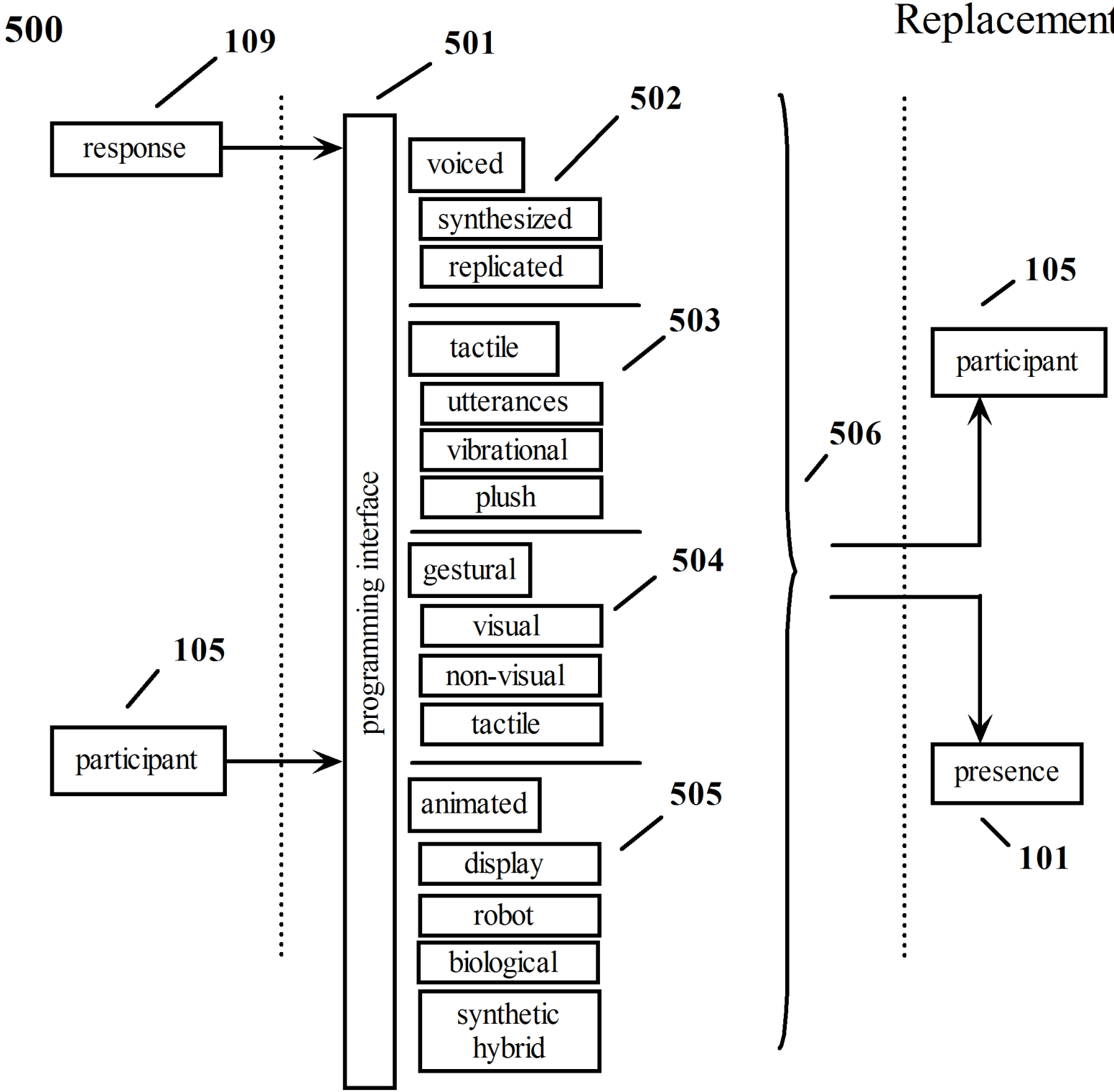
500
109
501
response
voiced
502
synthesized
replicated
105
participant
tactile
503
utterances
vibrational
plush
506
programming interface
gestural
504
visual
non-visual
tactile
105
participant
presence
animated
505
display
robot
biological
synthetic
hybrid
101

Figure 5