



Practical Morphological Anti-Aliasing on the GPU

SIGGRAPH 2010 Talk

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Geometrical antialiasing

- Without antialiasing
- Supersampling
- Multisampling [Akeley 93] and Coverage sampling [Nvidia]

Limitations

- Not trivial with deferred shading
- Memory consumption. Geometrical dependency



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Motivation

Post processing antialiasing

MorphoLogical AntiAliasing (MLAA) [Reshetov, HPG 09]

Similar technique used in God of War III and Saboteur (PS3)

Limitations

- Full CPU implementation, low rendering time on 1024x768 image
- Costly data transfer between GPU & CPU

Objectives

- Adapt MLAA to GPU
- Keep it as a post process technique

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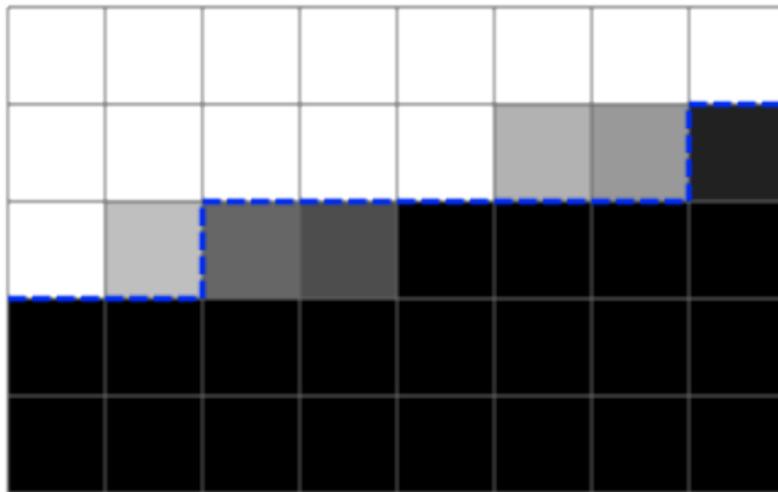
Antialiasing as a post process

From that ...



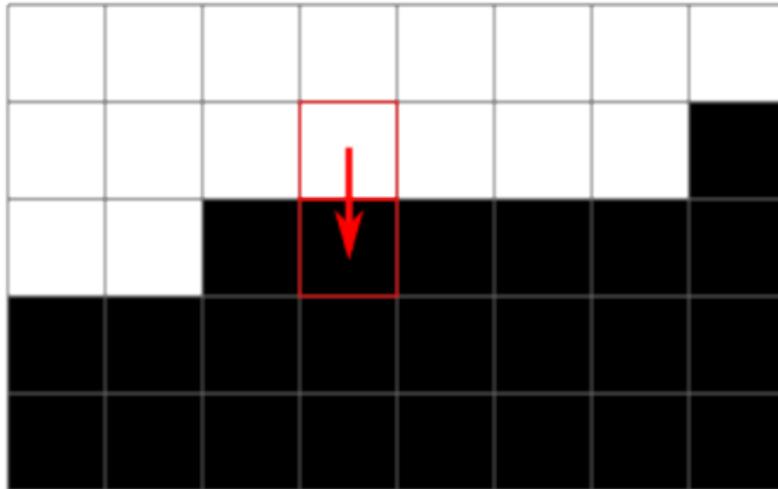
Antialiasing as a post process

... we want that



Antialiasing as a post process

Border pixels must blend with their neighbor ...



Antialiasing as a post process

... along 'L' shapes



Antialiasing as a post process

... along 'L' shapes



Blending weighted
by the yellow
trapeze area

$$C_{\text{new}} = C_{\text{old}} * (1 - \alpha) + \alpha C_{\text{opposite}}$$

Antialiasing as a post process

MLAA algorithm on the CPU

① Detect antialiased lines :

- Detect 'L', 'U' and 'Z' shapes
- 'U' or 'Z' are split into two 'L'

② Blend color along the 'L' shapes

- Blend pixels inside the 'L' shape with their opposite neighbor
- Weighted by the trapeze area

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GPU Implementation

Implementation on GPU issues

- Non linear image processing involves deep branching
- Algorithm requires sparse memory access
- GPU is limited to pixel-wise operation

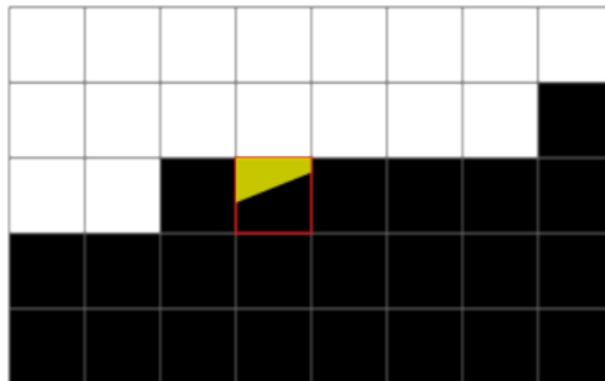
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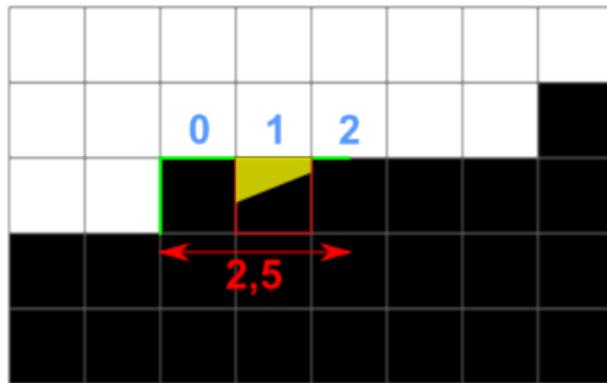
How can we
detect
the L shapes?

GPU Implementation



To blend the red pixel, we need to compute the yellow area

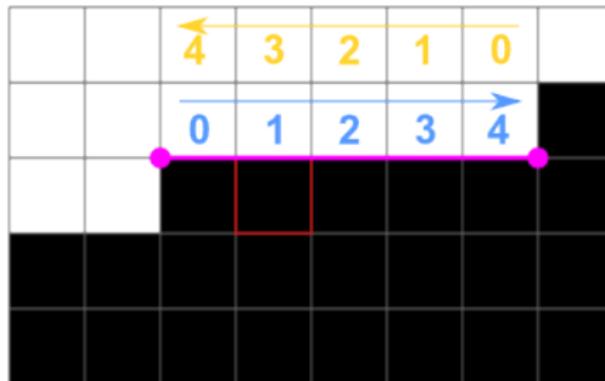
GPU Implementation



This can be obtained using the pixel's relative position p related to the L shape and its length $L/2$

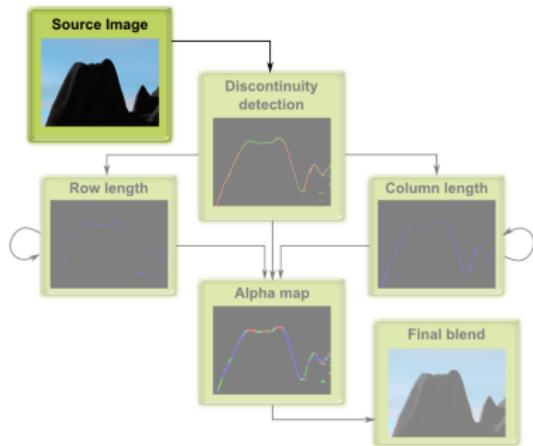
$$\alpha = \left(1 + \frac{\frac{L}{2} - p - 1}{\frac{L}{2}} \right) / 4.0$$

GPU Implementation



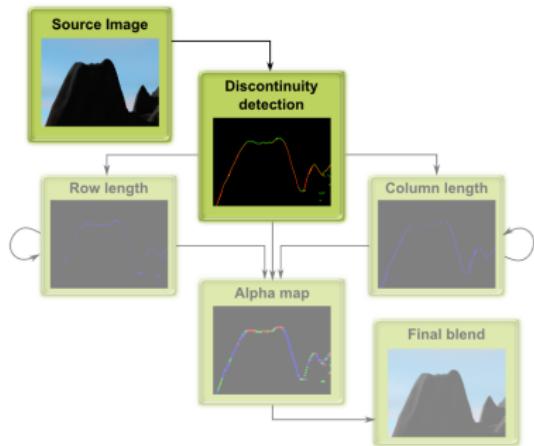
The red pixel position is the minimum of the distance to the two discontinuity line extremities

Algorithm overview



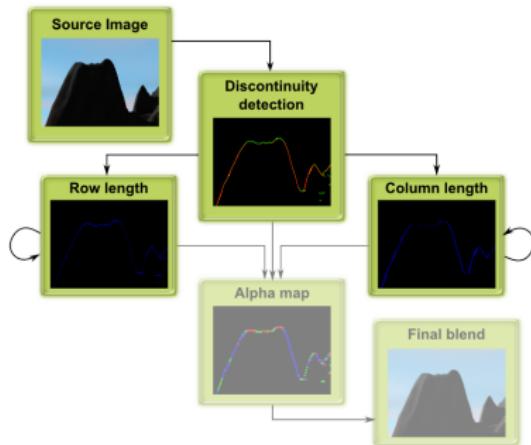
- ① Detect discontinuity lines
- ② Compute the positions
 - On rows and columns
 - Related to the two extremities
 - Using the “recursive doubling” algorithm
- ③ Compute the trapeze area for each pixel
- ④ Final blending

Algorithm overview



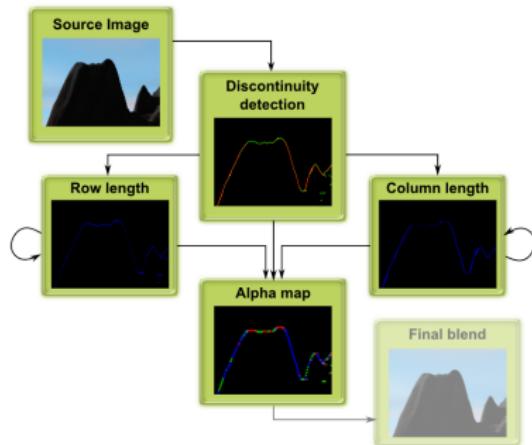
- ➊ Detect discontinuity lines
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Algorithm overview



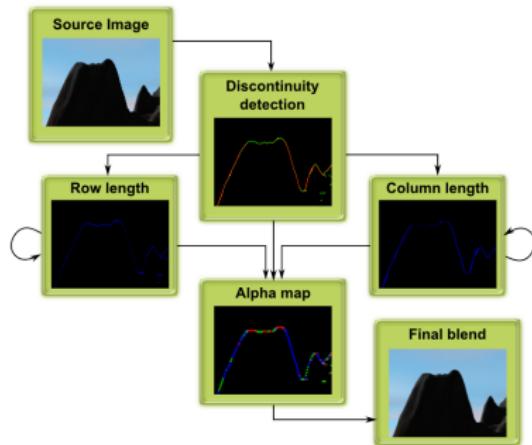
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Computation of discontinuity lines

1 - Detect discontinuities of color

- Using a simple distance on $L^* a^* b^*$ color space
- Result stored in a texture



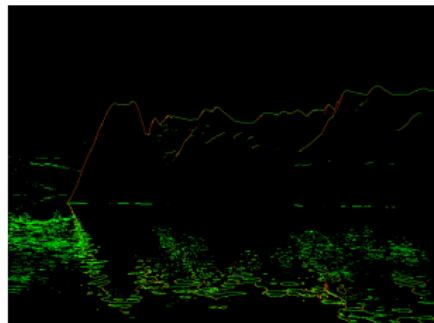
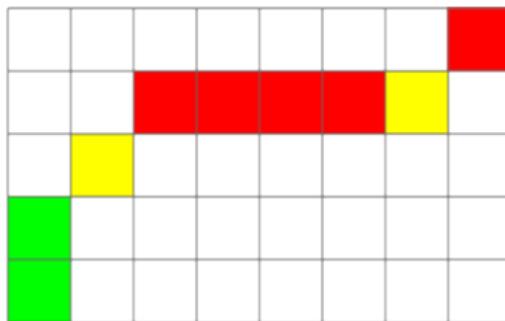
channel R : discontinuity in pixel bottom

channel G : discontinuity in pixel right

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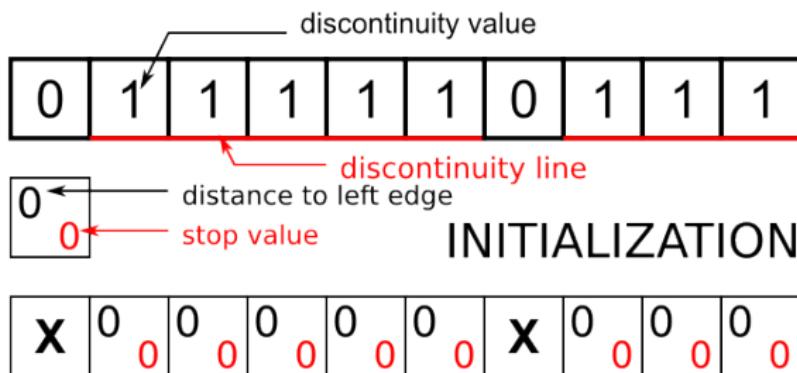
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Line length computation

2 - Computation of line length and relative position

On rows and columns and in both directions, using a ‘recursive doubling’ technique.

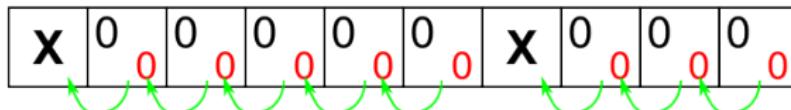


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0	1	1	1	1	1	0	1	1	1
---	---	---	---	---	---	---	---	---	---

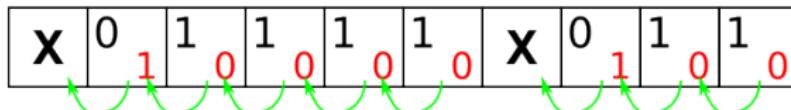
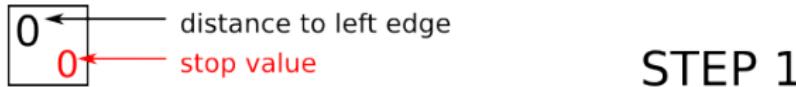


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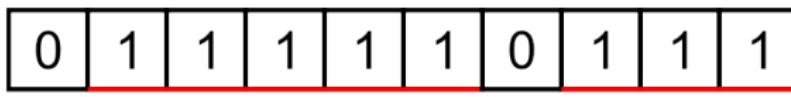
0	1	1	1	1	1	0	1	1	1
---	---	---	---	---	---	---	---	---	---



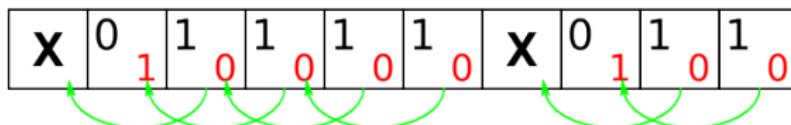
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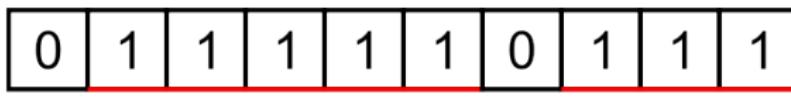
STEP 2



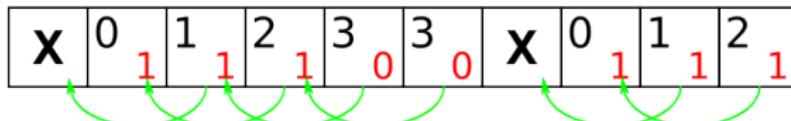
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STEP 2



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0	1	1	1	1	1	0	1	1	1
---	---	---	---	---	---	---	---	---	---



STEP 3

X	0	1	2	3	0	3	0	X	0	1	2	1
---	---	---	---	---	---	---	---	---	---	---	---	---



Line length computation

2 - Computation of line length and relative position

On rows and columns and in both directions, using a ‘recursive doubling’ technique.

0	1	1	1	1	1	0	1	1	1
---	---	---	---	---	---	---	---	---	---

0
0

distance to left edge

stop value

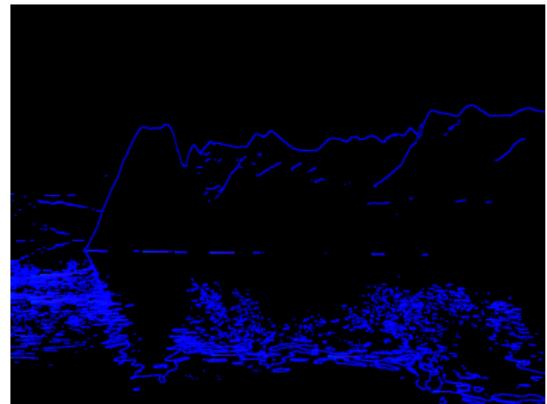
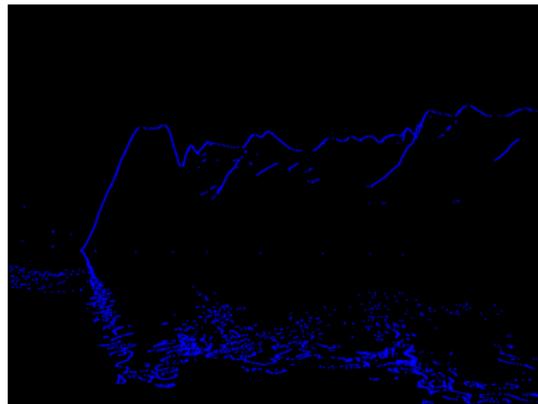
STEP 3

X	0	1	2	3	4	X	0	1	2
	1	1	1	1	1		1	1	1

Line length computation

2 - Computation of line length and relative position

Number of iteration for row = $\log_2(\text{width})$. Number of iteration for columns = $\log_2(\text{height})$ Results are stored in textures (one for the rows, one for the columns)

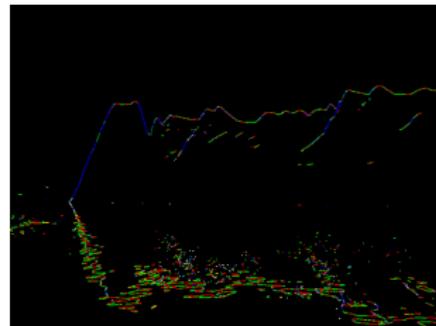
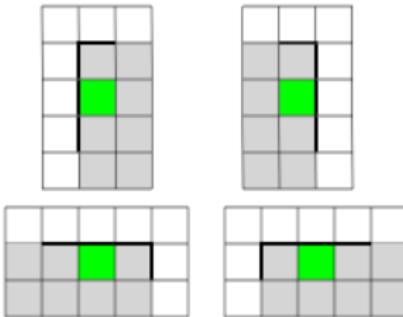


Blending map

3 - Computing the blending factors

- Select L shape type of each pixel (if any)
- For each remaining pixel, compute the trapeze area
- Results stored in an blending map, in each direction

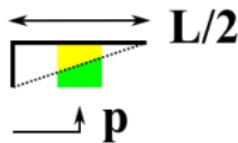
8 cases



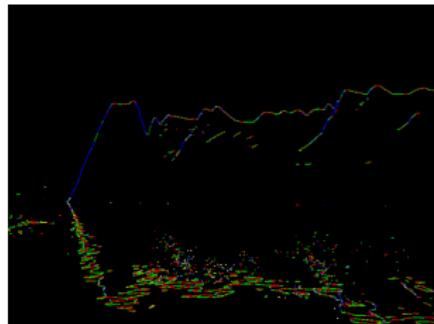
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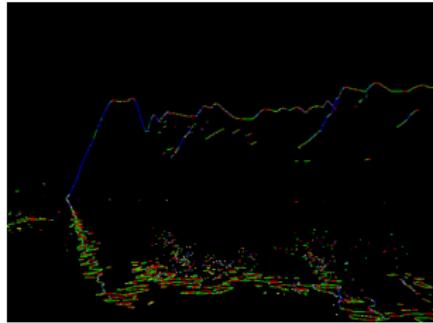
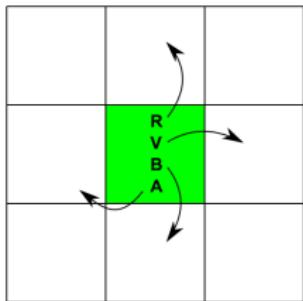
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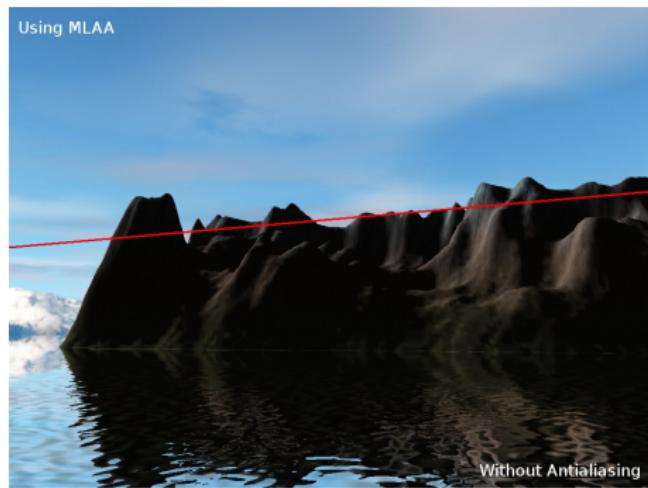
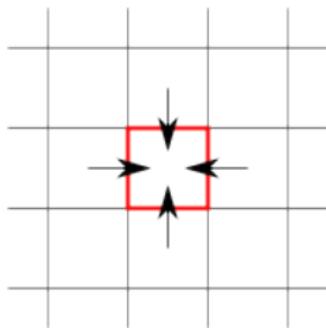
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Final rendering

4 - Final blending

- We blend each pixel with its 4 neighbors
- Using previously computed blending map



Computation times

Image size	1248x1024	1600x1200
MLAA CPU	67ms	128ms
MLAA GPU	3.49ms	5.54ms

TAB.: Algorithm cost (in ms) using a GeForce 295 GTX and a Core2Duo 2.20GHz

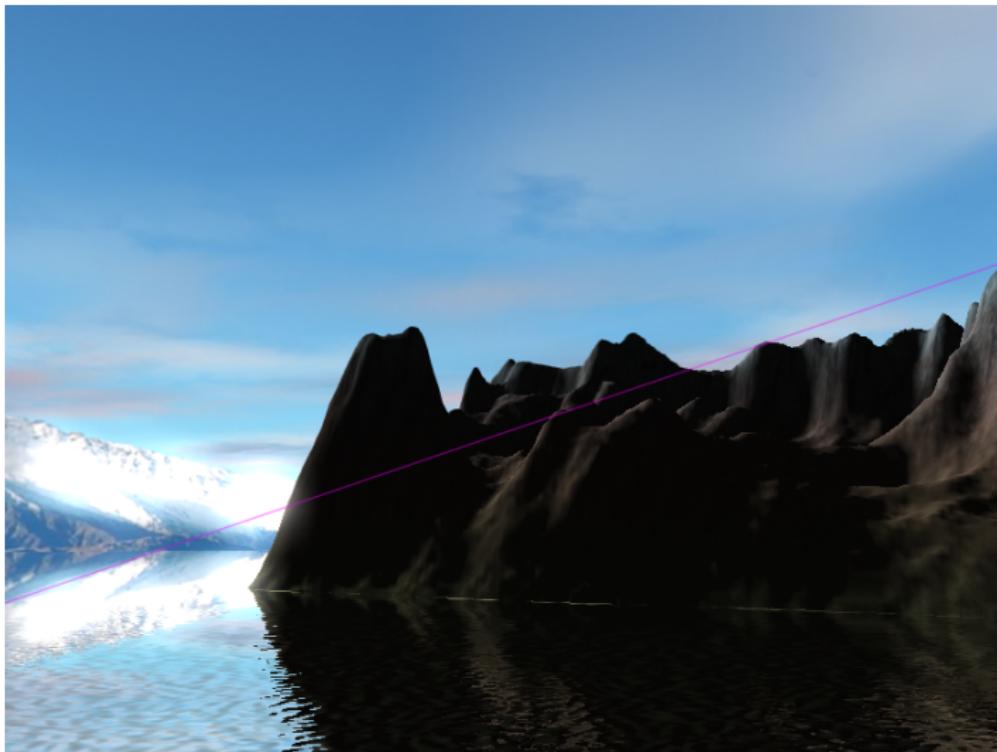
Step	1	2	3	4
Percent	16	64	13	7

TAB.: Detail of each step cost in the algorithm

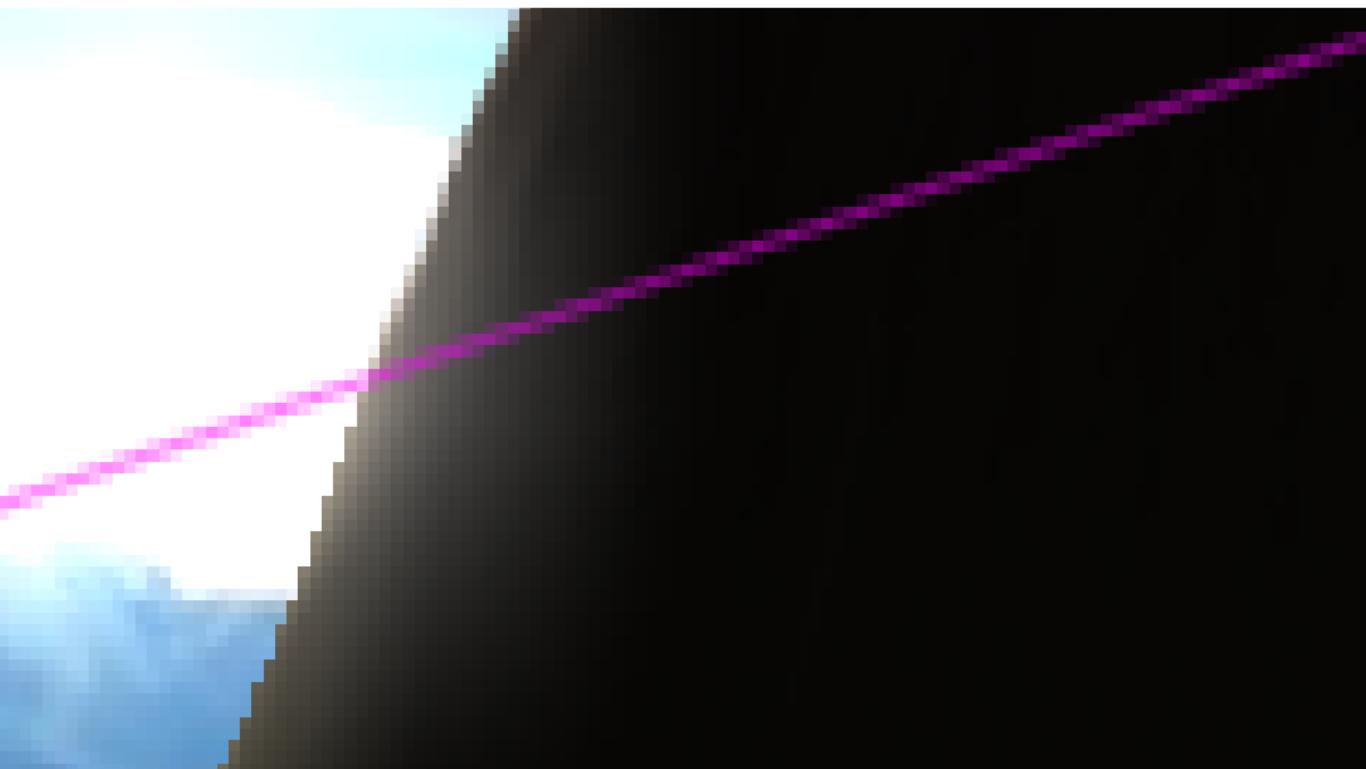
Used with ...

... many effects like motion blur, bloom, cartoon shading, shadow mapping or parallax mapping.

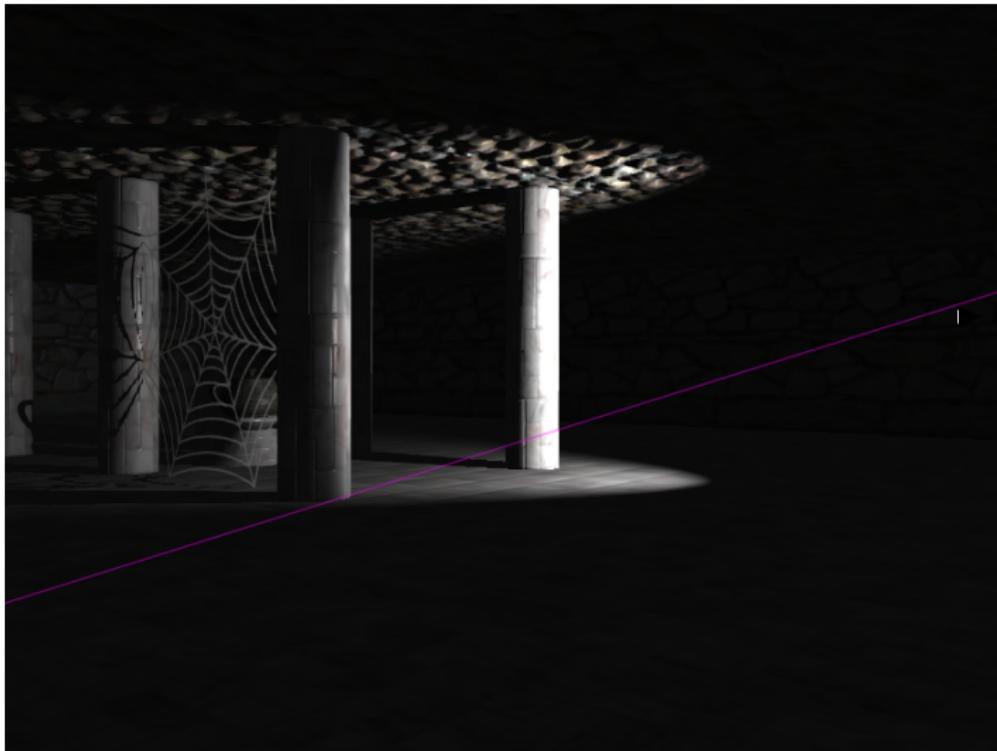
Result on bloom



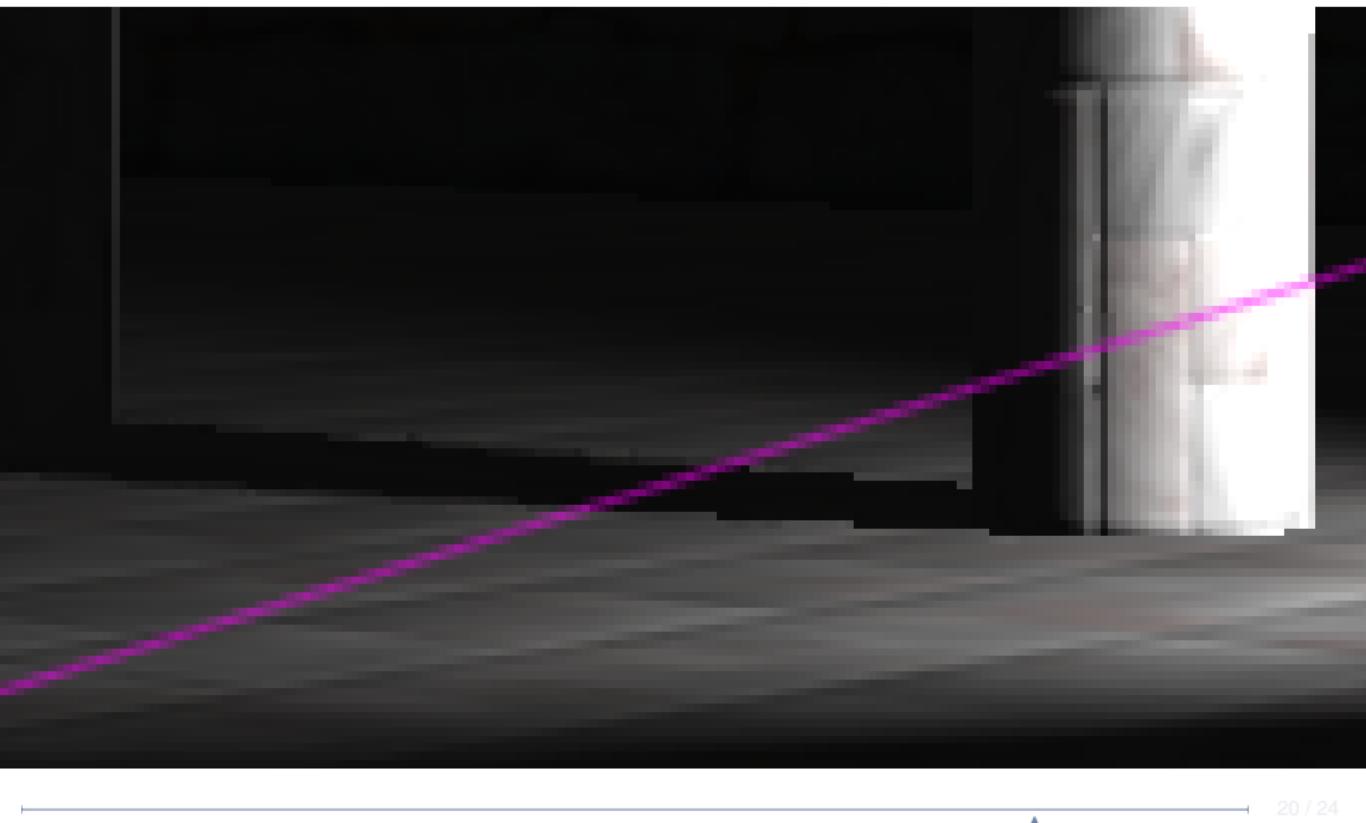
Result on bloom



Result on shadow mapping



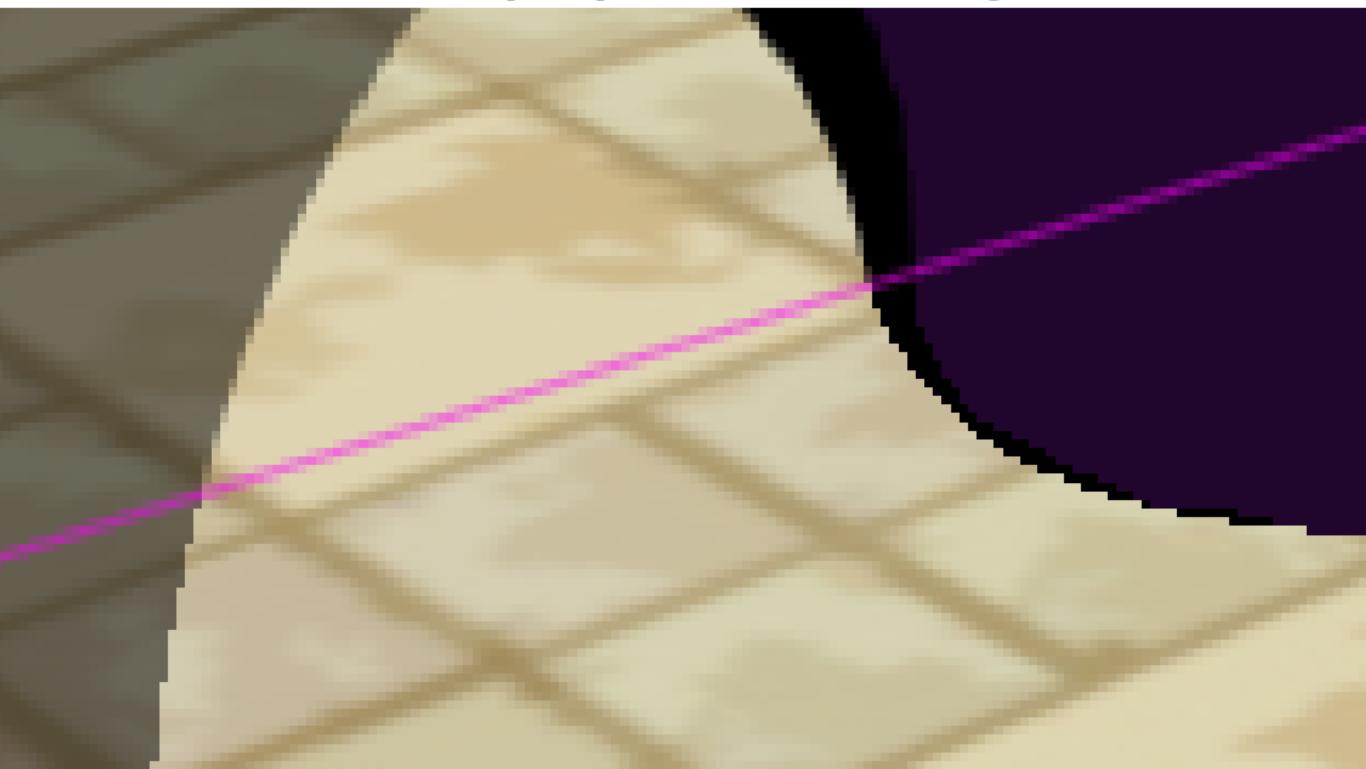
Result on shadow mapping



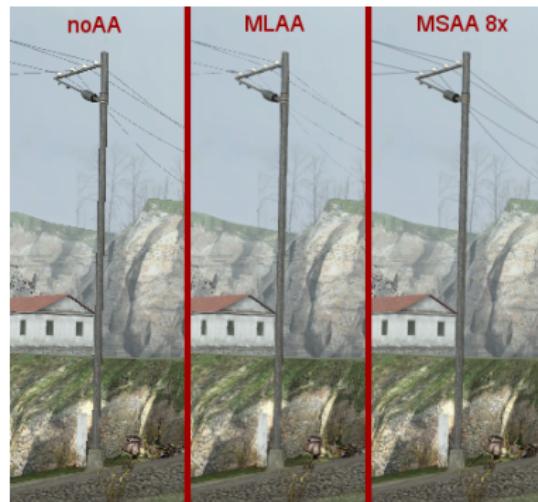
Result on per pixel toonshading



Result on per pixel toonshading



Comparison



Comparison



Conclusion

Overview

- Antialiasing as a post process
- Implemented fully on the GPU, rendering engine friendly
- A new line length computation algorithm
- around 4ms overhead with a high performance graphic card

Discussion & Future works

- No subpixel antialiasing available
- Packing and profiling
- Other topological configuration than the L ?

Conclusion

Thanks

Duran Duboi R&D Team, Baptiste Malaga, Franck Letellier, Vincent
Nozick, Nadine Domangé

Code available

in <http://igm.univ-mlv.fr/~biri/mlaa-gpu/>

Questions ?

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sdeverly@quintaindustries.com