Unit 6 Numerical Integrations

Numerical Analysis

May 5, 2015

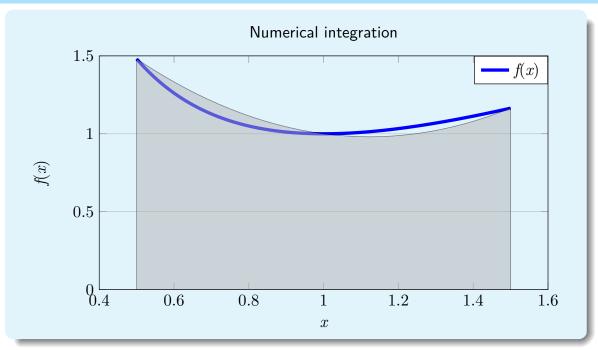
Numerical Analysis

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Numerical Integrations



To find

$$\int_{0.5}^{1.5} (\log^2(x) + 1) dx$$

- Given function f(x), $x \in [a, b]$, and f(x) can be evaluate accurately, but costly.
- Closed form solution is not known.

Numerical Integrations, II

- Integration of a function f(x) over an interval [a,b] tends to have fewer explicit formulas than differentiation, thus there are more studies done on numerical integration.
- Function f(x) needs to be integrable and the definite integral over the interval [a,b] is sought for

 $I(f) = \int_{a}^{b} f(x) \, dx \tag{6.1.1}$

- Finding the explicit formula to approximate of the integral I(f) is called a quadrature formula or numerical integration formula.
- An example is to replace f by an approximation f_n , n >= 0, and compute $I(f_n)$ instead of I(f). Denote $I_n(f) = I(f_n)$, then

$$I_n(f) = \int_a^b f_n(x) dx.$$
 (6.1.2)

• If f is a continuous function over the range [a, b], then the quadrature error $E_n(f) = I(f) - I_n(f)$ satisfies

$$|E_n(f)| \le \int_a^b |f(x) - f_n(x)| dx \le (b - a) ||f - f_n||_{\infty}.$$
 (6.1.3)

If for some n, $||f-f_n||_{\infty} < \epsilon$ then $|E_n(f)| \le \epsilon(b-a)$.

ullet The quadrature error can be managed by choosing the right approximation of f_n .

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Numerical Integrations, III

• One approximation of Eq. (6.1.2) is as following

$$I_n(f) = \sum_{i=0}^n \alpha_i f(x_i). \tag{6.1.4}$$

- This is a weighted sum of f at each node x_i .
- $\alpha_i \in \mathbb{R}$ is the coefficient or weight.
- Note that Eq. (6.1.4) is a linear combination of f_i .
- ullet The accuracy of the integration is heavily dependent on n.
- Interpolatory quadrature formulas are one example of the quadrature formulas, where f is replaced by interpolating polynomials.
- Define the degree of exactness of a quadrature formula as the maximum integer, $r \geq 0$ such that

$$I_n(f) = I(f), \quad \text{for all } f \in \mathbb{P}_r.$$
 (6.1.5)

 \mathbb{P}_r is the set of polynomial of degree less than or equal to r.

Lagrange quadrature is

$$I_n(f) = \sum_{i=0}^n f(x_i) \int_a^b l_i(x) dx,$$
 (6.1.6)

where l_i is the characteristic Lagrange polynomial of degree n associated with node x_i , and Lagrange quadrature has the degree of exactness of n.

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Rectangle Formula

• The rectangle integration formula is

$$I_0(f) = (b-a)f(\frac{a+b}{2})$$
(6.1.7)

- Rectangle formula replaces f over [a, b] with the constant function equals to the value of f at the midpoint of [a, b].
- If $f \in C^2([a,b])$ then expand f around $x_0 = (a+b)/2$

$$f(x) = f(x_0) + f'(x_0)(x - x_0) + f''(\xi)(x - x_0)^2 / 2,$$

And, let H = (b - a)/2, we have

$$\int_{a}^{b} f(x) dx = (b - a) f(x_{0}) + f'(x_{0}) \frac{y^{2}}{2} \Big|_{y=-H}^{H} + f''(\xi) \frac{y^{3}}{6} \Big|_{y=-H}^{H}$$
$$= (b - a) f(x_{0}) + f''(\xi) \frac{H^{3}}{3}.$$

Thus, the quadrature error is

$$E_0(f) = \frac{H^3}{3}f''(\xi), \quad H = \frac{b-a}{2}$$
 (6.1.8)

where $\xi \in [a, b]$.

• The rectangle formula has the degree of exactness equal to 1.

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Composite Rectangle Formula

- The quadrature error of rectangle formula is proportional to H^3 .
- If H=(b-a) is large then the quadrature error is large.
- In practice, we can reduce the quadrature error by adopting the composite quadrature formula: divide [a,b] into m subintervals each with width of $h=(b-a)/m, m\geq 1$ and the quadrature nodes are $x_k=a+(2k+1)h/2,$ $k=0,\cdots,m-1.$ Then the composite rectangle formula is

$$I_{0,m}(f) = h \sum_{k=0}^{m-1} f(x_k).$$
 (6.1.9)

• The quadrature error is then

$$E_{0,m}(f) = I(f) - I_{0,m}(f) = \sum_{k=0}^{m-1} (I(f) - I_{0,m}(f))$$

$$= m \cdot \frac{1}{3} \cdot \left(\frac{h}{2}\right)^3 f''(\xi) = \frac{mh^3}{24} f''(\xi)$$

$$= \frac{(b-a)h^3}{24h} f''(\xi) = \frac{(b-a)h^2}{24} f''(\xi)$$
(6.1.10)

ullet By choosing appropriate m the quadrature error can be controlled.

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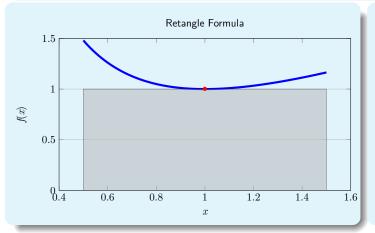
Composite Rectangle Formula, II

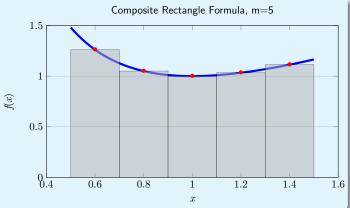
• In deriving the composite rectangle quadrature error, we have used the following theorem.

Theorem 6.1.1. Discrete mean-value theorem

Let $f \in C^0([a, b])$ and let x_j be s+1 points in [a, b] and δ_j be s+1 constants, all having the same sign. Then there is an $\eta \in [a, b]$ such that

$$\sum_{j=0}^{s} \delta_{j} f(x_{j}) = f(\eta) \sum_{j=0}^{s} \delta_{j}.$$
 (6.1.11)





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Composite Rectangle Formula, Algorithm

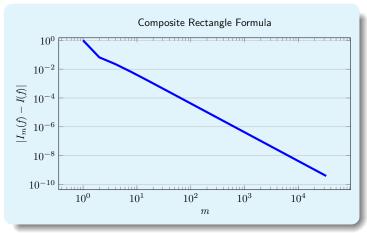
Algorithm 6.1.2. Composite Rectangle Formula

Given the function f in the interval $\left[a,b\right]$ and an integer m

let
$$h=\frac{b-a}{m}$$
; $x=a+\frac{h}{2}$; $I=0$; while $(x\leq b)\{$
$$I=I+f(x)*h;$$

$$x=x+h;$$
 }

 ${\it I}$ is the integral.



- As m increases, the rectangle quadrature produces more accurate result.
- It converges to I(f) as $m \to \infty$.
- The convergence rate is constant, $O(m^{-2})$.

The Trapezoidal Formula

• The trapezoidal quadrature approximates function f by a first order polynomial of $f_1(x) = a_0 + a_1 x$.

With $f_1(a) = f(a)$ and $f_1(b) = f(b)$. Thus,

$$f_1(x) = \frac{x-a}{b-a}f(b) + \frac{x-b}{a-b}f(a) = \frac{f(b)-f(a)}{b-a}x + \frac{bf(a)-af(b)}{b-a}$$
(6.1.12)

$$I_1(f) = \int_a^b f_1(x) dx = (b - a) \frac{f(a) + f(b)}{2}.$$
 (6.1.13)

• By Theorem (5.1.16), the quadrature error is then

$$E_1(f) = \int_a^b \frac{1}{2} (x - a)(x - b) f''(\xi) dx = -\frac{H^3}{12} f''(\xi), \quad H = b - a,$$
 (6.1.14)

where $\xi \in [a, b]$.

- The trapezoidal quadrature method has degree of exactness equal to 1.
 - The same as the rectangle quadrature method.

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The Composite Trapezoidal Formula

• The composite trapezoidal formula divides the interval [a, b] into m equal subintervals and apply the trapezoidal formula in each region. Let the points be $a = x_0, x_1, x_2, \dots, x_{m-1}, x_m = b$,

$$I_{1,m}(f) = \sum_{k=0}^{m-1} (x_{k+1} - x_k) \frac{f(x_k) + f(x_{k+1})}{2} = \frac{h}{2} \sum_{k=0}^{m-1} (f(x_k) + f(x_{k+1}))$$

$$= h \left(\frac{f(x_0)}{2} + f(x_1) + f(x_2) + \dots + f(x_{m-2}) + \frac{f(x_m)}{2} \right), \qquad (6.1.15)$$

where $h = \frac{b-a}{m}$.

- Note that the series summation has the values at both end points (f(a)) and f(b) with the weight of 1/2, while all other points have the weight of 1.
- And the quadrature error is

$$E_{1,m}(f) = I(f) - I_{1,m}(f) = \sum_{k=0}^{m-1} (I(f) - I_{1,k}(f))$$
$$= -\frac{b-a}{12} h^2 f''(\xi), \tag{6.1.16}$$

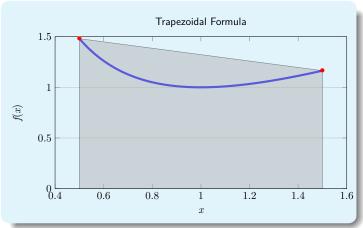
assuming $f \in C^2([a, b])$ and $\xi \in (a, b)$.

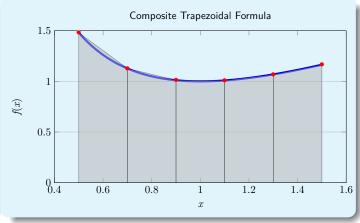
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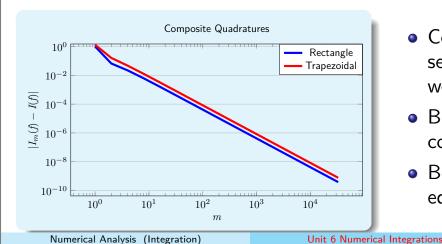
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The Composite Trapezoidal Formula, II







- Composite trapezoidal method seems to track the function curve well.
- But the quadrature errors are compatible to rectangle method.
- Both have the degree of exactness equal to 1.

The Cavalieri-Simpson Formula

• The Cavalieri-Simpson formula is obtained when f is replaced by the interpolating polynomial of degree 2 at the nodes, $x_0 = a$, $x_1 = (a+b)/2$, and $x_2 = b$. It can be derived that the resulting formula is

$$I_2(f) = \frac{b-a}{6} \left[f(a) + 4f(\frac{a+b}{2}) + f(b) \right]. \tag{6.1.17}$$

and the quadrature error is

$$E_2(f) = -\frac{H^5}{90}f^{(4)}(\xi), \quad H = \frac{b-a}{2}.$$
 (6.1.18)

- Thus, the Cavalieri-Simpson formula has the degree of exactness equal to 3.
- The composite Cavalieri-Simpson formula has the following form, assuming the quadrature nodes are $x_k = a + kh/2$, $k = 0, \dots, 2m$ and h = (b a)/m.

$$I_{2,m}(f) = \frac{h}{6} \left[f(x_0) + 2 \sum_{j=1}^{m-1} f(x_{2j}) + 4 \sum_{k=0}^{m-1} f(x_{2k+1}) + f(x_{2m}) \right].$$
 (6.1.19)

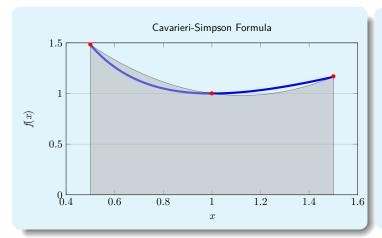
with the quadrature error

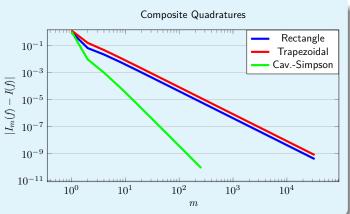
$$E_{2,m}(f) = -\frac{b-a}{180}(h/2)^4 f^{(4)}(\xi), \tag{6.1.20}$$

if $f \in C^4([a, b])$, and $\xi \in (a, b)$. The degree of exactness is 3.

The Cavalieri-Simpson Formula, II

- Composite quadrature formulas are effective in performing numerical integrations.
- Formulas with higher degree of exactness can produce more accurate integration with fewer nodes.
- Integrations by composite quadrature are easy to implement and very efficient in CPU time and memory space.





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Newton-Cotes Formulas

- Newton-Cotes formulas are based on Lagrange interpolation with equally spaced nodes in [a,b].
- For an n>0, the nodes are placed at $x_k=x_0+kh$, $k=0,\cdots,n$ with h=(b-a)/n. Note that $x_0=a$ and $x_n=b$.
- Rectangle, trapezoidal and Simpson formulas are special instances of the Newton-Cotes formulas, with $n=0,\ n=1$ and n=2.
 - In the case n=0, h=b-a and $x_0=a$, $x_1=b$, we have retangle formula.
- With Lagrange interpolation,

$$f = \sum_{i=0}^{n} \prod_{k=0, k \neq i}^{n} \frac{x - x_k}{x_i - x_k} f(x_i) = \sum_{i=0}^{n} \prod_{k=0, k \neq i}^{n} \frac{t - k}{i - k} f(x_i).$$
 (6.1.21)

The second part of the above equation is obtained by a change of variable $x = x_0 + th$. Thus,

$$I_n(f) = \int_{x=a}^b \sum_{i=0}^n \prod_{k=0, k \neq i}^n \frac{x - x_k}{x_i - x_k} f(x_i) dx = \sum_{i=0}^n f(x_i) \int_{t=0}^n \prod_{k=0, k \neq i}^n \frac{t - k}{i - k} h dt = h \sum_{i=0}^n w_i f(x_i).$$
(6.1.22)

with

$$w_i = \int_{t=0}^n \prod_{k=0}^n \frac{t-k}{i-k} dt.$$
 (6.1.23)

Newton-Cotes Formulas, II

• In the case n=0, $f(x)=f(\frac{a+b}{2})$ is a constant, and

$$w_0 = \int_{t=0}^{1} 1 \, dt = 1.$$

Thus,

$$I_0(f) = hf(\frac{a+b}{2}).$$
 (6.1.24)

• When n=1,

$$w_0 = \int_{t=0}^1 \frac{t-1}{0-1} dt = -\left[\frac{t^2}{2} - t\right]_{t=0}^1 = \frac{1}{2}$$

$$w_1 = \int_{t=0}^1 \frac{t-0}{1-0} dt = \left[\frac{t^2}{2}\right]_{t=0}^1 = \frac{1}{2}$$

Thus,

$$I_1(f) = \frac{h}{2}(f(x_0) + f(x_1)) = h\frac{f(a) + f(b)}{2}.$$
 (6.1.25)

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Newton-Cotes Formulas, III

• When n=2,

$$w_0 = \int_{t=0}^2 \frac{(t-1)(t-2)}{(0-1)(0-2)} dt = \frac{1}{2} \left[\frac{t^3}{3} - \frac{3t^2}{2} + 2t \right]_{t=0}^2 = \frac{1}{3}$$

$$w_1 = \int_{t=0}^2 \frac{(t-2)(t-0)}{(1-2)(1-0)} dt = -\left[\frac{t^3}{3} - \frac{2t^2}{2} \right]_{t=0}^2 = \frac{4}{3}$$

$$w_2 = \int_{t=0}^2 \frac{(t-0)(t-1)}{(2-0)(2-1)} dt = \frac{1}{2} \left[\frac{t^3}{3} - \frac{t^2}{2} \right]_{t=0}^2 = \frac{1}{3}$$

Thus,

$$I_{2}(f) = h\left(\frac{1}{3}f(x_{0}) + \frac{4}{3}f(x_{1}) + \frac{1}{3}f(x_{2})\right)$$

$$= \frac{b-a}{6}\left(f(x_{0}) + 4f(x_{1}) + f(x_{2})\right). \tag{6.1.26}$$

Newton-Cotes Formulas, IV

• When n=3,

$$w_{0} = \int_{t=0}^{3} \frac{(t-1)(t-2)(t-3)}{(0-1)(0-2)(0-3)} dt = \frac{-1}{6} \left[\frac{t^{4}}{4} - \frac{6t^{3}}{3} + \frac{11t^{2}}{2} - 6t \right]_{t=0}^{3} = \frac{3}{8}$$

$$w_{1} = \int_{t=0}^{3} \frac{(t-2)(t-3)(t-0)}{(1-2)(1-3)(1-0)} dt = \frac{1}{2} \left[\frac{t^{4}}{4} - \frac{5t^{3}}{3} + \frac{6t^{2}}{2} \right]_{t=0}^{3} = \frac{9}{8}$$

$$w_{2} = \int_{t=0}^{3} \frac{(t-3)(t-0)(t-1)}{(2-3)(2-0)(2-1)} dt = \frac{-1}{2} \left[\frac{t^{4}}{4} - \frac{4t^{3}}{3} + \frac{3t^{2}}{2} \right]_{t=0}^{3} = \frac{9}{8}$$

$$w_{3} = \int_{t=0}^{3} \frac{(t-0)(t-1)(t-2)}{(3-0)(3-1)(3-2)} dt = \frac{1}{6} \left[\frac{t^{4}}{4} - \frac{3t^{3}}{3} + \frac{2t^{2}}{2} \right]_{t=0}^{3} = \frac{3}{8}$$

Thus,

$$I_3(f) = h\left(\frac{3}{8}f(x_0) + \frac{9}{8}f(x_1) + \frac{9}{8}f(x_2) + \frac{3}{8}f(x_3)\right)$$

$$= \frac{b-a}{24}\left(3f(x_0) + 9f(x_1) + 9f(x_2) + 3f(x_3)\right). \tag{6.1.27}$$

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Newton-Cotes Formulas, V

The n-th order Newton-Cotes integration formula is

$$I_n(f) = h \sum_{i=0}^n w_i f(x_i),$$
 (6.1.28)

where $h = \frac{b-a}{n}$, $x_i = a + ih$, and the coefficients, w_i are shown below.

| n | w_0 | w_1 | w_2 | w_3 | w_4 | w_5 | w_6 |
|---|--------|---------|---------|---------|---------|---------|--------|
| 1 | 1/2 | 1/2 | | | | | |
| 2 | 1/3 | 4/3 | 1/3 | | | | |
| 3 | 3/8 | 9/8 | 9/8 | 3/8 | | | |
| 4 | 14/45 | 64/45 | 24/45 | 64/45 | 14/45 | | |
| 5 | 95/288 | 375/288 | 250/288 | 250/288 | 375/288 | 95/288 | |
| 6 | 41/140 | 216/140 | 27/140 | 272/140 | 27/140 | 216/140 | 41/140 |

Newton-Cotes Formulas, VI

Theorem 6.1.3.

Given the Newton-Cotes integration formula as shown in Eq. (6.1.28), then

$$w_i = w_{n-i}, (6.1.29)$$

$$\sum_{i=0}^{n} w_i = n. {(6.1.30)}$$

Eq. (6.1.29) is due to the symmetry of the quadrature, and Eq. (6.1.30) can be proved by applying to a constant f = 1. In this case

$$I_n(f) = b - a = \frac{b - a}{n} \sum_{i=0}^{n} w_i.$$

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Newton-Cotes Formulas, VII

Theorem 6.1.4.

Given the Newton-Cotes integration formula as shown in Eq. (6.1.28), then the quadrature error is

$$E_n(f) = \frac{h^{n+3} f^{(n+2)}(\xi)}{(n+2)!} \int_0^n t \prod_{i=0}^n (t-i) dt, \quad \text{if } n \text{ is even},$$
 (6.1.31)

$$= \frac{h^{n+2} f^{(n+1)}(\xi)}{(n+1)!} \int_0^n \prod_{i=0}^n (t-i) dt, \quad \text{if } n \text{ is odd.}$$
 (6.1.32)

- Thus, the degree of exactness of Newton-Cotes integration formula is n+1 when n is even; and it is n when n is odd.
- And

$$E_n(f) \approx O(h^{n+3})$$
 when *n* is even, (6.1.33)

$$\approx O(h^{n+2})$$
 when *n* is odd. (6.1.34)

Also note that

$$\int_0^n t \prod_{i=0}^n (t-i)dt < 0, \quad \text{if } n \text{ is even}, \tag{6.1.35}$$

$$\int_0^n \prod_{i=0}^n (t-i)dt < 0, \quad \text{if } n \text{ is odd.}$$
 (6.1.36)

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Composite Newton-Cotes Formulas

- The composite Newton-Cotes Formulas divide the integration interval [a, b] into m subintervals, $[a_i, b_i]$, $i = 0, \dots, m-1$, with $a_0 = a$; $a_{i+1} = b_i = a + (b-a)/m$, $i = 0, \dots, m-2$; $b_{m-1} = b$.
- Then carry out Newton-Cotes integration on each subinterval $[a_i, b_i]$.
- The overall integration is the sum of the integrations of the subintervals.

$$I(f) = \int_{a}^{b} f(x) dx = \sum_{i=0}^{m-1} \int_{a_{i}}^{b_{i}} f(x) dx$$
$$= h \sum_{i=0}^{m-1} \sum_{k=0}^{n} w_{k} f(a_{i} + kh)$$
(6.1.37)

where an n-th order quadrature is assumed and h=(b-a)/mn.

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Composite Newton-Cotes Formulas, II

 The quadrature error of the composite Newton-Cotes Formula can be derived as

Theorem 6.1.5.

Given an $f \in C^{n+2}([a,b])$ the n-th order and m subintervals composite Newton-Cotes formula, then

$$E_{n,m}(f) = \frac{b-a}{(n+2)!} \frac{H^{n+2}}{n^{n+3}} f^{(n+2)}(\xi) \int_0^n t \prod_{i=0}^n (t-i) dt, \quad \text{if } n \text{ is even,}$$
 (6.1.38)

$$= \frac{b-a}{(n+1)!} \frac{H^{n+1}}{n^{n+2}} f^{(n+1)}(\xi) \int_0^n \prod_{i=0}^n (t-i) dt, \quad \text{if } n \text{ is odd}$$
 (6.1.39)

where H = (b - a)/m and $\xi \in (a, b)$.

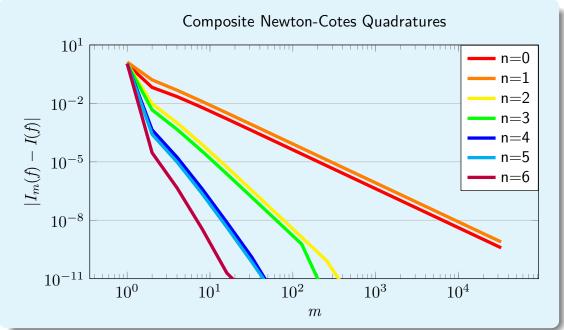
 Thus the composite Newton-Cotes formulas have very significant improvement on quadrature errors.

Composite Newton-Cotes Formulas, III

• The quadrature errors of composite Newton-Cotes quadratures are shown

below

$$I = \int_{0.5}^{1.5} (\log^2(x) + 1) \, dx$$



- Note that n=0 and n=1 quadratures have similar errors
 - So do n=2 and n=3; and n=4 and n=5.
- ullet Higher order quadratures need smaller number of m to get accurate integration

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Summary

- Numerical integration and quadrature formula
- Rectangle formula
 - Composite formula
- Trapezoidal formula
 - Composite formula
- Cavalieri-Simpson formula
- Newton-Cotes formulas
 - Composite formulas