

# Deep Learning In Practice

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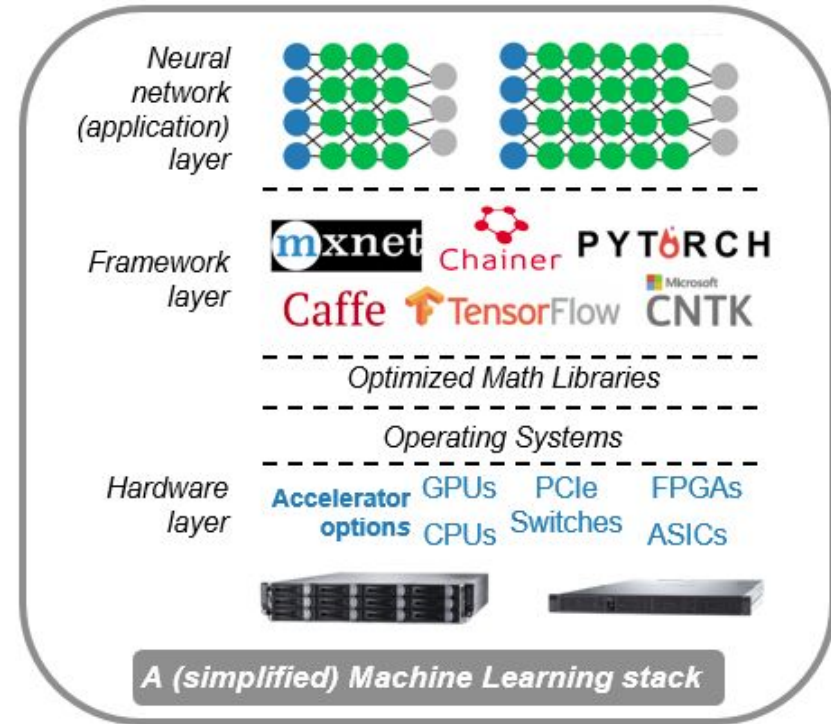


# Deep Learning Stack



Deep learning programs can involve:

- matrix multiplications,
- computing derivatives
- loading data from network/hard disk
- plotting and visualization of loss functions

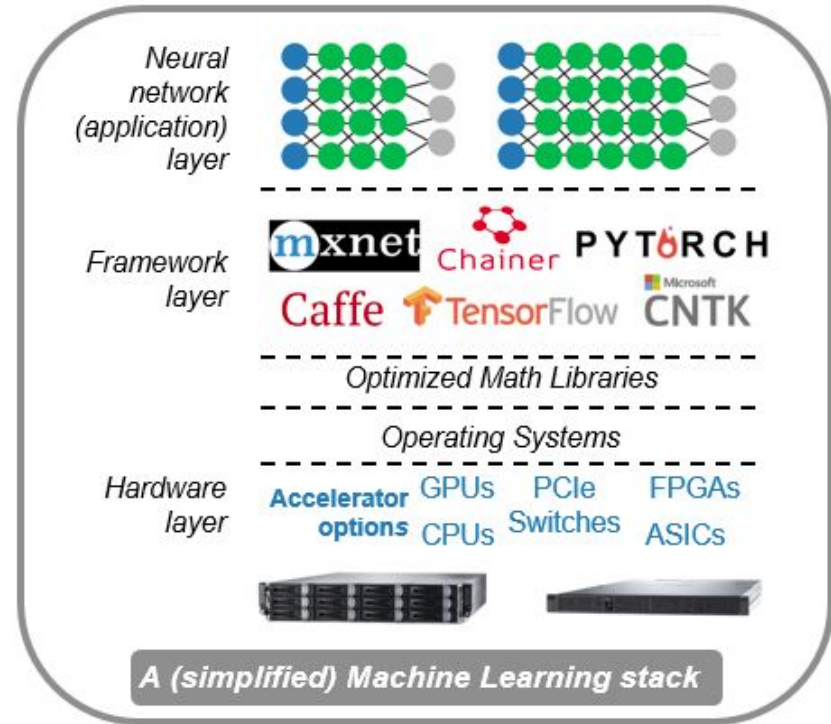




# Deep Learning Stack



- For fast execution, programs need to be parallelized and efficient assembly code needs to be generated.
- Needs to run in various platforms like cpu, gpu, mobiles, clusters.
- There is a stack of libraries that takes care of these, so that we can focus on designing neural networks.





# Deep Learning Libraries



|            | Language | Created By         |      |
|------------|----------|--------------------|------|
| Torch      | Lua      | NYU & IDIAP        | 2002 |
| Theano     | Python   | Toronto & Montreal | 2009 |
| Caffe      | C++      | UC Berkeley        | 2012 |
| Tensorflow | Python   | Google             | 2015 |
| Pytorch    | Python   | Facebook           | 2017 |

- Not comprehensive. Almost every company have their own implementation.
- Deployment happens in C/CPP, Python only used during training.



# Tensors



Basic objects of a Deep Learning Library

All data, intermediate outputs, learnable parameters are represented by a **tensor**.

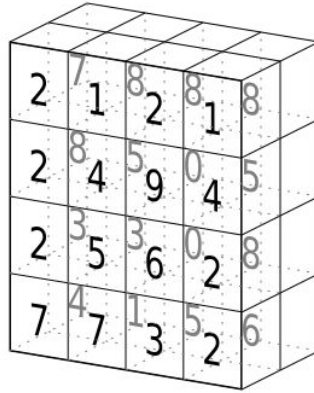
Tensors have a **size**.

|     |
|-----|
| 't' |
| 'e' |
| 'n' |
| 's' |
| 'o' |
| 'r' |

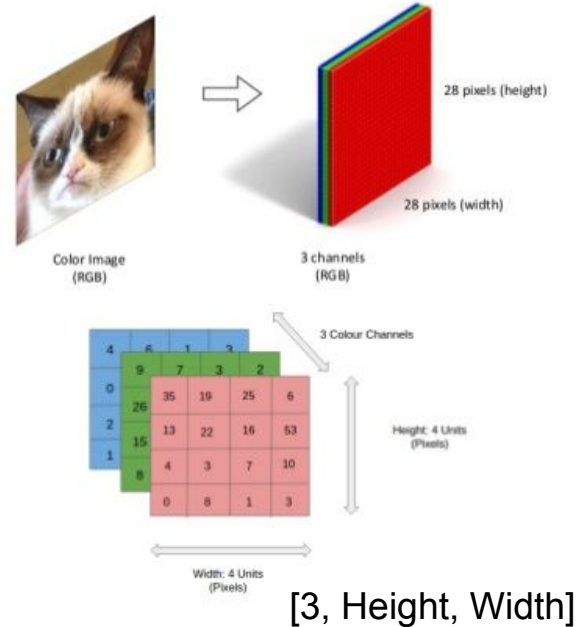
Size [6]

|   |   |   |   |
|---|---|---|---|
| 3 | 1 | 4 | 1 |
| 5 | 9 | 2 | 6 |
| 5 | 3 | 5 | 8 |
| 9 | 7 | 9 | 3 |
| 2 | 3 | 8 | 4 |
| 6 | 2 | 6 | 4 |

[6, 4]



[2, 4, 4]





# Structure of a Deep Learning Program

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1. Loading Data
2. Defining the Model
3. Defining Training Procedure
4. Looping over Data
5. Computing testing accuracy



# Step 1: Loading Data

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Machine learning datasets can be very large (few GBs to TBs).

Only a small batch (**minibatch**) is loaded at a time for processing.



# Example : MNIST Classification



Input :  $x$  is a  $[28,28]$  shaped matrix, giving pixel values of the image

Output :  $y$  is a  $[10]$  shaped vector, giving the probabilities of being 0 to 9.

Dataset : Consist of  $(x,y)$  pairs,  $x$  is the input and  $y$  is called the label.

Divided into train, test and validation.

If the dataset gives  $y$  as a digit, convert it to probability vector by **one hot encoding**.



Note:  $y$  can sometimes be a number between 0-9 or a vector of dimension 10.





# Code for MNIST



```
mnist_train = datasets.MNIST(
    root='./mnist/',
    train=True,
    transform=transforms.ToTensor(),
    download=True
)

train_loader = DataLoader(dataset=mnist_train,
                           batch_size=100,
                           shuffle=True)

for mini_batch in train_loader:
    images, labels = mini_batch
    for j in range(batch_size):
        print images[j].size(), labels[j]
```

Prints:     torch.Size([1, 28, 28]) 3

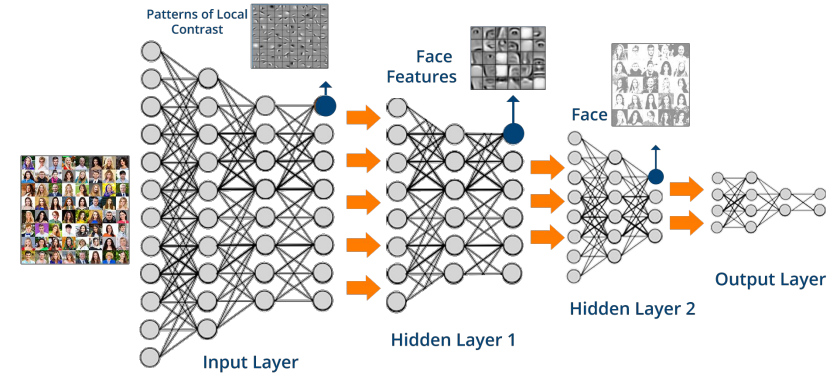
1. Download and extract MNIST in to local machine.
2. Shuffle the dataset such that the labels are very well mixed and create a loader that loads 100 images at a time.
3. Two loops
  - a. Outer loops loads 100 images each
  - b. Inner loop iterates over the 100 images and their labels.



# Step 2: Define the Model



- We need to specify the architecture of the deep learning model.
- Typically consists of a sequence of layers.
- Layers could be Linear(Fully Connected), ReLU Activation, CNN, RNN etc.
- Each layer can have [hyperparameters](#).
- Depth of the model = number of layers (can be 30-100). Results in better models.



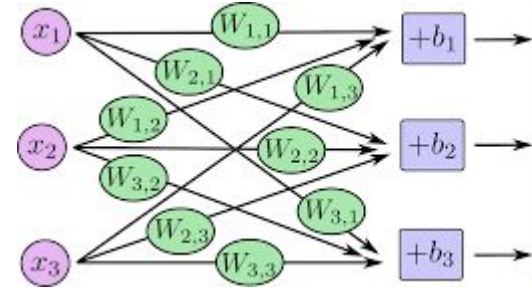


# Model Architecture : Linear Model



```
class Net(nn.Module):  
    def __init__(self):  
        super(Net, self).__init__()  
        self.fc = nn.Linear(28*28, 10)  
  
    def forward(self, x):  
        x = x.view(-1, 28*28)  
        x = self.fc(x)  
        return x
```

```
network = Net()  
logits = network(image)  
predictions = softmax(logits)
```



Convert input from a tensor with size [28, 28] to [784]

Obtain prediction probabilities for 10 classes, by applying softmax function.



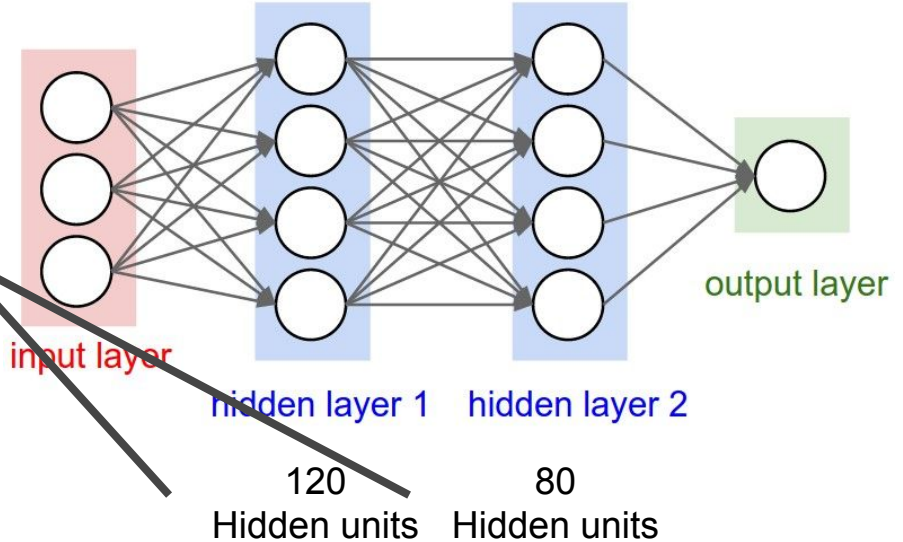
# Model Architecture : MLP Model



```
class Net(nn.Module):  
    def __init__(self):  
        super(Net, self).__init__()  
        self.fc1 = nn.Linear(28*28, 120)  
        self.fc2 = nn.Linear(120, 80)  
        self.fc3 = nn.Linear(80, 10)
```

```
    def forward(self, x):  
        x = x.view(-1, 28*28)  
        x = F.relu(self.fc1(x))  
        x = self.relu(self.fc2(x))  
        x = self.fc3(x)  
        return x
```

Activation in between linear layers





# Model Architecture : CNN Model



```
class LeNet(nn.Module):
```

```
    def __init__(self):
```

```
        super(LeNet, self).__init__()
```

```
        self.conv1 = nn.Conv2d(1, 6, 5)
```

```
        self.conv2 = nn.Conv2d(6, 16, 5)
```

```
        self.fc1 = nn.Linear(16*5*5, 120)
```

```
        self.fc2 = nn.Linear(120, 84)
```

```
        self.fc3 = nn.Linear(84, 10)
```

```
    def forward(self, x):
```

```
        out = F.relu(self.conv1(x))
```

```
        out = F.max_pool2d(out, 2)
```

```
        out = F.relu(self.conv2(out))
```

```
        out = F.max_pool2d(out, 2)
```

```
        out = out.view(out.size(0), -1)
```

```
        out = F.relu(self.fc1(out))
```

```
        out = F.relu(self.fc2(out))
```

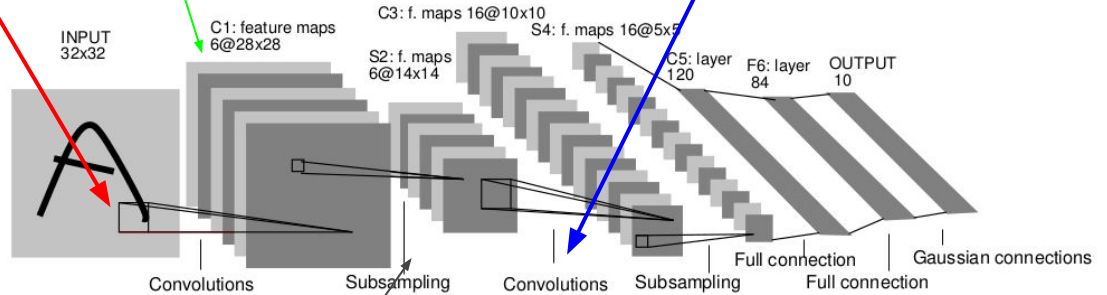
```
        out = self.fc3(out)
```

```
    return out
```

6 channels

5x5 windows

Conv2: 6 → 16 channels, 5x5 window size



Maxpool reduces dimension. Has no parameters



# Step 3: Specify Loss & Gradient Update Algo



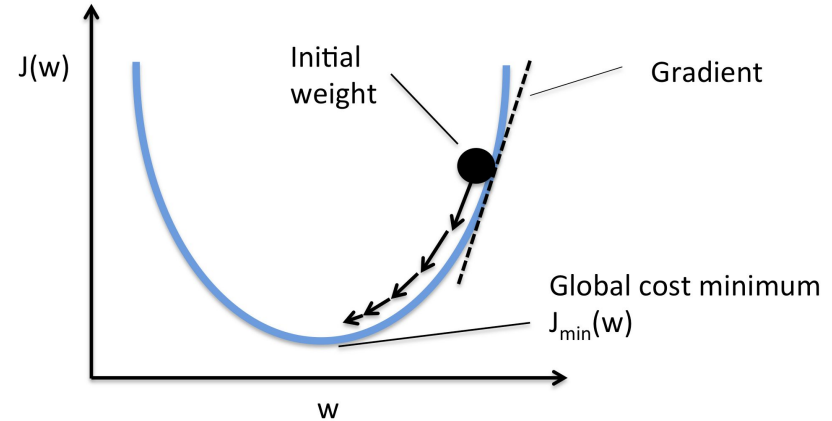
The difference between predictions and correct value.  
Different loss function for different tasks.

```
loss = nn.CrossEntropyLoss()
```

Updating the weight using the gradients can be done using learning rate.

There are multiple gradient update algorithms.

```
optimizer = optim.SGD(net.parameters(), lr=0.001,  
momentum=0.9)
```

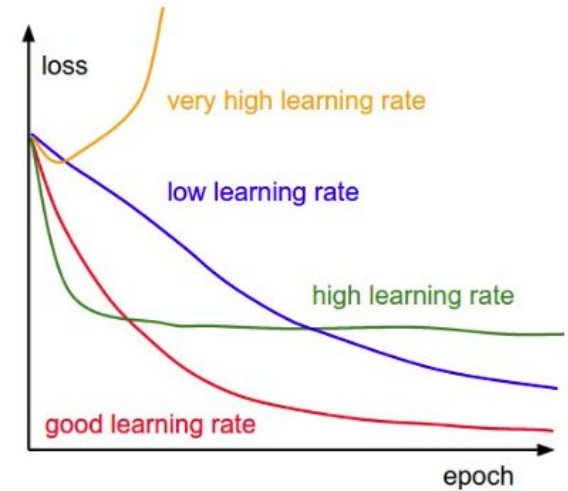




# Step 4: Training Loop



- Repeat
  - a. Take a small random subset of the dataset that will fit in memory (minibatch)
  - b. Forward Pass: pass the subset through the model and obtain predictions
  - c. Compute the mean loss function for the subset
  - d. Backward Pass: compute the gradients of the parameters, last layer to the first, update the gradients using **learning rate**
  - e. Plot loss





# Step 5: Computing accuracy on Testing data

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Similar to Step 4, in looping over the test data.

However we do not do the backward pass.

We just compute the accuracy of the model.



# Demo

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# GPUs and Deep Learning

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In deep learning programs, the same operation needs to be done for different data.

For example:

Every image in a batch has to be processed by the DNN.

Every neuron operation is the same, if we consider the weights also as inputs.

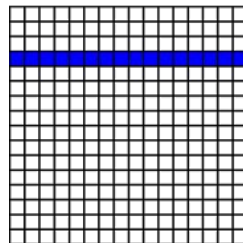


# GPUs and Deep Learning

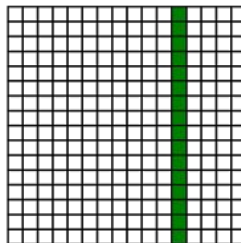
GPUs have 1000s of small processors that run **same instructions** on **different data**.



A



B



C

