

Kosen Club CP 勉強会

GRAPH-BFS, DIJKSTRA, BELLMAN-FORD, FLOYD-WARSHALL

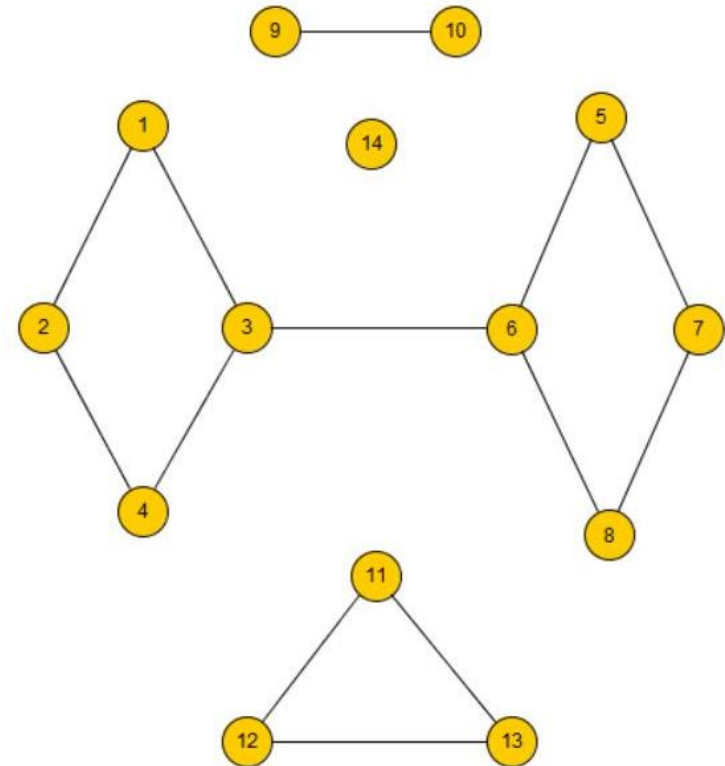
1.Shortest Path Algorithms

Algorithms	BFS	Dijksra	Bellman-Ford	Floyd-Warshall
Scope	1 to all	1 to all	1 to all	All to all
Weight	Only uniform	Non-negative	All	All
Implementation	Medium	Hard	Medium	Easy
Time complexity	$O(N)$	$O(E \cdot \log V)$	$O(V \cdot E)$	$O(V^3)$
Space complexity	$O(E)$	$O(E)$	$O(E)$	$O(V^2)$

2.BFS

[Breadth-first search – Wikipedia](#)

```
1 procedure BFS(G, root) is
2   let Q be a queue
3   label root as explored
4   Q.enqueue(root)
5   while Q is not empty do
6     v := Q.dequeue()
7     if v is the goal then
8       return v
9     for all edges from v to w in G.adjacentEdges(v) do
10      if w is not labeled as explored then
11        label w as explored
12        Q.enqueue(w)
```



3.Dijkstra

[Dijkstra's algorithm - Wikipedia](#)

```
1 function Dijkstra(Graph, source):
2     dist[source] ← 0                // Initialization
3
4     create vertex priority queue Q
5
6     for each vertex v in Graph:
7         if v ≠ source
8             dist[v] ← INFINITY      // Unknown distance from source to v
9             prev[v] ← UNDEFINED     // Predecessor of v
10
11     Q.add_with_priority(v, dist[v])
12
13
14     while Q is not empty:           // The main Loop
15         u ← Q.extract_min()         // Remove and return best vertex
16         for each neighbor v of u:   // only v that are still in Q
17             alt ← dist[u] + length(u, v)
18             if alt < dist[v]
19                 dist[v] ← alt
20                 prev[v] ← u
21             Q.decrease_priority(v, alt)
22
23     return dist, prev
```

4. Bellman-Ford

[Bellman-Ford algorithm - Wikipedia](#)

```
distance := list of size n
predecessor := list of size n

// Step 1: initialize graph
for each vertex v in vertices do

    distance[v] := inf           // Initialize the distance
    predecessor[v] := null       // And having a null predecessor

distance[source] := 0           // The distance from the source is 0

// Step 2: relax edges repeatedly
repeat |V|-1 times:
    for each edge (u, v) with weight w in edges do
        if distance[u] + w < distance[v] then
            distance[v] := distance[u] + w
            predecessor[v] := u

// Step 3: check for negative-weight cycles
for each edge (u, v) with weight w in edges do
    if distance[u] + w < distance[v] then
        error "Graph contains a negative-weight cycle"

return distance, predecessor
```

5.Floyd-Warshall

[Floyd–Warshall algorithm - Wikipedia](#)

```
let dist be a  $|V| \times |V|$  array of minimum distances initialized to  $\infty$  (infinity)
for each edge  $(u, v)$  do
     $\text{dist}[u][v] \leftarrow w(u, v)$  // The weight of the edge  $(u, v)$ 
for each vertex  $v$  do
     $\text{dist}[v][v] \leftarrow 0$ 
for  $k$  from 1 to  $|V|$ 
    for  $i$  from 1 to  $|V|$ 
        for  $j$  from 1 to  $|V|$ 
            if  $\text{dist}[i][j] > \text{dist}[i][k] + \text{dist}[k][j]$ 
                 $\text{dist}[i][j] \leftarrow \text{dist}[i][k] + \text{dist}[k][j]$ 
            end if
```