

In [1]:

```
%run CPL_Library.ipynb # Running the entire library in one line because
                        # importing does not work with JupyterLab
```

Question 1

In [2]:

```
print("The augmented matrix is: ")
A,ro,co=read_matrix('As3matrixA.txt')
print_matrix(A,ro,co)
GJ, d=gauss_jordan(A,ro,co)
if GJ!=None:
    print("Solutions are : ")
    for i in range(ro):
        print(ROUND(GJ[i][ro],2))
else:
    print("No unique solution")
```

The augmented matrix is:

```
1   1   1   1   13
2   3   0  -1  -1
-3   4   1   2   10
1   2  -1   1   1
```

Solutions are :

```
2.0 2
-0.0 2
6.0 2
5.0 2
```

Question 2

In [3]:

```
print("The augmented matrix is: ")
B,ro,co=read_matrix('As3matrixB.txt')
print_matrix(B,ro,co)
GJ, d=gauss_jordan(B,ro,co)
if GJ!=None:
    print("Solutions are : ")
    for i in range(ro):
        print(GJ[i][ro])
else:
    print("No unique solution")
```

The augmented matrix is:

0	2	-3	-1
1	0	1	0
1	-1	0	3

Solutions are :

1.0
-2.0
-1.0

Question 3

In [4]:

```

print("The augmented matrix is: ")
C,ro,co=read_matrix('As3matrixC.txt')
print_matrix(C,ro,co)
GJ, d=gauss_jordan(C,ro,co)
C2,ro,co=read_matrix('As3matrixC.txt')
if GJ!=None:
    # Finding the inverse and printing in rounded form
    # Also finding the matrix multiplication for verification and then rounding at the end
    M=get_inv(C,ro)
    MM,k,l=matrix_multiply(M,ro,ro,C2,ro,ro) # using only n x n matrix i.e. unaugmented matrix
    M=round_matrix(M)
    print("The inverse matrix is: ")
    print_matrix(M,ro,ro)
    print("Verification: after multiplying the matrix and its inverse, we get : ")
    MM=round_matrix(MM)
    print_matrix(MM,ro,ro)
else:
    print("No unique solution")

```

The augmented matrix is:

0	2	1	1	0	0
4	0	1	0	1	0
-1	2	0	0	0	1

The inverse matrix is:

-0.33	0.33	0.33
-0.17	0.17	0.67
1.33	-0.33	-1.33

Verification: after multiplying the matrix and its inverse, we get :

1.0	0	0
0	1.0	0.0
0	0	1.0

Question 4

In [5]:

```
print("The augmented matrix is: ")
D,ro,co=read_matrix('As3matrixD.txt')
print_matrix(D,ro,co)
GJ, d=gauss_jordan(D,ro,co)
if GJ!=None:
    print("Determinant = "+str(d))
else:
    print("No unique solution")
```

The augmented matrix is:

1	4	2	3	1	0	0	0
0	1	4	4	0	1	0	0
-1	0	1	0	0	0	1	0
2	0	4	1	0	0	0	1

Determinant = 65.0

In []: