Dissipation and dispersion in finite difference solutions of hyperbolic PDEs Numerical solutions of PDEs

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Summary

- Hyperbolic problems
 - What is an hyperbolic problem?
 - Some comments
- 2 Finite differences
- Upwind method
- 4 Lax-Wendroff
- 5 Leap-frog

What is an hyperbolic problem?

Usually transport wave-like phenomena with finite speed of propagation. Examples:

- 1d transport/advection eq. $u_t + au_x = 0$
- Conservation laws $u_t + (f(u))_x = 0$
- Wave eq. $u_{tt} + cu_{xx} = 0$

What is an hyperbolic problem?

All of the prevoius can be grouped with the general tranport system of equations:

$$\mathbf{u}_t + A\mathbf{u}_x = 0$$

where A matrix which can depend on t, x, u and has a full set of real eigenvalues.

e.g. for the conservation law equation

$$u_t + (f(u))_x = 0 \Rightarrow u_t + A(u)u_x = 0$$

where $A(u) = \frac{\partial f}{\partial u}$.

Some comments

Hyperbolic problems

- There is no dissipation: $||u(t,\cdot)||_{L_2} = ||u_0||_{L_2}$
- Information propagates at finite speed
- Discontinuites in initial data is propagated ⇒ discontinue solution
- CFL condition necessary for convergence of a finite difference scheme

Finite differences

If the PDE is defined in a domain $I \times \Omega$ where I is the time interval $[0, T_f]$ and Ω is the space domain of one variable [a, b], we can discretize the PDE domain with $N_t \times N_x$ points. We can than define a general explicit difference scheme at time $t = t_n$ as

$$v_j^{n+1} = \sum_{i=-1}^r \beta_i v_{j+i}^n$$

where $j = l, ..., N_x - r - 1$, $n = 0, ..., N_t$ and v_j^n is a mesh function over the discretised domain.

If:

- PDE has constant coefficients
- Problem is defined on infinte mesh or has periodic boundary conditions

Can perform a Fourier analysis of how the difference scheme acts on the initial condition.

If $\hat{v}(t,\xi)$ is Fourier transform of the solution and $\iota=\sqrt{-1}$, we have

$$v(t,x) = \frac{1}{\sqrt{2\pi}} \int_{-\infty}^{\infty} e^{\iota \xi x} \hat{v}(t,\xi) d\xi$$

The difference scheme gives

$$\int_{-\infty}^{\infty} e^{\iota \xi x} \hat{v}(t+\tau,\xi) d\xi = \sum_{i=-l}^{r} \beta_{i} \int_{-\infty}^{\infty} e^{\iota \xi(x+ih)} \hat{v}(t,\xi) d\xi$$

$$= \int_{-\infty}^{\infty} \left(\sum_{i=-l}^{r} \beta_{i} e^{\iota \xi ih} \right) e^{\iota \xi x} \hat{v}(t,\xi) d\xi$$

$$\sum_{i=-l}^{r} \beta_{i} e^{\iota \xi ih} = g(\zeta) \implies \hat{v}(t+\tau,\xi) = g(\zeta) \hat{v}(t,\xi)$$

$$\zeta = \xi h, \ \tau = \frac{T_{f}}{M}, \ h = \frac{b-a}{M}$$

- $||g|| \Rightarrow$ analysis of dissipation of wave numbers
- $Arg(g) \Rightarrow$ analysis of dispersion of wave numbers
- If the PDE has s components than g is an $s \times s$ amplification matrix G. Dissipation and dispersion studied via the eigenvalues of G.

Dissipation and dispersion in the finite difference scheme can occur even if the PDE has not these characteristics.

Advection equation

Consider the advection equation equipped with initial and boundary condition:

$$\begin{cases} u_t + au_x = 0, & x, t \in [a, b] \times [0, T_f] \\ u(0, x) = u_0, & x \in [a, b] \end{cases}$$

Boundary condition depends on the sign of a. e.g. if a>0 the boundary condition reads $u(a,t)=f(t) \ \forall \ t \in [0,T_f]$

Upwind method

Considering a discretization of $[0, T_f] \times [a, b]$ and that U_j^n is mesh function approximating u solution of PDE we can discretize the operators as follows:

$$\begin{cases} \frac{U_j^{n+1} - U_j^n}{\tau} = \frac{U_j^n - U_{j-1}^n}{h}, & \text{if } a > 0\\ \\ \frac{U_j^{n+1} - U_j^n}{\tau} = \frac{U_{j+1}^n - U_j^n}{h}, & \text{if } a < 0 \end{cases}$$

$$n = 0, ..., N_t - 1$$

Upwind method

Can be rewritten as:

$$U_j^{n+1} = \begin{cases} (1-\nu)U_j^n + \nu U_{j-1}^n & \text{if } a > 0\\ (1+\nu)U_j^n - \nu U_{j+1}^n & \text{if } a < 0 \end{cases}$$

where
$$\nu = a \frac{\tau}{h}, \ n = 0, ..., N_t - 1$$

Amplification factor for a > 0 is $g(\zeta) = (1 - \nu) + \nu e^{-\iota \xi h}$:

- $\|g\| \le 1 \ \forall \ \xi \iff 0 \le |\nu| \le 1$
- Dissipative scheme
- Monotone scheme: if $\nu \leq 1 \Rightarrow \max_{j} |v_{j}^{n+1}| \leq \max_{j} |v_{j}^{n}|$ \Rightarrow stability even if $a = a(x, t) \iff |a_{i}^{n} \frac{\tau}{h}| \leq 1$
- $Arg(g) = -\tan^{-1}\left(\frac{\nu\sin\xi h}{(1-\nu) + \nu\cos\xi h}\right)$

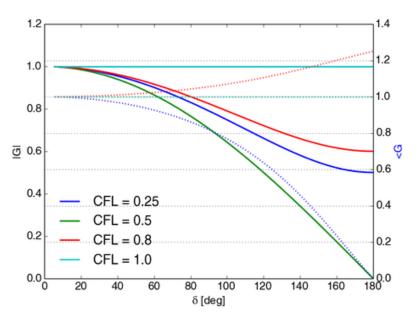
PDE admits plane-wave solutions of the form

$$u(t,x) = e^{\iota(\xi x + \omega t)}$$

where $\xi =$ wave number, $\omega =$ frequency.

PDE imposes the **dispersion relation** $\omega = \omega(\xi)$ and **phase velocity** $c = \frac{\omega}{\xi}$. e.g. Advection eq. imposes $\omega = -a\xi$ and c = -aindependent on wave number.

To study dispersion, we can study the ratio $\phi_e = \frac{Arg(g)}{c}$



Dissipation can be explained also as follows:

$$0 = \frac{U_j^{n+1} - U_j^n}{\tau} + a \frac{U_j^n - U_{j-1}^n}{h} =$$

$$= \frac{U_j^{n+1} - U_j^n}{\tau} + a \frac{U_{j+1}^n - U_{j-1}^n}{2h} - \frac{a * h}{2} \frac{U_{j+1}^n - 2U_j^n + U_{j-1}^n}{h^2}$$

i.e. it is a difference scheme for the parabolic PDE

$$u_t + au_x - \frac{ah}{2}u_{xx} = 0$$

So upwind scheme pollutes PDE with artificial diffusion.

Lax-Wendroff

It takes the form

$$U_j^{n+1} = \frac{1}{2}\nu(1+\nu)U_{j-1}^n + (1-\nu^2)U_j^n - \frac{1}{2}\nu(1-\nu)U_{j+1}^n$$

Can be rewritten as

$$\frac{U_i^{n+1} - U_i^n}{\tau} + a \frac{U_{i+1}^n - U_{i-1}^n}{2h} - \frac{\tau a^2}{2} \frac{U_{i+1}^n - 2U_i^n + U_{i-1}^n}{h^2} = 0$$

So it approximates the PDE $u_t + au_x = \frac{\tau a^2}{2}u_{xx}$. Comparing with upwind:

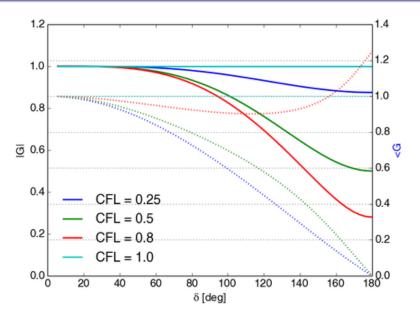
$$\frac{|a|}{2} = \frac{|a|\tau}{2\nu} = \frac{a^2\tau}{2|a|\nu} \ge \frac{a^2\tau}{2}$$

So LW expected to be less dissipative.

Amplification factor

$$g(\zeta) = 1 - 2\eta^2 \sin^2 \frac{1}{2} \zeta - \iota \eta \sin \zeta$$

- $|g|^2 = 1 4\nu^2(1 \nu^2)\sin^4\frac{1}{2}\zeta \le 1 \iff |\nu| \le 1$ Order of amplitude error ζ^4 when $\zeta = h\xi$ small
- $Arg(g) = -\tan^{-1} \frac{\nu \sin \zeta}{1 2\nu^2 \sin^2 \frac{1}{2}\zeta}$





Lax-Wendroff with variable coefficient

Now
$$a = a(x, t)$$

Leap-frog scheme

$$\frac{U_j^{n+1} - U_j^{n-1}}{2\tau} + a \frac{U_{j+1}^n - U_{j-1}^n}{2h} = 0$$

Oss.: need special procedure to obtain U_1 , e.g. with Lax-Wendroff

conservation law - burgers

Leap-frog ○●○ bibliography