

**Math 126, Fall 2019**  
**Introduction to Partial Differential Equation**  
Tim Laux, 3106 Etcheverry, 9-10AM

# Contents

1	Introduction	1
---	--------------	---

# Intro

## Question 0.1

Why study PDE?

**Answer 0.2.** TL;DR. It's useful.

**Note 0.3.** Office hour : MWF 9-10AM 895 Evans, GSI Office hour : MW 1-3 PM 1049 Evans

# 1 Introduction

## Question 1.1

What is a partial differential equation?

## Example 1.2

This is an example of ODE:

$$u = u(x), \quad \frac{d}{dx}u = u.$$

## Example 1.3

A PDE consist of the form

$$u = u(x_1, x_2, \dots, x_d), \quad u_{x_k} = \frac{\partial u}{\partial x_k}$$

Where  $x_i$  are scalars.

## Example 1.4

The most general form of a PDE of first order in two dimension, say  $u = u(x, y)$  and of the form

$$F(x, y, u(x, y), u_x(x, y), u_y(x, y)) = 0, \text{ or } F(x, y, u, u_x, u_y) = 0$$

## Example 1.5

The most general form of a PDE of second order in two dimension, say  $u = u(x, y)$  and of the form

$$G(x, y, u, u_x, u_y, u_{xx}, u_{yy}, u_{xy}) = 0$$

**Definition 1.6**

A vector  $x$  is defined as

$$x = \vec{x} = (x_1, x_2, \dots, x_n).$$

**Definition 1.7**

Let  $u$  be a function of vector  $x$  of  $n$ -dimension. The gradient of  $u$  is denoted as

$$\nabla u = (u_{x_1}, u_{x_2}, \dots, u_{x_n})$$

**Example 1.8** 1. Linear transport equation  $u_t + bu_t = 0, \quad b \in \mathbb{R}$

2. Burgher's Equation  $u_t + u \cdot u_x = 0$

3. Laplace's Equation  $u_{xx} + u_{yy} = 0$

4. Hermite Equation  $-(u_{xx} + u_{yy}) = \lambda u, \quad \lambda \in \mathbb{R}$

5. Wave with intersection  $u_{tt} - u_{xx} + u^3 = 0$

6. Linear diffusion with source  $u_t - u_{xx} - f(x, t) = 0$

7. Schroedinger's equation  $u_t - i \cdot u_{xx} = 0$

**Example 1.9 (Cauchy-Riemann Equation)**

$$\begin{cases} u_x &= u_y \\ u_y &= -u_x \end{cases}$$

**Remark 1.10**

Things that we are interested in

1. Find analytical formulas for some specific PDE's
2. Well-possessedness
  - Existence (Does there exists a solution?)
  - Uniqueness (Is this the only solution?)
  - Stability (If I change the data slightly, does the solution changes just by a little bit?)
3. Predicting qualitative (and sometimes quantitative) behavior of the solution without having a solution formula.
4. Devise an analyze numerical algorithms to approximate solutions.

**Remark 1.11** (Digression to Linear Algebra)

Let  $\mathcal{L}$  be a linear operator in a function space.

$$\forall v, u, c \quad \mathcal{L}(u + v) = \mathcal{L}(u) + \mathcal{L}(v), \quad \mathcal{L}(cu) = c\mathcal{L}(u)$$

**Definition 1.12**

A PDE is called homogeneous linear PDE if it's of the form  $\mathcal{L}(u) = 0$ . If it's the form  $\mathcal{L}(u) = f$ , then it's called inhomogeneous PDE.

**Example 1.13**

Consider the equation

$$\cos(xy)u_x + \sin(e^x)u_yy = e^{x^2 \sin(y)}$$

Let

$$\mathcal{L}(u(x, y)) = \cos(xy)u_x + \sin(e^x)u_{yy}$$

$\mathcal{L}$  is a linear operator, so the PDE is an inhomogeneous linear PDE.

**Theorem 1.14** (Principle of superposition)

Let  $u_1, u_2, \dots, u_n$  be solutions of  $\mathcal{L}(u_k) = 0$ , and let  $c_1, c_2, \dots, c_n$  be scalars. then

$$u(x) = \sum_{i=1}^n c_i u_i(x) \quad \text{solves} \quad \mathcal{L}(u) = 0$$

**Example 1.15** (Cool problem)

$$\begin{cases} u_t + u \cdot \nabla u - \mu \Delta u &= -\nabla p \\ \operatorname{div} u &= 0 \end{cases}$$

where  $u = u(x, y, z, t)$ ,  $u = \begin{pmatrix} u_1 \\ u_2 \\ u_3 \end{pmatrix}$  velocity field, where  $p$  is pressure and  $\mu$  is the viscosity of the liquid.

$$u_{yy}u_{xx}$$