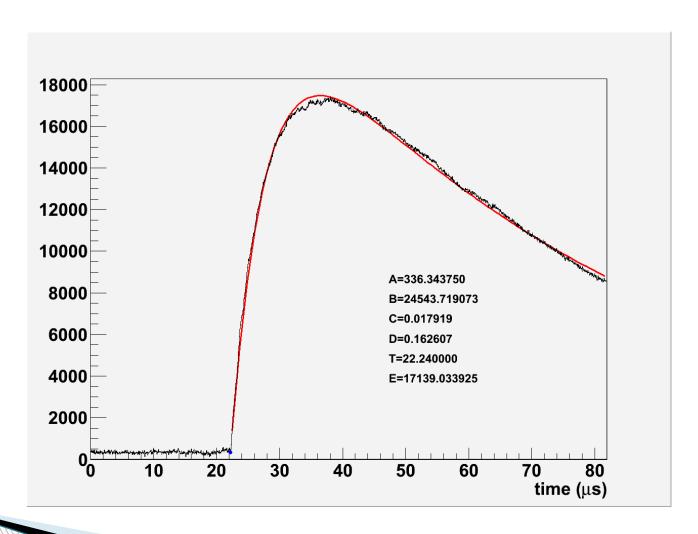
- Parameters to extract from waveforms
 - Energy
 - Electron
 - Proton
 - Photon
 - Time of Flight
 - Electron-proton
 - Electron photon

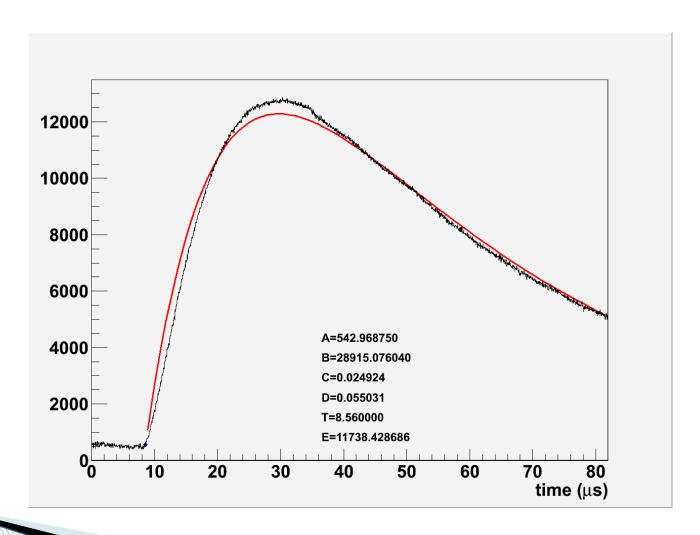
- Fit function
 - A+Be-C(x-t)(1-e-D(x-t))
 - A = signal drift (electronics)
 - B = intensity
 - C = falling rate (electronics)
 - D = rising rate (BGO to APD)
 - t = time
 - E = energy
- Hybrid linear/non-linear regression
- Allows measurement of additional parameters
- Poor fits with some signals

$$x_{\text{max}} = t + \frac{1}{D} \ln \left(1 + \frac{D}{C} \right)$$

$$E = \frac{BD}{C+D} \left(1 + \frac{D}{C}\right)^{-\frac{C}{D}}$$







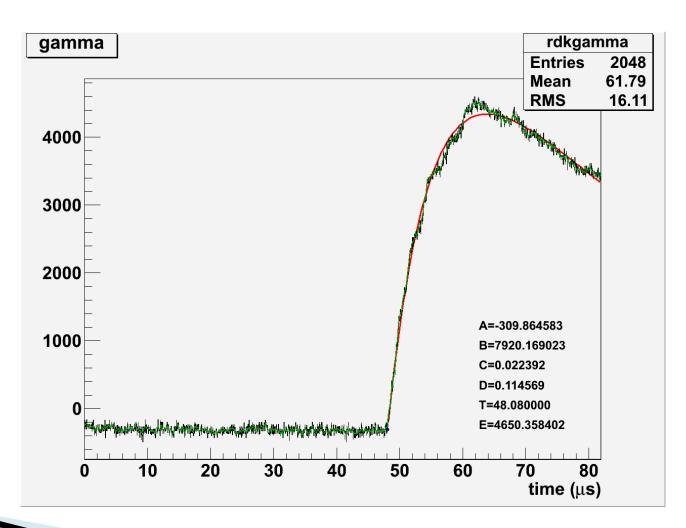
Smoothing

- Adaptation of locally weighted scatterplot smoothing (LOWESS) algorithm
- Uniform spacing of points allows the use of a simple transformation matrix
- Adjustable smoothing radius R
- Tradeoff between timing resolution and noise reduction

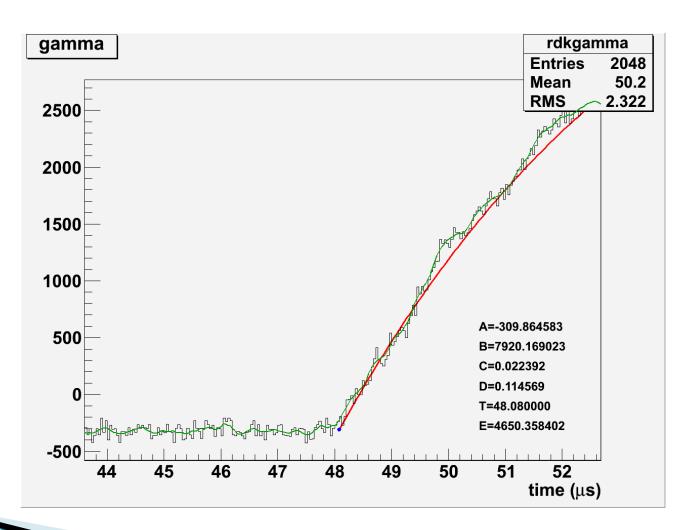
$$X = \begin{bmatrix} 1 & -R \\ 1 & -R+1 \\ \vdots & \vdots \\ 1 & R-1 \\ 1 & R \end{bmatrix} \qquad W_{ii} = 1 - \left| \frac{X_{i1}}{R+1} \right|^{3}$$

$$T = \begin{bmatrix} 1 & 0 \end{bmatrix} \cdot (X^T W X)^{-1} X^T W \qquad y'_x = T \cdot y_{x-R, x+R}$$

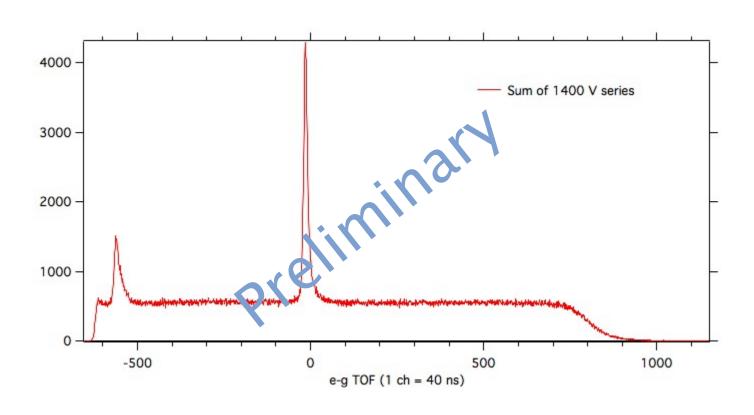
Smoothing



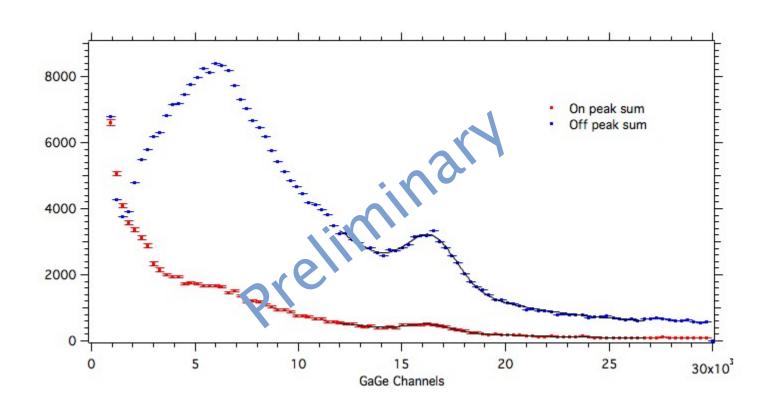
Smoothing



Results



Results



Results

