# Appendix: The Slow and The Furious? Performance Antipattern Detection in Cyber-Physical Systems

Imara van Dinten<sup>a,\*</sup>, Pouria Derakhshanfar<sup>b</sup>, Annibale Panichella<sup>a</sup>, Andy Zaidman<sup>a</sup>

<sup>a</sup> Delft University of Technology, Van Mourik Broekmanweg 6, 2628 XE, Delft, The Netherlands <sup>b</sup> JetBrains Research, Huidekoperstraat 26-28, 1017 ZM, Amsterdam, The Netherlands

#### 1. Introduction

This appendix consists of additional tables and information for Study I of the paper "The Slow and The Furious? Performance Antipattern Detection in Cyber-Physical Systems".

#### 1.1. Appendix Structure

The appendix is structured as follows: Section 2 describes the keywords selected during the Initial Keyword Selection, Section 3 shows examples of the keywords selected during Keyword Expansion, Section 4 expands on the Commits selected and their relationship with the total number of Commits.

#### List of Tables

| 1 | From the Initial Keyword Set: the number of occurrence of each keyword and instances a   |   |
|---|--|---|
|   | commit containing this keyword also contained a antipattern                              | 2 |
| 2 | Example of Topic Modelling from the PX4-Autopilot project, highlighted are the words se- |   |
|   | lected   | 2 |
| 3 | Resulting the Keyword Expansion, shown are the additional set of keywords per project    | 3 |
| 4 | Expanded project information visualizing the commit results                              | 3 |

### 2. Initial Keyword Selection

This section relates to the paper's section 3.2.1 "Initial Keyword Selection".

From the Initial Keyword Set, the number of occurrences of each keyword is visualized in Table 1. Further, shown in this table is the number of instances a commit containing this keyword also contained an antipattern.

We decided to share this information in the appendix as this might be of interest as a motivation for future research towards a link between keywords and antipatterns.

## 3. Keyword Set Expansion with Information Retrieval and Topic Modeling

This section relates to the paper's section 3.2.2 "Keyword Set Expansion with Information Retrieval and Topic Modeling". As decribed in the paper, we applied Information Retrieval (IR) and Topic Modeling (TM) techniques to expand our set of keywords.

As an example, three topics from the PX4-Autopilot project are shown in Table 2. From these three topics, the words *size* and *rate* have been chosen. The full analysis of each project is publically available on GitHub <sup>1</sup>. The TM process resulted in a selection of keywords, for each project, as shown in Table 3.

<sup>\*</sup>Corresponding author

Email addresses: I.vanDinten@tudelft.nl (Imara van Dinten, A.Panichella@tudelft.nl (Annibale Panichella)

<sup>1</sup> https://github.com/ciselab/CPS\_repo\_mining/tree/main/T-Model

| Keyword     | Occur | rences           | Antipatterns |          |  |  |
|-------------|-------|------------------|--------------|----------|--|--|
| •           | Total | $\mathbf{First}$ | None         | Detected |  |  |
| increase    | 481   | 398              | 115          | 283      |  |  |
| memory      | 239   | 230              | 154          | 76       |  |  |
| performance | 101   | 98               | 58           | 40       |  |  |
| faster      | 84    | 65               | 29           | 36       |  |  |
| fast        | 74    | 57               | 39           | 18       |  |  |
| slow        | 69    | 57               | 32           | 25       |  |  |
| runtime     | 50    | 46               | 42           | 4        |  |  |
| decrease    | 53    | 33               | 11           | 22       |  |  |
| hang        | 144   | 19               | 17           | 2        |  |  |
| infinite    | 17    | 15               | 11           | 4        |  |  |
| overhead    | 28    | 14               | 8            | 6        |  |  |
| slower      | 15    | 12               | 6            | 6        |  |  |
| deadlock    | 10    | 9                | 3            | 6        |  |  |
| speed       | 60    | 1                | 0            | 1        |  |  |
| memory leak | 36    | 1                | 1            | 0        |  |  |
| increases   | 5     | 1                | 0            | 1        |  |  |
| stuck       | 3     | 1                | 1            | 0        |  |  |
| slowing     | 2     | 2                | 2            | 0        |  |  |
| bottleneck  | 3     | 0                | _            | -        |  |  |
| memory-heap | 0     | 0                | _            | -        |  |  |
| memory-leak | 0     | 0                | _            | -        |  |  |
| livelock    | 0     | 0                | _            | -        |  |  |
| impasse     | 0     | 0                | -            | -        |  |  |
| Total       | 1474  | 1059             | 529          | 530      |  |  |

|    | Topic 1                  | Topic 2                 | Topic 3              |
|----|--------------------------|-------------------------|----------------------|
| 1  | param                    | stack                   | control              |
| 2  | config                   | $\log$                  | mode                 |
| 3  | default                  | $\mathbf{size}$         | attitude             |
| 4  | romfs                    | reduce                  | fw                   |
| 5  | startup                  | $\log ger$              | vtol                 |
| 6  | parameters               | sdlog                   | controller           |
| 7  | params                   | output                  | pos                  |
| 8  | board                    | logging                 | rate                 |
| 9  | configs                  | px                      | manual               |
| 10 | $\operatorname{script}$  | buffer                  | land                 |
| 11 | $\operatorname{start}$   | usage                   | offboard             |
| 12 | $\operatorname{trigger}$ | $\operatorname{adjust}$ | $\operatorname{att}$ |
| 13 | info                     | queue                   | transition           |
| 14 | exclude                  | $\operatorname{start}$  | throttle             |
| 15 | rcs                      | $\operatorname{debug}$  | tecs                 |
| 16 | meta                     | space                   | detector             |
| 17 | airframe                 | verbose                 | parameter            |
| 18 | scripts                  | dataman                 | estimator            |
| 19 | vtol                     | priority                | altitude             |
| 20 | camera                   | ensure                  | wing                 |

Table 1: From the Initial Keyword Set: the number of occurrence of each keyword and instances a commit containing this keyword also contained a antipattern.

Table 2: Example of Topic Modelling from the PX4-Autopilot project, highlighted are the words selected.

## 4. Expanded table of commit results

This section relates to the paper's section 3.4 "Results". As described in the paper, the PyRock tool returned a number of commits that potentially contain performance issues. Table 4 visualizes the total number of commits of each project ① with the number of selected commits (by PyRock) ②, false positives ③ and true positives ④, and the number of performance issues found ⑤. A single commit can contain more than one performance issue. Therefore, the number of performance issues found in a project can exceed the number of true positive commits.

| Projects             | Words (Nr. of Antipatterns/Nr. of Commits)   |
|----------------------|--|
| PX4-Autopilot        | size $(26/277)$ , rate $(50/355)$ , speed $(7/175)$ , timeout $(38/134)$ , unneeded  |
|                      | (1/62)   |
| Andruino-esp32       | corrected $(1/4)$ , optimize $(0/7)$ , wrong $(0/18)$ , size $(0/30)$ , timeout $(3/15)$ , timer $(0/16)$ , iot $(0/11)$   |
| Grbl                 | cleaned $(2/16)$ , reflect $(0/7)$ , caused $(0/2)$ , changed $(0/10)$ , error $(0/24)$ ,  |
|                      | refactored $(0/12)$ , override $(0/6)$ , cleanup $(0/8)$ , tidying $(0/2)$ , optimiza-   |
|                      | tion $(0/7)$ , disabling $(0/4)$ , size $(0/10)$ , edit $(0/17)$ , edits $(0/6)$ , speed   |
|                      | (0/11), improved $(0/9)$ , rate $(1/17)$ , computation $(0/2)$ , clean $(1/29)$ ,  |
| Dronekit Android     | tweaks $(0/5)$ , optimized $(1/5)$ , corrected $(0/6)$ , realtime $(0/2)$ cleaned $(0/24)$ , broken $(0/11)$ , speed $(2/26)$  |
|                      | 1  |
| Node AR Drone        | missing $(0/4)$ , errors $(0/6)$ , simplify $(0/2)$ , timeout $(1/4)$ , drop $(0/4)$ ,   |
|                      | explicit $(0/2)$ , expose $(0/3)$ , size $(0/4)$ , pave $(0/5)$ , wip $(0/2)$ , increased $(1/2)$ , broken $(0/2)$ , fixes $(0/5)$ , failing $(0/2)$ , check $(0/4)$ |
| Android App Manager  | improved $(0/3)$ , failure $(0/2)$   |
| Cylon                | halting $(0/3)$ , improve $(0/17)$   |
| Johnny Five          | clock $(0/6)$ , scaling $(2/8)$ , duration $(0/5)$ , improved $(1/17)$ , nitpicking  |
|                      | (0/11), sensitivity $(1/12)$ , time $(3/56)$ , speed $(3/20)$  |
| Robonomics-JS        | -  |
| Robonomics-Contracts | cleaning $(0/2)$ , expenses $(0/3)$  |
| Vacuum Robot Mark II | unnecessary $(0/2)$  |
| TurtleBot            | convenient $(0/2)$ , cleanup $(0/13)$ , compatibility $(0/4)$  |
| TurtleBot 3          | compatibility $(0/4)$ , rate $(9/10)$ , inertia $(1/4)$ , frequency $(4/4)$ , size   |
|                      | (2/2), limit $(1/3)$   |
| Valetudo             | time $(1/35)$ , timers $(0/9)$ , speed $(0/14)$ , timer $(0/16)$ , improve $(0/19)$  |

 ${\it Table 3: Resulting the Keyword Expansion, shown are the additional set of keywords per project.}$ 

|                      | 1       | 2        |          | 3         |           | 4         |          | 5      |
|----------------------|---------|----------|----------|-----------|-----------|-----------|----------|--------|
|                      | # of    | Analysed |          | False     |           | True      |          | # of   |
| Project Name         | Commits | Commits  |          | Positives |           | Positives |          | Issues |
| PX4-Autopilot        | 35537   | 1869     | (5.26%)  | 1297      | (69.40%)  | 572       | (30.60%) | 653    |
| Andruino-esp32       | 1747    | 140      | (8.01%)  | 114       | (81.43%)  | 26        | (18.57%) | 29     |
| Grbl                 | 699     | 217      | (31.04%) | 199       | (91.71%)  | 18        | (8.29%)  | 27     |
| DroneKit Android     | 5810    | 99       | (1.70%)  | 88        | (88.89%)  | 11        | (11.11%) | 11     |
| Node AR Drone        | 281     | 48       | (17.08%) | 47        | (97.92%)  | 1         | (2.08%)  | 2      |
| Android App Manager  | 231     | 7        | (3.03%)  | 6         | (85.71%)  | 1         | (14.29%) | 2      |
| Cylon                | 1323    | 21       | (1.59%)  | 21        | (100.00%) | 0         | (0.00%)  | 0      |
| Johnny Five          | 3355    | 147      | (4.38%)  | 131       | (89.12%)  | 16        | (10.88%) | 14     |
| Robonomics-JS        | 68      | 0        | (0.00%)  | 0         | (0.00%)   | 0         | (0.00%)  | 0      |
| Robonomics-Contracts | 502     | 7        | (1.39%)  | 7         | (100.00%) | 0         | (0.00%)  | 0      |
| Vacuum Robot Mark II | 54      | 2        | (3.70%)  | 2         | (100.00%) | 0         | (0.00%)  | 0      |
| TurtleBot            | 1142    | 24       | (2.10%)  | 20        | (83.33%)  | 4         | (16.67%) | 4      |
| TurtleBot 3          | 526     | 27       | (5.13%)  | 10        | (37.04%)  | 17        | (62.96%) | 21     |
| Valetudo             | 1043    | 91       | (8.72%)  | 84        | (92.31%)  | 7         | (7.69%)  | 7      |
| Total                | 52318   | 2699     | (5.16%)  | 2026      | (75.06%)  | 673       | (24.94%) | 770    |

Table 4: Expanded project information visualizing the commit results.