

Projection

Module `projection`

Functions

Function `draw_scene`

```
def draw_scene(  
    state: projection.State  
) -> numpy.ndarray
```

Read the dataset and draw the scene

Args

state State object

Returns

np.ndarray Image of the scene

Function `main`

```
def main()
```

Function `project_bbox3D_img`

```
def project_bbox3D_img(  
    bbox: bbox.BoundingBox,  
    camera_pose: numpy.ndarray,  
    camera_matrix: numpy.ndarray,  
    img: numpy.ndarray  
) -> numpy.ndarray
```

Project a 3D bounding box in the image plane

Args

bbox BoundingBox object

camera_pose Camera pose

camera_matrix Camera matrix

img Image to draw on

Returns

np.ndarray Image with the bounding box projected

Classes

Class `State`

```
class State(  
    ...
```

```

        datasets_folder: str = '/Users/caillotantoine/Datasets',
        dataset_name: str = 'CARLA_Dataset_A',
        frame: int = 180
    )

```

Class variables

Variable `dataset_name` Type: `str`

Name of the dataset

Variable `datasets_folder` Type: `str`

Path to the dataset folder

Variable `frame` Type: `int`

Frame to observe

Variable `mutex` Type: `<built-in function allocate_lock>`

Mutex to read and write the State object

Methods

Method `read_vars`

```

    def read_vars(
        self
    ) -> Tuple[str, str, int]

```

Read the State object

Returns

(str, str, int): (`datasets_folder`, `dataset_name`, `frame`)

Generated by *pdoc* 0.10.0 (<https://pdoc3.github.io>).