Vibrations and Waves by George C. King Problems

Chris Doble

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1 Simple Harmonic Motion

1.1

(a) (i)
$$T = 4 \,\mathrm{s}$$

(ii) $\omega = \frac{\pi}{2} \operatorname{rad/s}$

(iii)
$$\omega^2 = \frac{k}{m} \Rightarrow k = m\omega^2 = \frac{\pi^2}{8} \text{ N/m}$$

1.2

(a)

$$x = A \cos \omega t$$

$$= A \cos 2\pi f t$$

$$v = -2\pi f A \sin 2\pi f t$$

$$v_{\text{max}} = 2\pi f A$$

$$= 1.38 \,\text{m/s}$$

(b)

$$a = -4\pi^2 f^2 A \cos 2\pi f t$$

$$a_{\text{max}} = 4\pi^2 f^2 A$$

$$= 3.82 \times 10^3 \,\text{m/s}^2$$

1.3

$$a_{\text{max}} \leq g$$

$$4\pi^2 f^2 A \leq g$$

$$f \leq \sqrt{\frac{g}{4\pi^2 A}}$$

$$\leq 1.11 \,\text{Hz}$$

1.4

(a)

$$\frac{U}{E} = \frac{\frac{1}{2}k(\frac{1}{2}A)^2}{\frac{1}{2}kA^2} = \frac{1}{4} \Rightarrow \frac{K}{E} = \frac{3}{4}$$

- (b) (i) The total energy will increase by a factor of 4
 - (ii) The maximum velocity will increase by a factor of 2
 - (iii) The maximum acceleration will increase by a factor of 2 and the period won't change

(a)
$$E = \frac{1}{2}mv^2 + \frac{1}{2}kx^2 = 0.41 \text{ J}$$

$$E = \frac{1}{2}kA^2$$

$$A = \sqrt{\frac{2E}{k}}$$

$$= 4.5 \text{ cm}$$

$$\omega = \sqrt{\frac{k}{m}}$$

$$= \sqrt{\frac{1600}{3}}$$

$$= \frac{40}{\sqrt{3}}$$

$$= 23 \text{ rad/s}$$

$$x = A \cos(\omega t + \phi)$$

$$\phi = \arccos\left(\frac{x}{A}\right) - \omega t$$

$$= 2.7 \text{ rad}$$

$$x = 0.045 \cos(23t + 2.7) \text{ m}$$

1.6

Using the angular frequency of system (b) ω_b as the baseline, the angular frequency of system (a) ω_a is

$$F = ma = -2kx$$

$$a = -\frac{2k}{m}x$$

$$\omega_a = \sqrt{\frac{2k}{m}}$$

$$= \sqrt{2}\omega_b$$

and the angular frequency of system (c) ω_c is

$$F = ma = -\frac{k}{2}x$$

$$a = -\frac{k}{2m}x$$

$$\omega_c = \sqrt{\frac{k}{2m}}$$

$$= \sqrt{\frac{1}{2}}\omega_b$$

(a) The test tube experiences a bouyancy force of $F=Ag\rho x$ so its equation of motion is

$$F = ma = -Ag\rho x$$

$$a = -\frac{Ag\rho}{m}x$$

$$\omega = \sqrt{\frac{Ag\rho}{m}}$$

(b) The work done by the bouyancy force when moving from equilibrium to x and thus the potential energy is

$$U = \int_0^x Ag\rho x' dx'$$
$$= \frac{1}{2}Ag\rho x^2$$

so the total energy of the system is

$$E = \frac{1}{2}mv^2 + \frac{1}{2}Ag\rho x^2$$

1.8

$$s \propto kg^{\alpha} m^{\beta} (m/s^2)^{\gamma}$$

so $\alpha = 0$, $\beta = 1/2$, and $\gamma = -1/2$ meaning

$$T \propto \sqrt{rac{l}{g}}$$

(a)

$$x = A \cos \sqrt{\frac{g}{l}} t$$

$$v = -\sqrt{\frac{g}{l}} A \sin \sqrt{\frac{g}{l}} t$$

$$v_{\text{max}} = \sqrt{\frac{g}{l}} A$$

$$= 0.018 \,\text{m/s}$$

(b) The pendulum reaches its maximum speed at the bottom of its swing which occurs after a quarter cycle

$$\frac{1}{4}T = \frac{1}{4}\frac{2\pi}{\omega} = \frac{\pi}{2\sqrt{g/l}} = 0.43\,\mathrm{s}$$

1.10

$$I\frac{d^2\theta}{dt^2} = \tau$$

$$\frac{1}{3}ML^2\frac{d^2\theta}{dt^2} = -kL\sin\theta L\cos\theta$$

$$\frac{1}{3}M\frac{d^2\theta}{dt^2} = -k\theta$$

$$\frac{d^2\theta}{dt^2} = -\frac{3k}{M}\theta$$

$$T = \frac{2\pi}{\omega}$$

$$= 2\pi\sqrt{\frac{M}{3k}}$$

(a)

$$F = -\frac{dU}{dx} = -\left(\frac{6a}{x^7} - \frac{12b}{x^{13}}\right)$$
$$0 = \frac{12b}{x^{13}} - \frac{6a}{x^7}$$
$$= \frac{12b}{x^6} - 6a$$
$$6a = \frac{12b}{x^6}$$
$$x^6 = \frac{2b}{a}$$
$$x = \left(\frac{2b}{a}\right)^{1/6}$$

1.12

(a)

$$\begin{split} K &= \frac{1}{2}Mv^2 + \int dK \\ &= \frac{1}{2}Mv^2 + \int_0^L \frac{1}{2}\frac{m}{L} \left(\frac{l}{L}v\right)^2 dl \\ &= \frac{1}{2}Mv^2 + \frac{1}{2}\frac{mv^2}{L^3} \int_0^L l^2 dl \\ &= \frac{1}{2}Mv^2 + \frac{1}{2}\frac{mv^2}{L^3} \frac{1}{3}L^3 \\ &= \frac{1}{2}Mv^2 + \frac{1}{6}mv^2 \\ &= \frac{1}{2}(M+m/3)v^2 \\ E &= K + U \\ &= \frac{1}{2}(M+m/3)v^2 + \frac{1}{2}kx^2 \end{split}$$

(b)

$$\omega = \sqrt{\frac{k}{M + m/3}}$$

$$K = E - U$$

$$\frac{1}{2}mv^2 = U(A) - U(x)$$

$$v = \sqrt{2[U(A) - U(x)]/m}$$

$$\begin{split} T &= 4 \int_0^A \frac{dx}{v} \\ &= 4 \int_0^A \sqrt{\frac{m}{2[U(A) - U(x)]}} \, dx \\ &= 4 \sqrt{\frac{m}{2U(A)}} \int_0^A \frac{dx}{\sqrt{1 - U(x)/U(A)}} \end{split}$$

$$T = 4\sqrt{\frac{m}{2\alpha A^n}} \int_0^A \frac{dx}{\sqrt{1 - (x/A)^n}}$$
$$= 4\sqrt{\frac{m}{2\alpha A^n}} \int_0^1 \frac{A d\xi}{\sqrt{1 - \xi^n}}$$
$$= cA^{(n/2)-1}$$

2 The Damped Harmonic Oscillator

2.1

$$\begin{split} \left(\frac{\gamma}{2}\right)^2 &= \omega_0^2 \\ \frac{b}{2m} &= \sqrt{\frac{k}{m}} \\ b &= 2m\sqrt{\frac{k}{m}} \\ &= 2m\sqrt{\frac{mg/x}{m}} \\ &= 2m\sqrt{\frac{g}{x}} \\ &= 64\,\mathrm{kg/s} \end{split}$$

$$\frac{A_{n+1}}{A_n} = 0.90$$

$$e^{-2.5\gamma/2} = 0.90$$

$$e^{2.5\gamma/2} = \frac{1}{0.90}$$

$$\frac{2.5\gamma}{2} = \ln \frac{1}{0.90}$$

$$\gamma = \frac{2}{2.5} \ln \frac{1}{0.90}$$

$$= 8.43 \times 10^{-2} \text{ s}^{-1}$$

$$F = -bv$$

$$= -(4.21 \times 10^{-2})v$$

2.3

After 10 cycles the amplitude has decreased by a factor of 5/3. The energy of the system is proportional to the amplitude squared, so

$$E(300) = E(0)e^{-300/\tau}$$

$$e^{300/\tau} = \frac{E(0)}{E(300)}$$

$$\tau = \frac{300}{\ln[E(0)/E(300)]}$$

$$= \frac{300}{\ln\frac{25}{9}}$$

$$= 294 \text{ s}$$

$$Q = \omega_0 \tau$$

$$= \frac{2\pi\tau}{T}$$

$$= 61.5$$

$$\frac{E(10T)}{E_0} = \frac{E_0 e^{-\gamma 10T}}{E_0}$$

$$\frac{1}{2} = e^{-\gamma 10T}$$

$$\frac{E(50T)}{E_0} = \frac{E_0 e^{-\gamma 50T}}{E_0}$$

$$= (e^{-\gamma 10T})^5$$

$$= \left(\frac{1}{2}\right)^5$$

$$= \frac{1}{32}$$

2.5

(a)

$$\begin{split} Q_{0.01} &= 310 \\ \omega_{0.01} &= 3.14\,\mathrm{rad/s} \\ Q_{0.30} &= 10.5 \\ \omega_{0.30} &= 3.14\,\mathrm{rad/s} \\ Q_{1.00} &= 3.14 \\ \omega_{1.00} &= 3.10\,\mathrm{rad/s} \end{split}$$

(c)

$$\gamma^{2}/4 = \pi^{2}$$

$$\gamma = 2\pi$$

$$x = Ae^{-\pi t} + Bte^{-\pi t}$$

$$A = 10 \text{ mm}$$

$$v = -10\pi e^{-\pi t} + Be^{-\pi t} - \pi Bte^{-\pi t}$$

$$0 = -10\pi + B$$

$$B = 10\pi$$

$$x = 10e^{-\pi t} + 10\pi te^{-\pi t}$$

$$\frac{\omega}{\omega_0} = \frac{\omega_0 \sqrt{1 - 1/4Q^2}}{\omega_0}$$
$$= \sqrt{1 - 1/4Q^2}$$
$$= 1 - \frac{1/4Q^2}{2} + \cdots$$
$$\approx 1 - \frac{Q^2}{8}$$

2.7

The amplitude of each pendulum decreases over time by a factor of

$$\exp\left(-\frac{\gamma t}{2}\right) = \exp\left(-\frac{bt}{2m}\right)$$

$$= \exp\left(-\frac{bt}{2 \cdot \frac{4}{3}\pi r^3 \rho}\right)$$

$$= \exp\left(-\frac{3bt}{8\pi r^3 \rho}\right)$$

$$= \exp\left(-\frac{3bt}{8\pi r^3}\right)^{1/\rho}.$$

After 10 minutes the amplitude of oscillation of the aluminium pendulum has decreased to half of its initial value

$$\exp\left(-\frac{225b}{\pi r^3}\right)^{1/\rho_a} = \frac{1}{2}$$
$$\exp\left(-\frac{225b}{\pi r^3}\right) = \left(\frac{1}{2}\right)^{\rho_a}$$

so the brass pendulum's amplitude of oscillation has decreased by a factor of

$$\exp\left(-\frac{225b}{\pi r^3}\right)^{1/\rho_b} = \left(\frac{1}{2}\right)^{\rho_a/\rho_b}$$
$$= 0.802$$

(a)

$$\begin{split} x &= A \sin \omega t \\ v &= \omega A \cos \omega t \\ a &= -\omega^2 A \sin \omega t \\ E &= \int_0^T \frac{K e^2 a^2}{c^3} dt \\ &= \int_0^T \frac{K e^2 \omega^4 A^2 \sin^2 \omega t}{c^3} dt \\ &= \frac{K e^2 \omega^4 A^2}{c^3} \int_0^{2\pi/\omega} \sin^2 \omega t dt \\ &= \frac{K e^2 \omega^4 A^2}{c^3} \left[\frac{t}{2} - \frac{1}{4\omega} \sin 2\omega t \right]_0^{2\pi/\omega} \\ &= \frac{K e^2 \omega^3 A^2 \pi}{c^3} \end{split}$$

(b)

$$Q = \frac{\frac{1}{2}m\omega^2 A^2}{\frac{Ke^2\omega^3 A^2\pi}{2\pi c^3}}$$
$$= \frac{c^3m}{e^2K\omega}$$

(c)

$$\tau = \frac{1}{\gamma}$$

$$= \frac{Q}{\omega}$$

$$= \frac{c^3 m}{e^2 K \omega^2}$$

$$= \frac{c^3 m}{e^2 K (2\pi (c/\lambda))^2}$$

$$= \frac{\lambda^2 cm}{4\pi^2 e^2 K}$$

$$\approx 1.13 \times 10^{-8} \text{ s}$$