Unit 0. Introduction

Numerical Analysis

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Numerical Analysis

- Mathematics are important in our study, research and work.
 - Mathematical formulation provides clear and precise description of the problem.
 - Quantified or analytically.
 - Analytic solutions have been studied throughout your lives.
 - Few problems have closed form solutions.
 - How do you solve mathematical problems to get numerical solutions?
- Numerical methods apply computation tools (computers) to solve mathematical problems to get numerical solutions.
 - Explore the mathematical properties of the problems.
 - Develop algorithm to solve the problem effectively.
 - Find approximated solutions if more efficient.
 - Overcome computer inexactness.
- Numerical methods have been used extensively in our daily lives already.
 - List your examples.

Topics to Be Studied

- In this course, we will study the following topics in numerical analysis.
 - Linear system solutions,
 - Errors,
 - Iterative solution methods,
 - Eigenvalues and eigenvectors,
 - Interpolations,
 - Integrations,
 - Nonlinear system solutions,
 - Ordinary differential equations,
 - Boundary value problems.

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Linear System Solutions

You know how to solve this problem.

$$\begin{array}{ccc}
2x_1 & +x_2 & = 1 \\
x_1 & +2x_2 & = 1
\end{array}$$

• How about this?

$$70x_1 +60x_2 +50x_3 +40x_4 +30x_5 +20x_6 +10x_7 = 1$$

$$60x_1 +70x_2 +60x_3 +50x_4 +40x_5 +30x_6 +20x_7 = 2$$

$$50x_1 +60x_2 +70x_3 +60x_4 +50x_5 +40x_6 +30x_7 = 3$$

$$40x_1 +50x_2 +60x_3 +70x_4 +60x_5 +50x_6 +40x_7 = 4$$

$$30x_1 +40x_2 +50x_3 +60x_4 +70x_5 +60x_6 +50x_7 = 3$$

$$20x_1 +30x_2 +40x_3 +50x_4 +60x_5 +70x_6 +60x_7 = 2$$

$$19x_1 +29x_2 +39x_3 +49x_4 +59x_5 +69x_6 +59x_7 = 1$$

- What if we have 1,000 or 1,000,000 variables?
 - Can we solve it efficiently?

Errors

- We know computer numbers are inexact.
 - Experimental data have inherent inaccuracy also.
 - How do these errors affect our solutions?
 - Can the algorithm be rewritten for smaller errors?

$$\begin{bmatrix} 70 & 60 & 50 & 40 & 30 & 20 & 10 \\ 60 & 70 & 60 & 50 & 40 & 30 & 20 \\ 50 & 60 & 70 & 60 & 50 & 40 & 30 \\ 40 & 50 & 60 & 70 & 60 & 50 & 40 \\ 30 & 40 & 50 & 60 & 70 & 60 & 50 \\ 20 & 30 & 40 & 50 & 60 & 70 & 60 \\ 19 & 29 & 39 & 49 & 59 & 69 & 59 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 3 \\ 2 \\ 1 \end{bmatrix}.$$

$$\mathbf{x}^T = \begin{bmatrix} 0.45 & 0 & 0 & 0.1 & 0 & -3.9 & 4.35 \end{bmatrix}$$

$$\begin{bmatrix} 70 & 60 & 50 & 40 & 30 & 20 & 10 \\ 60 & 70 & 60 & 50 & 40 & 30 & 20 \\ 50 & 60 & 70 & 60 & 50 & 40 & 30 \\ 40 & 50 & 60 & 70 & 60 & 50 & 40 \\ 30 & 40 & 50 & 60 & 70 & 60 & 50 \\ 20 & 30 & 40 & 50 & 60 & 70 & 60 \\ 20 & 30 & 40 & 50 & 60 & 70 & 60 \\ 19 & 29 & 39 & 49 & 59 & 69 & 59 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \\ x_5 \\ x_6 \\ x_7 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \\ 3 \\ 4 \\ 3 \\ 2 \\ 1.1 \end{bmatrix}.$$

$$\mathbf{x}^T = \begin{bmatrix} 0.4 & 0 & 0 & 0.1 & 0 & -3.5 & 3.9 \end{bmatrix}$$

A small error can cause significant changes in solutions.

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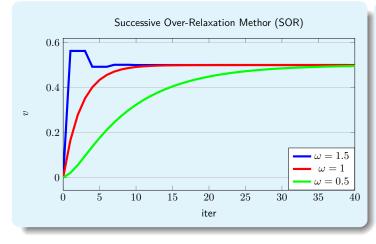
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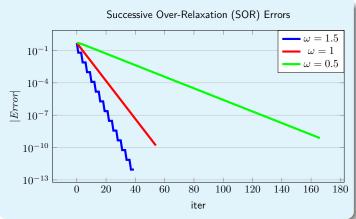
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Iterative Solution Methods

- Solving a linear system with n variables takes $\mathcal{O}(n^3)$ CPU time.
- ullet For large n the solution time can be too long.
- Iterative solution methods find an approximate solution with less amount of time.
- Matrix may need to possess some special properties to be applicable.
- More general solutions have been developed, but not covered in this course.





Eigenvalues and Eigenvectors

You know how to find the eigenvalues and eigenvectors for

$$\begin{bmatrix} 2 & 1 \\ 1 & 2 \end{bmatrix}$$

• How about this?

$$\lambda^{T} = [339.07 \ 96.29 \ 20.67 \ 10.89 \ 6.80 \ 5.41 \ -0.12]$$

- What if we have a $1,000 \times 1,000$ or $1,000,000 \times 1,000,000$ matrix?
 - Can we solve it efficiently?

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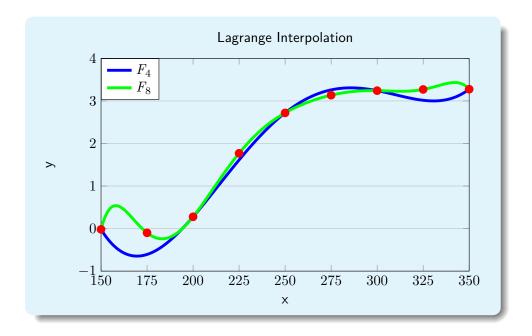
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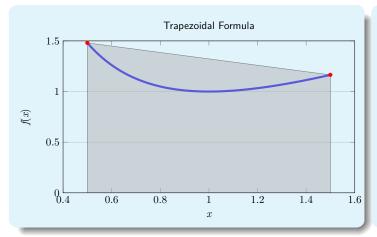
Interpolations

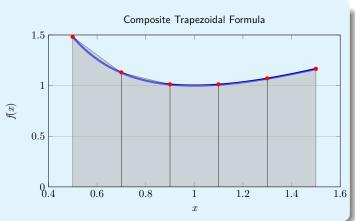
- Given a set of data, find a function to represent these data points.
 - Polynomial interpolations,
 - Rational interpolations (not covered),
 - Spline interpolations.



Integrations

- Integral equations have few closed form solutions.
- Numerical integration has been studied and adopted early.





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Nonlinear System Solutions

• Example of nonlinear function

$$f(x) = \log^2(x) - x + 0.9$$

- What is the value of x such that f(x) = 0?
- f(x) can be any nonlinear function.
- What are the roots of

$$x^7 + 6x^5 + 3x^4 + 10x^3 + 25x^2 + 100 = 0.$$

- It has been proven that no closed form solution exists for polynomial of order greater than 5.
- Numerical methods are usually necessary to find the solutions.

Ordinary Differential Equations

 Differential equations have been used extensively in science and engineering fields.

$$\frac{dx(t)}{dt} = f(t, x(t)), \qquad t \ge 0,$$

$$x(0) = x_0.$$

- Finding the solution quickly and accurately is the key of this study.
- Electric circuits with capacitors or inductors, or both, need to be solved using this method if time domain solution is needed.
- Again, solution is usually an approximation.
 - Limitations and accuracy should be well versed to get acceptable solutions.
- In many applications, f(t, x(t)) is nonlinear. Thus, solving ODE needs to apply all techniques learned in this course.

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Practice and Programming

- We will analyze different numerical analysis topics and develop algorithms or methods to solving these problems.
- These algorithms or methods can be implemented using different tools.
- Some tools are primitive and need more efforts.
- Some with built-in functions and are very easy to use.
- In this class, we will adopt C++ to practice detailed implementations.
- Basic functions will be developed such that you know all the basics.
- Using operator overloading, our program will be very easy to understand and minimize potential errors.
- C++ class and operator overloading will be reviewed next.
- Since all the algorithms will be discussed, the programming difficulty level is actually quite low.
- You should enjoy our homework every week.