

Optimization Project: Support Vector Machine

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January 12th, 2017

1 Project description

- Project
- Optimization problem
- Implementation

2 Results

- Testing the implementation
- Plotting the classification frontier

3 Extensions

- Cross Validation
- Coordinate Descent
- ACCPM

4 Demo

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Project

Support Machine Vector

Objective

Classify data

Project

Support Machine Vector

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Classify data

- Applied to **binary classification** ($y_i \in \{1, -1\}$);

Project

Support Machine Vector

Objective

Classify data

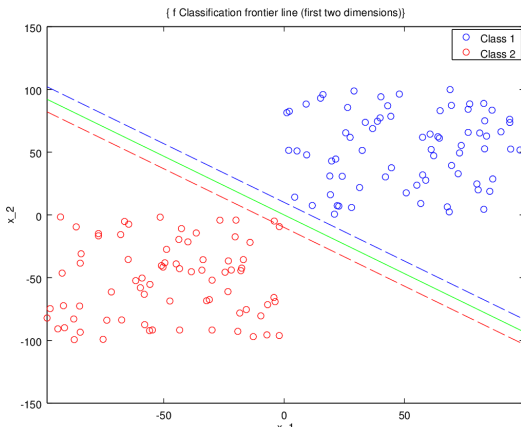
- Applied to **binary classification** ($y_i \in \{1, -1\}$);
- Looking for a **hyperplane** $f : x \rightarrow \omega^T x (+b)$ such as:

$$\forall i, f(x_i) = \begin{cases} < 0 & \text{si } y_i = -1 \\ > 0 & \text{si } y_i = 1 \end{cases} \Leftrightarrow \forall i, y_i \times f(x_i) > 0 \quad (1)$$

Project

Support Machine Vector

Figure: Example with two classes (**red** and **blue**)



Optimization problem

Looking for the optimization problem

Naive optimization problem

γ : distance between the lines $f(x) = 1$ and $f(x) = -1$.

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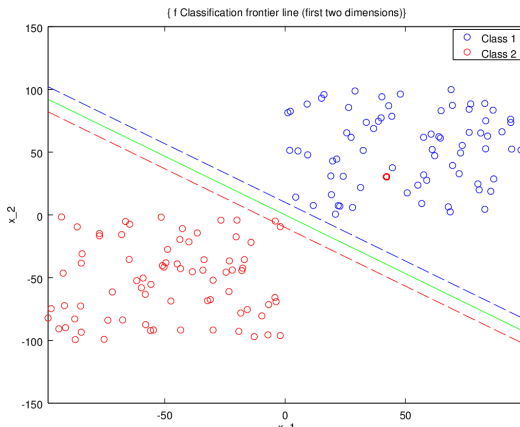
$$\begin{aligned} \Leftrightarrow \min_{\omega} \frac{1}{2} \|\omega\|^2 \\ \text{subject to } \forall i, y_i \times f(x_i) &> 0 \end{aligned}$$

Beware: if the data set is not linearly separable!

Optimization

Looking for the optimization problem

Figure: Example with two classes (**red** and **blue**)



Optimization problem

Adapting the problem to **non-separable** sets

Let z_i be $\max(0, 1 - y_i \times f(x_i))$ (**Hinge loss**).

Optimization problem

Adapting the problem to **non-separable** sets

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Having the problem **convex** and always **feasible**

Penalty for **classification errors** with $(z_i)_i$ and C :

$$\begin{aligned} \min_{\omega, z} \quad & \frac{1}{2} \|\omega\|^2 + C \sum_{i \leq m} z_i \\ \text{subject to} \quad & \\ & \forall i, z_i \geq 0 \\ & \forall i, y_i \times (\omega^T x_i) \geq 1 - z_i \end{aligned}$$

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Implementation

Solving the optimization problem

- Use **Newton's method**:

Reminder: Update of x with **Newton's method**

$$x_{n+1} \leftarrow x_n + s \times \nabla^2 \text{obj}(x_n)^{-1} \nabla \text{obj}(x_n)$$

(finding **step size** value s by **backtracking line search**)

Implementation

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- Make the problem independant from **dimension**;

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- Make the problem independent from **dimension**;
- Use **logarithmic barrier method**.

Implementation

Independence from dimension: **dual problem**

After Lagrangian calculation and minimization in ω :

Implementation

Independence from dimension: **dual problem**

After Lagrangian calculation and minimization in ω :

Dual problem

$$\begin{aligned} \max_{\lambda \in \mathbb{R}^{+m}} & -\frac{1}{2} \left\| \sum_i \lambda_i y_i x_i \right\|_2^2 + \mathbf{1}^T \lambda \\ \text{subject to } & \forall i, 0 \leq \lambda_i \leq C \\ & \text{(KKT conditions)} \end{aligned}$$

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Independence from dimension: **dual problem**

After Lagrangian calculation and minimization in ω :

Dual problem

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Get **primal solution** from dual solution

$$\omega^* = \sum_i \lambda_i^* y_i x_i$$

Implementation

Make the problem independant from dimension

Use the **kernel trick** :

Dual problem

Let K be $X^T X$ (linear kernel):

$$\begin{aligned} \max \quad & -\frac{1}{2} \lambda^T \text{diag}(y) K \text{diag}(y) \lambda + \mathbf{1}^T \lambda \\ \text{subject to} \quad & \forall i, 0 \leq \lambda_i \leq C \end{aligned}$$

Implementation

Delete inequality constraints

Use the **logarithmic barrier method** :

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Delete inequality constraints

Use the **logarithmic barrier method** :

Barrier function

$$\begin{aligned}\Phi(\lambda) &= \sum_i (-\log(C - \lambda_i) - \log(\lambda_i)) \\ &= -\sum_i \log((C - \lambda_i)\lambda_i)\end{aligned}$$

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Delete inequality constraints

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Final optimization problem

$$\max -\frac{1}{2}\lambda^T \text{diag}(y)K\text{diag}(y)\lambda + \mathbf{1}^T \lambda + \Phi(\lambda)$$

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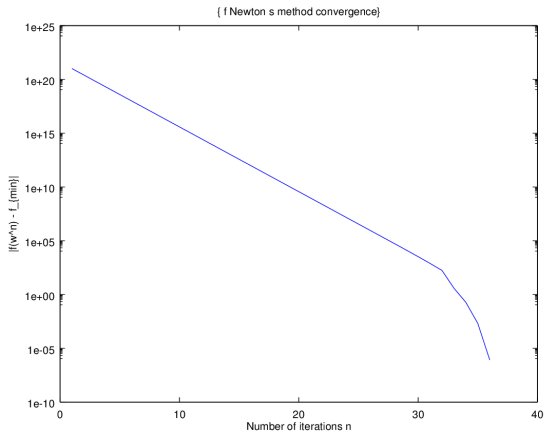
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Testing the implementation

Newton's method convergence



Testing the implementation

Dependence on the sample size

Table: Time complexity dependence

Set	C	d	n	Iteration number	Time (s)
1	5	40000	10	11	0.315
1	5	40	100	12	0.715
1	5	40	1000	large	> 1,000

Testing the implementation

Performance in function of C

Performed on the same sample set:

Table: Computation time & Performance in function of C

C	Time (s)	Training Error	Val Error	Test Error
1	132.15	6	2	3
10	0.74	6	2	3
100	0.89	1	12	3

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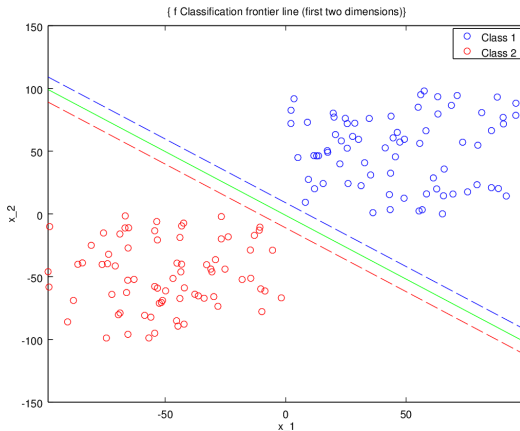
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Plotting the **classification frontier**

For $C = 5$, $n = 150$, $d = 200$

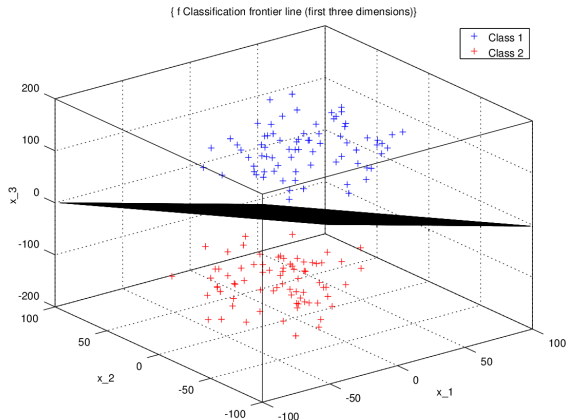
Normalized points with Gaussian distribution (2D):



Plotting the **classification frontier**

For $C = 5$, $n = 150$, $d = 200$

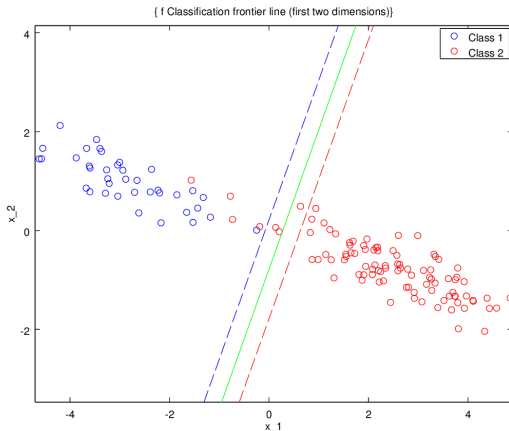
Normalized points with Gaussian distribution (3D):



Plotting the **classification frontier**

Pour $C = 5, n = 100, d = 2$

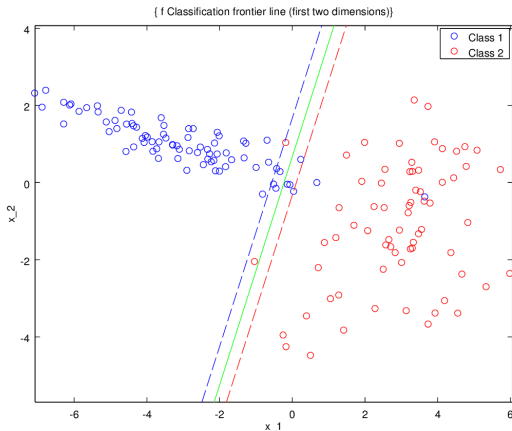
Generation with Gaussian distribution (2D) (set A) :



Plotting the **classification frontier**

Pour $C = 5, n = 100, d = 2$

Generation with Gaussian distribution (2D) (set B) :



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Cross Validation

- **Cross validation** (choice of the best value for C);

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Cross Validation

- **Cross validation** (choice of the best value for C);

Leave-one-out technique

Having a sample size of size n , for each value of C to test:

- 1 for $i \in [1, n]$
- 2 **Leave out sample i**
- 3 Train the SVM on other samples
- 4 Test the SVM on sample i
- 5 Get the **Mean-Squared Error** for the n loops
- 6 If it is the minimum MSE computed so far
- 7 Then update the best value of C

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Coordinate Descent

- Implementation of **Coordinate Descent**;

Extensions

Coordinate Descent

■ Implementation of **Coordinate Descent**;

Reminder: Coordinate Descent

for $i, j \in [1, d]$, and iteration k

$$\begin{aligned} a_i^{k+1} &= \operatorname{argmin}_{a_i} f(a_1, a_2, \dots, a_i, \dots, a_d) \\ a_j^{k+1} &= a_j^k \text{ for } j \neq i \end{aligned}$$

Extensions

Coordinate Descent results

Performed on the same sample set (as in the testing of the original SVM):

Table: Computation time & Performance in function of C

C	Time (s)	Training Error	Val Error	Test Error
1	0.37	11	6	5.33
10	0.34	5	4	3.39
100	0.29	1	8	3.56
10,000	0.29	6	4	2.76

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Extensions

ACCPM

- Implementation of **Analytic Center Cutting-Plane Method**;

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ACCPM

- Implementation of **Analytic Center Cutting-Plane Method**;

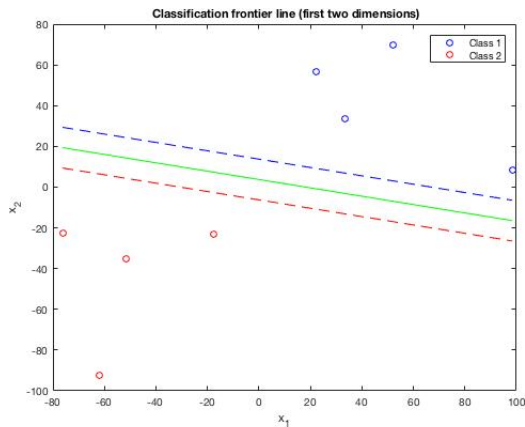
Reminder: ACCPM

- 1 Compute the **analytic center of constraint polyhedron**
- 2 Compute the objective value and the gradient
- 3 While objective value is evolving greatly enough
- 4 Add an inequality to constraint polyhedron
- 5 Optional: **Constraint Dropping**

Extensions

ACCPM results

Figure: For data of size 8, and dimension 2



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Demo of the SVM