

Optimization Project: Support Vector Machine

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January 12th, 2017

1 Project description

- Project
- Optimization problem
- Implementation

2 Results

- Testing the implementation
- Plotting the classification frontier

3 Extensions

4 Demo

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Project

Support Machine Vector

Objective

Classify data

Project

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- Applied to **binary classification** ($y_i \in \{1, -1\}$);

Project

Support Machine Vector

Objective

Classify data

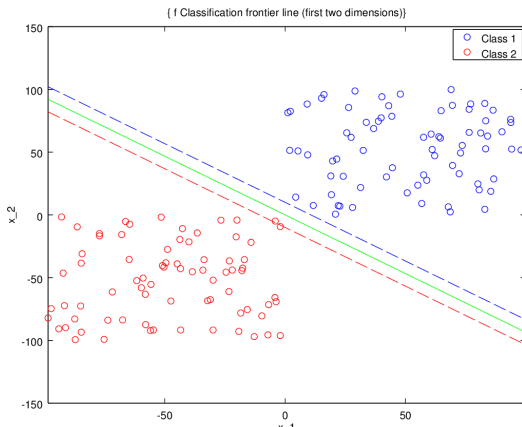
- Applied to **binary classification** ($y_i \in \{1, -1\}$);
- Looking for a **hyperplane** $f : x \rightarrow \omega^T x$ such as:

$$\forall i, f(x_i) = \begin{cases} < 0 & \text{si } y_i = -1 \\ > 0 & \text{si } y_i = 1 \end{cases} \Leftrightarrow \forall i, y_i \times f(x_i) > 0 \quad (1)$$

Project

Support Machine Vector

Figure: Example with two classes (**red** and **blue**)



Optimization problem

Looking for the optimization problem

Naive optimization problem

γ : distance between the lines $f(x) = 1$ and $f(x) = -1$.

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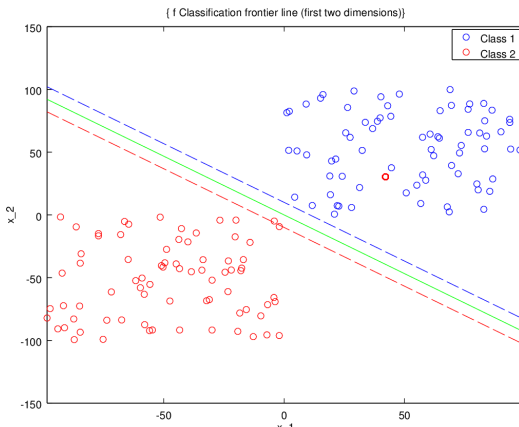
$$\begin{aligned} \Leftrightarrow \min_w \frac{1}{2} \|w\|^2 \\ \text{subject to } \forall i, y_i \times f(x_i) &> 0 \end{aligned}$$

Beware: if the data set is not linearly separable!

Optimization

Looking for the optimization problem

Figure: Example with two classes (red and blue)



Optimization problem

Adapting the problem to **non-separable** sets

Let z_i be $\max(0, 1 - y_i \times f(x_i))$ (**Hinge loss**).

Optimization problem

Adapting the problem to **non-separable** sets

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Having the problem **convex** and always **feasible**

Penalty for **classification errors** with $(z_i)_i$ and C :

$$\begin{aligned} \min_{w,z} \quad & \frac{1}{2} \|w\|^2 + C \sum_{i \leq m} z_i \\ \text{subject to} \quad & \\ & \forall i, z_i \geq 0 \\ & \forall i, y_i \times (\omega^T x_i) \geq 1 - z_i \end{aligned}$$

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Implementation

Solving the optimization problem

- Use **Newton's method** to find ω :

Reminder: Update of ω with **Newton's method**

$$\omega_{n+1} \leftarrow \omega_n + s \times \nabla^2 \text{obj}(\omega_n)^{-1} \nabla \text{obj}(\omega_n)$$

(finding **step size** value s by **backtracking line search**)

Implementation

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- Make the problem independent from **dimension**;
- Use **logarithmic barrier method**.

Implementation

Independence from dimension: **dual problem**

After Lagrangian calculus and minimization in ω :

Implementation

Independence from dimension: **dual problem**

After Lagrangian calculus and minimization in ω :

Dual problem

$$\begin{aligned} \max_{\lambda \in \mathbb{R}^+{}^m} & -\frac{1}{2} \left\| \sum_i \lambda_i y_i x_i \right\|_2^2 + \mathbf{1}^T \lambda \\ \text{subject to } & \forall i, 0 \leq \lambda_i \leq C \\ & \text{(KKT conditions)} \end{aligned}$$

Implementation

Independence from dimension: **dual problem**

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Dual problem

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Get **primal solution** from dual solution

$$\omega^* = \sum_i \lambda_i^* y_i x_i$$

Implementation

Make the problem independant from dimension

Use the **kernel trick** :

Dual problem

Let K be $X^T X$ (linear kernel):

$$\begin{aligned} \max \quad & -\frac{1}{2} \lambda^T \text{diag}(y) K \text{diag}(y) \lambda + \mathbf{1}^T \lambda \\ \text{subject to} \quad & \forall i, 0 \leq \lambda_i \leq C \end{aligned}$$

Implementation

Delete inequality constraints

Use the **logarithmic barrier method** :

Implementation

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Use the **logarithmic barrier method** :

Barrier function

$$\begin{aligned}\Phi(\lambda) &= \sum_i (-\log(C - \lambda_i) - \log(\lambda_i)) \\ &= -\sum_i \log((C - \lambda_i)\lambda_i)\end{aligned}$$

Implementation

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Final optimization problem

$$\max -\frac{1}{2}\lambda^T \text{diag}(y)K\text{diag}(y)\lambda + \mathbf{1}^T \lambda + \Phi(\lambda)$$

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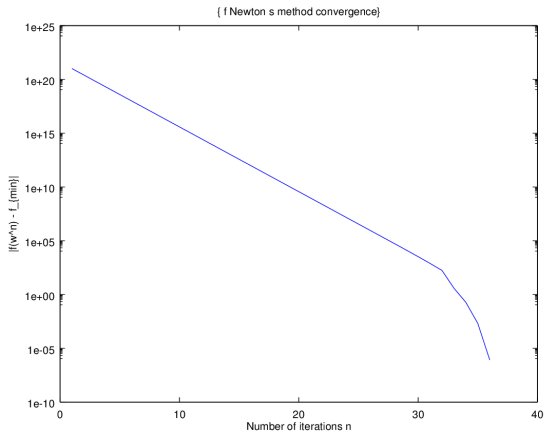
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Testing the implementation

Newton's method convergence



Testing the implementation

Dependence on the sample size

Table: Time complexity dependence

Set	C	d	n	Iteration number	Time
1	5	40000	10	11	0.315
1	5	40	100	12	0.715
1	5	40	1000	large	> 1,000

Testing the implementation

Speeding of convergence when C increases

Performed on the same sample set:

Table: Computation time in function of C

Test Set	C	d	n	#iterations	Time	Fail (%)
1	1	40	10	11	25.414	0
1	5	40	10	11	0.177	0
1	10	40	10	11	0.168	0

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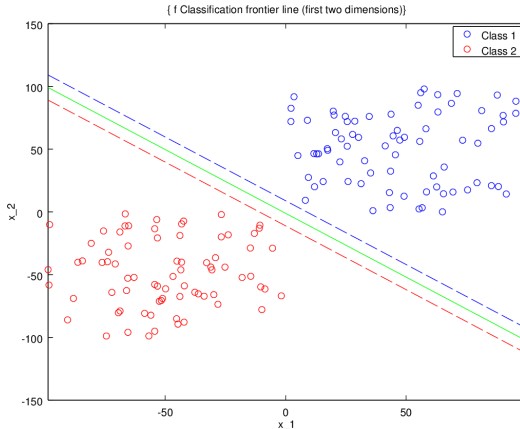
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Plotting the **classification frontier**

Pour $C = 5, n = 150, d = 200$

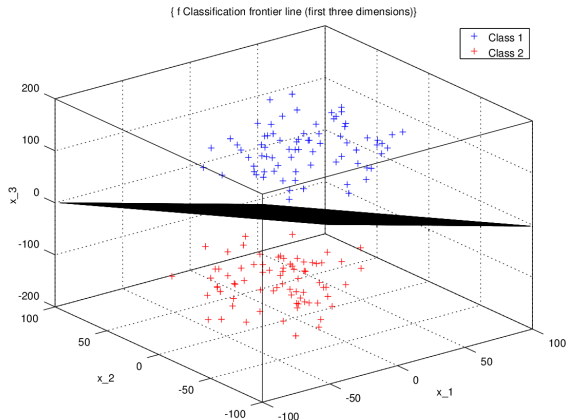
Points centrés réduits avec des fonctions gaussiennes (2D) :



Tracé de la frontière de classification

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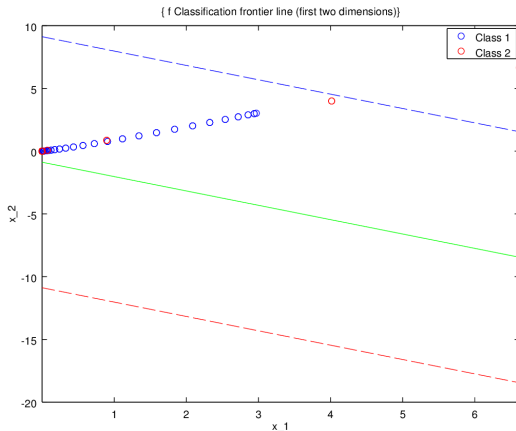
Points centrés réduits avec des fonctions gaussiennes (3D) :



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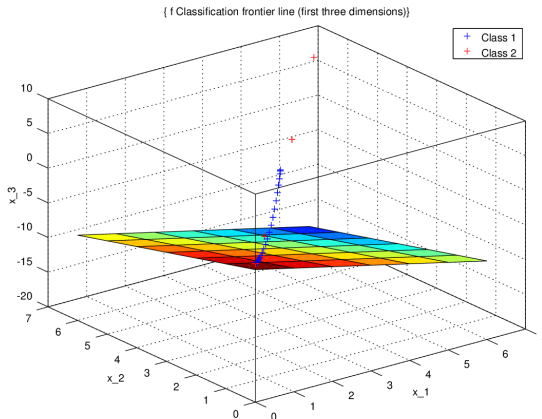
Génération avec des fonctions gaussiennes (2D) :



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Extensions

Adding to the project

- **Cross validation** (choice of the best value for C);

Extensions

Adding to the project

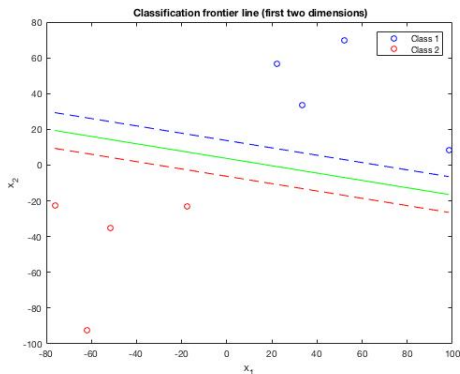
- **Cross validation** (choice of the best value for C);
- Implementation of **Coordinate Descent**;

Extensions

ACCPM results

■ Implementation of ACCPM;

Figure: For data of size 8, and dimension 2



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Demo of the SVM