Recorded at time: 1545209024.611 base_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec crane_plus_mounting_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec crane plus internal mounting plate link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec crane_plus_internal_base_bracket_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec crane_plus_internal_shoulder_servo_link Broadcaster: /robot_state_publisher Average rate: 7.021 Hz Most recent transform: 1545209024.515 (0.097 sec old) Buffer length: 4.700 sec crane_plus_shoulder_revolute_link Broadcaster: /robot_state_publisher Average rate: 6.946 Hz Most recent transform: 1545209024.519 (0.093 sec old) Buffer length: 4.895 sec crane_plus_shoulder_flex_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec crane_plus_internal_upper_arm_upper_joiner_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec crane_plus_internal_upper_arm_lower_joiner_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec crane_plus_internal_lower_arm_servo_link Broadcaster: /robot_state_publisher Average rate: 9.168 Hz Most recent transform: 1545209024.440 (0.172 sec old) Buffer length: 4.799 sec crane_plus_elbow_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec crane_plus_internal_lower_arm_joiner_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec crane plus internal wrist servo link Broadcaster: /robot_state_publisher Average rate: 9.807 Hz Most recent transform: 1545209024.551 (0.061 sec old) Buffer length: 4.895 sec crane_plus_wrist_link Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec crane_plus_internal_wrist_joiner_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 1.250 Hz Most recent transform: 1545209024.233 (0.378 sec old) Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec Buffer length: 4.000 sec crane_plus_gripper_link crane_plus_internal_gripper_servo_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 9.193 Hz Most recent transform: 0.000 (1545209024.611 sec old) Most recent transform: 1545209024.568 (0.044 sec old) Buffer length: 0.000 sec Buffer length: 4.895 sec crane plus internal fixed finger_joiner_link crane_plus_moving_finger_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1545209024.611 sec old) Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec crane_plus_internal_fixed_finger_link crane_plus_internal_moving_finger_plate_link Broadcaster: /robot_state_publisher Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz Average rate: 10000.000 Hz Most recent transform: 0.000 (1545209024.611 sec old) Most recent transform: 0.000 (1545209024.611 sec old) Buffer length: 0.000 sec Buffer length: 0.000 sec crane_plus_fixed_finger_tip_link crane_plus_moving_finger_tip_link

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