

# Constrained Functions

Text: Chapter 6

There are some situations in which we want to include known restrictions about  $x(t)$ .

- ▶  $x(t)$  is always positive
- ▶  $x(t)$  is always increasing (or decreasing)
- ▶  $x(t)$  is a density

**Idea:** Enforce these conditions by transforming  $x(t)$ .

# Positive Smoothing

We want to ensure that  $x(t) > 0$ .

Observation:

$$e^w : (-\infty, \infty) \rightarrow (0, \infty)$$

So try the transformation

$$x(t) = e^{W(t)}$$

with

$$W(t) = \Phi(t)\mathbf{c}$$

and penalize the roughness of  $W(t)$

# Estimating a Positive Smooth

We now want to minimize

$$\text{PENSSE}_\lambda(W) = \sum_{i=1}^n \left( y_i - e^{W(t_i)} \right)^2 + \lambda \int [LW(t)]^2 dt$$

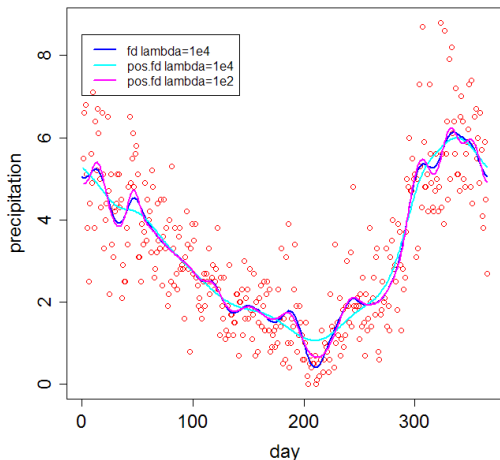
This does not have an explicit formula.

But it is convex – there is only one minimum.

Requires numerical optimization, but this is generally fast.

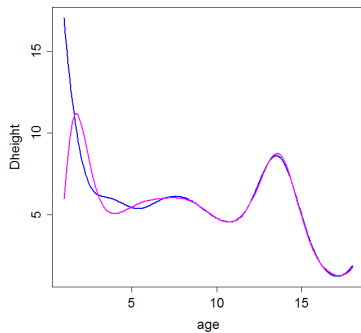
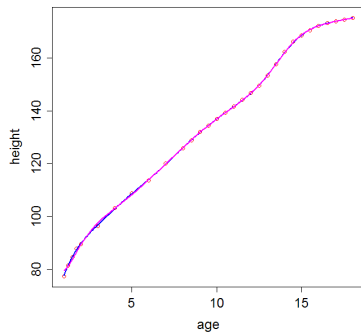
# Positive Smoothing Vancouver Precipitation

Constraints imply smoothness (of a certain type) – tend to need less smoothing on  $W$ .



# Monotone Smoothing

Berkeley growth study – heights aged 1 - 18



# Monotone Smoothing

We need  $x(t)$  always increasing:

$$Dx(t) > 0$$

suggests

$$Dx(t) = e^{W(t)} \rightarrow x(t) = \alpha + \int_{t_0}^t e^{W(s)} ds$$

again,  $W(t) = \Phi(t)c$

# Estimating a Monotone Smooth

We now want to minimize

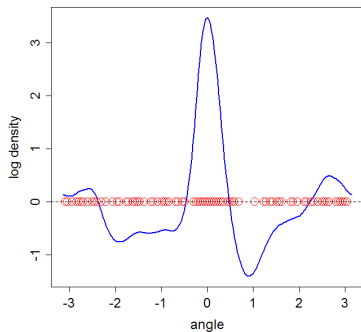
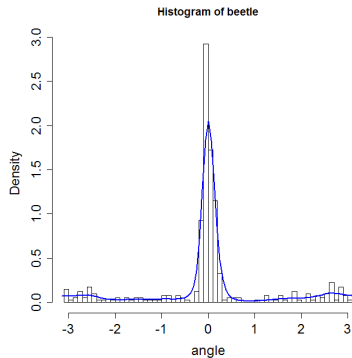
$$\text{PENSSE}_\lambda(W) = \sum_{i=1}^n \left( y_i - \alpha - \int_{t_0}^{t_i} e^{W(s)} ds \right)^2 + \lambda \int [LW(t)]^2 dt$$

- ▶ No explicit formula
- ▶ No good formula for the integral
- ▶ Still a convex problem; numerics work fairly quickly

Note,  $LW(t) = D^2W(t)$  suggests that any  $x(t) = \alpha + e^{\beta t}$  is smooth.

# Density Estimation

## Position of Beetles in Angles





# Density Estimation

$x(t)$  a density  $\Rightarrow$  positive, integrates to 1

$$x(t) = e^{W(t)} / \int e^{W(t)} dt$$

But we observe only  $t_1, \dots, t_n$ .

Need to find an objective to minimize.

## Penalized Likelihood

Likelihood of  $W(t)$  is probability of seeing  $t_1, \dots, t_n$  if  $W$  is true.

Easier to work with log likelihood

$$l(W|t_1, \dots, t_n) = \sum_{i=1}^n \left( W(t_i) - \log \int e^{W(t)} dt \right)$$

Minimize the *penalized negative log likelihood*:

$$\text{PENLOGLIK}_\lambda(W) = - \sum_{i=1}^n W(t_i) + n \log \int e^{W(t)} dt + \lambda \int [LW(t)]^2 dt$$

Usual comments about numerics apply.

# Thinking about Smoothness

What is an appropriate measure of smoothness for densities?

$$x(t) = Ce^{W(t)}$$

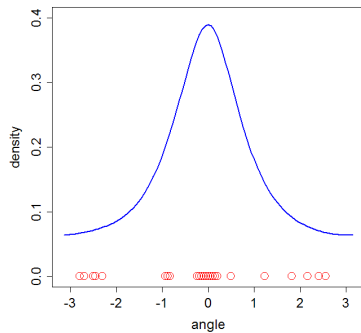
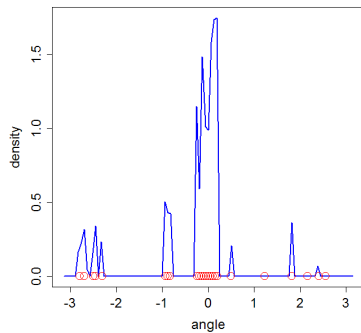
Compare to Normal density

$$f(t) = \frac{1}{\sqrt{2\pi}\sigma} e^{-(t-\mu)^2/\sigma^2}$$

then  $W(t) = t^2$  should be smooth  $\Rightarrow LW(t) = D^3W(t)$ .

Alternatively,  $LW(t) = D^2W(t) \Rightarrow$  exponential distribution is smooth – useful for positive data.

# Rough to Smooth Densities



# Summary

Can put constraints to force

- ▶  $x(t) > 0$  by  $x(t) = e^{W(t)}$
- ▶  $x(t)$  monotone by  $x(t) = \alpha + \int_{t_0}^t e^{W(s)} ds$
- ▶  $x(t)$  a density by  $x(t) = e^{W(t)} / \int e^{W(t)} dt$

Extension: penalized maximum likelihood for  $x(t)$  not directly observed.

Requires nonlinear optimization, but still relatively fast.