



Supervised Learning: Linear Models

P J Narayanan







THE PERSON

Outline

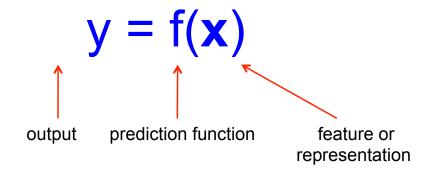
- Model fitting: Prediction of y from x
 - Linear regression: Model is linear
 - Gradient descent method to find best fitting line
- Logistic regression: when y is binary
 - Function model is different
 - Gradient descent works
 - Used for classification. Gives probabilities
- Linear classifiers: Find line to separate classes
 - Linear separability







The machine learning framework



- **Training:** given a *training set* of labeled examples $\{(\mathbf{x}_1, \mathbf{y}_1), ..., (\mathbf{x}_N, \mathbf{y}_N)\}$, estimate the prediction function f by minimizing the prediction error.
- **Testing**: apply f to a never before seen test example x and output the predicted value y = f(x)

Slide credit: L. Lazebnik



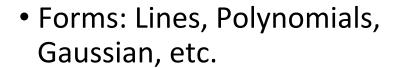


THE PERSON

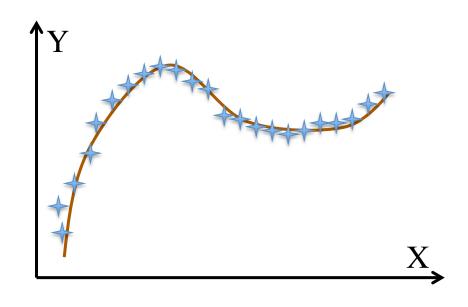
Fitting Functions to Data

Why?

- Discover (hidden) structure in the data, given samples
- A functional form is a compact representation usable for interpolation and extrapolation



Called *regression* in general



$$y = f(x)$$

Scalar or vector valued x, yMultivariate when x is a vector x







Linear Model

• Linear when f is a line. In general, a hyperplane

$$-y = a x + b$$

• *a*, *b*: parameters of the model

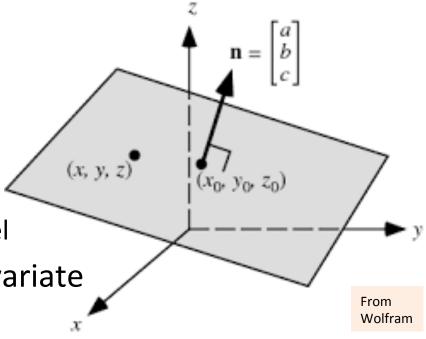


•
$$x = [1 \ x_1 \ x_2 \ ... \ x_d]^T$$

- Vector w represents the parameters of the model
- Line: Only 2 parameters in 2D.

d parameters in a d-dimensional space

$$y = f_{\mathbf{w}}(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$$







Notations

$$\mathbf{x} = \begin{bmatrix} 1 \\ x_1 \\ x_2 \\ \vdots \\ x_d \end{bmatrix}$$
 $\mathbf{w} = \begin{bmatrix} w_0 \\ w_1 \\ w_2 \\ \vdots \\ w_d \end{bmatrix}$

$$\mathbf{w} \cdot \mathbf{x} = \mathbf{w}^T \mathbf{x} = w_0.1 + w_1 x_1 + w_2 x_1 + \dots + w_d x_d$$





THE STATE OF

The Problem

- Find w given examples (x_i, y_i) , i = 1, 2, ..., m
- Supervised situation: output label is available for a number $\,m\,$ of training input samples
- Objective: predict y values for input values x that are not seen before
 - Called generalization in Machine Learning
- How do we find w? Gradient descent!

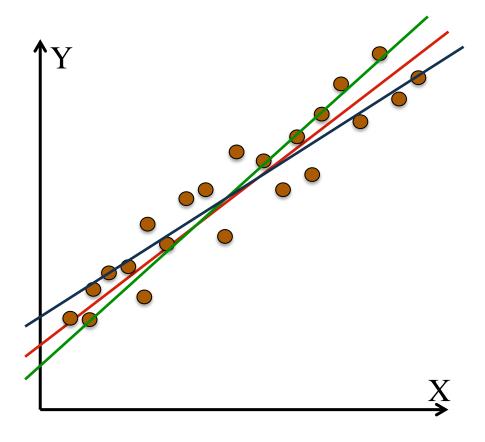




THE PARTY

Typical Scenario

- Data points of x against y appear distributed
- Ideal: All points on the line if model is truly linear
 - Measurement errors and "noise" create deviations
- Several ways to find the best line
 - Analytical, Least Squared Error,
 Gradient Descent



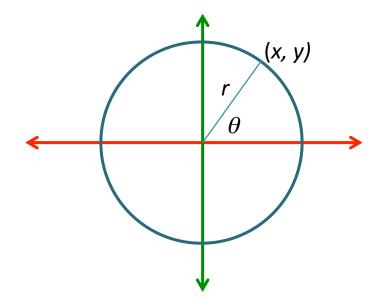






Larger Issues

- What's great about linear?
 - Simple
- But the world is not linear
- But many can be converted to!
 - Circular to linear
 - ExOR to linear
 - Pendulum: T^2 to L is linear



$$x = r\cos\theta, y = r\sin\theta$$

Circle is r = k in the r- θ space

 $a r + b \theta + c = 0$ is a weird shape!







Questions?





TIME STATE

Iterative Procedure

- Start with a guess for model parameters w
 - Adjust till it fits well
- Prediction for a given x: $f_w(x) = w^T x$
- Consider the j^{th} training sample (x^j, y^j)
- Predicted value:
 Observed value: y^j
- Typically **not** equal! The difference guides change in w

$$y = f_{\mathbf{w}}(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$$

$$f_{\mathbf{w}}(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$$

$$f_{\mathbf{w}}(\mathbf{x}^j) = \mathbf{w}^T \mathbf{x}^j$$

$$y^j \neq f_{\mathbf{w}}(\mathbf{x}^j)$$





THE PARTY NAMED IN

Loss Function

- **Error** or **loss**: *D()*. How far is the prediction from the observed value?
 - Different loss functions used
- Strategy: Bring the predicted value closer to the observed value by adjusting w
- How do we adjust w?
 Gradient descent

$$D(f_{\mathbf{w}}(\mathbf{x}^j), y^j)$$

$$\sum_{j} D(f_{\mathbf{w}}(\mathbf{x}^{j}), y^{j})$$



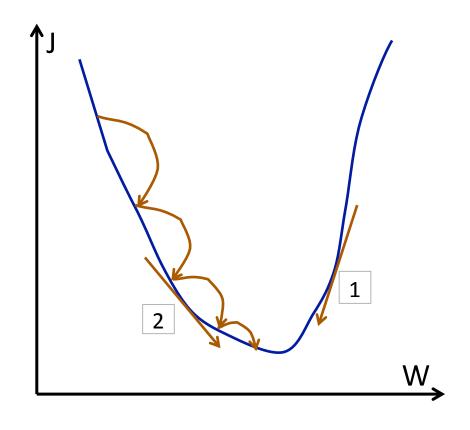


THE PARTY

Gradient Descent

- Minimum of the function lies in the opposite direction of the gradient
 - 1. Positive gradient: function will increase if we go forward
 - 2. Negative gradient: minimum lies ahead
- Take a step against gradient:

$$\mathbf{w}' = \mathbf{w} - \eta \ \nabla J(\mathbf{w})$$







Thurst start

Fine Points

When do we stop the iterations?

- When the gradient value is too low ($< \varepsilon$)
 - Future changes will be low!
- When the change in objective function is too small
 - We are close already

How about the step size?

Ensure smooth convergence

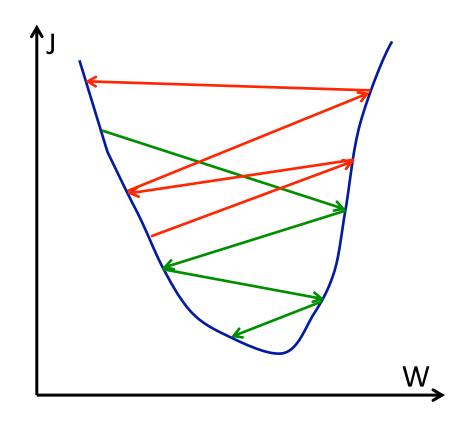




TIMES OF THE

Gradient Descent

- Converges to the minimum when function is convex
 - Converges to a local minimum otherwise
- Learning rate is critical
 - Start high to make rapid strides
 - Reduce with time for smoother convergence









Questions?





Troping plans

Minimize Loss Function

- A loss function: L2 or Euclidean distance
- J(w) is the function to be minimized with respect to w
- Cost due to a sample & Cost for all of them

$$J(\mathbf{w}) = \frac{1}{2} ||(f_{\mathbf{w}}(\mathbf{x}^j) - y^j)||_2$$
$$= \frac{1}{2} (f_{\mathbf{w}}(\mathbf{x}^j) - y^j)^2$$

$$= \frac{1}{2} \sum_{j=1}^{m} (f_{\mathbf{w}}(\mathbf{x}^{j}) - y^{j})^{2}$$





THITTIN STORY

LMS Update Rule

 Gradient descent follows this equation

$$\mathbf{w}' = \mathbf{w} - \eta \nabla J(\mathbf{w})$$

 What is the gradient of J(w)?

$$\frac{1}{2}\nabla_w(f_{\mathbf{w}}(\mathbf{x}^j) - y^j)^2 = (f_{\mathbf{w}}(\mathbf{x}^j) - y^j)\mathbf{x}^j$$

 This is a vector of d dimensions, like x, w





THITTH STORY

Batch and Stochastic GD

- Batch GD: Go through all input samples and update at end
 - Uses "true" gradient
 - Expensive computationally
- Stochastic GD: Update weights after each sample
 - More "noisy", but faster
 - Noise may actually help!
- Mini-batch: Update after a small number of samples

$$\mathbf{w}' = \mathbf{w} - \eta \sum_{j} (f_{\mathbf{w}}(\mathbf{x}^{j}) - y^{j}) \mathbf{x}^{j}$$

$$\mathbf{w}' = \mathbf{w} - \eta (f_{\mathbf{w}}(\mathbf{x}^j) - y^j) \mathbf{x}^j$$





THE PERSON

Summary

- Linear regression fits a line or a hyperplane to a set of points
 - Models the behaviour of the (continuous) dependent variable against the independent one
- Several methods exist to perform line fitting
 - Iterative methods work well in several situations
 - Machine learning uses lots of data. Incremental methods are more suitable

Gradient Descent is a versatile method!







Questions?

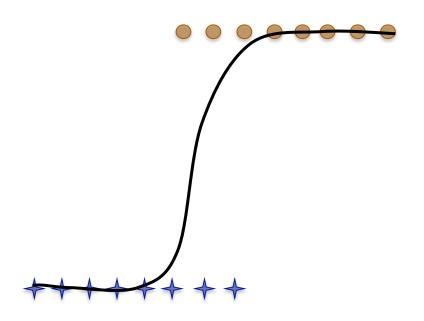






Categorical/Binary Functions

- When y value is a category label (with no clear relative ordering)
- Easy case: y is binary.
 Yes/No. True/False. 1/0.
- Can be interpreted as the probability of an outcome being true, given an event





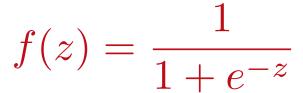


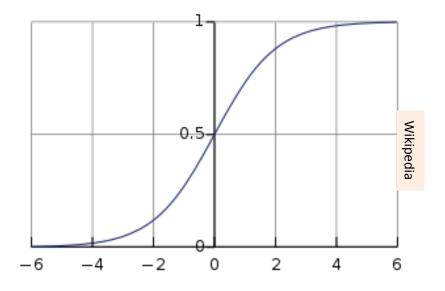
Time of the

Logistic Function

- The logistic function comes handy
- Goes from 0 to 1 as z goes from $-\infty$ to $+\infty$
- Can be interpreted as a probability

$$P(success) = f(effort)$$





Use kz to make it steeper. $(z-z_0)$ to shift transition point







Logistic Function

- The logistic function
 - Probability of an outcome

$$f(z) = \frac{1}{1 + e^{-z}}$$

Has an interesting derivative form

$$f'(z) = f(z)(1 - f(z))$$

• Connect with linear:

$$z = \mathbf{w}^{\mathrm{T}} \mathbf{x}$$

$$f_{\mathbf{w}}(\mathbf{x}) = \frac{1}{1 + e^{-\mathbf{w}^T \mathbf{x}}}$$

Generalized Linear Model with parameters w





Time Sure

Logistic Regression

 Fit a logistic function to the outcome y with respect to x.

$$\mathbf{w}' = \mathbf{w} - \eta (f_{\mathbf{w}}(\mathbf{x}^j) - y^j) \mathbf{x}^j$$

 Gradient Descent can be used to minimize the loss function

The Maths is involved and uses Maximum Likelihood estimate, etc.

 Results in the exact same update rule as linear regression though f is non-linear

Can use Batch or Stochastic Gradient Descent methods







Binary Classification

- Logistic regression gives probability of outcome
- Convert to a classifier with output True or False
- Classification rule:

if
$$f(\mathbf{w}^{\mathsf{T}}\mathbf{x}) > 0.5$$
 True. Else False

Can be extended to multiple classes also





THE STATE OF

Summary

- Logistic function can map inputs to the probability of a categorical output
 - Can be used as a classifier for Yes/No questions
- Another form of f(x). Another form of loss function
- Gradient Descent works well for this also.
 All one needs is a gradient
- Differentiability of the loss function is important!







Questions?

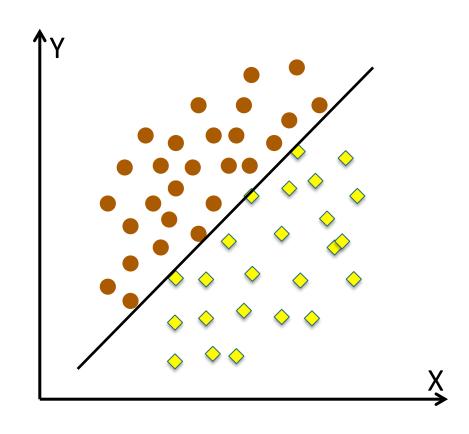




Trop 15 and

Linear Classifier

- Logistic regression fits a function to y (outcome) of the independent variable x
- Classification can be done by partitioning the space among the classes
- Liner classifiers have linear partition or decision boundaries







Tropic prop

Decision Boundary

- Decision boundary: hyperplane
- Class 1 lies on the positive side and Class 0 on the negative side
 - -t=1 for Class 1 and t=-1 for Class 0
 - Negate features of Class 0 by (tx)
- For each training sample \mathbf{x}^{j} , distance to line $\mathbf{w}^{T}(t\mathbf{x}^{j}) \geq 0$
- Loss function J(w)
- Gradient Descent can work!

$$\mathbf{w}^T \mathbf{x} = 0$$

$$J(\mathbf{w}) = \frac{1}{2} \sum_{j} (\mathbf{w}^{T}(t\mathbf{x}^{j}))^{2}$$

$$\nabla J(\mathbf{w}) = \sum_{j} [\mathbf{w}^{T}(t\mathbf{x}^{j})] (t\mathbf{x}^{j})$$



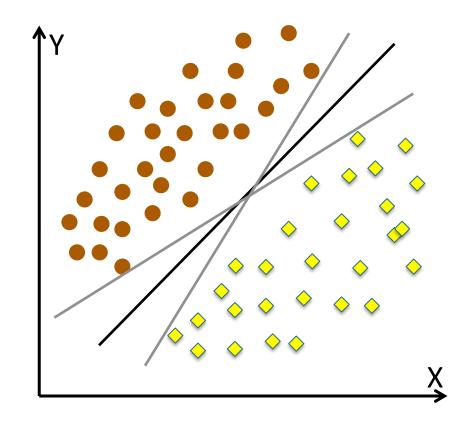


THE PERSON NAMED IN

Boundary with Margin

- Several lines separate the classes when there is a large gap
- Need to find the middle line with maximum distance to points of each class
- Require $\mathbf{w}^T(t\mathbf{x}^j) \ge b$, where b is a margin

Will see this later!





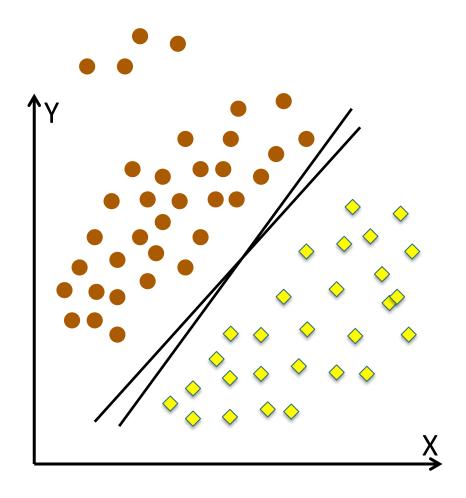


February 10, 2018

THE PERSON

What's truly important?

- Every sample contributes by w^Tx
 - Susceptible to samples that are far from the boundary
 - Called outliers
- Samples close to the boundary alone should matter in finding the boundary!
 - Will see it in SVM



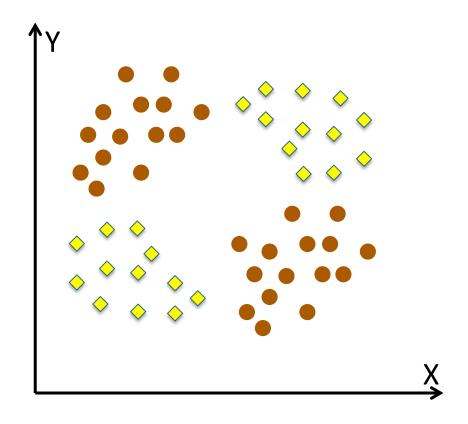






Linear Separability

- No line can separate the classes cleanly
 - This is called the ExOR problem
- Some can be transformed to a linearly separable case
 - Map x to $\phi(x)$
 - Separable in $\phi(x)$







TIMES OF THE

Summary & Questions

- Linear methods are simple and versatile
 - Several situations can be mapped to linear
- Other advanced methods are variations or extensions of simple linear methods
 - Support Vector Machines
 - Neural Networks including Deep ones







Thank You!



