

# Data-Driven Prognostics of Lithium-Ion Rechargeable Batteries Using Bilinear Kernel Regression

*Charlie Hubbard, John Bavlisk, Chinmay Hegde and Chao Hu*  
*Iowa State University*



# Applications

- Electric/hybrid vehicles



- Mobile devices



- Medical devices

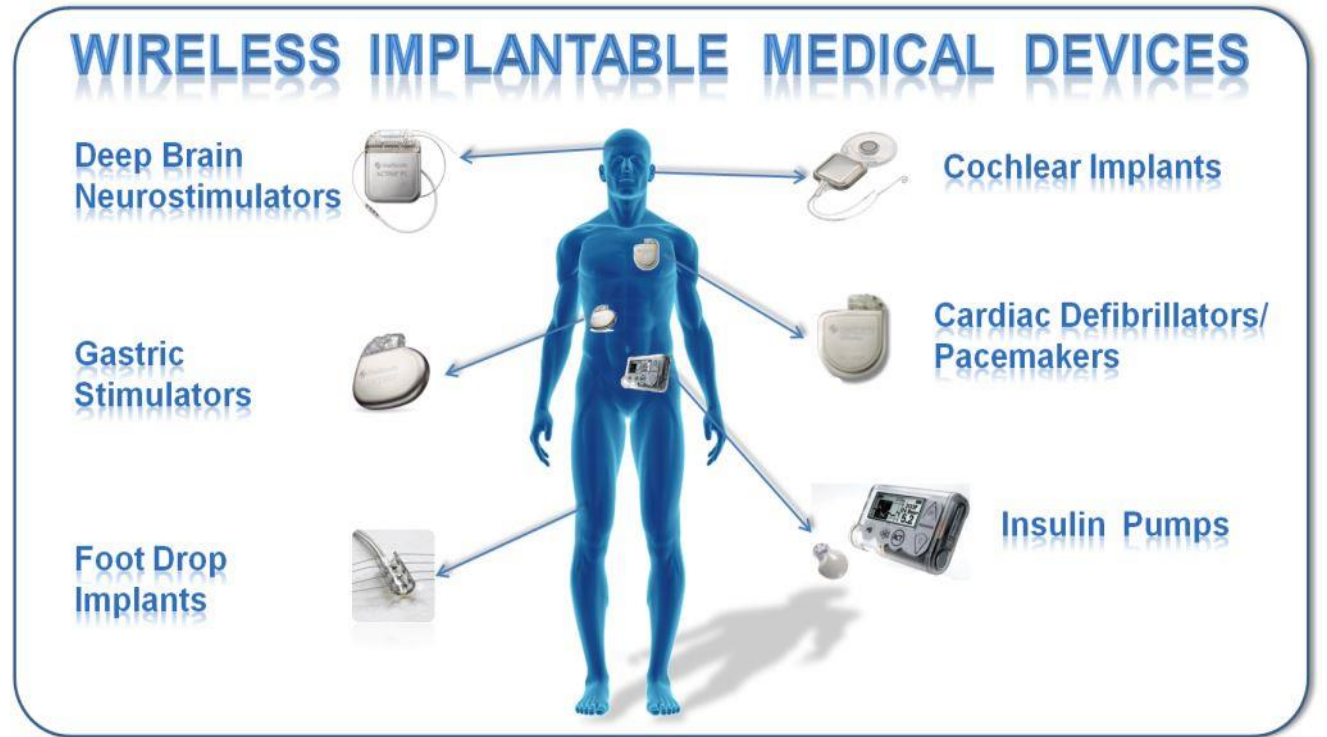


Image credit: <http://uhaweb.hartford.edu/>;  
<https://rahulmittal.files.wordpress.com/>;  
<http://www.carsdirect.com/>

# Health of an Li-Ion Battery

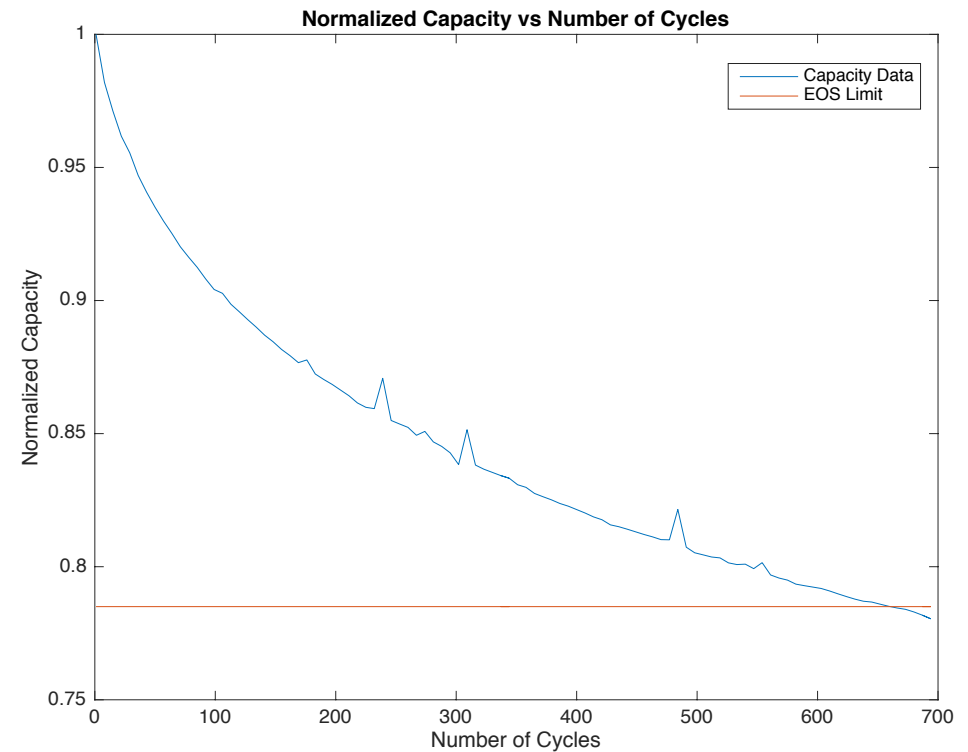
- Available signals
  - Current
  - Voltage
  - Internal temperature
- Battery-health indicators
  - State of Charge (SOC)
  - State of Health (SOH)
  - Remaining Useful Life (RUL)



Image credit: [www.ionarchive.com](http://www.ionarchive.com)

# Remaining Useful Life Estimation

- Remaining Useful Life (RUL)
  - End of Service limit determined by application
  - Measured in charge/discharge cycles

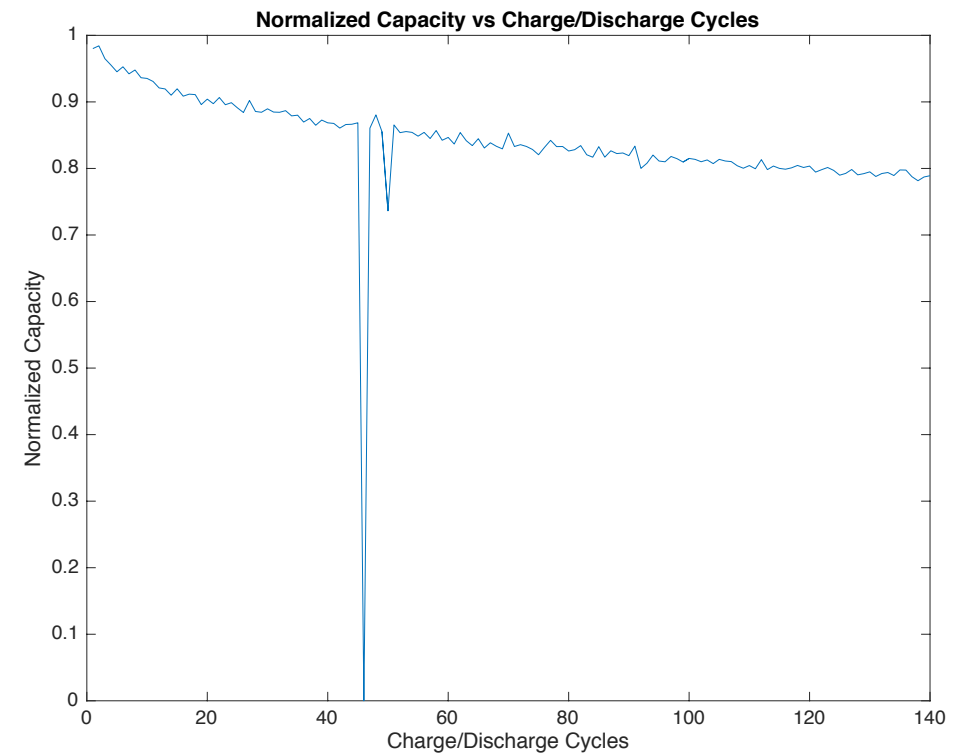


# Methods for SOH/RUL Estimation

- Model-based
  - Assume knowledge of physical system
  - Fit data to model of system
    - Si, et. al 2013
    - Gebraeel & Pan 2008
- Data-driven
  - Assume no knowledge of physical system
  - Machine learning/pattern recognition methods determine model
    - Neural Networks – Liu, et. al 2010;
    - Relevance Vector Machines – Hu, et. al 2015;

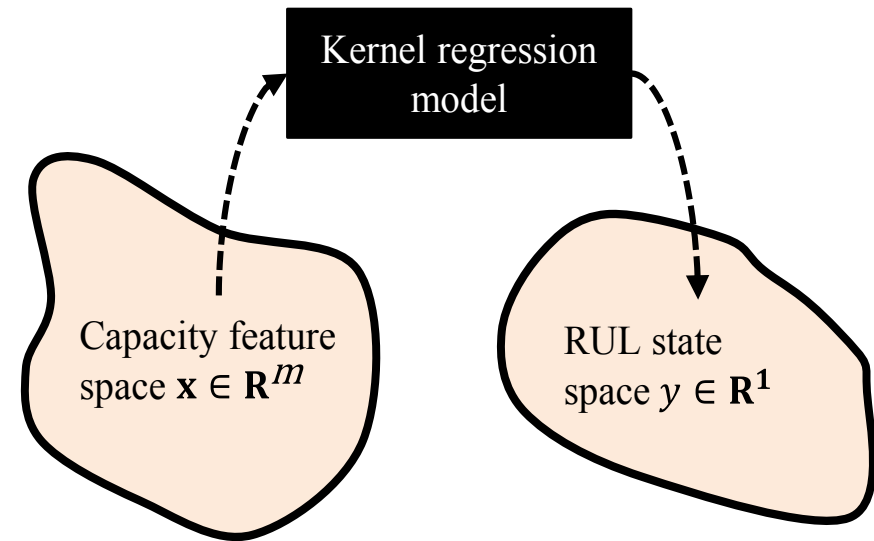
# Data Deficiencies

- Types of deficiencies
  - Missing data
  - Noise
- Handling of deficiencies
  - Remove spurious data points
  - Allow model to ignore them



# Our Approach

- Data-driven
- Least-squares regression based
  - Add additional regression step to find (and remove) noise in training data
  - Add kernel to transform data
  - Add regularization to encourage sparsity



# Least-squares Regression

- Feature vector:  $x$ 
  - Contains  $n$  most recent capacity readings

- Data matrix:  $X =$

$$\begin{pmatrix} x_{11} & \cdots & x_{1n} \\ \vdots & \ddots & \vdots \\ x_{m1} & \cdots & x_{mn} \end{pmatrix}$$

- Empirically determined RUL:  $y$

- RUL vector:  $Y = \begin{pmatrix} y_1 \\ \vdots \\ y_m \end{pmatrix}$

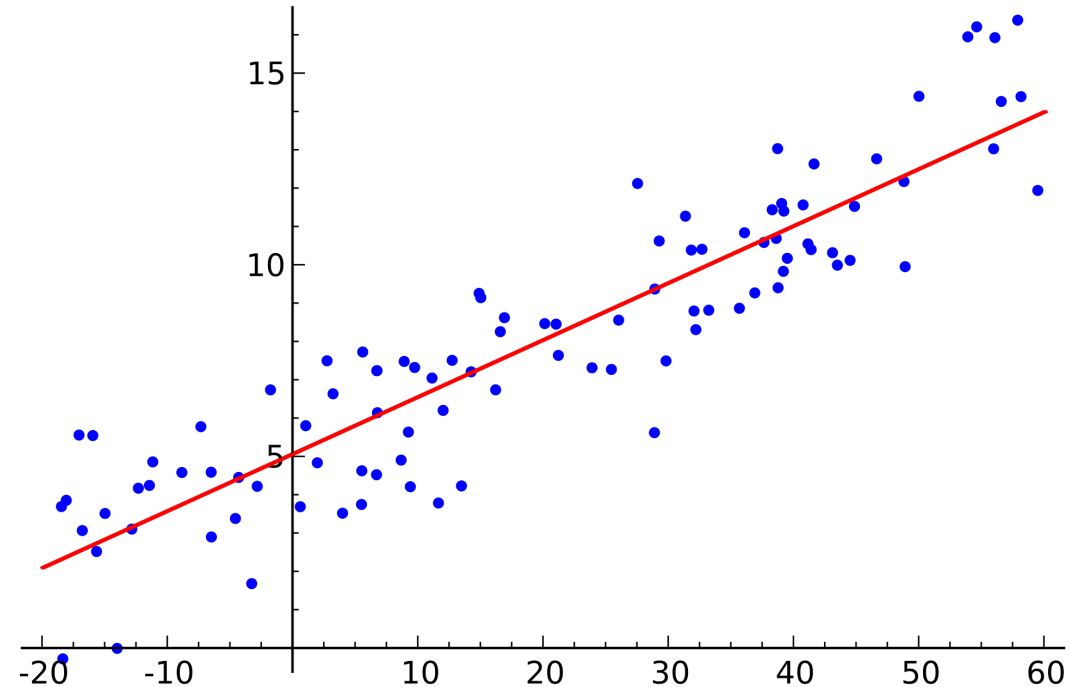


# Least-squares Regression

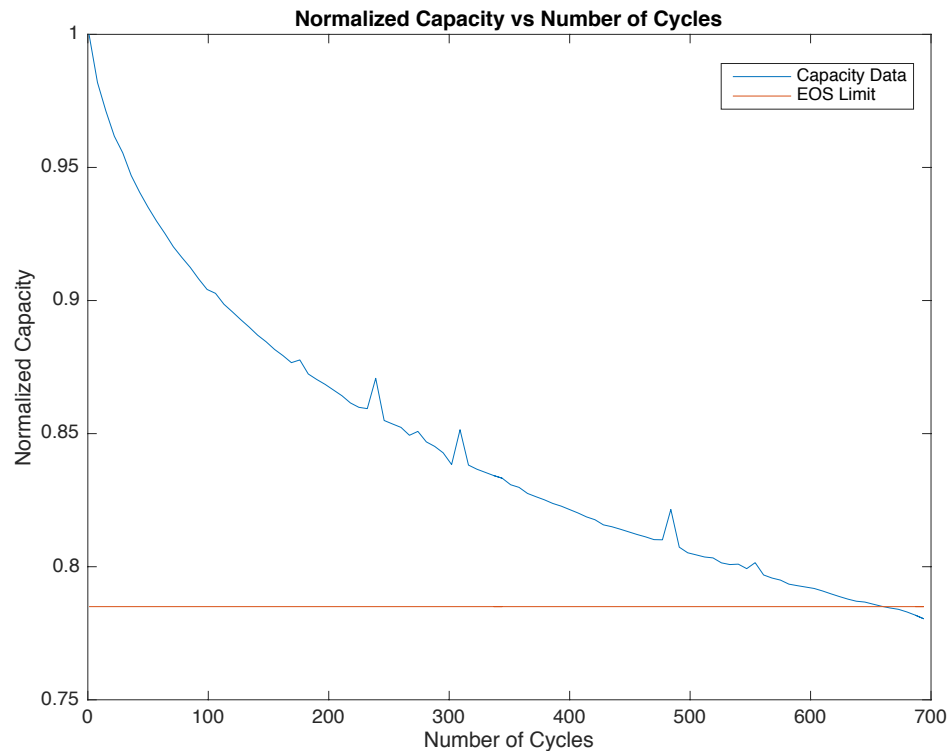
- Given  $X$  and  $Y$ , solve:

$$\min_w \|Y - Xw\|_2^2$$

- Prediction vector:  $\widehat{w}$
- Predicted RUL:  $\hat{y} = \langle x, \widehat{w} \rangle$



# Kernel Least-Squares Regression



- Replace  $X$  with kernel matrix,  $K$ 
  - Transform data to higher-dimensional space
  - Allows us to fit linear predictor,  $w$  to non-linear data
- Kernel choice is flexible
  - Dependent on data set
  - Gaussian Kernel is a common choice

# Gaussian Kernel Matrix, $K$

- $i^{th}$  row of  $K$  given by:

$$K_i = \exp\left(-\frac{\|x - x_i\|_2^2}{r^2}\right)$$

- Add a vector of ones as the first column of  $K$ 
  - Allow of non-zero “y-intercept” for linear function

$$K_{i,1} = \begin{matrix} 1 \\ \vdots \\ 1 \end{matrix}$$

$$K_{i,(j \neq 1)} =$$

$$\begin{pmatrix} \exp\left(-\frac{\|x_1 - x_1\|_2^2}{r^2}\right) & \cdots & \exp\left(-\frac{\|x_1 - x_{m+1}\|_2^2}{r^2}\right) \\ \vdots & \ddots & \vdots \\ \exp\left(-\frac{\|x_m - x_1\|_2^2}{r^2}\right) & \cdots & \exp\left(-\frac{\|x_m - x_{m+1}\|_2^2}{r^2}\right) \end{pmatrix}$$

# Kernel Least-Squares Regression

- Given  $X$  and  $Y$ , obtain  $\widehat{w}$  by solving:

$$\min_w \|Y - Kw\|_2^2$$

- Given feature vector  $x$ , compute:  $k(x)$  where  $k(x)_1 = 1$ ,

$$k(x)_j = \exp\left(-\frac{\|x - x_j\|_2^2}{r^2}\right), j = \{2, \dots, m + 1\}$$

- Predicted RUL:  $\hat{y} = \langle k(x), \widehat{w} \rangle$

# Kernel Regression and LASSO

## Overfitting

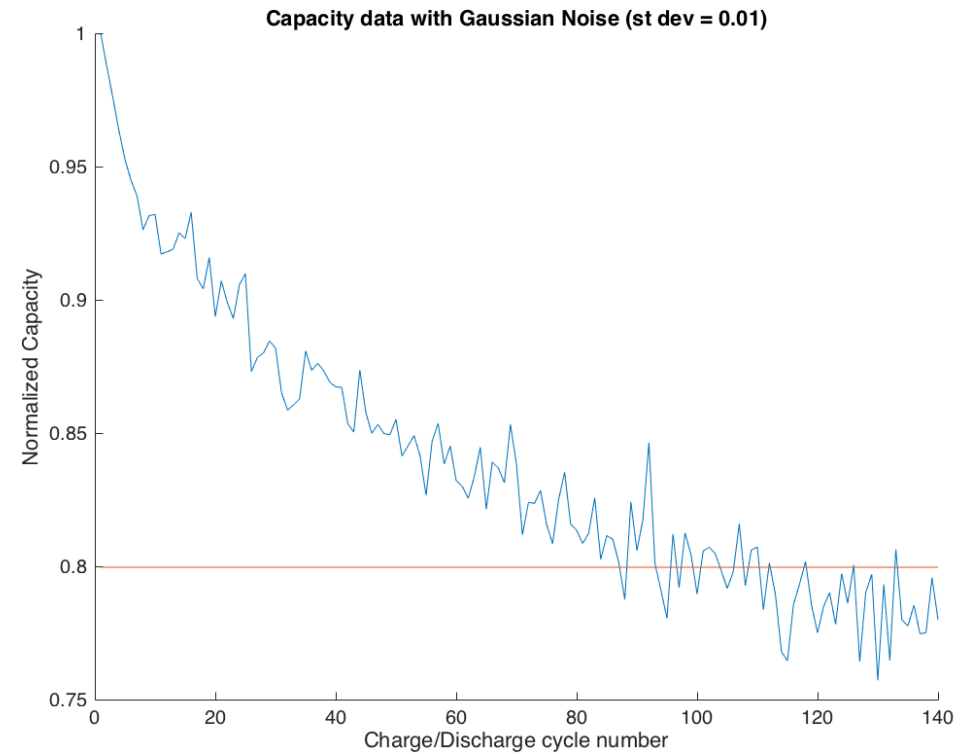
- Kernel regression can over-fit to training data
- Forcing  $w$  to be sparse can prevent over-fitting
  - $w$  will be allowed to have only a few non-zero entries
  - Only the most representative points will be used to calculate  $\hat{y}$

## Enforcing Sparsity

- Least Absolute Shrinkage and Selection Operator (LASSO)
- Rewrite regression problem as:
$$\min_w \|Y - Kw\|_2^2 + \lambda \|w\|_1$$

# Noise and Bilinear Regression

- Noise appears in almost every data set
- Writing  $K = K_{true} + E$  we look to find and remove errors from  $K$  to obtain more accurate predictions



# Bilinear Regression

- Kernel regression with LASSO (noiseless training data):

$$\min_w \|Y - K_{true}w\|_2^2 + \lambda\|w\|_1$$

- With noise in training data:  $K - E = K_{true}$

$$\min_{w,E} \|Y - (K - E)w\|_2^2 + \lambda\|w\|_1$$

- Include a regularization term on E

$$\min_{w,E} \|Y - (K - E)w\|_2^2 + \lambda\|w\|_1 + \tau\|E\|_p^p$$

# Algorithm – Bilinear Regression

## Setup

- **INPUTS:** Training data  $\{(\mathbf{x}_i, y_i)\}$ ,  
 $i=1, 2, \dots, n$ .
- **OUTPUTS:** Estimated kernel prediction vector  $\hat{\mathbf{w}}$ .
- **PARAMETERS:** Optimization parameters  $\lambda$  and  $\tau$ , kernel bandwidth  $r$ , number of iterations  $T$

## Algorithm

**Initialize:**  $\hat{\mathbf{w}}_0 \leftarrow 0, \hat{E}_0 \leftarrow 0, t \leftarrow 0$ .

**Compute:** the kernel matrix  $K$ .

**While**  $t < T$  **do:**

$t \leftarrow t + 1$

Set  $\bar{K} = K - \hat{E}_t$ . Solve:

$$\hat{\mathbf{w}}_{t+1} = \arg \min \lambda \|\mathbf{w}\|_1 + \|\mathbf{y} - \bar{K}\mathbf{w}\|_2^2$$

Set  $\bar{\mathbf{y}} = \mathbf{y} - K\hat{\mathbf{w}}_{t+1}$ . Solve:

$$\hat{E}_{t+1} = \arg \min \tau \|\text{vec}(E)\|_p^p + \|\bar{\mathbf{y}} + E\hat{\mathbf{w}}_{t+1}\|_2^2$$

Record prediction error:

$$\text{PredErr}(t) = \|\mathbf{y} - (K - \hat{E}_{t+1})\hat{\mathbf{w}}_{t+1}\|_2^2$$

**Find**  $t^*$  that minimizes  $\text{Prederr}(t)$ .

**Output:**  $\hat{\mathbf{w}} \leftarrow \hat{\mathbf{w}}_{t^*}$



# Data Set

## Test Cells

- 8 test cells
- Normalized capacity data from 700 charge/discharge cycles
  - Cells were cycled from 2002-2012
  - Weekly discharge rate

## Noise Addition

- Imbued with Gaussian noise
  - Zero mean
  - std. dev.  $\sigma = \{0, 0.005, 0.010, 0.015\}$

# Experiment Setup

## Cross Validations and Error Metric

- Leave-one-out cross validations (CVs)
- Root mean squared error (RMSE)

$$RMSE = \sqrt{\frac{1}{U} \sum_{l=1}^8 \sum_{i \in I_l} \left( \hat{y}_{\mathbf{X} \setminus \mathbf{x}_l}(\mathbf{x}_i) - y(\mathbf{x}_i) \right)^2}$$

## Test Procedure

- Feature vectors: three most recent capacity readings
- For each noise level  $\sigma$ 
  - Perform two 8-fold CVs

# Results

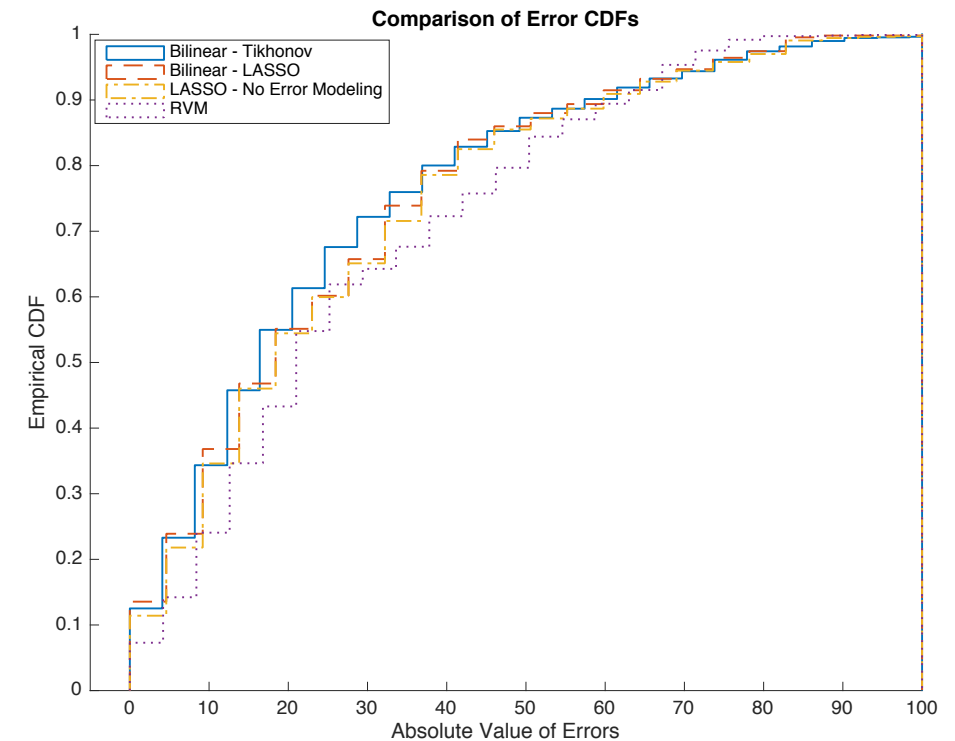
Prediction Method	RMSE						
	Noise in Training Data (std. dev of Gaussian noise)				Noise in Test and Training Data (std. dev of Gaussian noise)		
	0	0.005	0.01	0.015	0.005	0.01	0.015
Lasso	31.24	33.052	34.72	50.42	42.33	61.53	83.67
Bi-Lasso	30.26	31.62	33.28	46.22	40.96	60.16	82.40
Bi-Tikhonov	29.57	30.92	32.80	48.88	40.57	60.58	83.52
RVM	30.91	32.67	36.16	47.67	41.50	60.22	82.58

# Results

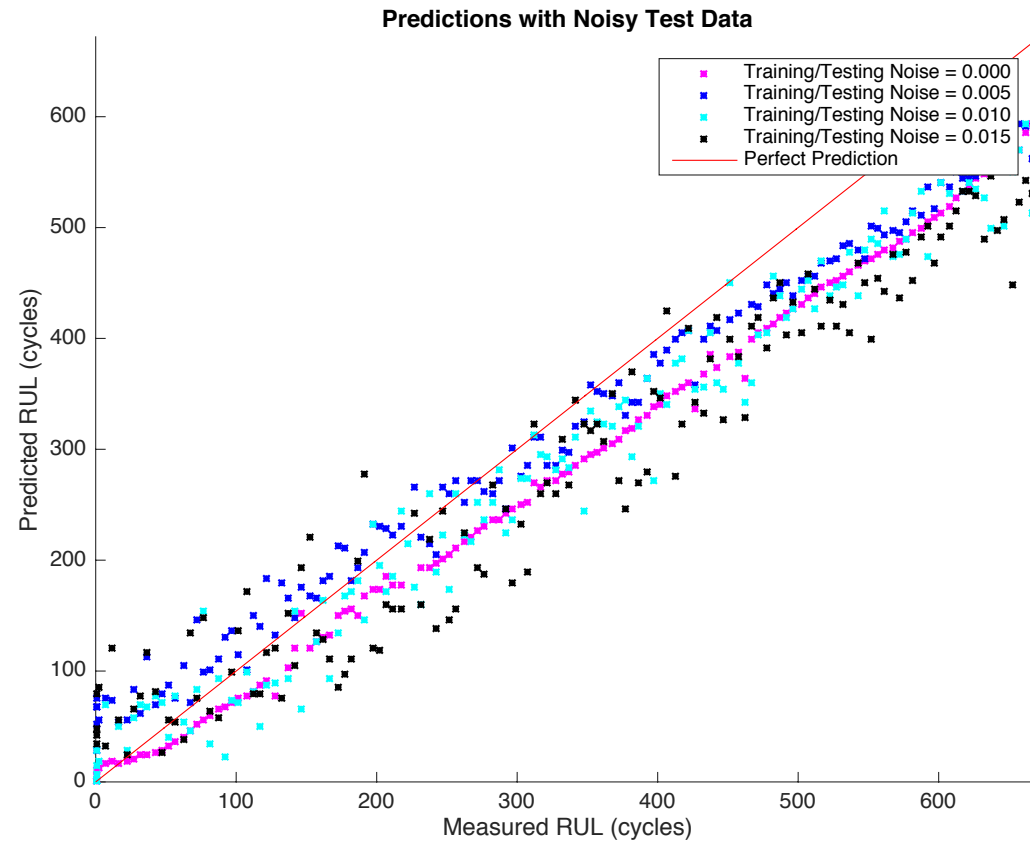
## Noise-free test data

RMSE				
	0	0.005	0.01	0.015
Lasso	31.24	33.052	34.721	50.415
Bi-Lasso	30.259	31.615	33.282	46.222
Bi-Tikhonov	29.572	30.921	32.8	48.88
RVM	30.91	32.67	36.16	47.67

## Error CDF's

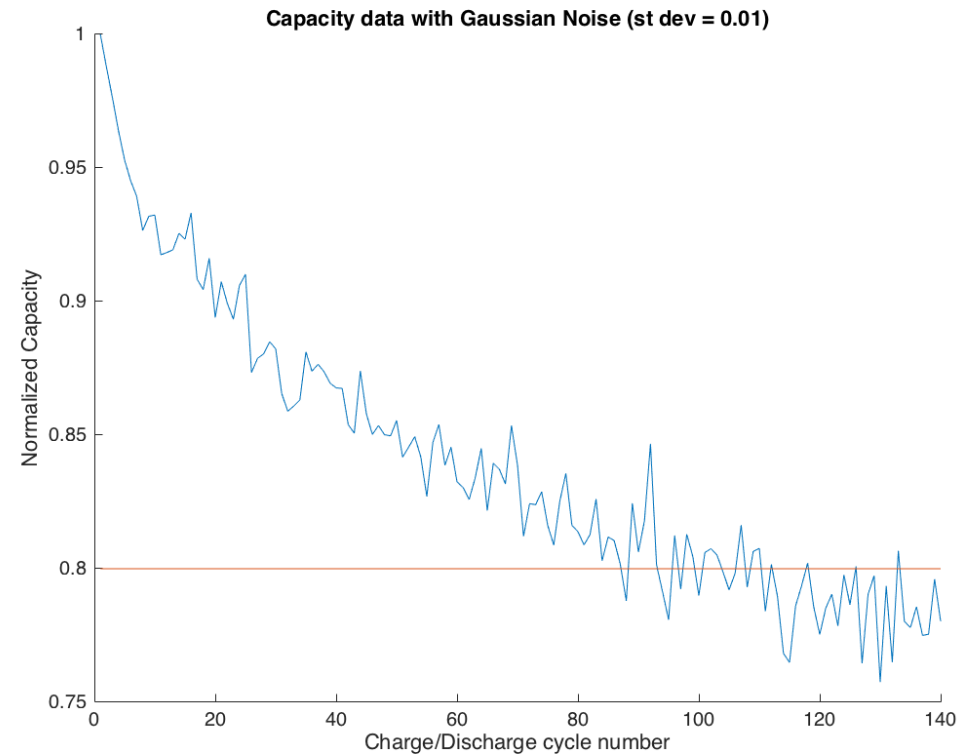


# Testing with Noisy Data



# Summary

- RUL predictions in batteries can be of critical importance
- Capacity fade data is nonlinear and often noisy
- Our model leverages:
  - Error estimation (and removal)
  - Data transformations
  - Sparse predictions
- Key contribution: Provide accurate RUL estimation in the presence of noisy data



# References

- Hubbard, Bavlisk, Hu, Hegde (2016).  
*Data-Driven Prognostics of Lithium-Ion Rechargeable Batteries Using Bilinear Kernel Regression.*  
Annual Conference of the Prognostics and Health Management Society 2016.
- Liu, J., Saxena, A., Goebel, K., Saha, B., & Wang, W. (2010).  
*An adaptive recurrent neural network for remaining useful life prediction of lithium-ion batteries.*  
National Aeronautics and Space Administration Moffett Field, CA Ames Research Center.
- Hu, C., Jain, G., Schmidt, C., Strief, C., & Sullivan, M. (2015).
  - Online estimation of lithium-ion battery capacity using sparse Bayesian learning. *Journal of Power Sources*, 289, 105-113.
- Si, X. S., Wang, W., Hu, C. H., Chen, M. Y., & Zhou, D. H. (2013).  
A Wiener-process-based degradation model with a recursive filter algorithm for remaining useful life estimation. *Mechanical Systems and Signal Processing*, 35(1), 219-237.
- Gebraeel, N., & Pan, J. (2008).  
Prognostic degradation models for computing and updating residual life distributions in a time-varying environment. *IEEE Transactions on Reliability*, 57(4), 539-550