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# 1 First-order ODEs

Form: IVP

$$\frac{dy}{dx} = f(x, y)$$
$$y(x_0) = y_0$$

**Test:** f(x,y) and  $\partial f/\partial y$  are continuous over I **Property:** A unique solution is guaranteed over I

## 1.1 Separable Equations

Form:

$$\frac{dy}{dx} = g(x)h(y)$$

**Solution:** Divide by h(y) then integrate with respect to x.

$$\frac{dy}{dx} = g(x)h(y)$$

$$\frac{1}{h(y)}\frac{dy}{dx} = g(x)$$

$$\int \frac{1}{h(y)}\frac{dy}{dx} dx = \int g(x) dx$$

$$\int \frac{1}{h(y)} dy = \int g(x) dx$$

$$H(y) = G(x) + c$$

#### 1.2 Linear Equations

Form:

$$\frac{dy}{dx} + P(x)y = f(x)$$

#### Solution:

- 1. Determine the integrating factor  $e^{\int P(x) dx}$
- 2. Multiply by the integrating factor
- 3. Recognise that the left hand side of the equation is the derivative of the product of the integrating factor and y
- 4. Integrate both sides of the equation
- 5. Solve for y

#### 1.3 Exact Equations

Form:

$$z = f(x, y) = c$$
 
$$dz = \frac{\partial f}{\partial x} dx + \frac{\partial f}{\partial y} dy = M(x, y) dx + N(x, y) dy = 0$$

Test:

$$\frac{\partial M}{\partial y} = \frac{\partial N}{\partial x}$$

#### Solution:

1. Integrate M(x,y) with respect to x to find an expression for z=f(x,y)

$$\frac{\partial f}{\partial x} = M(x, y)$$
  
$$f(x, y) = \int M(x, y) dx + g(y)$$

2. Differentiate f(x,y) with respect to y and equate it to N(x,y) to find g'(y)

$$\frac{\partial f}{\partial y} = N(x, y) = \frac{\partial}{\partial y} \int M(x, y) \, dx + g'(y)$$
$$g'(y) = N(x, y) - \frac{\partial}{\partial y} \int M(x, y) \, dx$$

- 3. Integrate g'(y) with respect to y to find g(y) and substitute it into f(x,y)
- 4. Equate f(x,y) with an unknown constant c

**Note:** The steps can be performed with x and y reversed, i.e. start by integrating N(x,y) with respect to y, etc.

## 1.4 Exact Equations with Integration Constant

Form:

$$M(x,y) dx + N(x,y) dy = 0$$

**Test:**  $(M_y - N_x)/N$  is a function of x alone or  $(N_x - M_y)/M$  is a function of y alone

Solution:

1. Compute the integrating factor

$$\mu(x) = e^{\int \frac{M_y - N_x}{N} \, dx}$$

or

$$\mu(y) = e^{\int \frac{N_x - M_y}{M} \, dy}$$

as appropriate

- 2. Multiple the equation by this factor
- 3. The equation is now exact and can be solved as above

#### 1.5 Homogeneous Equations

Form:

$$M(x,y) dx + N(x,y) dy = 0$$

**Test:** M and N are homogeneous functions of the same degree **Solution:** 

1. Rewrite as

$$M(x,y) = x^{\alpha}M(1,u)$$
 and  $N(x,y) = x^{\alpha}N(1,u)$  where  $u = y/x$ 

or

$$M(x,y) = y^{\alpha}M(v,1)$$
 and  $N(x,y) = y^{\alpha}N(v,1)$  where  $v = x/y$ 

- 2. Substitute y = ux and dy = u dx + x du or x = vy and dx = v dy + y dv as appropriate
- 3. Solve the resulting first-order separable DE
- 4. Substitude u = y/x or v = x/y as appropriate

### 1.6 Bernoulli's Equation

Form:

$$\frac{dy}{dx} + P(x)y = f(x)y^n$$

**Test:**  $n \neq 0$  and  $n \neq 1$ 

Solution:

- 1. Substitude  $y=u^{1/(1-n)}$  and  $\frac{dy}{dx}=\frac{d}{dx}(u^{1/(1-n)})$
- 2. Solve the resulting linear equation
- 3. Substitude  $u = y^{1-n}$

## 1.7 Reduction to Separation of Variables

Form:

$$\frac{dy}{dx} = f(Ax + By + C), B \neq 0$$

Solution:

1. Substitute

$$Ax + By + C = u$$

- 2. Solve the resulting separable equation
- 3. Substitute

$$u = Ax + By + C$$

#### 1.8 Riccati's Equation

Form:

$$\frac{dy}{dx} = P(x) + Q(x)y + R(x)y^2$$

**Test:** You know a particular solution  $y_1$  of the equation **Solution:** 

- 1. Substitute  $y = y_1 + u$  and  $y' = y'_1 + u'$
- 2. Solve the resulting Bernoulli equation
- 3. Substitude  $u = y y_1$

#### 2 Higher-order ODEs

#### Initial Value Problems

Form: *n*-th order IVP

$$a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx_{n-1}} + \dots + a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$$

subject to

$$y(x_0) = y_0, y'(x_0) = y_1, \dots, y^{(n-1)}(x_0) = y_{n-1}$$

**Test:**  $a_n(x), a_{n-1}(x), \ldots, a_0(x), \text{ and } g(x) \text{ are continuous on an interval } I \text{ and } I$  $a_n(x) \neq 0$  for every x in I

**Property:** A unique solution exists for every  $x = x_0$  in I

#### 2.2Linear Independence

**Form:** A set of functions  $f_1, f_2, ..., f_n$ **Test:** The Wronskian  $W(f_1, f_2, ..., f_n) \neq 0$  for every x in an interval I where

$$W(f_1, f_2, \dots, f_n) = \begin{vmatrix} f_1 & f_2 & \cdots & f_n \\ f'_1 & f'_2 & \cdots & f'_n \\ \vdots & \vdots & & \vdots \\ f_1^{(n-1)} & f_2^{(n-1)} & \cdots & f_n^{(n-1)} \end{vmatrix}$$

**Property:** The functions are linearly independent in I

#### 2.3 Homogeneous Linear nth-Order Equations

The general solution is of the form

$$y = c_1 y_1 + c_2 y_2 + \dots + c_n y_n$$

where  $c_i$  are arbitrary constants and  $y_i$  are a fundamental set of solutions (i.e. a set of n linearly independent solutions).

## 2.4 Nonhomogeneous Linear nth-Order Equations

The general solution is of the form

$$y = y_c + y_p = c_1 y_1(x) + c_2 y_2(x) + \dots + c_n y_n(x) + y_p(x)$$

where  $y_c$  is the complementary function (i.e. the general solution of the associated homogeneous equation) and  $y_p$  is a particular solution.

### 2.5 Homogeneous Linear Second-Order Equations

Form:

$$y'' + P(x)y' + Q(x)y = 0$$

**Test:** A non-trivial solution  $y_1(x)$  is known **Solution:** 

1. Recognise that the ratio of two linearly independent functions isn't constant, i.e.

$$u(x) = \frac{y_1(x)}{y_2(x)}$$
 or  $y_2(x) = u(x)y_1(x)$ 

- 2. Substitute  $y_2(x) = u(x)y_1(x)$  into the DE this will result in a DE involving only u'' and u' which can be treated as a linear first-order DE in u' = w
- 3. Solve for w
- 4. Substitute w = u'
- 5. Integrate to find u
- 6. Multiply by  $y_1$  to find  $y_2$

or equivalently

$$y_2 = y_1(x) \int \frac{e^{-\int P(x) dx}}{y_1^2(x)} dx$$

# 2.6 Homogeneous Linear Equations with Constant Coefficients

Form:

$$a_n y^{(n)} + a_{n-1} y^{(n-1)} + \dots + a_1 y' + a_0 y = 0$$

**Solution:** 

1. Assume the equation has a solution of the form  $y = e^{mx}$ , giving

$$a_n m^n e^{mx} + a_{n-1} m^{n-1} e^{mx} + \dots + a_1 m e^{mx} + a_0 e^{mx} = 0$$

2. Divide by  $e^{mx}$ , giving the auxiliary/characteristic equation

$$a_n m^n + a_{n-1} m^{n-1} + \dots + a_1 m + a_0 = 0$$

- 3. Solve for m, where
  - $\bullet$  A real root m corresponds to a solution

$$y = ce^{mx}$$

• A complex root  $\alpha + i\beta$  corresponds to a solution

$$y = e^{\alpha x} (c_1 \cos \beta x + c_2 \sin \beta x)$$

ullet A root m of multiplicity k corresponds to the solutions

$$e^{mx}, xe^{mx}, x^2e^{mx}, \dots, x^{k-1}x^{mx}$$