University Physics with Modern Physics Mechanics Problems

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14 Periodic Motion

14.1 VP14.3.1

a)
$$T = \frac{1}{f} = \frac{1}{4.15} = 0.241\,\mathrm{s}$$

$$\omega = 2\pi f = 2\pi (4.15) = 26.1\,\mathrm{rad/s}$$

b)

$$\omega = \sqrt{\frac{k}{m}}$$

$$\omega^2 = \frac{k}{m}$$

$$m\omega^2 = k$$

$$(0.400)(26.1)^2 = k$$

$$272 \text{ N/m} = k$$

c)

$$F = kx$$
= (272)(0.0200)
= 5.44 N

14.2 VP14.3.2

a)

$$T = 2\pi \sqrt{\frac{m}{k}}$$

$$\frac{T}{2\pi} = \sqrt{\frac{m}{k}}$$

$$\frac{T^2}{4\pi^2} = \frac{m}{k}$$

$$\frac{kT^2}{4\pi^2} = m$$

$$\frac{(4.50)(1.20)^2}{4\pi^2} = m$$

$$0.164 \text{ kg} = m$$

b)

$$F = ma_{\text{max}} = kA$$
$$\frac{ma_{\text{max}}}{k} = A$$
$$\frac{(0.164)(1.20)}{(4.50)} = A$$
$$0.0437 \,\text{m} = A$$

14.3 VP14.3.3

a)

$$\frac{1}{2}mv^2 + \frac{1}{2}kx^2 = \frac{1}{2}kA^2$$

$$\sqrt{\frac{m}{k}v^2 + x^2} = A$$

$$\sqrt{\frac{1}{(2\pi f)^2}v^2 + x^2} = A$$

$$\sqrt{\frac{1}{(2\pi(50.0))^2}(12.4)^2 + (0.0300)^2} = A$$

$$0.0496 \,\mathrm{m} = A$$

b)

$$\frac{1}{2}mv^{2} = \frac{1}{2}kA^{2}$$

$$v = \sqrt{\frac{k}{m}}A$$

$$= 2\pi fA$$

$$= 2\pi (50.0)(0.0496)$$

$$= 15.6 \,\text{m/s}$$

14.4 VP14.3.4

a)

$$f = \frac{1}{2\pi} \sqrt{\frac{k}{m}}$$
$$= \frac{1}{2\pi} \sqrt{\frac{185}{5.00}}$$
$$= 0.968 \,\text{Hz}$$

b)

$$F = ma_{\text{max}} = kA$$

$$\frac{ma_{\text{max}}}{k} = A$$

$$\frac{(5.00)(1.52)}{185} = A$$

$$4.11 \times 10^{-2} \,\text{m} = A$$

14.5 VP14.4.1

a)

$$\frac{1}{2}mv^2 = \frac{1}{2}kA^2$$

$$\sqrt{\frac{m}{k}}v = A$$

$$\sqrt{\frac{0.150}{8.00}}0.350 = A$$

$$4.79 \times 10^{-2} \,\mathrm{m} = A$$

b)
$$\frac{1}{2}mv^2 = \frac{1}{2}(0.150)(0.350)^2 = 9.19 \times 10^{-3} \,\text{J}$$

c)
$$U = \frac{1}{2}kx^2 = \frac{1}{2}(8.00)(0.0300)^2 = 3.60 \times 10^{-3} \,\text{J}$$

$$K = E - U = 9.19 \times 10^{-3} - 3.60 \times 10^{-3} = 5.59 \times 10^{-3} \,\text{J}$$

14.6 VP14.4.2

a)

$$E = \frac{1}{2}kA^{2}$$

$$\frac{2E}{A^{2}} = k$$

$$\frac{2(6.00 \times 10^{-2})}{(0.0440)^{2}} = k$$

$$62.0 \text{ N/m} = k$$

b)

$$E = \frac{1}{2}mv^{2} + \frac{E}{2}$$

$$\sqrt{\frac{E}{m}} = v$$

$$\sqrt{\frac{6.00 \times 10^{-2}}{0.300}} = v$$

$$0.447 \,\text{m/s} = v$$

14.7 VP14.4.3

a)

$$E = \frac{1}{2}kA^{2}$$

$$\frac{2E}{A^{2}} = k$$

$$\frac{2(4.00 \times 10^{-3})}{(0.0300)^{2}} = k$$

$$8.89 \,\text{N/m} = k$$

$$E = \frac{1}{2}mv^2$$

$$\frac{2E}{v^2} = m$$

$$\frac{2(4.00 \times 10^{-3})}{(0.125)^2} = m$$

$$0.512 \,\text{kg} = m$$

b)

$$F = ma = kA$$

$$a = \frac{kA}{m}$$

$$= \frac{(8.89)(0.0300)}{0.512}$$

$$= 0.521 \text{ m/s}^2$$

c)

$$U = \frac{1}{2}kx^2$$

$$\sqrt{\frac{2U}{k}} = x$$

$$F = ma = kx$$

$$a = \frac{\sqrt{2kU}}{m}$$

$$= \frac{\sqrt{2(8.89)(3.00 \times 10^{-3})}}{0.512}$$

$$= 0.451 \,\text{m/s}^2$$

14.8 VP14.4.4

a) At maximum displacement from equilibrium the object's velocity is 0 and all energy is stored in elastic potential energy

$$E = \frac{1}{2}kA^2.$$

The object's kinetic energy will be equal to $\frac{1}{3}$ of its total mechanical energy when its potential energy is equal to $\frac{2}{3}$

$$U = \frac{2}{3}E$$

$$\frac{1}{2}kx^2 = \frac{2}{3}\left(\frac{1}{2}kA^2\right)$$

$$x = \pm\sqrt{\frac{2}{3}}A.$$

b) Similarly, the object's kinertic energy will be equal to $\frac{4}{5}$ of the total mechanical energy when its potential energy is equal to $\frac{1}{5}$

$$U = \frac{1}{5}E$$

$$\frac{1}{2}kx^2 = \frac{1}{5}\left(\frac{1}{2}kA^2\right)$$

$$x = \pm \frac{A}{\sqrt{5}}.$$

14.9 VP14.9.1

a) The period is given by

$$T = \frac{1}{f} = \frac{1}{0.609} = 1.64 \,\mathrm{s}.$$

b) Rearranging the formula for f we find that

$$f = \frac{1}{2\pi} \sqrt{\frac{g}{L}}$$
$$(2\pi f)^2 L = g$$
$$(2\pi (0.609))^2 (0.500) = g$$
$$7.32 \,\text{m/s}^2 = g.$$

14.10 VP14.9.2

The frequency of the air-track glider is given by

$$f = \frac{1}{2\pi} \sqrt{\frac{k}{m}}.$$

The frequency of the simple pendulum is given by

$$f = \frac{1}{2\pi} \sqrt{\frac{g}{L}}.$$

If their frequencies are to be equal then

$$\frac{1}{2\pi}\sqrt{\frac{k}{m}} = \frac{1}{2\pi}\sqrt{\frac{g}{L}}$$
$$\frac{k}{m} = \frac{g}{L}$$
$$L = \frac{gm}{k}$$
$$= \frac{(9.80)(0.350)}{8.75}$$
$$= 0.392 \,\mathrm{m}$$

14.11 VP14.9.3

Assuming the tire is hung from its rim then it is a physical pendulum and

$$\begin{split} f &= \frac{1}{2\pi} \sqrt{\frac{Mgd}{I}} \\ &= \frac{1}{2\pi} \sqrt{\frac{MgR}{2MR^2}} \\ &= \frac{1}{2\pi} \sqrt{\frac{g}{2R}}. \end{split}$$

14.12 VP14.9.4

The rod is a physical pendulum. Rearranging the formula for period we find

$$T = 2\pi \sqrt{\frac{I}{mgd}}$$

$$mgd \left(\frac{T}{2\pi}\right)^2 = I$$

$$(0.600)(9.80)(0.500) \left(\frac{1.59}{2\pi}\right)^2 = I$$

$$0.188 \, \text{kg/m}^2 = I$$

14.13 Bridging Problem

In order for the centre of mass of the cylinders to undergo simple harmonic motion it must experience a net force of the form

$$F = -k'x.$$

The normal and weight forces cancel, leaving only the friction force from the cylinders on the ground f and the restorative force from the spring -kx

$$F = f - kx.$$

The cylinders roll without slipping so

$$\omega = -\frac{v}{R}$$
$$\frac{d}{dt}(\omega) = \frac{d}{dt}(-\frac{v}{R})$$
$$\alpha = -\frac{a}{R}.$$

The friction force generates a torque

$$\tau = I\alpha = fR$$

$$\left(\frac{1}{2}MR^2\right)\left(-\frac{a}{R}\right) = fR$$

$$-\frac{1}{2}Ma = f.$$

Substituting this into the force equation we find that

$$F = Ma = -\frac{1}{2}Ma - kx$$
$$\frac{3}{2}Ma = -kx$$
$$Ma = -\frac{2}{3}kx$$

which matches the required form of F = -k'x where $k' = \frac{2}{3}k$. This gives a period of

$$T = 2\pi \sqrt{\frac{m}{k'}}$$
$$= 2\pi \sqrt{\frac{3m}{2k}}.$$